

Deep Learning lecture 8 Sequence Modeling (1)

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Apr-7

Today's Topic

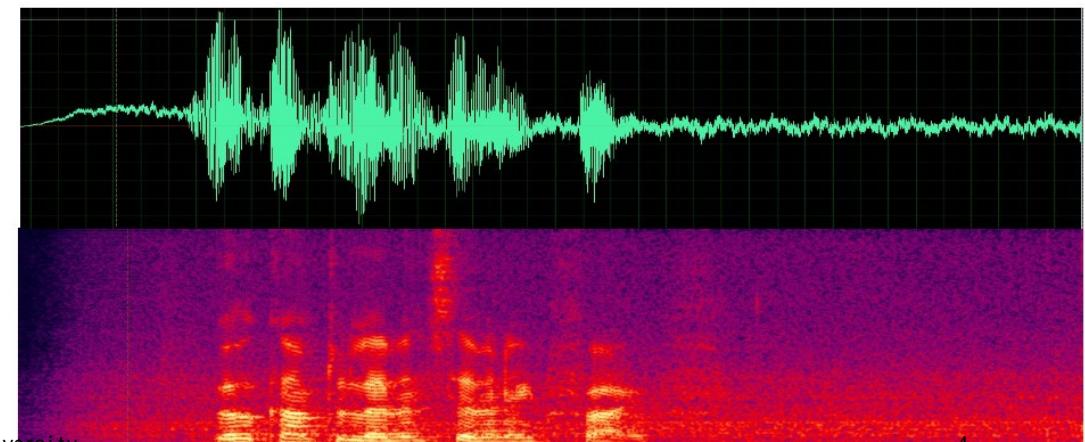
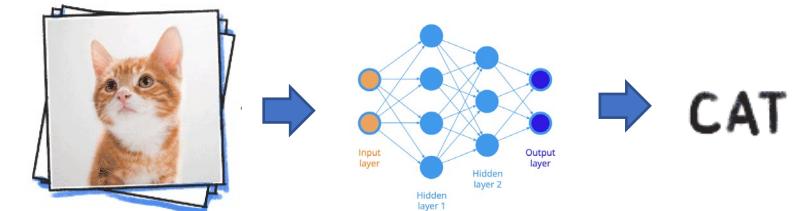
- Basic models for sequence data
 - Recurrent neural networks
 - LSTM
- Basic techniques for modeling natural language

Story So Far

- Supervised Learning (Lec. 2~3)
 - Discriminative Models
 - Network architectures and learning algorithms
- Generative Models (Lec. 4~7)
 - Energy-based models (contrastive divergence + MCMC)
 - VAE (variational inference)
 - GAN (neural loss function)
 - Flow model (bijections)
 - Diffusion model (denoising score matching)
 - Trade-offs between expressiveness, inference and training

Sequence Data

- Most existing discussions assume fixed dimensions
 - E.g.: Image classification and generation
 - Input image has fixed width and height
 - Fixed output dimension
 - Fixed amount of network layers and parameters
- What if the dimension of input varies a lot?
 - **Finding the “welcome”** (lecture 2)



Sequence Data

- Most existing discussions assume:
 - E.g.: Image classification and generation
 - Input image has fixed width and height
 - Fixed output dimension
 - Fixed amount of network layers
- What if the dimension of input is not fixed?
 - Finding the “welcome” (lecture)
 - Generating poet



ChatGPT

深度之梦
在数据的海洋里遨游，
算法如风，吹散迷雾。
神经元闪烁似星辰，
连接着未来的道路。
梯度回溯千重浪，
优化求解万象生。
一行代码塑乾坤，
模型自我去提升。



Sequence Data

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 - Fixed amount of network layers and parameters
- What if the dimension of input varies a lot?
 - Finding the “welcome” (lecture 2)
 - Generating poet
 - **Machine translation**



Sequence Data

- Most existing discussions assume fixed dimensions
 - E.g.: Image classification and generation
 - Input image has fixed width and height

We need a generative model for any data dimension!

- Generating poet
- Machine translation



Autoregressive Model

- Goal: a tractable $p(x)$ for x of any dimension L
 - In particular, we consider sequential data $x = [x_1, x_2, \dots, x_L]$, L may change

- Autoregressive modeling

$$p(x) = \prod_{1 \leq i \leq L} p(x_i | x_1 \dots x_{i-1})$$

- Key idea: decompose a joint sequence into ordered conditionals
 - Use previous dimensions to “*predict*” the next dimension
 - Example: Gaussian auto-regressive models

$$p(x_i | x_1 \dots x_{i-1}) \sim N(\mu_\theta(x_1 \dots x_{i-1}), \sigma_\theta^2(x_1 \dots x_{i-1}))$$

Autoregressive Model

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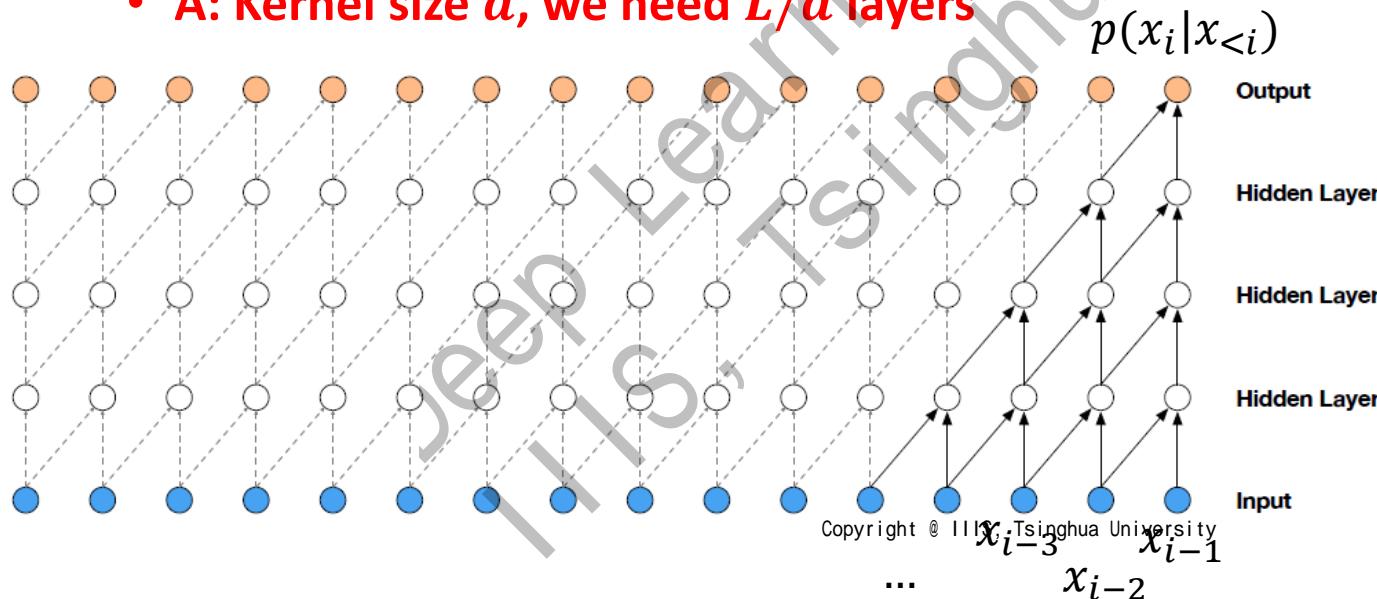
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How to design these two networks???

Temporal Convolution

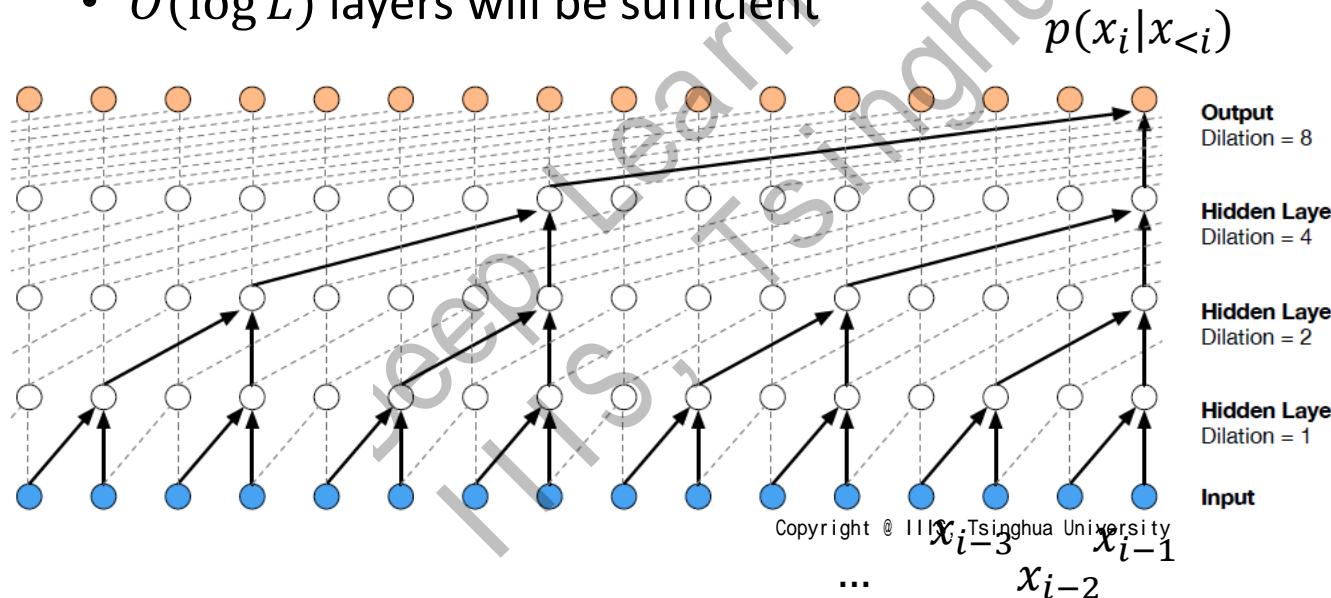
- WaveNet (DeepMind, 2016)
 - Goal: voice synthesis
 - $p(x) = \prod_i p(x_i | x_1, \dots, x_{i-1})$
 - Idea: temporal convolution
 - **Q: how many layers do you need?**
 - **A: Kernel size d , we need L/d layers**



Temporal Convolution

- WaveNet (DeepMind, 2016)

- Goal: voice synthesis
- $p(x) = \prod_i p(x_i | x_1, \dots, x_{i-1})$
- Idea: temporal convolution
 - **Dilated Convolution!**
 - $O(\log L)$ layers will be sufficient



1 Second

- Computation Cost**
- Generation
 - Sequential: $O(L)$
 - Likelihood:
 - fully parallel (CNN)

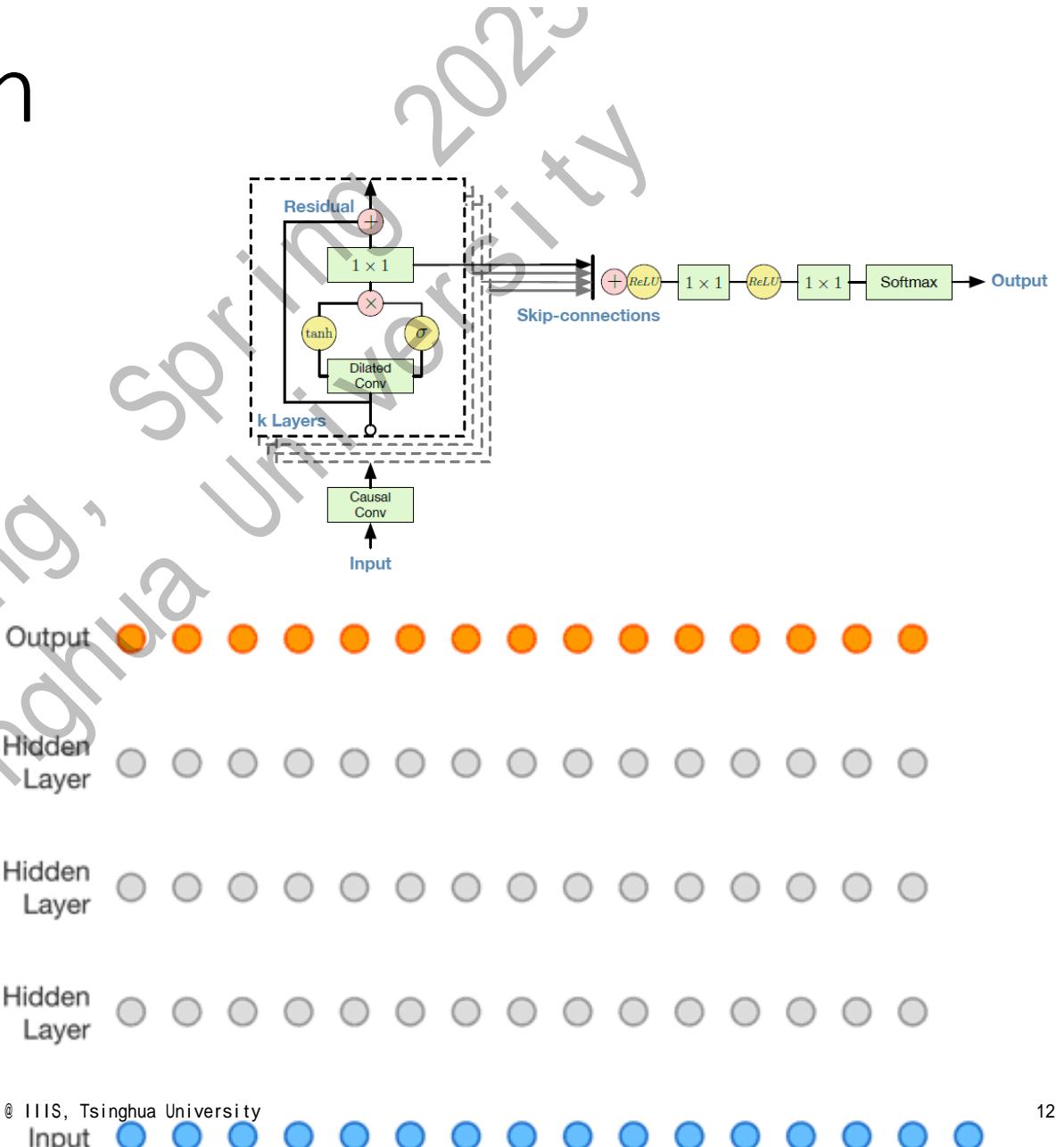
Temporal Convolution

- WaveNet (DeepMind, 2016)
 - $p(x) = \prod_i p(x_i | x_1, \dots, x_{i-1})$
 - Dilated Temporal Convolution
 - And more
 - Quantization
 - Residual connection
 - Conditioned generation
 - $p(x|h)$
- Remark
 - First deep generative model that can generate raw signals
(also check newer ones Jukebox & Suno)

<https://deepmind.com/blog/article/wavenet-generative-model-raw-audio>

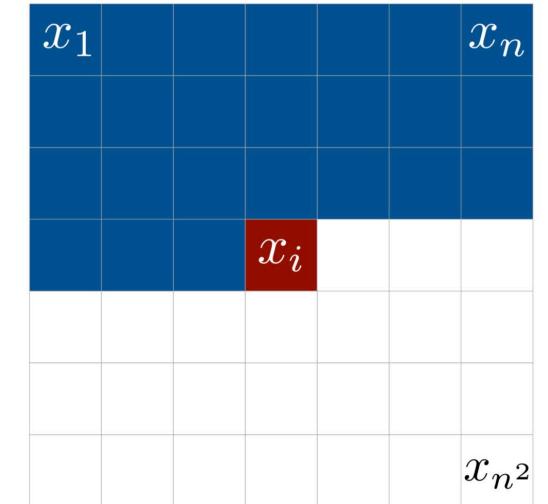
<https://openai.com/blog/jukebox/>

<https://www.suno.ai/>



Autoregressive Model for Images

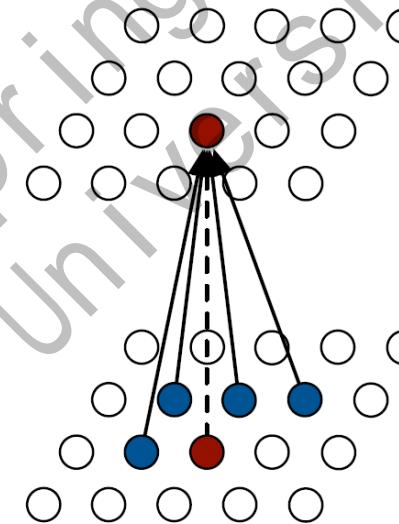
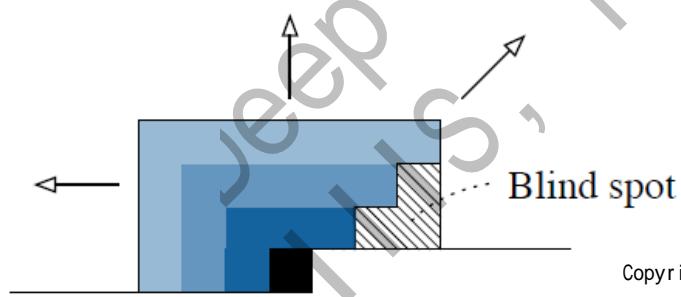
- PixelCNN (DeepMind, ICML 2016)
 - Autoregressive model over images
 - $p(x) = \prod_i^{D^2} p(x_i | x_1, \dots, x_{i-1})$
 - CNN?
 - How to design the convolution filter?
 - Goal: the convolution filter only takes in previous values



Context

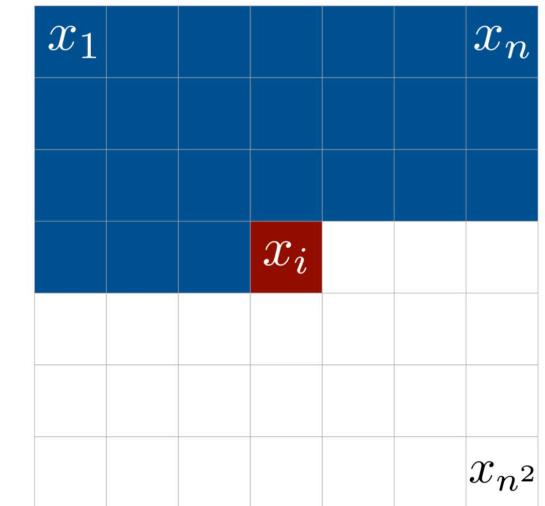
Autoregressive Model for Images

- PixelCNN (DeepMind, ICML 2016)
 - Autoregressive model over images
 - $p(x) = \prod_i^{D^2} p(x_i|x_1, \dots, x_{i-1})$
 - **Masked Convolution**
 - Each pixel only takes in previous values
 - Likelihood evaluation is in perfect parallel
 - Issues?
 - Receptive fields have blind spots!

