考試日期: 2023/06/14

Quiz 16

學號:

1. 請框出答案. 2. 不可使用手機、計算器,禁止作弊!

1. Find a Jordan canonical form and a Jordan basis for the matrix A

$$A = \begin{bmatrix} i & 0 & 0 & 0 & 0 \\ 0 & i & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 2 & 0 \\ 2 & 0 & -1 & 0 & 2 \end{bmatrix}$$

Solution:

It is easy to find that the A only has the eigenvalue 2, whose algebraic multiplicity is 5.

i.e. nullity = 2 and
$$null(A-iI)=sp(\vec{e_2},\begin{bmatrix} -2+i\\0\\0\\0\\2 \end{bmatrix})=sp(\vec{b_1},\vec{b_2}).$$

From above, we know that

$$(A - iI) : \vec{b}_1 \to \vec{0}$$
$$\vec{b}_2 \to \vec{0}$$

Thus, pick
$$\vec{b}_1 = \vec{e}_2$$
, and $\vec{b}_2 = \begin{bmatrix} -2+i \\ 0 \\ 0 \\ 0 \\ 2 \end{bmatrix}$.

From above, we know that $(A-2I): \vec{b}_4 \to \vec{b}_3 \to \vec{0}$ and $sp(\vec{e}_4, \vec{e}_5) = sp(\vec{b}_3, \vec{b}_5)$ $sp(\vec{e}_4, \vec{e}_5, \vec{e}_3) = sp(\vec{b}_3, \vec{b}_5, \vec{b}_4)$

Since $\vec{b}_4 \in null((A-2I)^2)$ and $\vec{b}_4 \notin null(A-2I)$, we can pick $\vec{b}_4 = \vec{e}_3$.

Let $\vec{b}_3 = (A - \lambda I)\vec{b}_4 = (A - 2I)\vec{e}_3 = -\vec{e}_5$.

Since $\vec{b}_5 \in null(A-2I)$ and $\vec{b}_5 \neq \vec{b}_3$, we can pick $\vec{b}_5 = \vec{e}_4$.

$$V = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 & \vec{b}_3 & \vec{b}_4 & \vec{b}_5 \end{bmatrix} = \begin{bmatrix} 0 & -2+i & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 2 & -1 & 0 & 0 \end{bmatrix}, J = \begin{bmatrix} i & 0 & 0 & 0 & 0 \\ 0 & i & 0 & 0 & 0 \\ 0 & 0 & 2 & 1 & 0 \\ 0 & 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix}, A = VJV^{-1}$$

2. Find a Jordan canonical form and a Jordan basis for the matrix A

$$A = \begin{bmatrix} 2 & 5 & 0 & 0 & -1 \\ 0 & 2 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix}$$

Solution:

It is easy to find that the A only has the eigenvalue 2, whose algebraic multiplicity is 5.

From above, we know that

$$(A-2I): \vec{b}_{3} \to \vec{b}_{2} \to \vec{b}_{1} \to \vec{0} \vec{b}_{5} \to \vec{b}_{4} \to \vec{0}$$
 and
$$sp(\vec{e}_{1}, \vec{e}_{4}) = sp(\vec{b}_{1}, \vec{b}_{4}) sp(\vec{e}_{1}, \vec{e}_{4}, \vec{e}_{2}, \vec{e}_{5}) = sp(\vec{b}_{1}, \vec{b}_{4}, \vec{b}_{2}, \vec{b}_{5}) sp(\vec{e}_{1}, \vec{e}_{4}, \vec{e}_{2}, \vec{e}_{5}, \vec{e}_{3}) = sp(\vec{b}_{1}, \vec{b}_{4}, \vec{b}_{2}, \vec{b}_{5}, \vec{b}_{3})$$

Since $\vec{b}_3 \in null((A-2I)^3)$ and $\vec{b}_3 \notin null((A-2I)^2)$, we can pick $\vec{b}_3 = \vec{e}_3$. Let $\vec{b}_2 = (A-\lambda I)\vec{b}_3 = (A-2I)\vec{e}_3 = \vec{e}_2$, and $\vec{b}_1 = (A-\lambda I)\vec{b}_2 = (A-2I)\vec{e}_2 = 5\vec{e}_1$. Since $\vec{b}_5 \in null((A-2I)^2)$ and $\vec{b}_5 \notin null(A-2I)$ and $\vec{b}_5 \neq \vec{b}_3$, we can pick $\vec{b}_5 = \vec{e}_5$. Let $\vec{b}_1 = (A-\lambda I)\vec{b}_5 = (A-2I)\vec{e}_5 = -\vec{e}_1 + \vec{e}_4$.

$$V = \begin{bmatrix} \vec{b}_1 & \vec{b}_2 & \vec{b}_3 & \vec{b}_4 & \vec{b}_5 \end{bmatrix} = \begin{bmatrix} 5 & 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}, J = \begin{bmatrix} 2 & 1 & 0 & 0 & 0 \\ 0 & 2 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 & 2 \end{bmatrix}, A = VJV^{-1}$$