we see that

$$d_1 = 0$$
,  $d_2 = -1$ , and  $d_3 = 1$ .

Thus, Eq. (8) has the form

$$T^{k}(x + 2) = 2^{k}(-1)x^{2} + 4^{k}(1)(x^{2} + x + 2)$$

In particular,

$$T^4(x+2) = -16x^2 + 256(x^2 + x + 2) = 240x^2 + 256x + 512.$$

## **SUMMARY**

Let  $T: V \rightarrow V$  be a linear transformation of a finite-dimensional vector space into itself.

1. If B and B' are ordered bases of V, then the matrix representations  $R_B$  and  $R_B$  of T relative to B and to B' are similar. That is, there is an invertible matrix C—namely,  $C = C_{B,B}$ —such that

$$R_{R'} = C^{-1}R_RC.$$

- 2. Conversely, two similar  $n \times n$  matrices represent the same linear transformation of  $\mathbb{R}^n$  into  $\mathbb{R}^n$  relative to two suitably chosen ordered bases.
- 3. Similar matrices have the same eigenvalues with the same algebraic and geometric multiplicities.
- 4. If A and R are similar matrices with  $R = C^{-1}AC$ , and if v is an eigenvector of A, then  $C^{-1}v$  is an eigenvector of R corresponding to the same eigenvalue.
- 5. The transformation T is diagonalizable if V has a basis B consisting of eigenvectors of T. In this case, the matrix representation  $R_B$  is a diagonal matrix and computation of  $T^k(v)$  by  $R_B^k(v_B)$  becomes relatively easy.

## **EXERCISES**

In Exercises 1–14, find the matrix representations  $R_B$  and  $R_B$  and an invertible matrix C such that  $R_B = C^{-1}R_BC$  for the linear transformation T of the given vector space with the indicated ordered bases B and B'.

- 1.  $T: \mathbb{R}^2 \to \mathbb{R}^2$  defined by T([x, y]) = [x y, x + 2y]; B = ([1, 1], [2, 1]), B' = E
- 2.  $T: \mathbb{R}^2 \to \mathbb{R}^2$  defined by T([x, y]) = [2x + 3y, x + 2y]; B = ([1, -1], [1, 1]), B' = ([2, 3], [1, 2])

- 3.  $T: \mathbb{R}^3 \to \mathbb{R}^3$  defined by T([x, y, z]) = [x + y, x + z, y z]; B = ([1, 1, 1], [1, 1, 0], [1, 0, 0]), B' = E
- 4.  $T: \mathbb{R}^3 \to \mathbb{R}^3$  defined by T([x, y, z]) = [5x, 2y, 3z]; B and B' as in Exercise 3
- 5.  $T: \mathbb{R}^3 \to \mathbb{R}^3$  defined by T([x, y, z]) = [z, 0, x];B = ([3, 1, 2], [1, 2, 1], [2, -1, 0]), B' = ([1, 2, 1], [2, 1, -1], [5, 4, 1])
- 6.  $T: \mathbb{R}^2 \to \mathbb{R}^2$  defined as reflection of the plane through the line 5x = 3y; B = ([3, 5], [5, -3]), B' = E