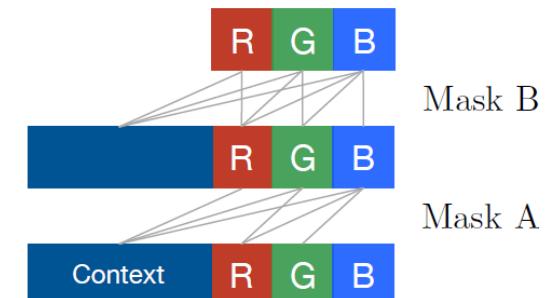


1	1	1	1	1
1	1	1	1	1
1	1	0	0	0
0	0	0	0	0
0	0	0	0	0

Mask

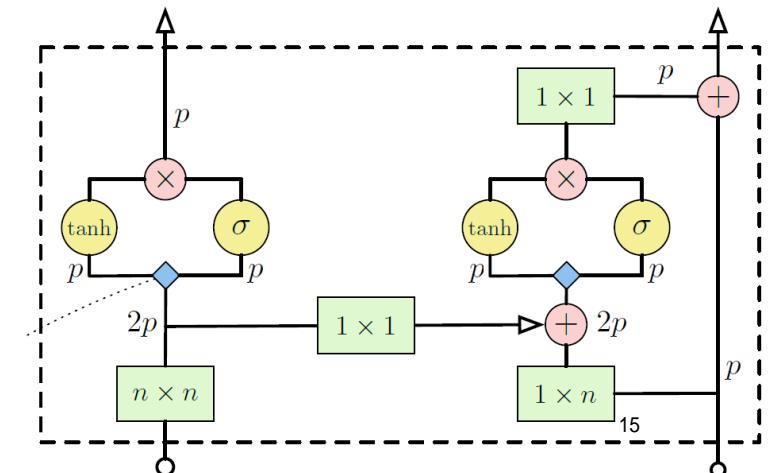
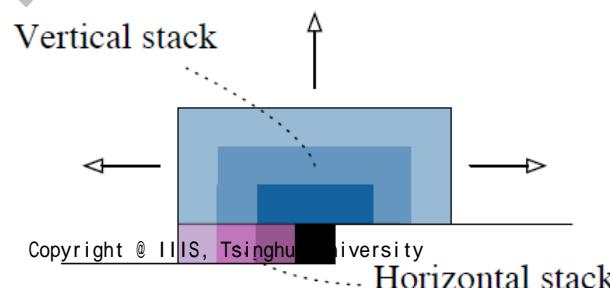
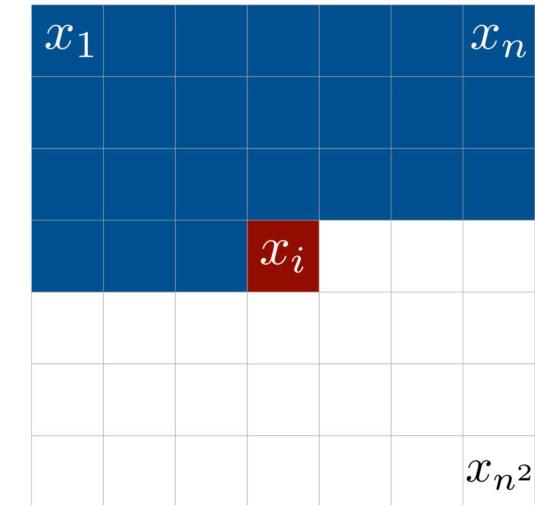
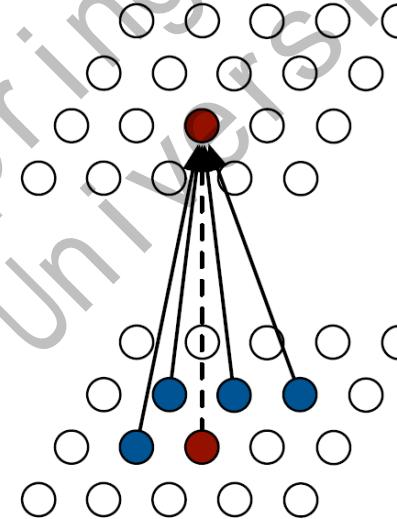


Context



Autoregressive Model for Images

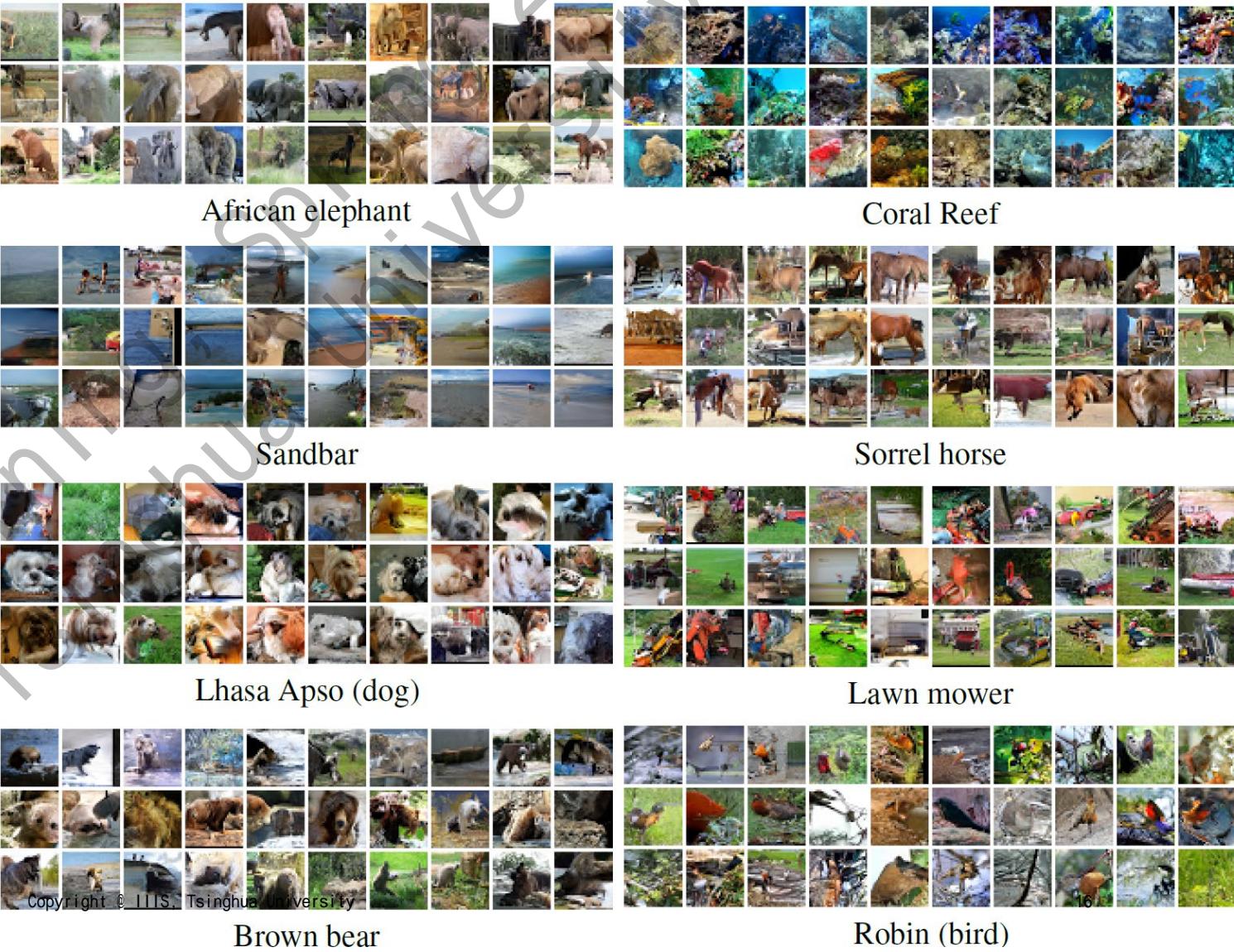
- PixelCNN (DeepMind, ICML 2016)
 - Autoregressive model over images
 - $p(x) = \prod_i^{N^2} p(x_i|x_1, \dots, x_{i-1})$
 - **Masked Convolution**
 - Each pixel only takes in previous values
 - Likelihood evaluation is in perfect parallel
- Gated PixelCNN (DeepMind, NIPS 2016)
 - Corrected receptive field (homework ☺)
 - Gated convolution
 - “Gating” technique
 - Inspired by LSTM
 - More details later



Autoregressive Model for Images

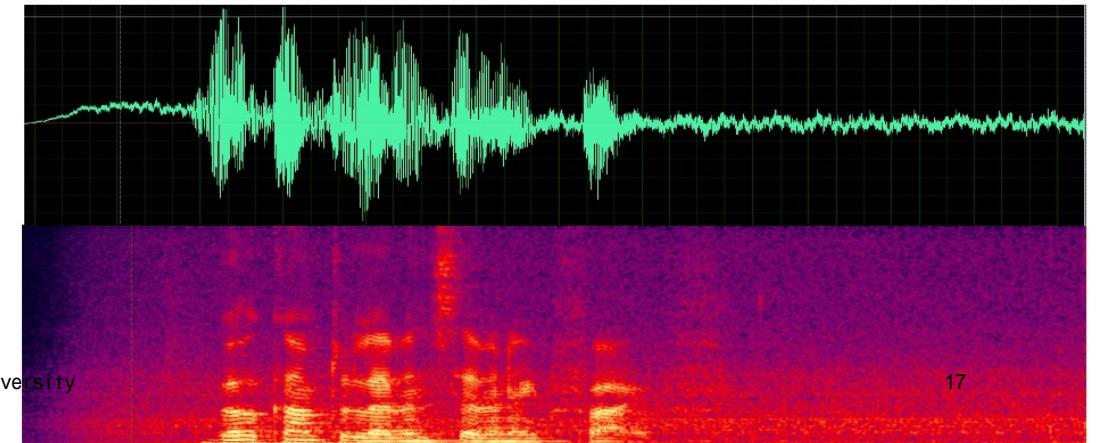
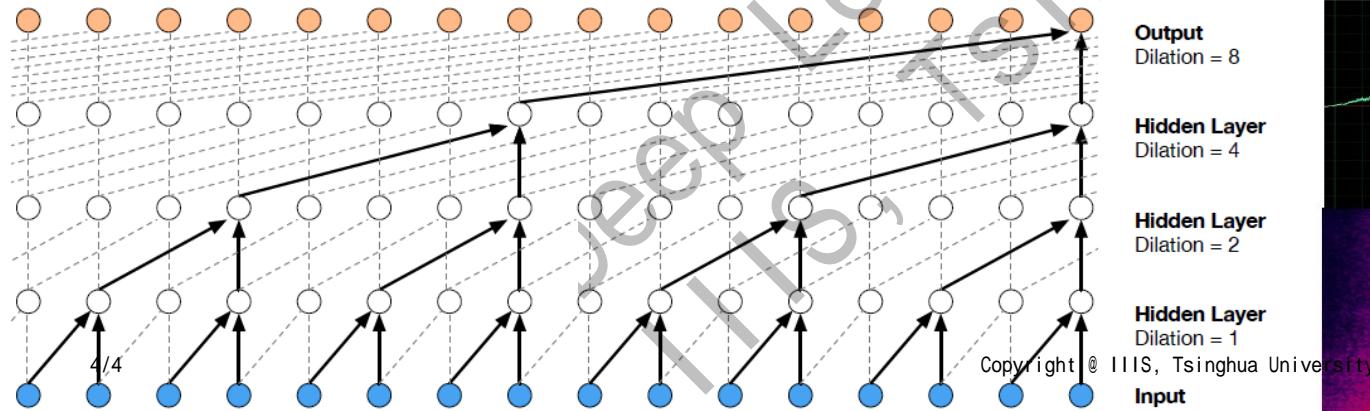
- Conditioned generation

Gated PixelCNN



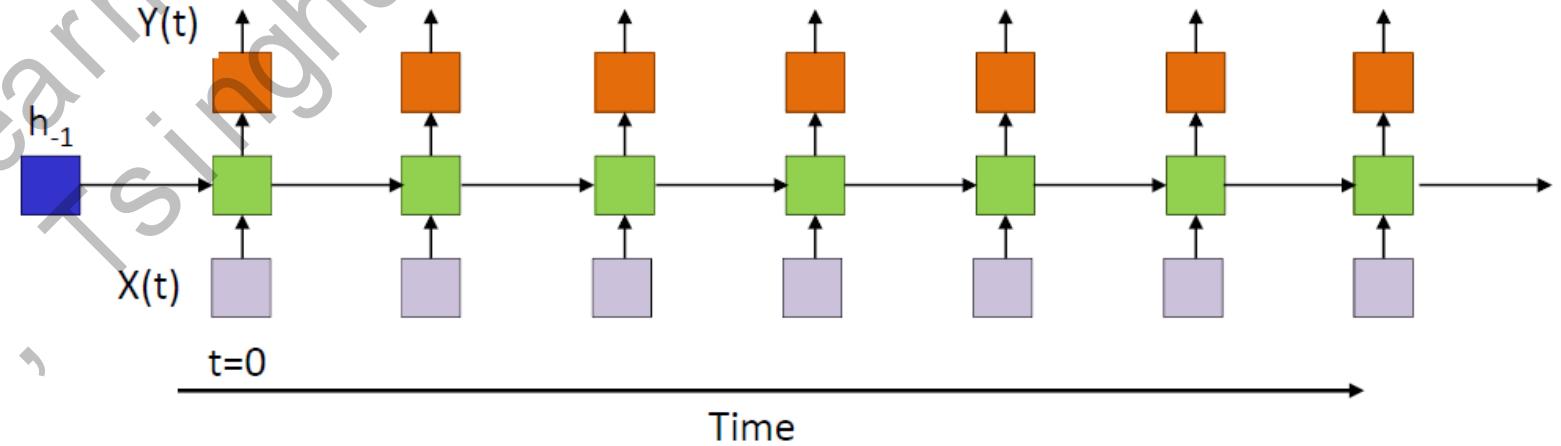
Sequence Data (Recap)

- Finding or synthesizing the “Welcome” voice
 - Input data $x = [x_1 \dots x_L]$, L may vary
 - Autoregressive modeling: $p(x) = \prod_i p(x_i | x_1 \dots x_{i-1})$
- Improved Temporal Convolution: Dilated ConvNet (WaveNet)
 - Parameter size is fixed, but need $O(\log L)$ layers to cover the entire sequence
 - This is a network of **varying/unbounded depth** for arbitrarily long sequences



State-Space Model

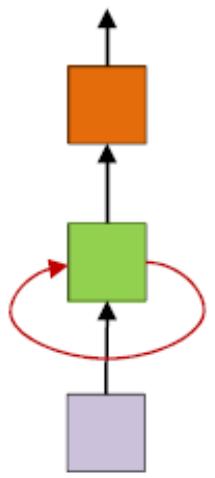
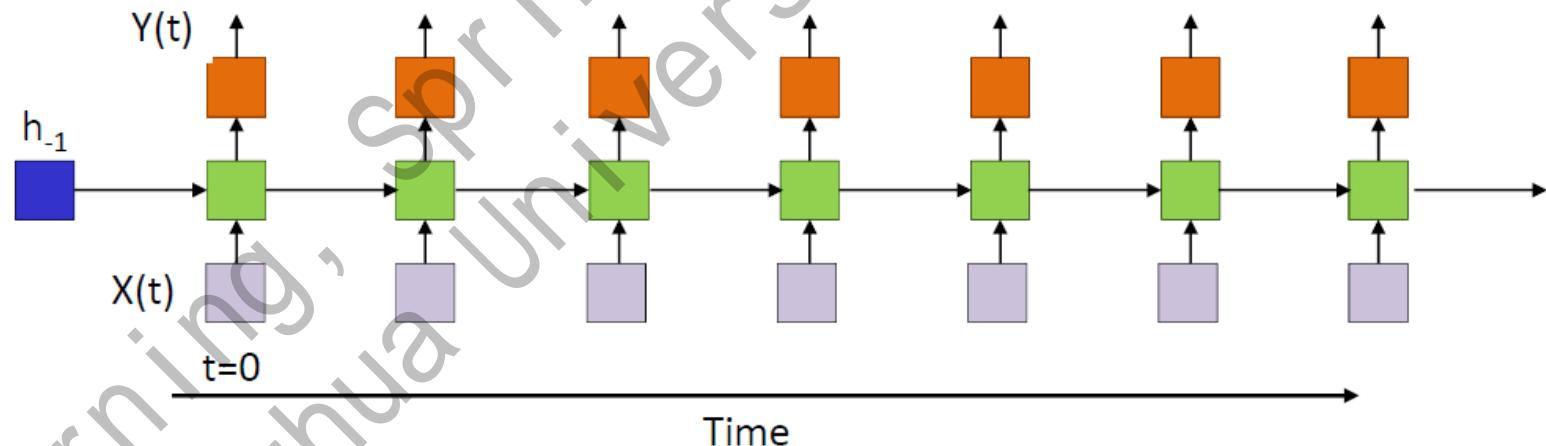
- Finding the “Welcome”
 - Input sequence data $X_1 \dots X_L$, L may vary (X_i can be a general vector)
 - Whether the voice contains “Welcome”
- Goal: a fixed-size model for arbitrarily long sequences
- State-Space Model
 - h_t : (hidden) state
 - X_t : input
 - Y_t : output
 - $Y_t, h_t = f(h_{t-1}, X_t; \theta)$
 - h_{-1} : initial state



4/4 Key idea: compress any prefix sequence $[x_0 \dots x_t]$ into a fixed dimension vector h_t

