

Section 9-2 How the "cross product" works in \mathbb{C}^3

Check the idea for cross product in Ch4.

4.1 AREAS, VOLUMES, AND CROSS PRODUCTS 241

The Cross Product

Equation (2) defines a **second-order determinant**, associated with a 2×2 matrix. Another application of these second-order determinants appears when we find a vector in \mathbb{R}^3 that is perpendicular to each of two given independent vectors $\mathbf{b} = [b_1, b_2, b_3]$ and $\mathbf{c} = [c_1, c_2, c_3]$. Recall that the unit coordinate vectors in \mathbb{R}^3 are $\mathbf{i} = [1, 0, 0]$, $\mathbf{j} = [0, 1, 0]$, and $\mathbf{k} = [0, 0, 1]$. We leave as an exercise the verification that

$$\mathbf{p} = \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} \mathbf{i} - \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} \mathbf{j} + \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix} \mathbf{k} \quad (3)$$

is a vector perpendicular to both \mathbf{b} and \mathbf{c} . (See Exercise 5.) This can be seen by computing $\mathbf{p} \cdot \mathbf{b} = \mathbf{p} \cdot \mathbf{c} = 0$. The vector \mathbf{p} in formula (3) is known as the **cross product** of \mathbf{b} and \mathbf{c} , and is denoted $\mathbf{p} = \mathbf{b} \times \mathbf{c}$.

There is a very easy way to remember formula (3) for the cross product $\mathbf{b} \times \mathbf{c}$. Form the 3×3 *symbolic matrix*

$$\begin{bmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{bmatrix}.$$

Formula (3) can be obtained from this matrix in a simple way. Multiply the vector \mathbf{i} by the determinant of the 2×2 matrix obtained by crossing out the row and column containing \mathbf{i} , as in

$$\begin{bmatrix} \overline{\mathbf{j}} & \overline{\mathbf{k}} \\ b_1 & b_3 \\ c_1 & c_3 \end{bmatrix}.$$

Similarly, multiply $(-\mathbf{j})$ by the determinant of the matrix obtained by crossing out the row and column in which \mathbf{j} appears. Finally, multiply \mathbf{k} by the determinant of the matrix obtained by crossing out the row and column containing \mathbf{k} , and add these multiples of \mathbf{i} , \mathbf{j} , and \mathbf{k} to obtain formula (3).

Similarly, in the complex space, let $\vec{p} = \vec{b} \times \vec{c}$ and then have $\vec{b} \cdot \vec{p} = 0 = \vec{c} \cdot \vec{p}$. Try to build \vec{p} in the same way, and note that the cross product will turn the first vector into its conjugation. $\vec{b} \cdot \vec{p} = \overline{\vec{b}^T} \vec{p}$.

$$\text{If } \vec{p} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \overline{b_1} & \overline{b_2} & \overline{b_3} \\ \overline{c_1} & \overline{c_2} & \overline{c_3} \end{vmatrix}, \text{ then } \vec{b} \cdot \vec{p} = \begin{vmatrix} \overline{b_1} & \overline{b_2} & \overline{b_3} \\ \overline{b_1} & \overline{b_2} & \overline{b_3} \\ \overline{c_1} & \overline{c_2} & \overline{c_3} \end{vmatrix} = 0 = \begin{vmatrix} \overline{c_1} & \overline{c_2} & \overline{c_3} \\ \overline{b_1} & \overline{b_2} & \overline{b_3} \\ \overline{c_1} & \overline{c_2} & \overline{c_3} \end{vmatrix} = \vec{c} \cdot \vec{p}$$

Hence, that is the "cross product" that we are looking for.