- 7.  $T: \mathbb{P}^3 \to \mathbb{R}^3$  defined as reflection of  $\mathbb{R}^3$  through the plane x + y + z = 0; B = ([1, 0, -1], [1, -1, 0], [1, 1, 1]), B' = E
- 8.  $T: \mathbb{R}^3 \to \mathbb{R}^3$  defined as reflection of  $\mathbb{R}^3$  through the plane 2x + 3y + z = 0; B = ([2, 3, 1], [0, 1, -3], [1, 0, -2]), B' = E
- 9.  $T: \mathbb{R}^3 \to \mathbb{R}^3$  defined as projection on the plane  $x_2 = 0$ ; B = E, B' = ([1, 0, 1], [1, 0, -1], [0, 1, 0])
- 10.  $T: \mathbb{R}^3 \to \mathbb{R}^3$  defined as projection on the plane x + y + z = 0; B and B' as in Exercise 7.
- 11.  $T: P_2 \to P_2$  defined by T(p(x)) = p(x+1) + p(x);  $B = (x^2, x, 1)$ ,  $B' = (1, x, x^2)$
- 12.  $T: P_2 \to P_2$  as in Exercise 11, but using  $B = (x^2, x, 1)$  and  $B' = (x^2 + 1, x + 1, 2)$
- 13.  $T: P_3 \to P_3$  defined by T(p(x)) = p'(x), the derivative of p(x);  $B = (x^3, x^2, x, 1)$ ,  $B' = (1, x + 1, x^2 + 1, x^3 + 1)$
- 14.  $T: W \to W$ , where  $W = \operatorname{sp}(e^x, xe^x)$  and T is the derivative transformation;  $B = (e^x, xe^x)$ ,  $B' = (2xe^x, 3e^x)$
- 15. Let T: P<sub>2</sub> → P<sub>2</sub> be the linear transformation and B' the ordered basis of P<sub>2</sub> given in Example 3. Find the matrix representation R<sub>B'</sub> of T by computing the matrix with column vectors T(b'<sub>1</sub>)<sub>B'</sub>, T(b'<sub>2</sub>)<sub>B'</sub>, T(b'<sub>3</sub>)<sub>B'</sub>.
- 16. Repeat Exercise 15 for the transformation in Example 5 and the basis  $B' = (x + 1, -1, x^2 + x)$  of  $P_2$ .

In Exercises 17–22, find the eigenvalues  $\lambda_i$  and the corresponding eigenspaces of the linear transformation T. Determine whether the linear transformation is diagonalizable.

- 17. T defined on  $\mathbb{R}^2$  by T([x, y]) = [2x 3y, -3x + 2y]
- 18. T defined on  $\mathbb{R}^2$  by T([x, y]) = [x y, -x + y]
- 19. T defined on  $\mathbb{R}^3$  by  $T([x_1, x_2, x_3]) = [x_1 + x_3, x_2, x_1 + x_3]$

- **20.** T defined on  $\mathbb{R}^3$  by  $T([x_1, x_2, x_3]) = [x_1, 4x_2 + 7x_3, 2x_2 x_3]$
- 21. T defined on  $\mathbb{R}^3$  by  $T([x_1, x_2, x_3]) = [5x_1, -5x_1 + 3x_2 5x_3, -3x_1 2x_2]$
- 22. T defined on  $\mathbb{R}^3$  by  $T([x_1, x_2, x_3]) = [3x_1 x_2 + x_3, -2x_1 + 2x_2 x_3, 2x_1 + x_2 + 4x_3]$
- 23. Mark each of the following True or False
- a. Two similar  $n \times n$  matrices represent the same linear transformation of  $\mathbb{R}^n$  into itself relative to the standard basis.
- \_\_\_ b. Two different  $n \times n$  matrices represent different linear transformations of  $\mathbb{R}^n$  into itself relative to the standard basis.
- c. Two similar  $n \times n$  matrices represent the same linear transformation of  $\mathbb{R}^n$  into itself relative to two suitably chosen bases for  $\mathbb{R}^n$ .
- \_\_\_\_ d. Similar matrices have the same eigenvalues and eigenvectors.
- e. Similar matrices have the same eigenvalues with the same algebraic and geometric multiplicities.
- \_\_\_ f. If A and C are  $n \times n$  matrices and C is invertible and v is an eigenvector of A, then  $C^{-1}v$  is an eigenvector of  $C^{-1}AC$ .
- \_\_\_ g. If A and C are  $n \times n$  matrices and C is invertible and v is an eigenvector of A, then Cv is an eigenvector of  $CAC^{-1}$ .
- h. Any two n × n diagonal matrices are similar.
- i. Any two  $n \times n$  diagonalizable matrices having the same eigenvectors are similar.
- \_\_\_ j. Any two  $n \times n$  diagonalizable matrices having the same eigenvalues of the same algebraic multiplicities are similar.
- 24. Prove statement 2 of Theorem 7.2.
- 25. Prove statement 3 of Theorem 7.2.
- 26. Let A and R be similar matrices. Prove in two ways that A<sup>2</sup> and R<sup>2</sup> are similar matrices: using a matrix argument, and using a linear transformation argument.
- 27. Give a determinant proof that similar matrices have the same eigenvalues.