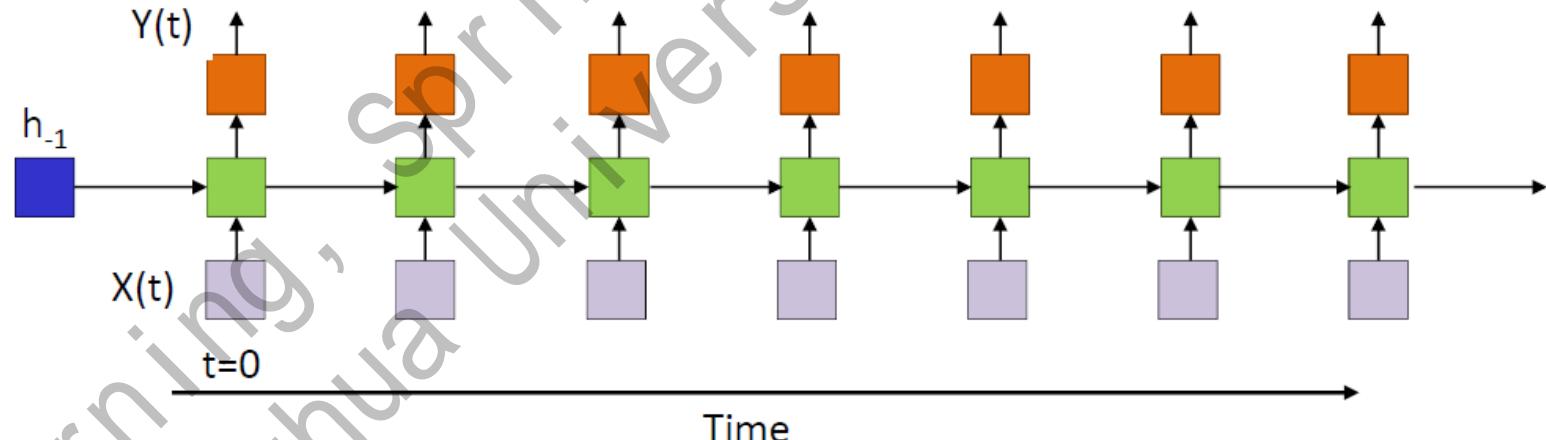
Recurrent Neural Network

- State-Space Model
 - h_t : (hidden) state
 - X_t : input; Y_t : output
 - $h_t = f_1(h_{t-1}, X_t; \theta)$
 - $Y_t = f_2(h_t; \theta)$
 - h_{-1} : initial state
- Same neural network across all the columns!
 - Simplified drawing (loops implies recurrence)
 - h_t : a vector that summarizes all past inputs (also called “memory”)
 - h_{-1} affects the whole network (typically set to zero)
 - Y_t is computed over X_0, \dots, X_t
 - X_t affect all the outputs and states after t



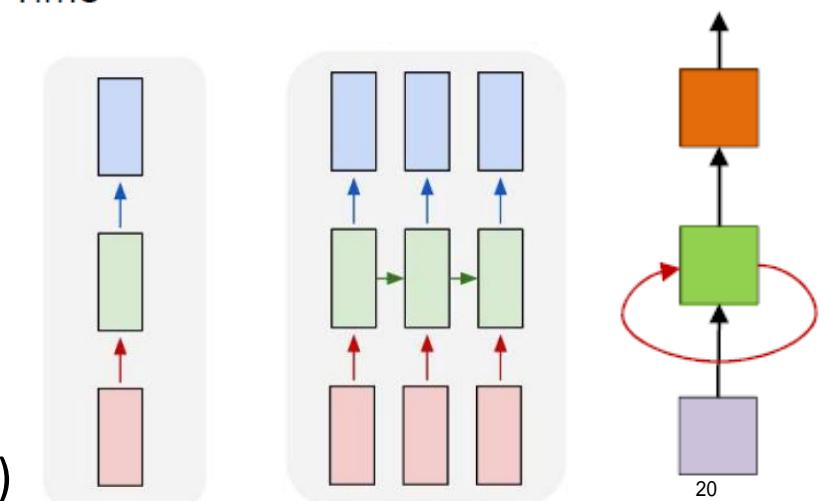
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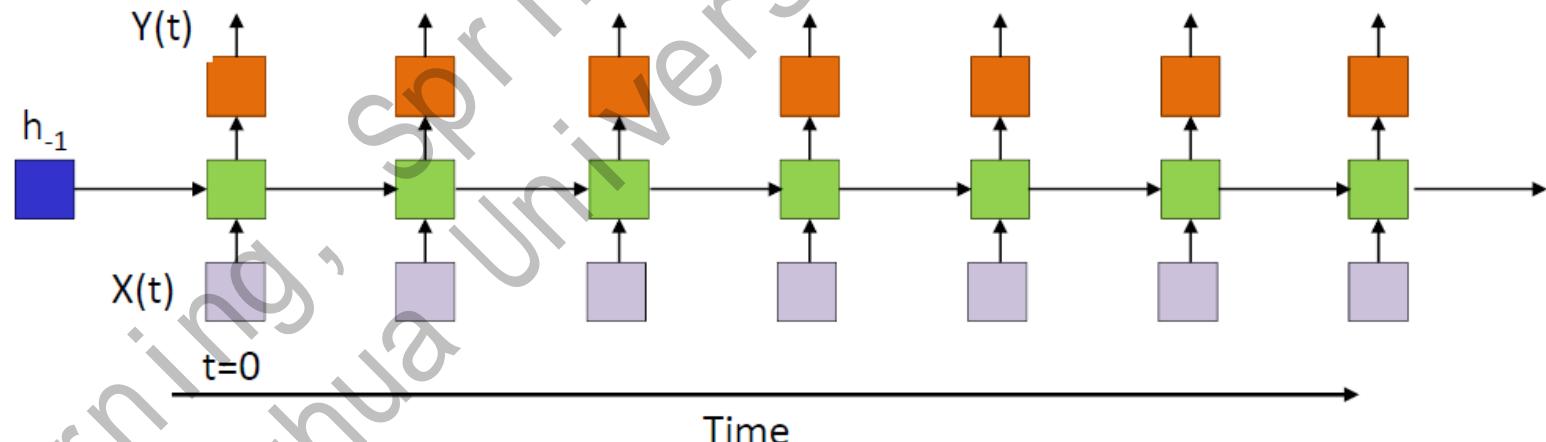
- Same neural network across all the columns!

- MLP v.s. RNN
 - RNN can be viewed as repeatedly applying MLPs
 - $h_t = f_1(W^{(1)} \cdot X_t + W^{(11)} \cdot h_{t-1} + b^{(1)})$
 - $Y_t = f_2(W^{(2)} h_t + b^{(2)})$
 - f_1, f_2 are activations (e.g., Sigmoid, tanh, ReLU, Softmax)



Recurrent Neural Network

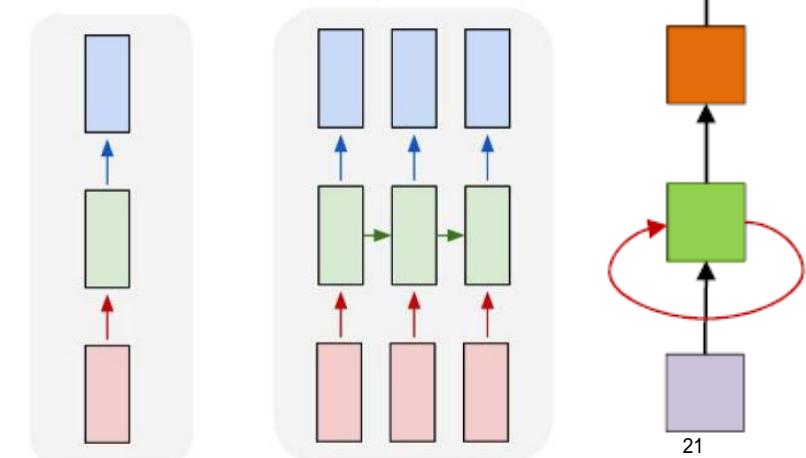
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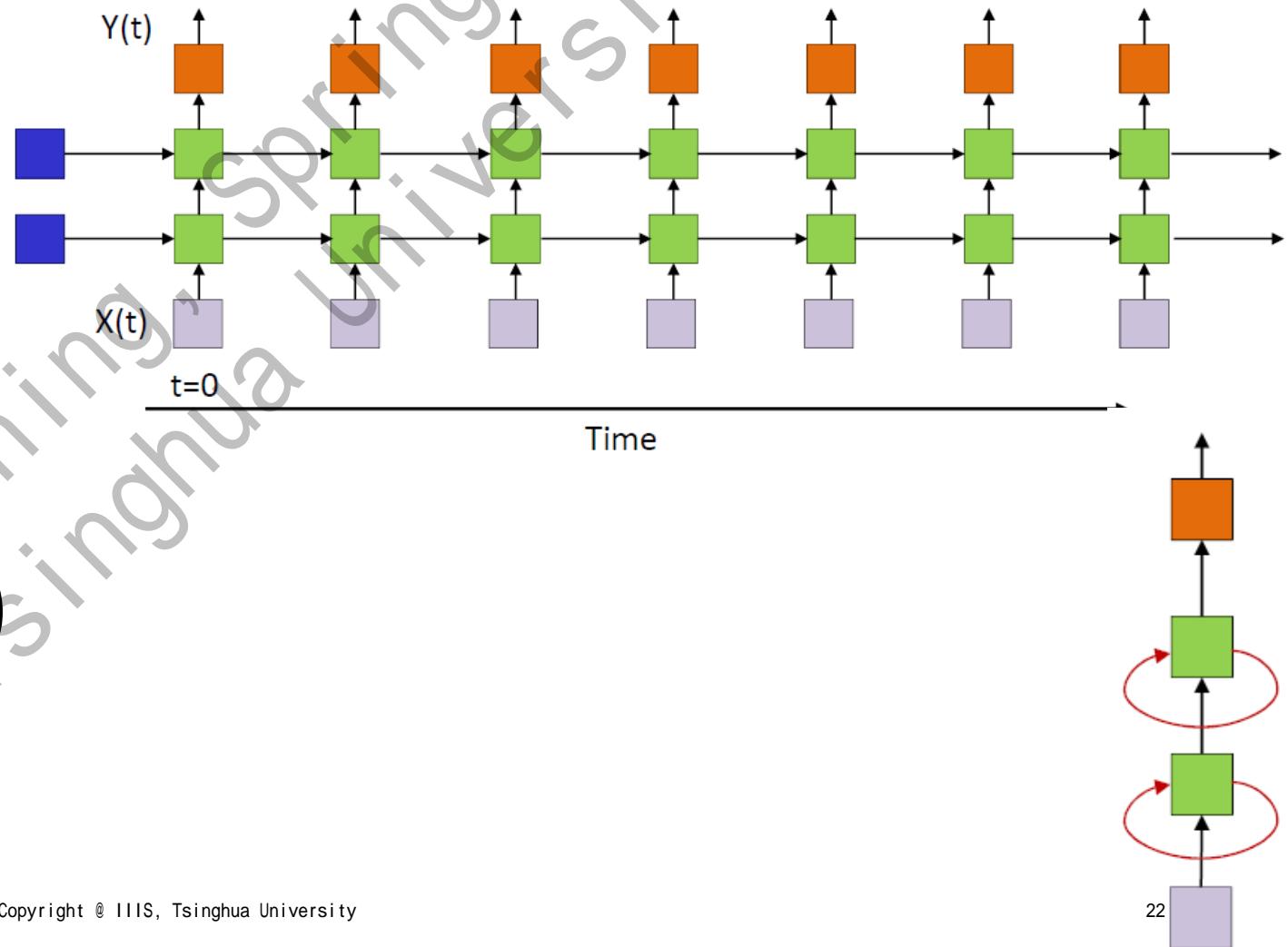
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Recurrent weights!



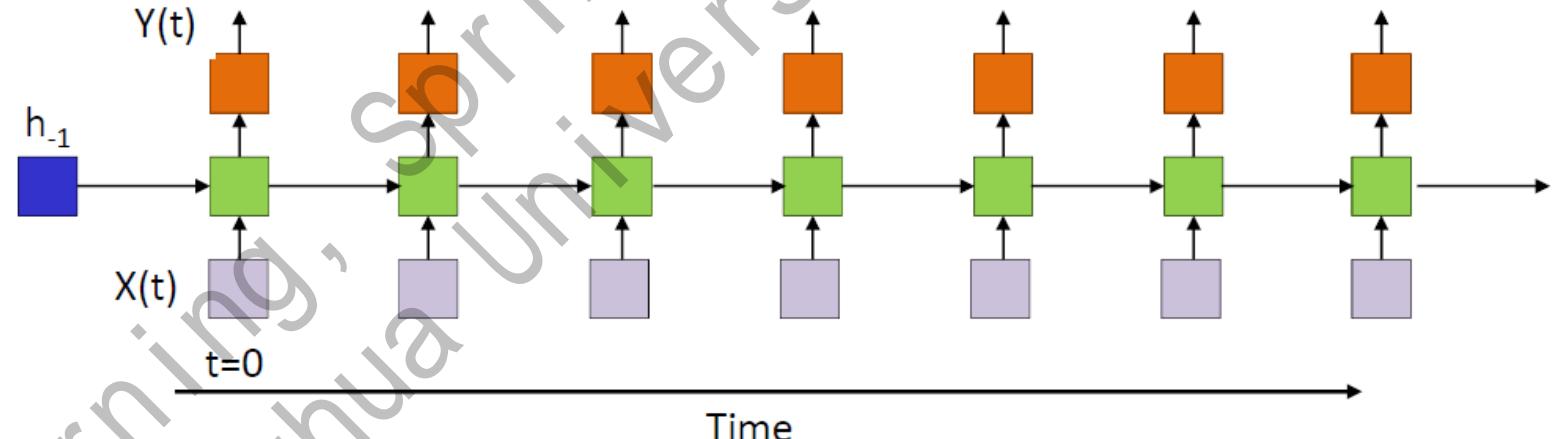
Recurrent Neural Network

- Stack K layers of RNNs!
 - Multi-layer RNN
- State-Space Model
 - $h_t^{(k)}$: (hidden) states
 - X_t : input; Y_t : output
 - $h_t^{(1)} = f_1^{(1)}(h_{t-1}^{(1)}, X_t; \theta)$
 - $h_t^{(k)} = f_1^{(k)}(h_{t-1}^{(k)}, h_t^{(k-1)}; \theta)$
 - $Y_t = f_2(h_t^{(K)}; \theta)$
 - $h_{-1}^{(k)}$: initial states



Recurrent Neural Network

- State-Space Model
 - h_t : (hidden) state
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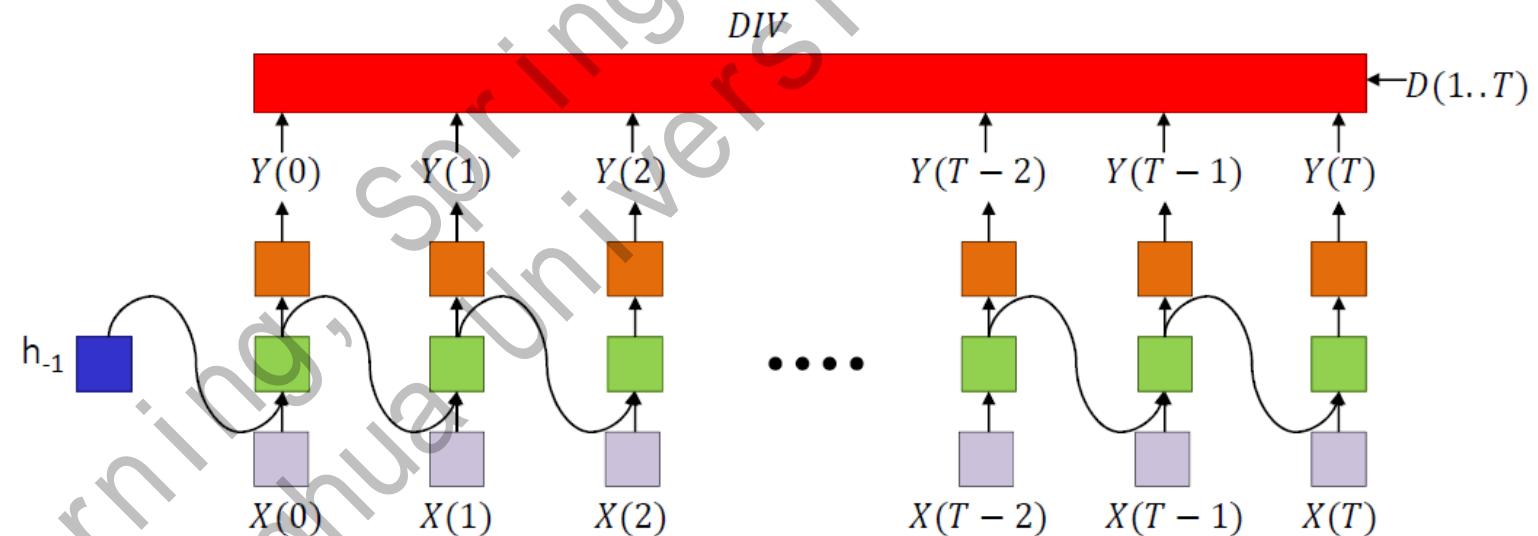


• How to train an RNN?

- Assume we have paired input and target sequence $\{(X_t, D_t)\}_t$
 - Remark
 - RNN can handle much more flexible data format than fully paired data
 - But let's simply keep this assumption for now

Recurrent Neural Network

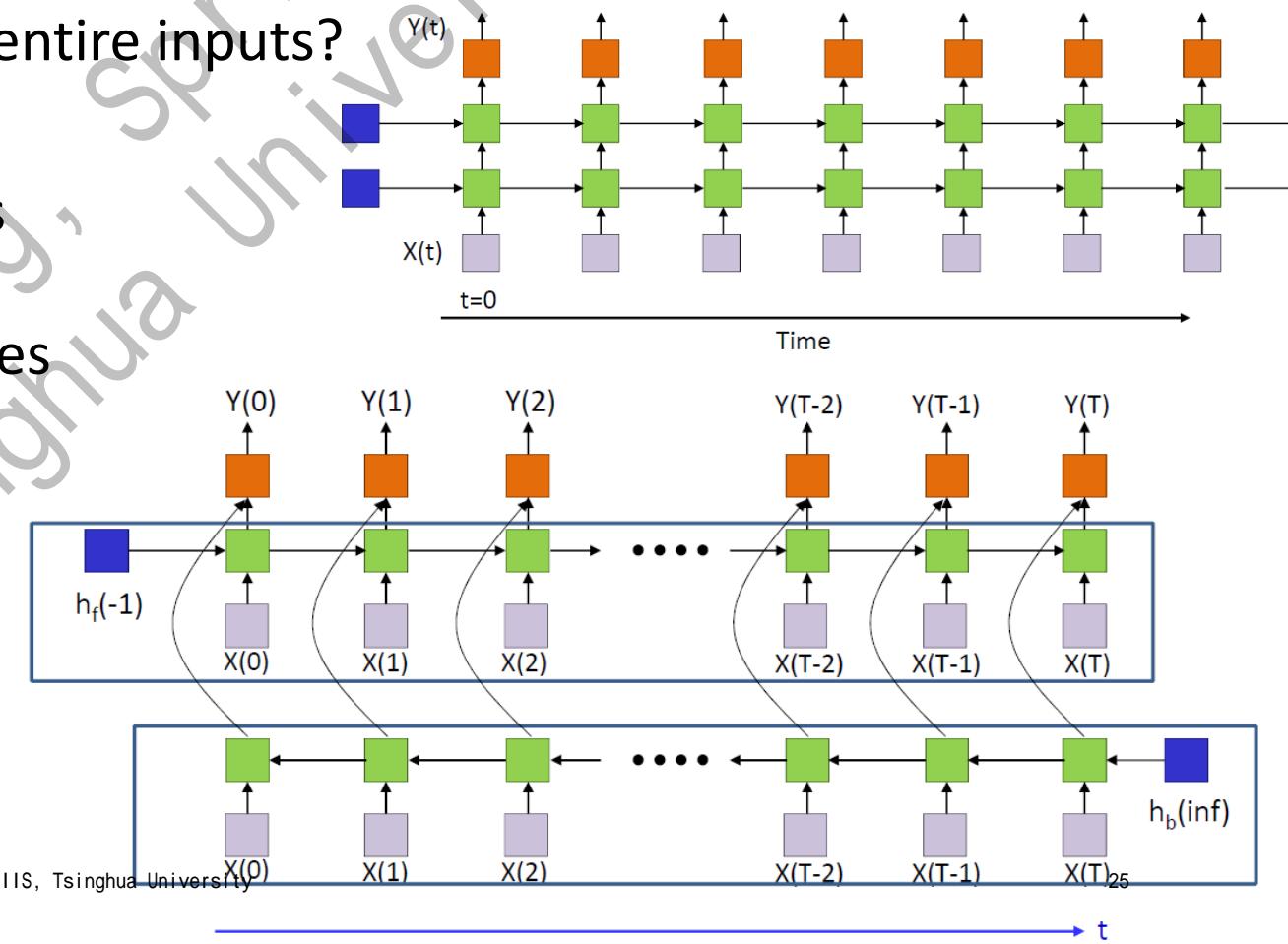
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- How to train an RNN?
 - Assume we have paired input and target sequence $\{(X_t, D_t)\}_t$
 - **We can define the loss function $L(\theta) = \sum_t \text{Div}(Y_t, D_t)$**
 - Goal: learn the best parameter θ^* via gradient descent
 - Backpropagation through time (BPTT)!
 - Forward pass from $t = 0 \rightarrow L$, backward pass $t = L \rightarrow 0$
 - Pay attention to gradient accumulation for recurrent weights!

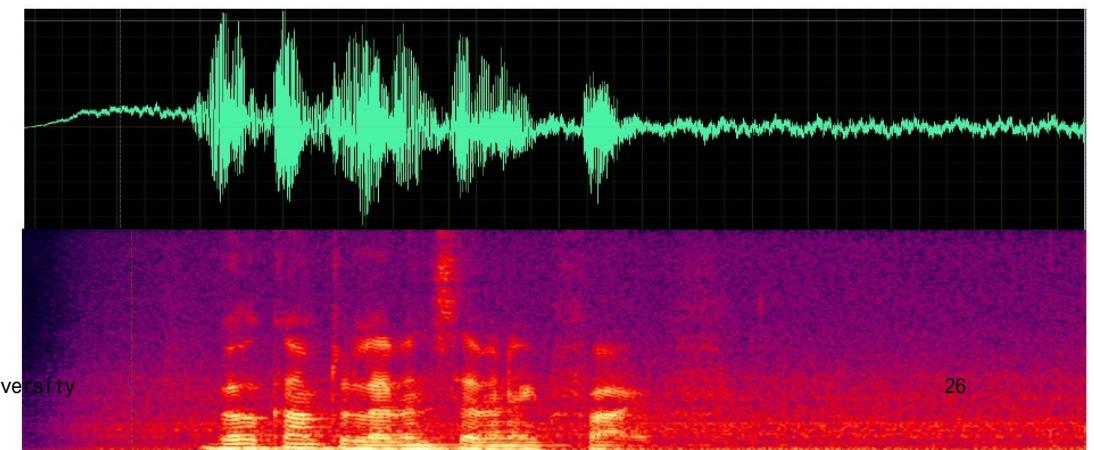
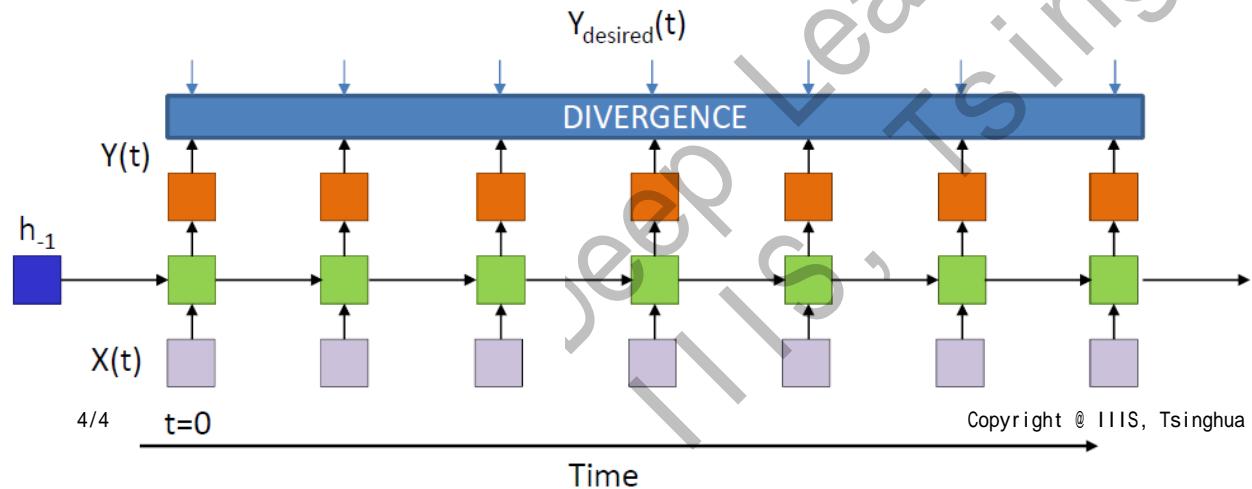
Extension

- In a standard RNN, Y_t only captures previous inputs
 - What if we want Y_t to handle the entire inputs?
- Bidirectional RNN
 - An RNN for forward dependencies
 - $t = 0 \dots T$
 - An RNN for backward dependencies
 - $t = T \dots 0$
 - $Y_t = f_2(h_t^f, h_t^b; \theta)$
 - BPTT for bidirectional RNN?
 - $\partial \text{Div} / \partial Y_t$ for all t
 - $t = T \dots 0$ for h_f
 - $t = 0 \dots T$ for h_b



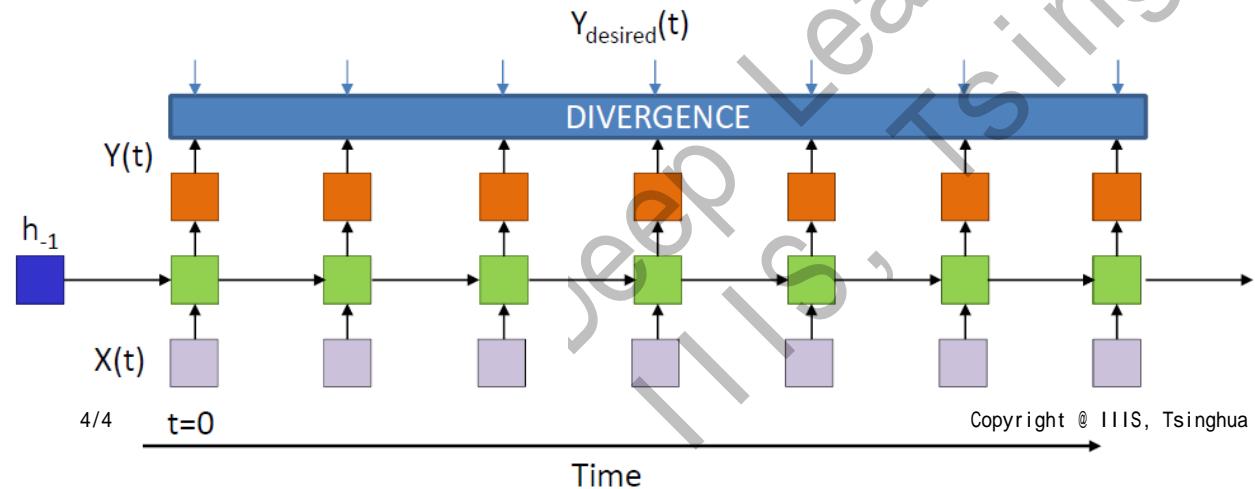
Extension

- Finding the “Welcome”
 - Input data $X_1 \dots X_L, L$ may vary
 - Whether the voice contains “Welcome”
- RNN for sequence classification
 - $Y = \max_t Y_t$
 - $L(\theta) = \text{cross_entropy}(Y, Y_{\text{desired}})$

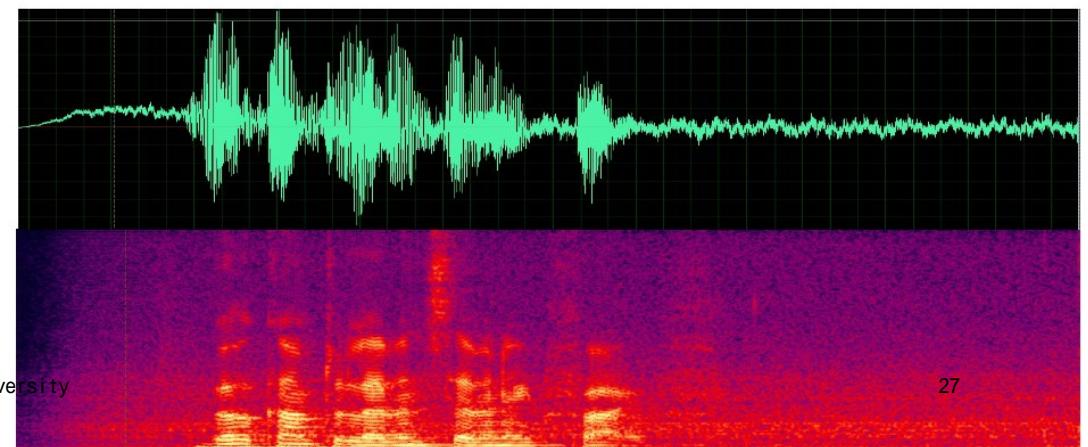


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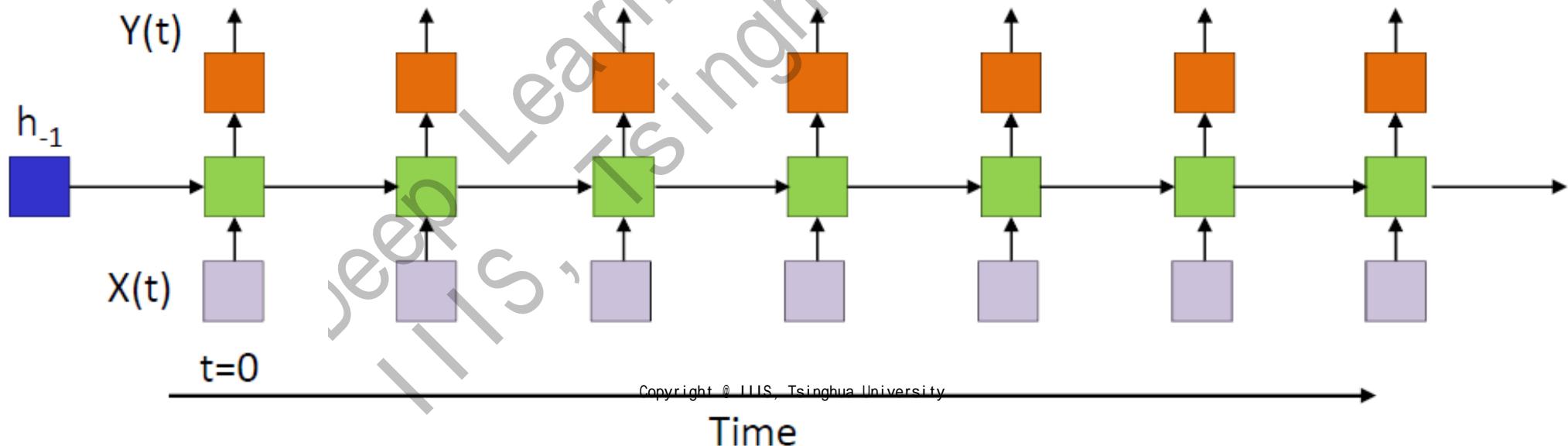


A 1-layer RNN can handle arbitrarily long sequence data
..... in theory!



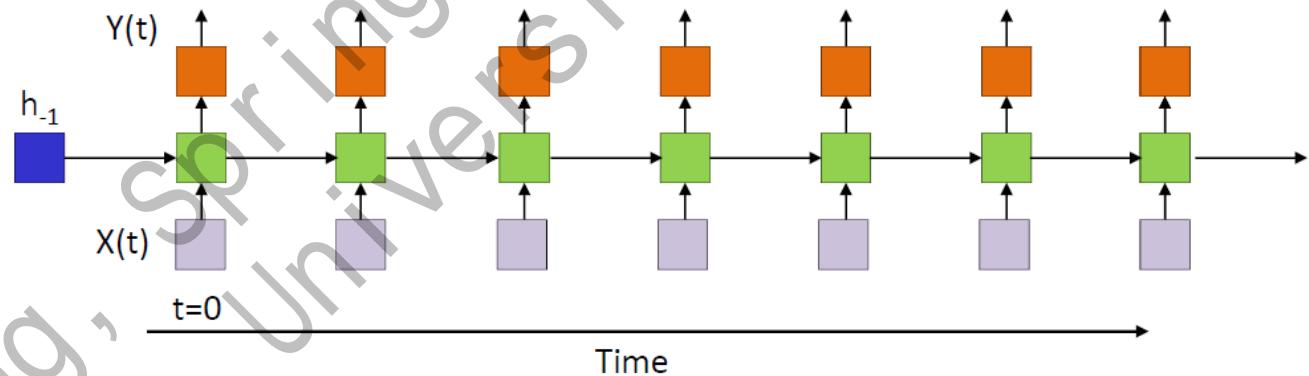
Practice Issues of RNN

- We start with a linear RNN
 - $z_t = W_h \cdot h_{t-1} + W_x \cdot X_t$
 - $h_t = z_t$
 - All activations are identity functions
 - We will add activations back later



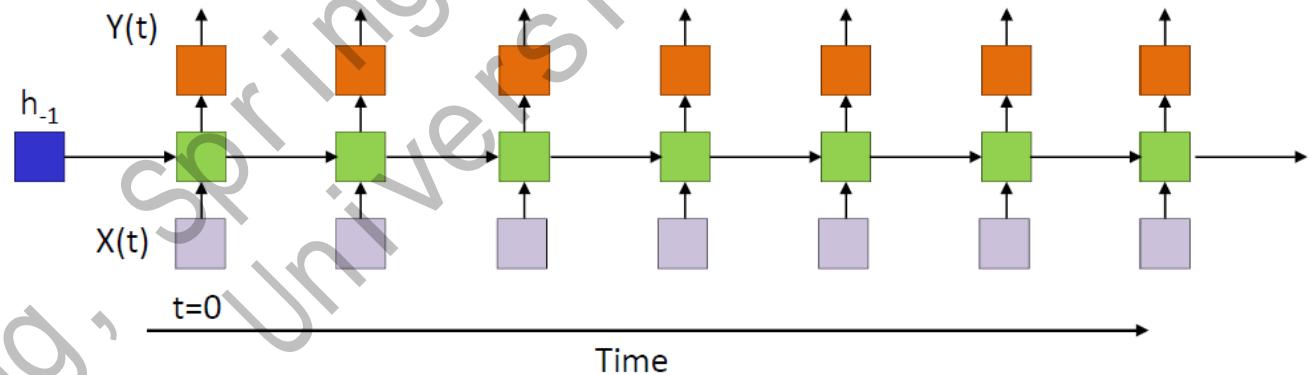
Practice Issues of RNN

- We start with a linear RNN
 - $z_t = W_h \cdot h_{t-1} + W_x \cdot X_t$
 - $h_t = z_t$
- Let's expand the recursions
 - $h_k = W_h \cdot h_{k-1} + W_x \cdot X_k$
 - $= W_h^2 h_{k-2} + W_h W_x \cdot X_{k-1} + W_x \cdot X_k$
 - $= W_h^3 h_{k-3} + W_h^2 W_x \cdot X_{k-2} + W_h W_x \cdot X_{k-1} + W_x \cdot X_k$
 - $= W_h^{k+1} h_{-1} + \sum_{i=0}^k W_h^{k-i} W_x \cdot X_i$



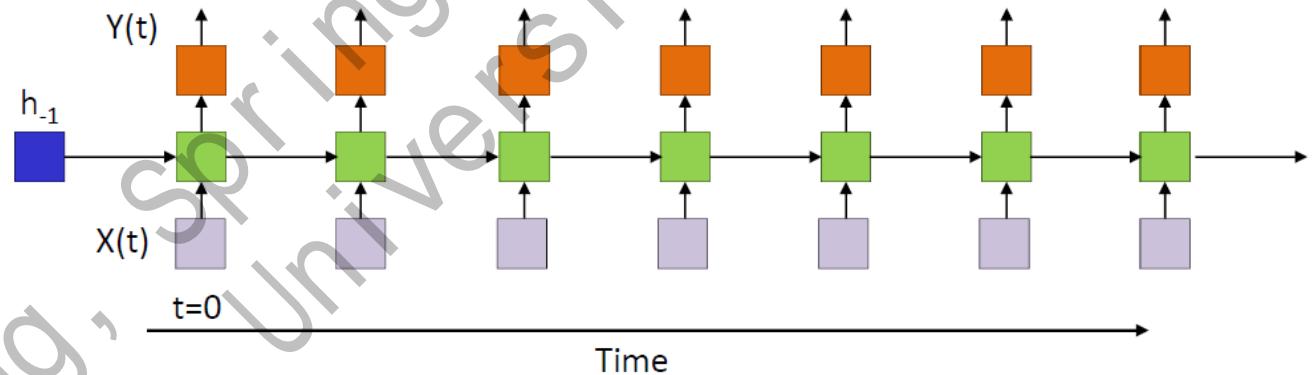
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 - $= W_h^{k+1} h_{-1} + \sum_{i=0}^k W_h^{k-i} W_x \cdot X_i$
 - The coefficient of signal at position i is **exponential over W_h**
 - The dynamics of the system is highly depending on the maximum eigenvalue of W_h



Practice Issues of RNN

- We start with a linear RNN
 - $z_t = W_h \cdot h_{t-1} + W_x \cdot X_t$
 - $h_t = z_t$
- Let's expand the recursions
 - $h_k = W_h^{k+1} h_{-1} + \sum_{i=0}^k W_h^{k-i} W_x \cdot X_i$
 - The coefficient of signal at position i is exponential over W_h
 - If $|\lambda_{\max}| > 1$, the system explodes
 - If $|\lambda_{\max}| < 1$, the system cannot capture long-term dependencies
 - If $|\lambda_{\max}| = 1$, the second largest eigenvalue matters

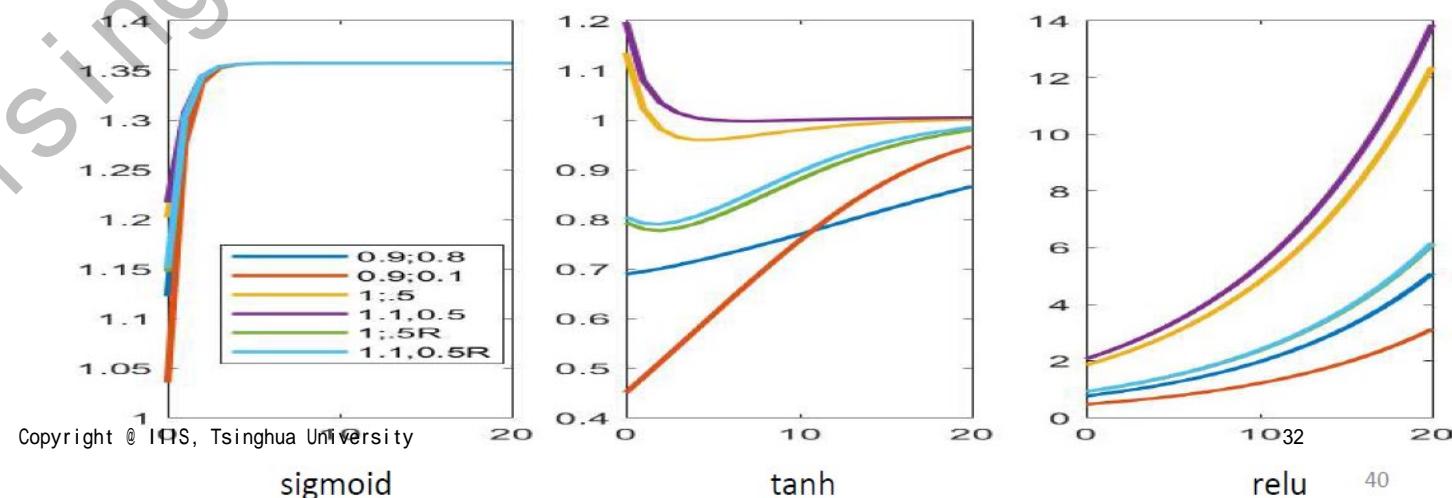
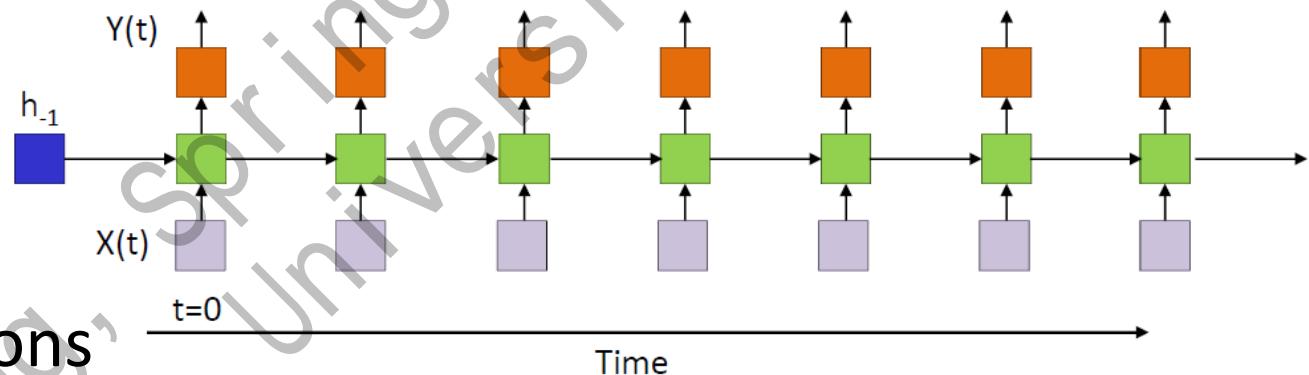


Practice Issues of RNN

- RNN with non-linearity
 - $z_t = W_h \cdot h_{t-1} + W_x \cdot X_t$
 - $h_t = f(z_t)$

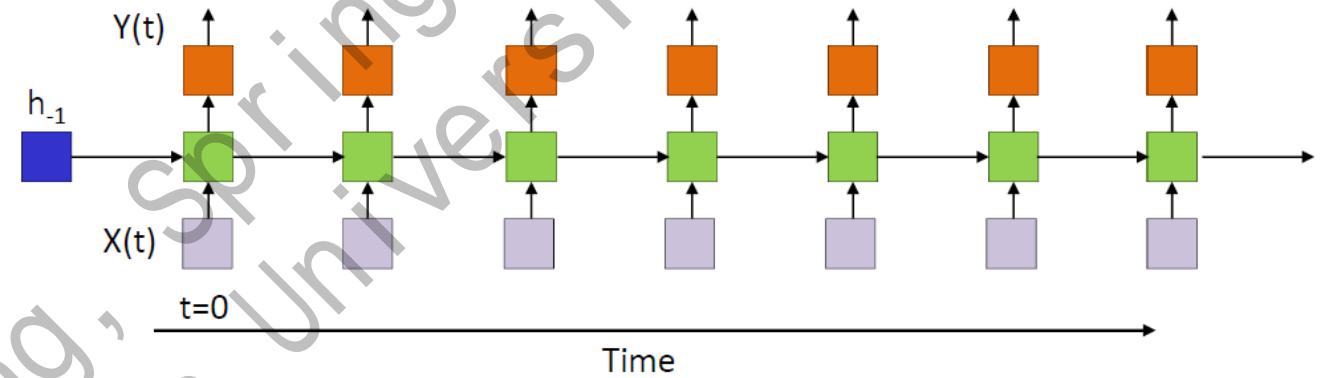
- Simulation results with activations

- A uniform start $h_{-1} = [1,1,1,1, \dots]/\sqrt{N}$
 - We simulate $|W_h^{k+1}h_{-1}|$ with various eigenvalues in W_h
 - Remark:
 - Tanh is preferred
 - ... but still saturates
 - **What about backward pass?**

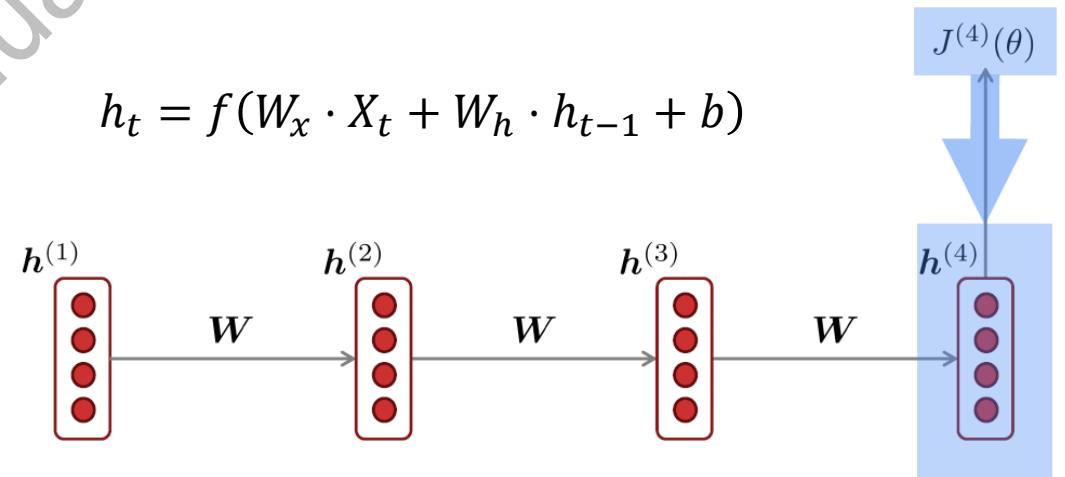


Practice Issues of RNN

- RNN with non-linearity
 - $z_t = W_h \cdot h_{t-1} + W_x \cdot X_t$
 - $h_t = f(z_t)$
- BPTT for RNN
 - Consider $J_k(\theta) = \text{Div}(Y_k, D_k)$
 - $\frac{\partial J_k}{\partial h_0} = \frac{\partial J_k}{\partial h_k} \prod_t \frac{\partial h_t}{\partial h_{t-1}}$
 - $\propto \prod_t W_h f'(Z_t) = W_h^k \prod_t f'(Z_t)$



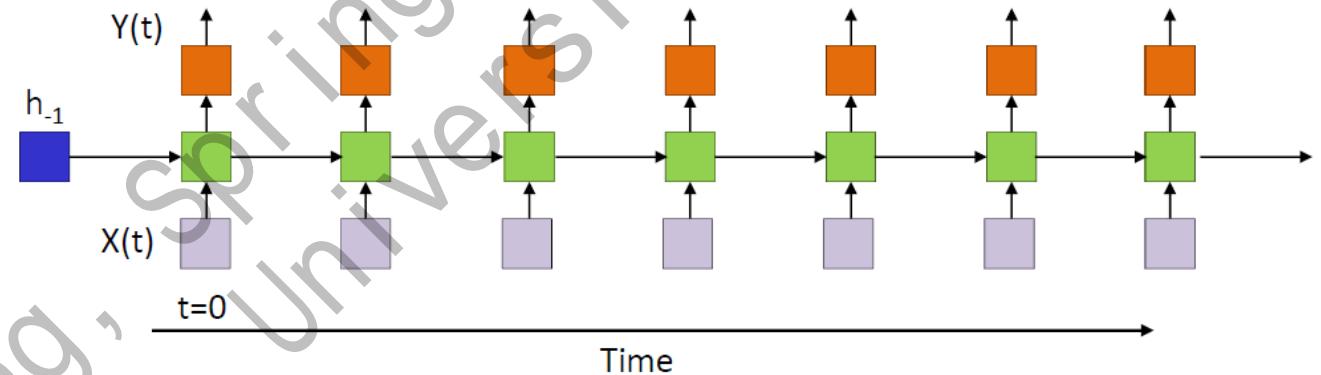
$$h_t = f(W_x \cdot X_t + W_h \cdot h_{t-1} + b)$$



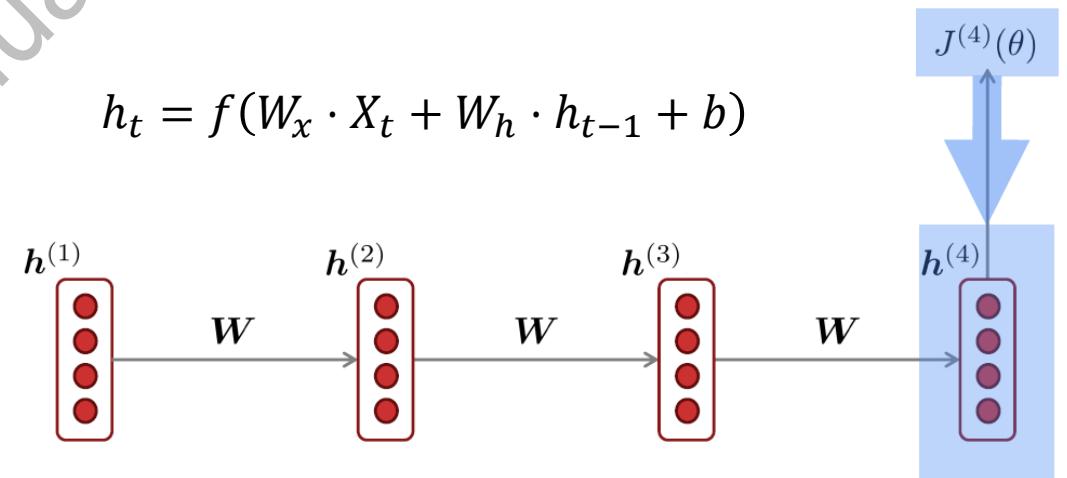
$$\frac{\partial J^{(4)}}{\partial h^{(1)}} \quad \frac{\partial h^{(2)}}{\partial h^{(1)}} \times \quad \frac{\partial h^{(3)}}{\partial h^{(2)}} \times \quad \frac{\partial h^{(4)}}{\partial h^{(3)}} \times \quad \frac{\partial J^{(4)}}{\partial h^{(4)}} \quad 33$$

Practice Issues of RNN

- RNN with non-linearity
 - $z_t = W_h \cdot h_{t-1} + W_x \cdot X_t$
 - $h_t = f(z_t)$
- BPTT for RNN
 - Consider $J_k(\theta) = \text{Div}(Y_k, D_k)$
 - $\frac{\partial J_k}{\partial h_0} = \frac{\partial J_k}{\partial h_k} \prod_t \frac{\partial h_t}{\partial h_{t-1}}$
 - $\propto \prod_t W_h f'(Z_t) = W_h^k \prod_t f'(Z_t)$
 - Possible gradient explosion!



$$h_t = f(W_x \cdot X_t + W_h \cdot h_{t-1} + b)$$



$$\frac{\partial J^{(4)}}{\partial h^{(1)}}$$

$$\frac{\partial h^{(2)}}{\partial h^{(1)}} \times$$

$$\frac{\partial h^{(3)}}{\partial h^{(2)}} \times$$

$$\frac{\partial h^{(4)}}{\partial h^{(3)}} \times \frac{\partial J^{(4)}}{\partial h^{(4)}}^{34}$$

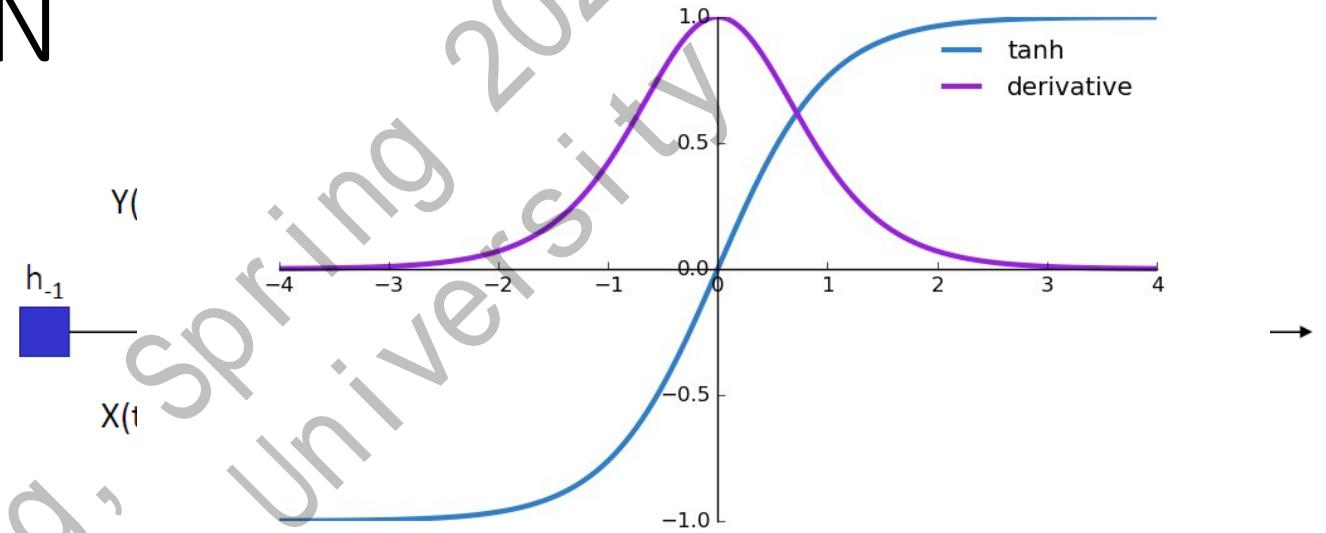
Practice Issues of RNN

- RNN with non-linearity

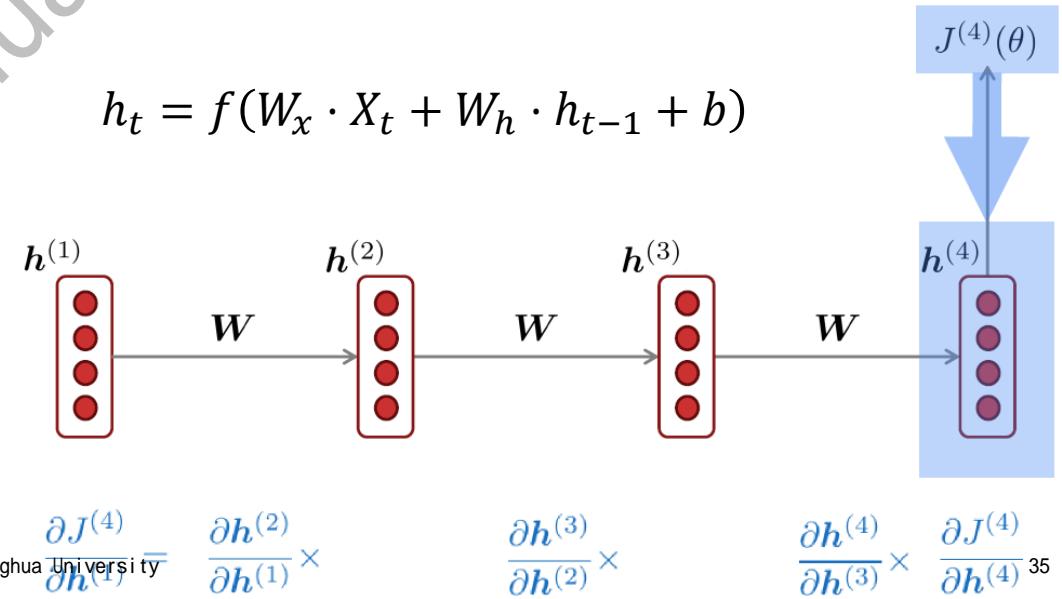
- $z_t = W_h \cdot h_{t-1} + W_x \cdot X_t$
- $h_t = f(z_t)$

- BPTT for RNN

- Consider $J_k(\theta) = \text{Div}(Y_k, D_k)$
- $\frac{\partial J_k}{\partial h_0} = \frac{\partial J_k}{\partial h_k} \prod_t \frac{\partial h_t}{\partial h_{t-1}}$
- $\propto \prod_t W_h f'(Z_t) = W_h^k \prod_t f'(Z_t)$
- f is activation (e.g., tanh)
 - $|f|_L \leq 1$
- **Gradient vanishing!**
 - RNN “forgets” long-term past!

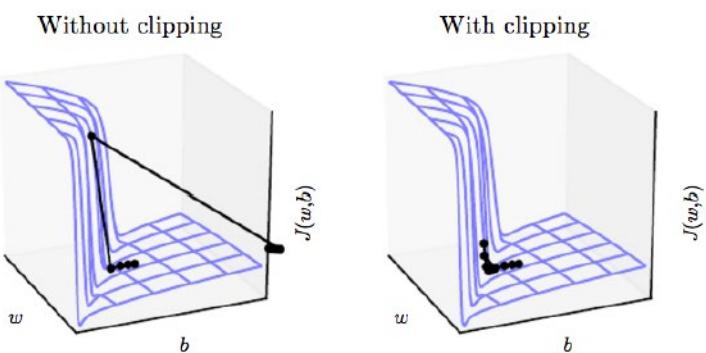
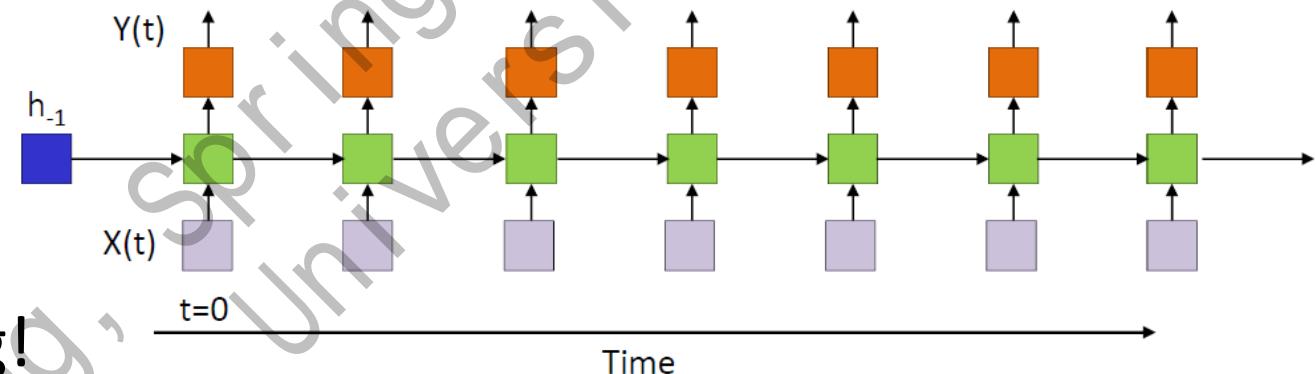


$$h_t = f(W_x \cdot X_t + W_h \cdot h_{t-1} + b)$$



Practice Issues of RNN

- RNN with non-linearity
 - $z_t = W_h \cdot h_{t-1} + W_x \cdot X_t$
 - $h_t = f(z_t)$
- Gradient Explosion & Vanishing!
 - Training instability and long-term dependency
- Tricks for explosion
 - Gradient clipping
 - Take a smaller step when gradient is too large
 - **Gradient clipping is an important trick in practice**



Algorithm 1 Pseudo-code for norm clipping

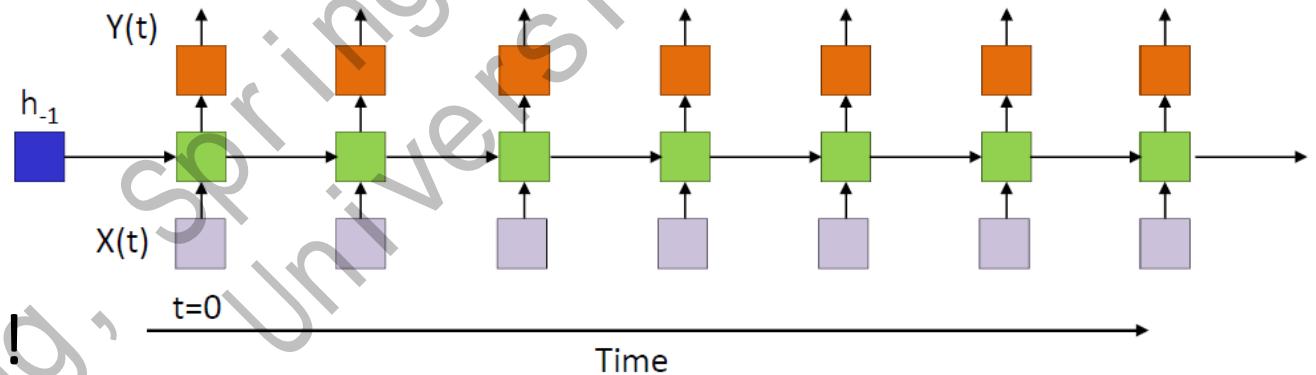
```

 $\hat{g} \leftarrow \frac{\partial \mathcal{E}}{\partial \theta}$ 
if  $\|\hat{g}\| \geq \text{threshold}$  then
     $\hat{g} \leftarrow \frac{\text{threshold}}{\|\hat{g}\|} \hat{g}$ 
end if

```

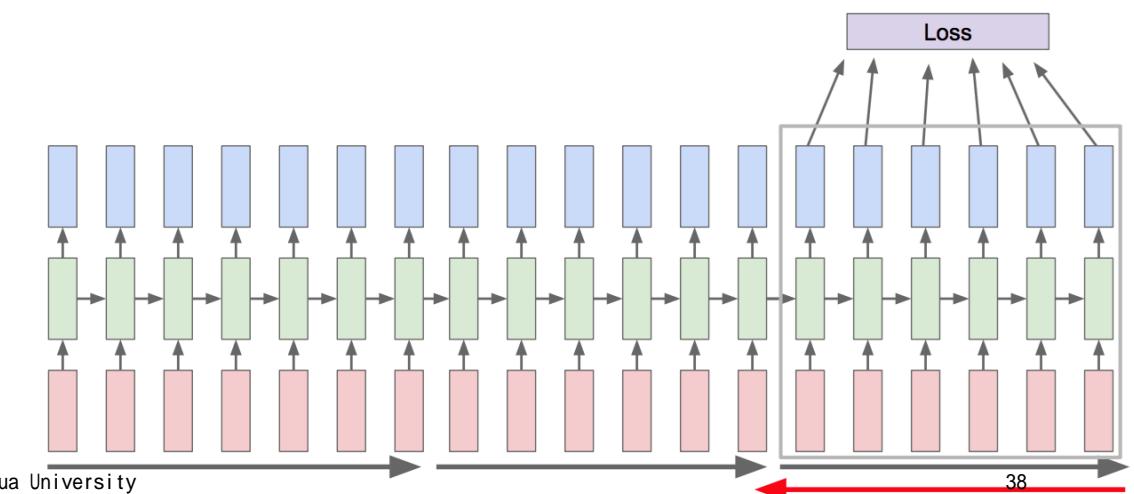
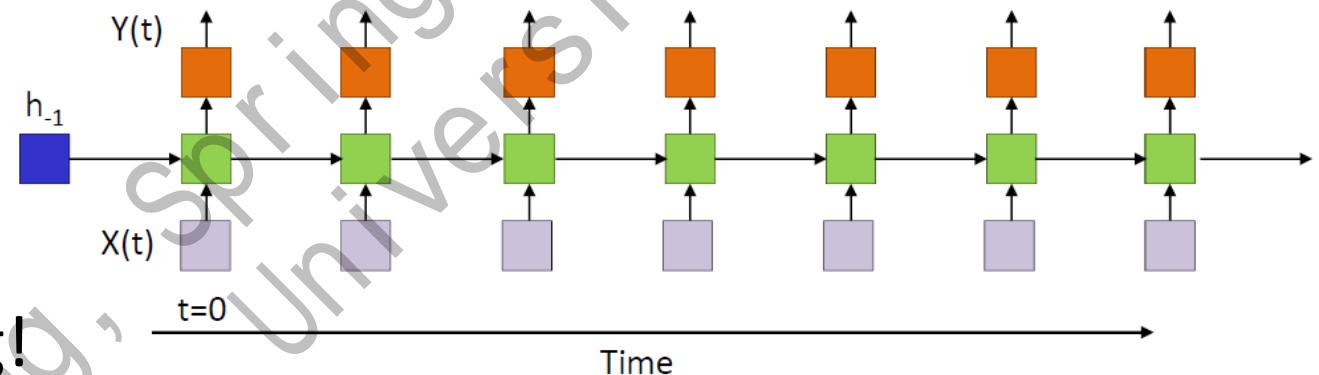
Practice Issues of RNN

- RNN with non-linearity
 - $z_t = W_h \cdot h_{t-1} + W_x \cdot X_t$
 - $h_t = f(z_t)$
- Gradient Explosion & Vanishing!
 - Training instability and long-term dependency
- Tricks for explosion
 - Gradient clipping
 - **Identity initialization**
 - Make sure the weight matrix is initialized to have $\lambda_{\max} = 1$



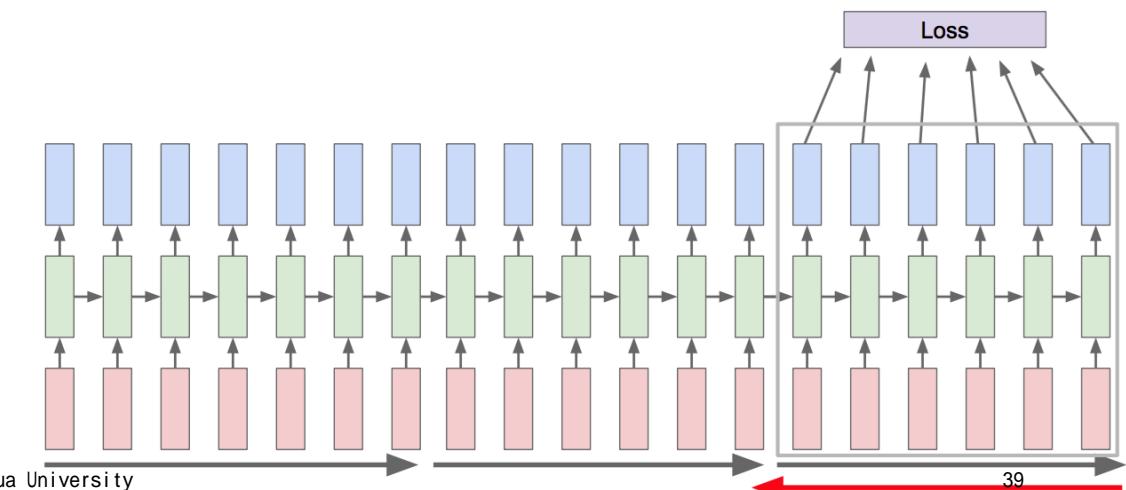
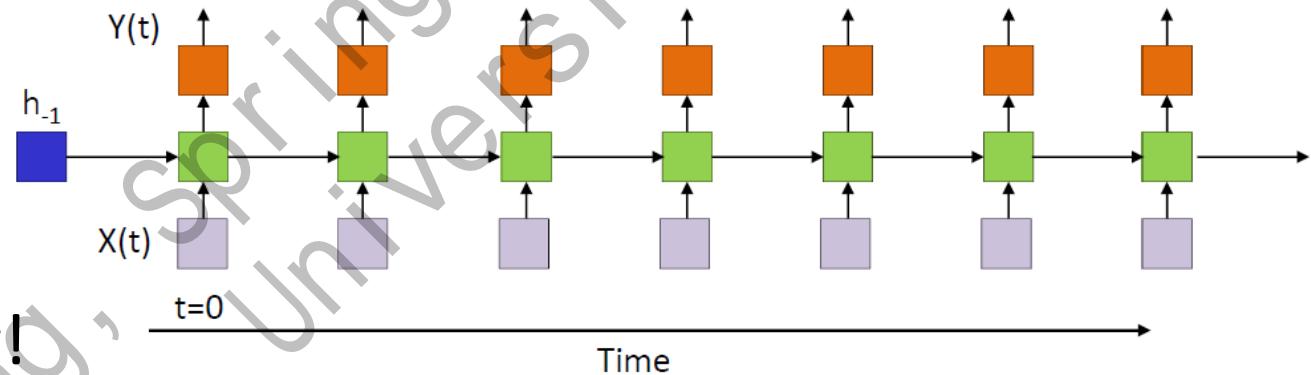
Practice Issues of RNN

- RNN with non-linearity
 - $z_t = W_h \cdot h_{t-1} + W_x \cdot X_t$
 - $h_t = f(z_t)$
- Gradient Explosion & Vanishing!
 - Training instability and long-term dependency
- Tricks for explosion
 - Gradient clipping
 - Identity initialization
 - **Truncated Backprop Through Time**
 - Only backpropagate for a few timesteps



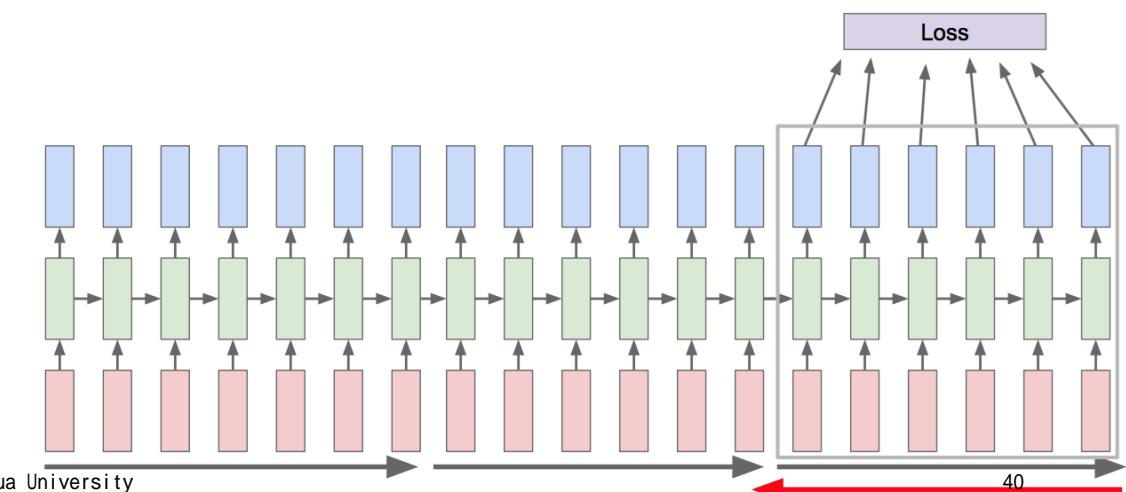
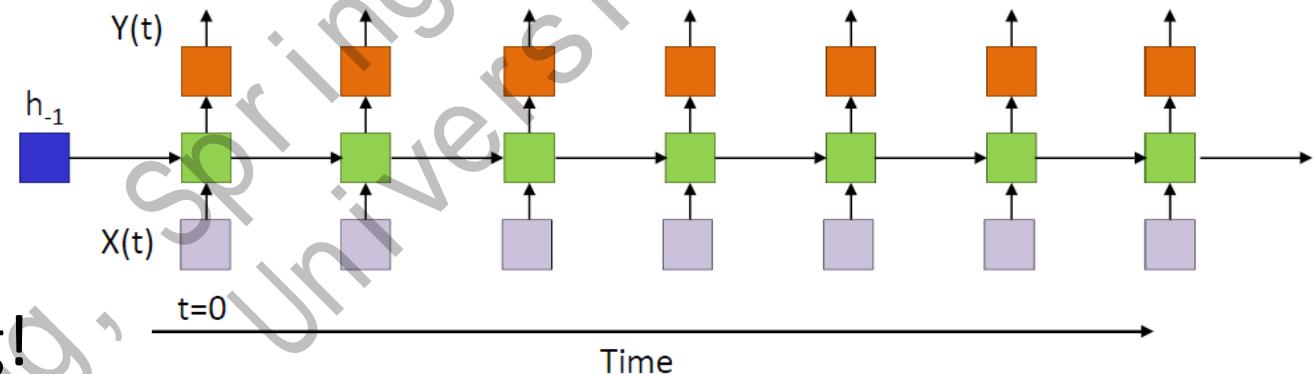
Practice Issues of RNN

- RNN with non-linearity
 - $z_t = W_h \cdot h_{t-1} + W_x \cdot X_t$
 - $h_t = f(z_t)$
- Gradient Explosion & Vanishing!
 - Training instability and long-term dependency
- Tricks for explosion
 - Gradient clipping
 - Identity initialization
 - Truncated Backprop Through Time
 - Only backpropagate for a few timesteps
 - **Gradient explosion is easy to solve**



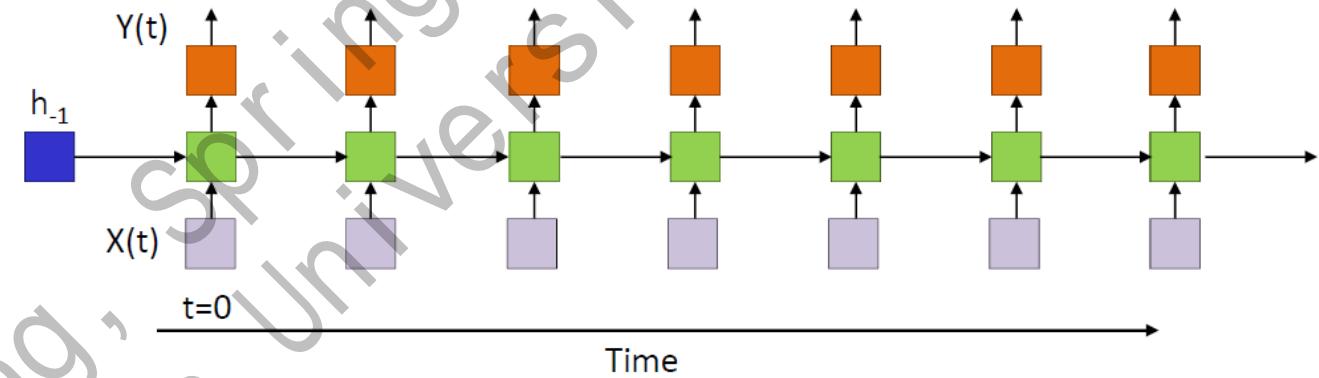
Practice Issues of RNN

- RNN with non-linearity
 - $z_t = W_h \cdot h_{t-1} + W_x \cdot X_t$
 - $h_t = f(z_t)$
- Gradient Explosion & Vanishing!
 - Training instability and long-term dependency
- Tricks for explosion
 - Gradient clipping
 - Identity initialization
 - Truncated Backprop Through Time
- **What about memory?**
 - *RNN forgets past due to activation*

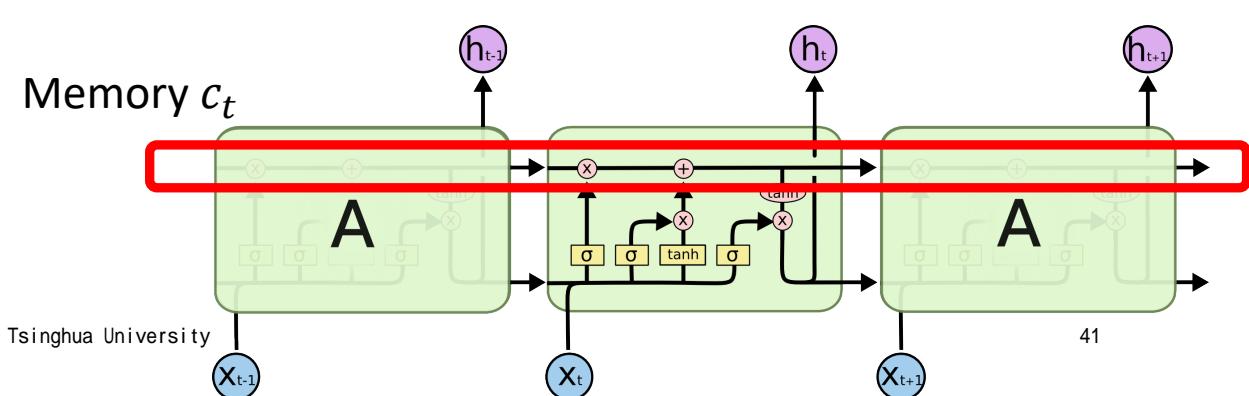
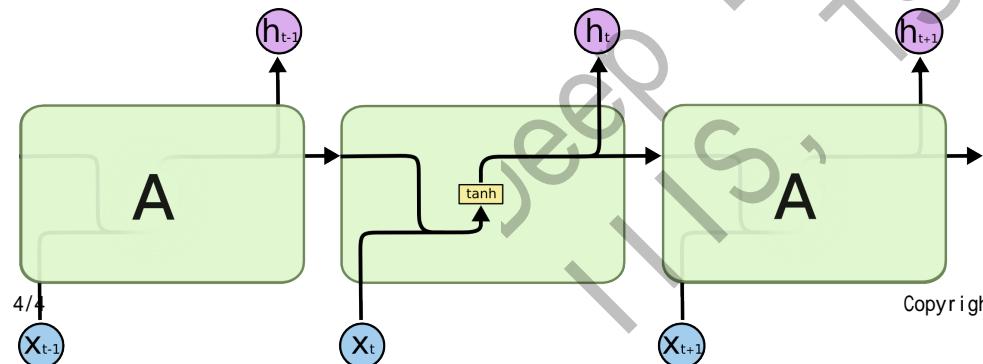


Preserve Long-Term Memory

- RNN with non-linearity
 - $z_t = W_h \cdot h_{t-1} + W_x \cdot X_t$
 - $h_t = f(z_t)$

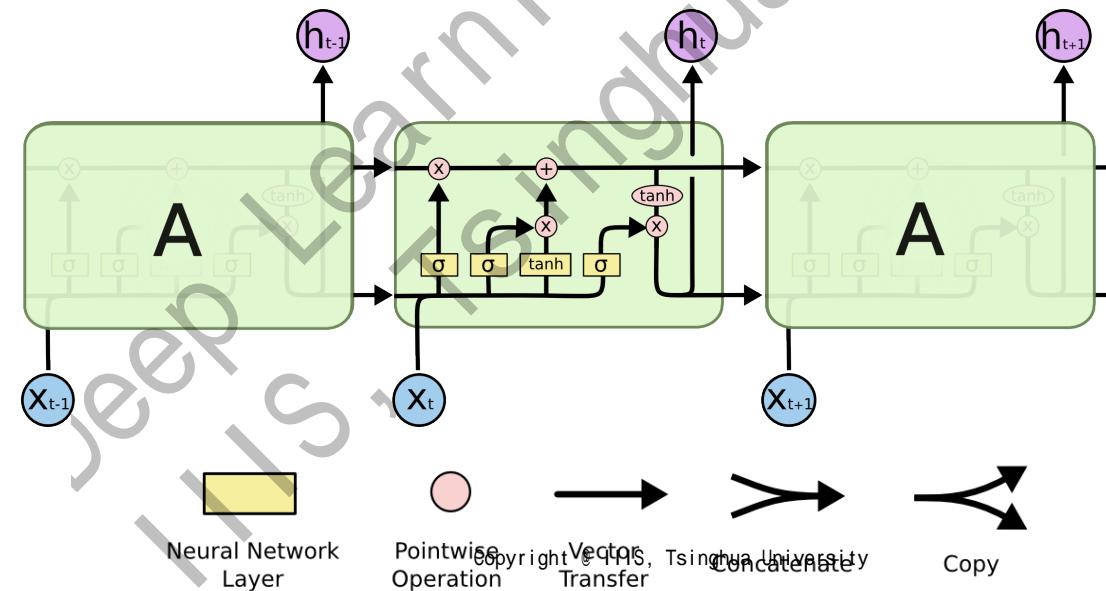


- It is difficult for RNN to preserve long-term memory
 - The hidden state h_t is constantly being written (short-term memory)
 - Let's keep a separate cell for maintaining long-term memory



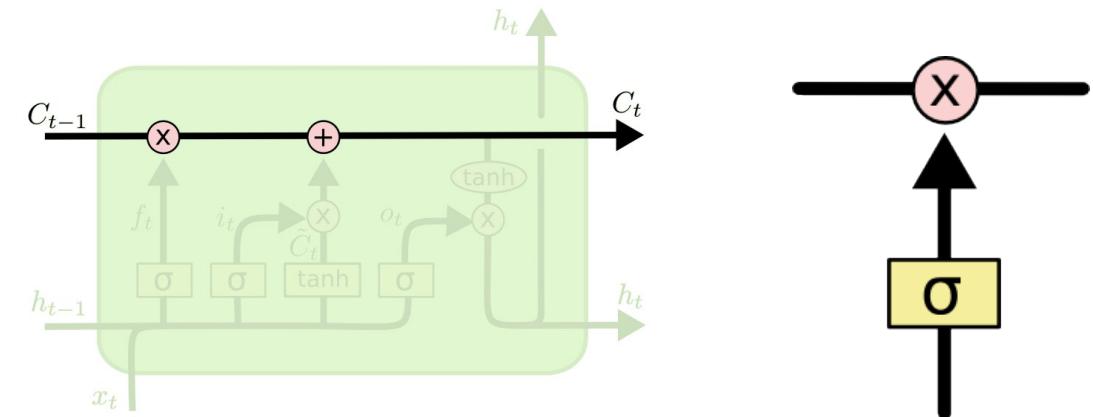
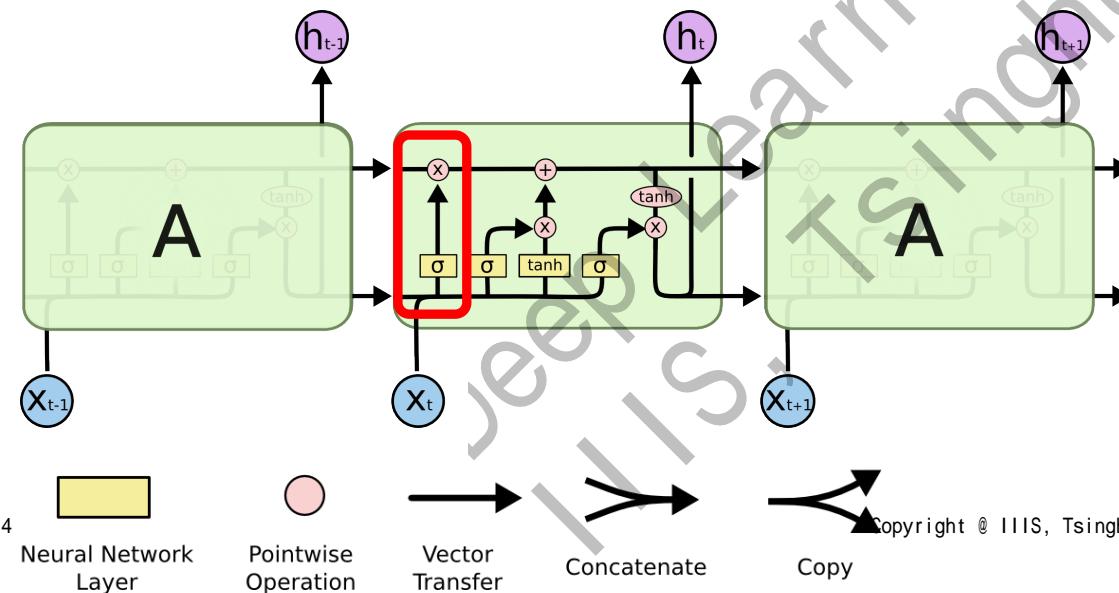
Long Short-Term Memory Network

- LSTM (Hochreiter & Schmidhuber, 1997)
 - A special RNN architecture for learning long-term dependencies
 - σ : layer with sigmoid activation
 - Let's walk through the architecture
 - Diagrams from <https://colah.github.io/posts/2015-08-Understanding-LSTMs/>



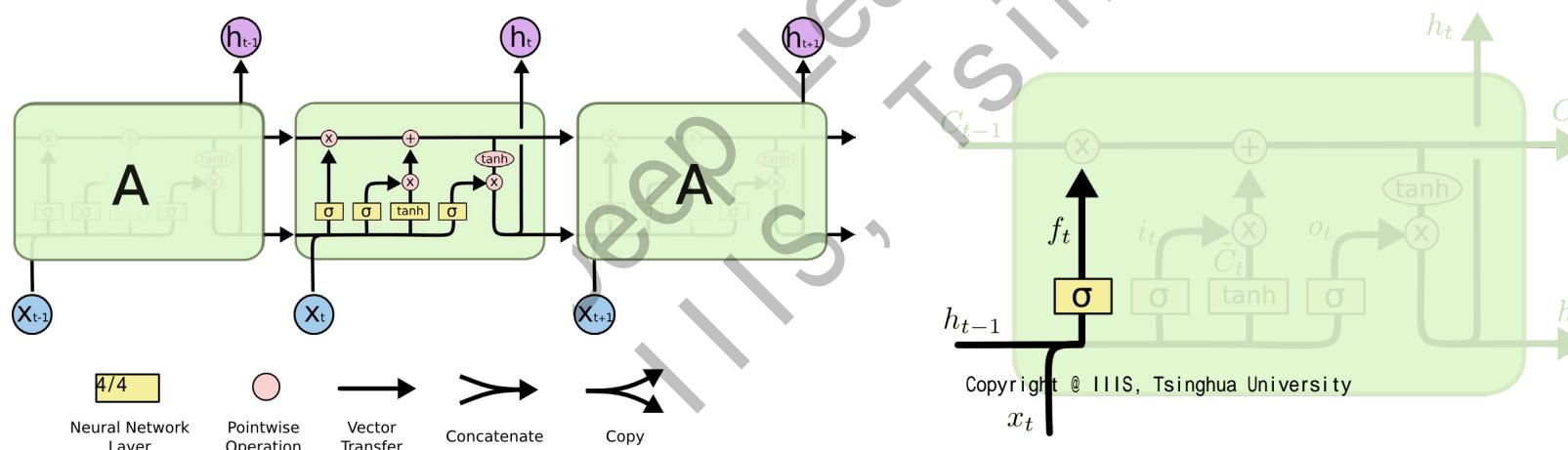
Long Short-Term Memory Network

- LSTM (Hochreiter & Schmidhuber, 1997)
 - Core idea: maintain separate state h_t and cell c_t (memory)
 - h_t : full update every iteration
 - c_t : only partially updated through **gates**
 - A σ layer outputs “importance” (0~1) for each entry and only modify those entries in c_t



Long Short-Term Memory Network

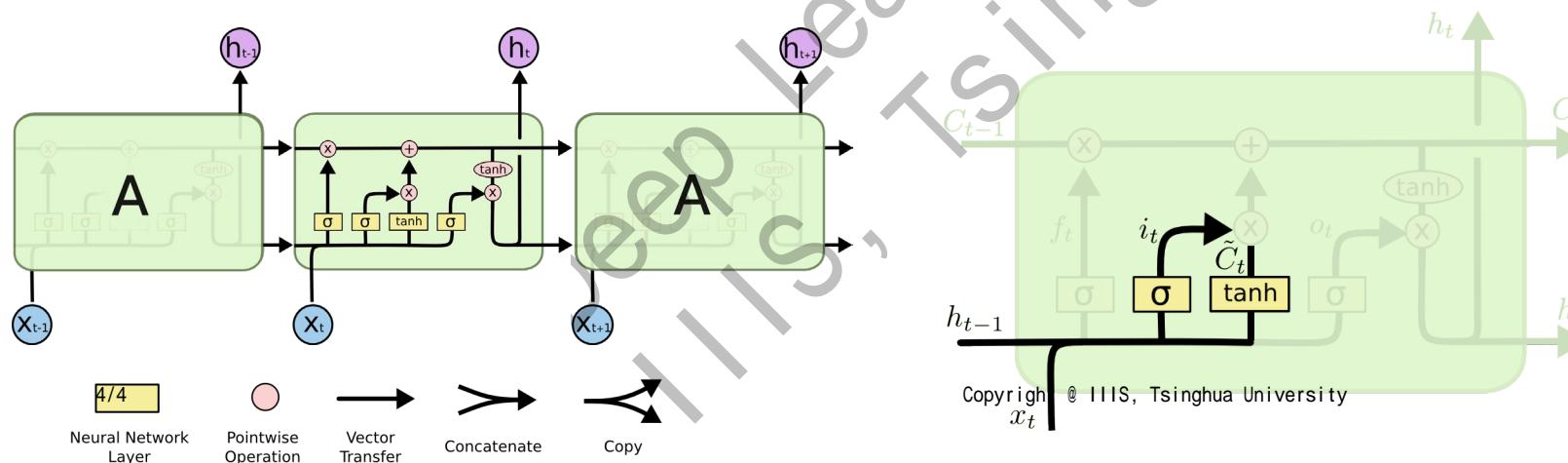
- LSTM (Hochreiter & Schmidhuber, 1997)
 - Forget gate f_t
 - f_t outputs whether we want to “forget” things from c_t or carry it
 - Compute $c_{t-1} \odot f_t$ (element-wise)
 - $f_t(i) \rightarrow 0$: we want to forget $c_t(i)$
 - $f_t(i) \rightarrow 1$: we want to keep the information in $c_t(i)$



$$f_t = \sigma (W_f \cdot [h_{t-1}, x_t] + b_f)$$

Long Short-Term Memory Network

- LSTM (Hochreiter & Schmidhuber, 1997)
 - Input gate i_t
 - i_t extracts useful information from X_t to update memory
 - \tilde{c}_t : information from X_t to update memory (dimension projection)
 - i_t : which dimensions in the memory should be updated by X_t
 - $i_t(j) \rightarrow 1$: we want to keep the information in $\tilde{c}_t(j)$ to update memory
 - $i_t(j) \rightarrow 0$: $\tilde{c}_t(j)$ should not contribute to memory

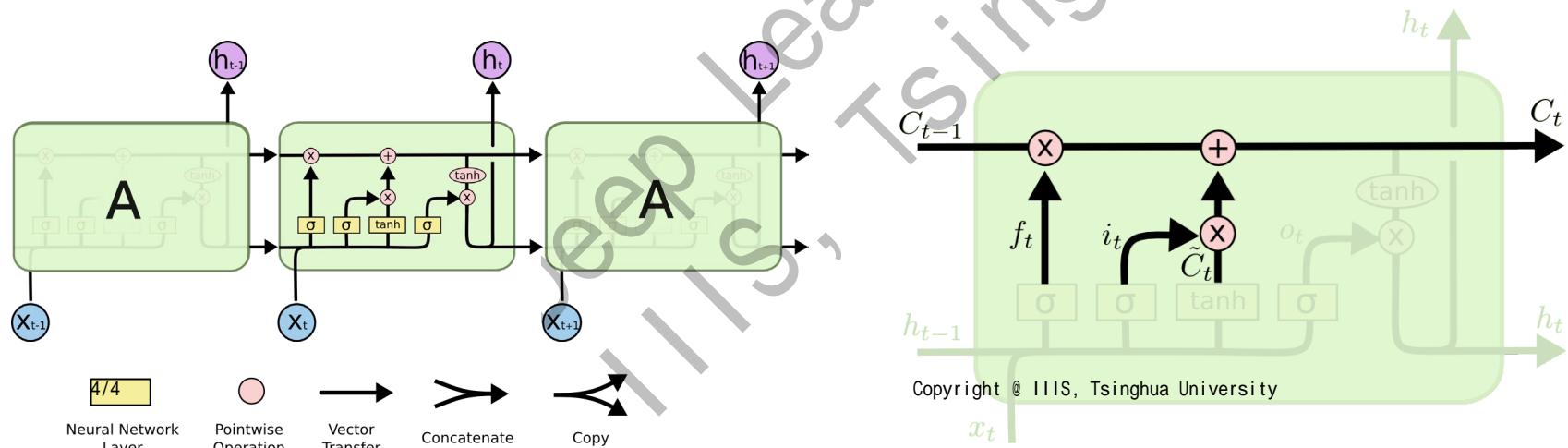


$$i_t = \sigma(W_i \cdot [h_{t-1}, x_t] + b_i)$$

$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$

Long Short-Term Memory Network

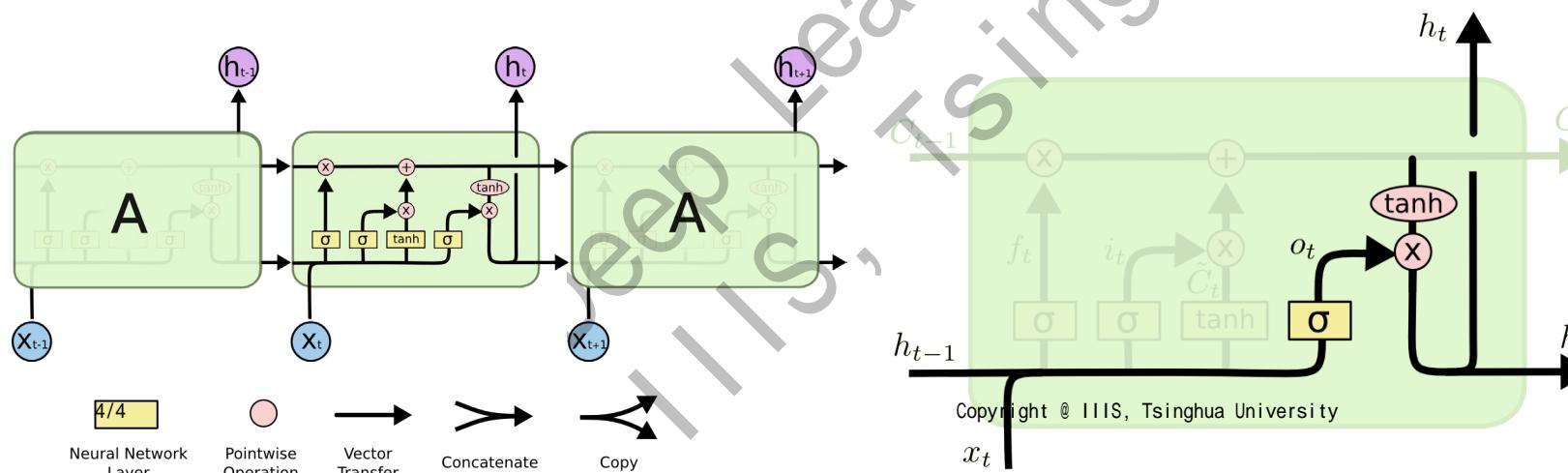
- LSTM (Hochreiter & Schmidhuber, 1997)
 - Memory update
 - $c_t = f_t \odot c_{t-1} + i_t \odot \tilde{c}_t$
 - f_t forget gate; i_t input gate
 - $f_t \odot c_{t-1}$: drop useless information in old memory
 - $i_t \odot \tilde{c}_t$: add selected new information from current input



$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$

Long Short-Term Memory Network

- LSTM (Hochreiter & Schmidhuber, 1997)
 - Output gate o_t
 - Compute next hidden state $h_t = o_t \odot \tanh(c_t)$
 - $\tanh(c_t)$: non-linear transformation over all past information
 - o_t : choose important dimensions for next state
 - $o_t(j) \rightarrow 1$: $\tanh(c_t(j))$ is critical for next state
 - $o_t(j) \rightarrow 0$: $\tanh(c_t(j))$ does not worth reporting



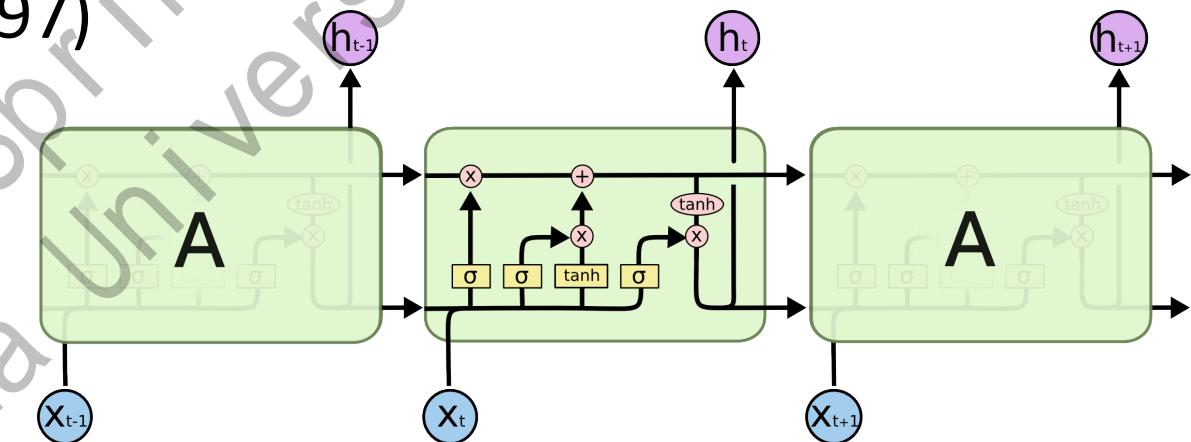
$$o_t = \sigma (W_o [h_{t-1}, x_t] + b_o)$$

$$h_t = o_t * \tanh (C_t)$$

Long Short-Term Memory Network

- LSTM (Hochreiter & Schmidhuber, 1997)

- $h_t = o_t \odot \tanh(c_t)$
- $c_t = f_t \odot c_{t-1} + i_t \odot \tilde{c}_t$
- $Y_t = g(h_t)$
- Uninterrupted gradient flow!
 - No more matrix multiplication for c_t
 - In practice: ~ 100 timesteps of memory instead of ~ 7

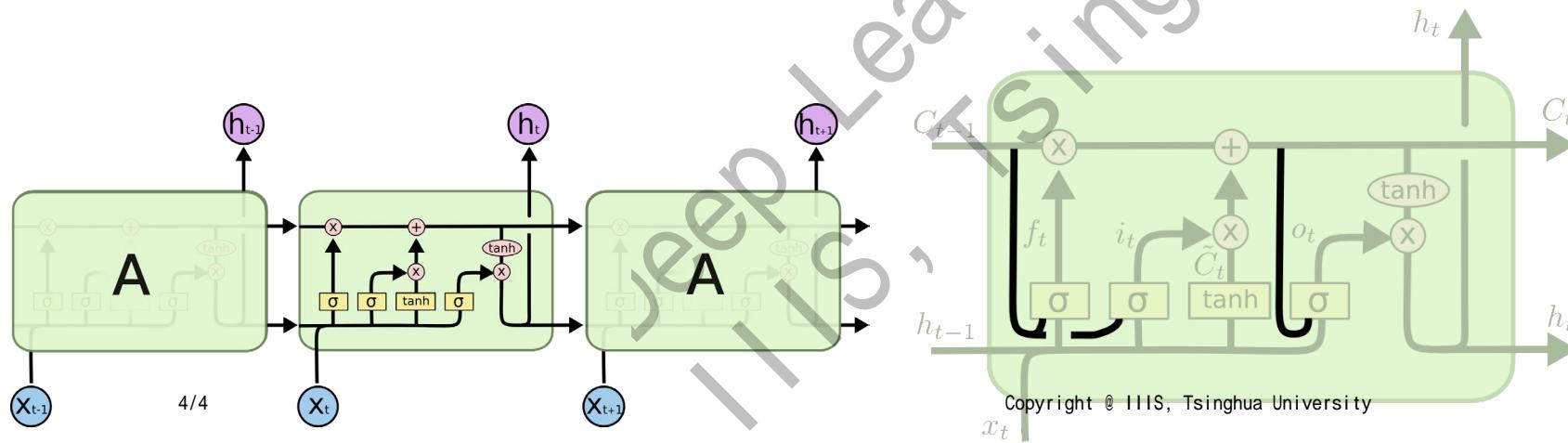


- Remark

- LSTM does not have guarantees for gradient explosion/vanishing
- An architecture that makes learning long-term dependency easier
- LSTMs is the dominant approach for sequence modeling from 2013~2016

LSTM Variants

- Peephole Connections (Gers & Schmidhuber 2000)
 - Also allow gates to take in c_t information



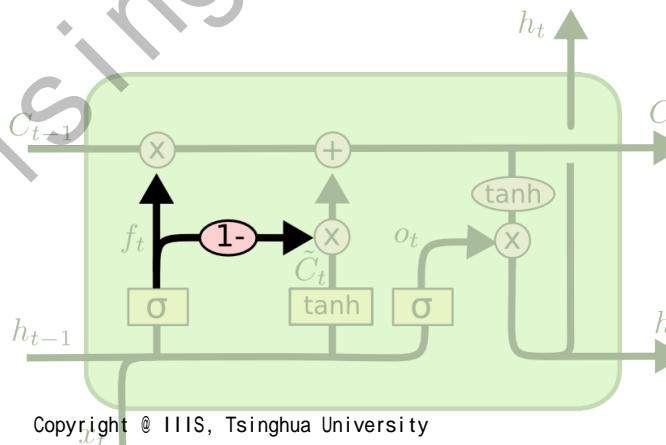
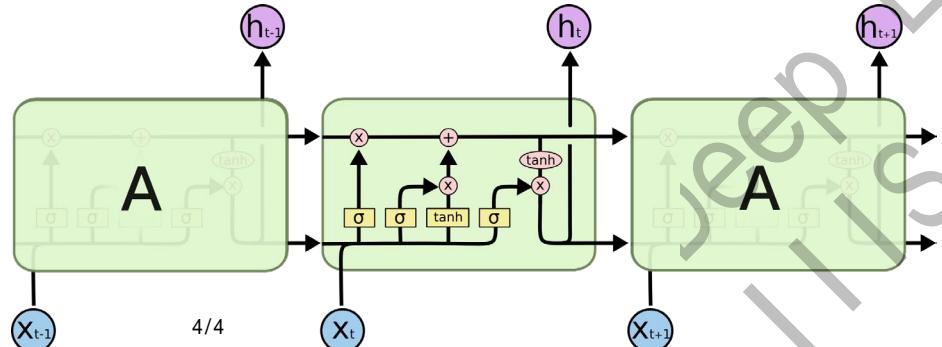
$$f_t = \sigma (W_f \cdot [C_{t-1}, h_{t-1}, x_t] + b_f)$$

$$i_t = \sigma (W_i \cdot [C_{t-1}, h_{t-1}, x_t] + b_i)$$

$$o_t = \sigma (W_o \cdot [C_t, h_{t-1}, x_t] + b_o)$$

LSTM Variants

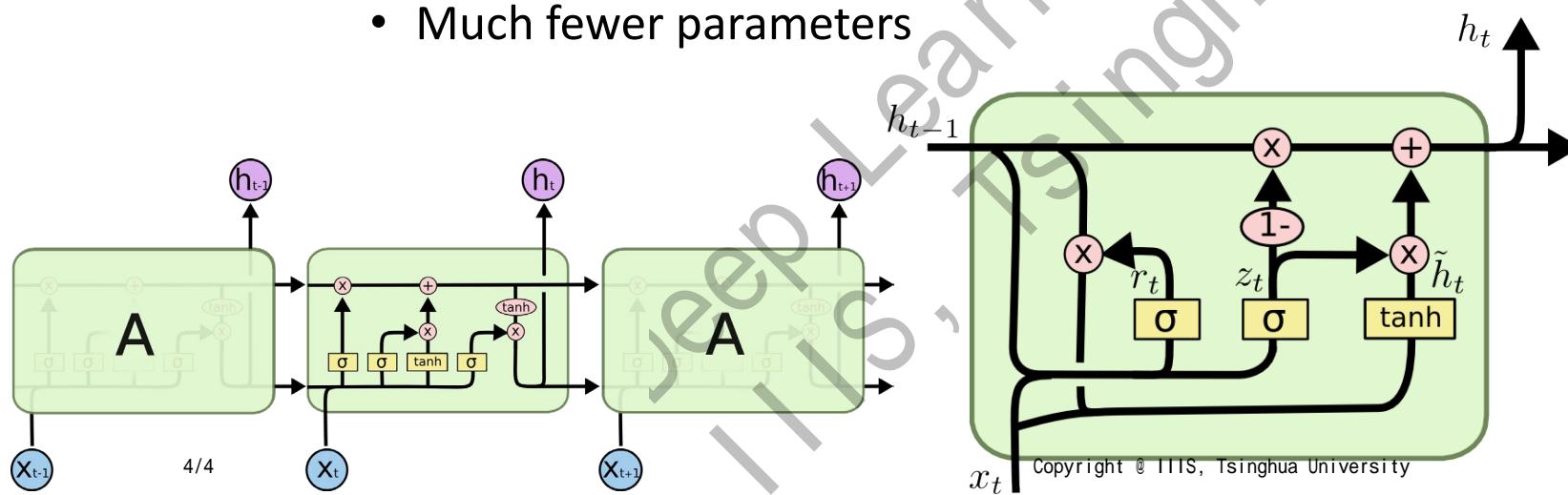
- Peephole Connections (Gers & Schmidhuber 2000)
- Simplified LSTM
 - Assume $i_t = 1 - f_t$
 - So only two gates are needed
 - Fewer parameters



$$C_t = f_t * C_{t-1} + (1 - f_t) * \tilde{C}_t$$

LSTM Variants

- Peephole Connections (Gers & Schmidhuber 2000)
- Simplified LSTM
- Gated Recurrent Unit (GRU, Cho et al, 2014)
 - Typically we only use h_t to produce outputs in LSTM
 - GRU: Merge h_t and c_t
 - Much fewer parameters



$$z_t = \sigma (W_z \cdot [h_{t-1}, x_t])$$

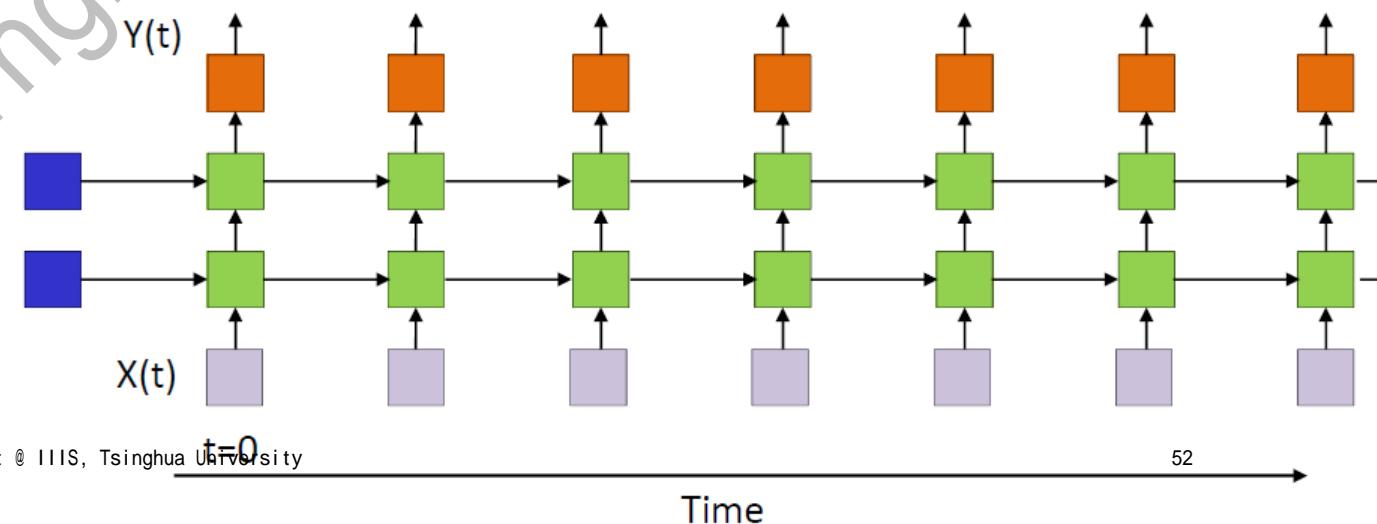
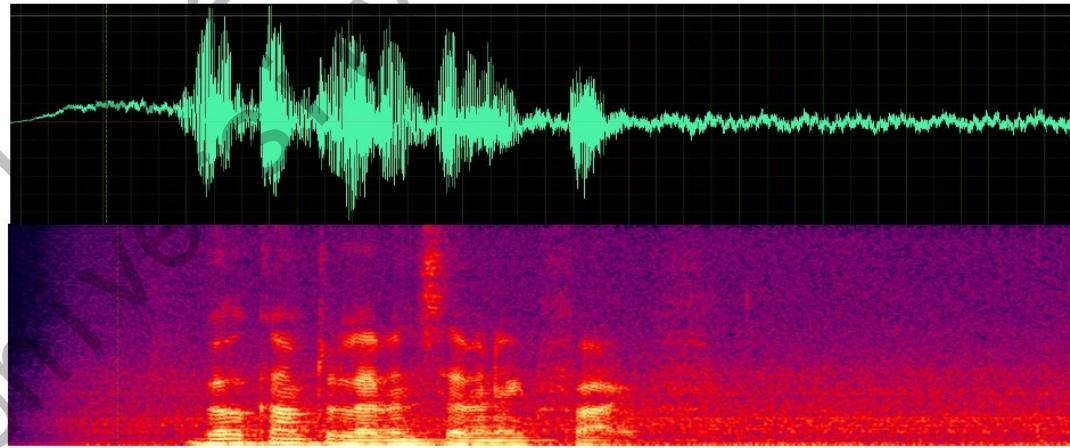
$$r_t = \sigma (W_r \cdot [h_{t-1}, x_t])$$

$$\tilde{h}_t = \tanh (W \cdot [r_t * h_{t-1}, x_t])$$

$$h_t = (1 - z_t) * h_{t-1} + z_t * \tilde{h}_t$$

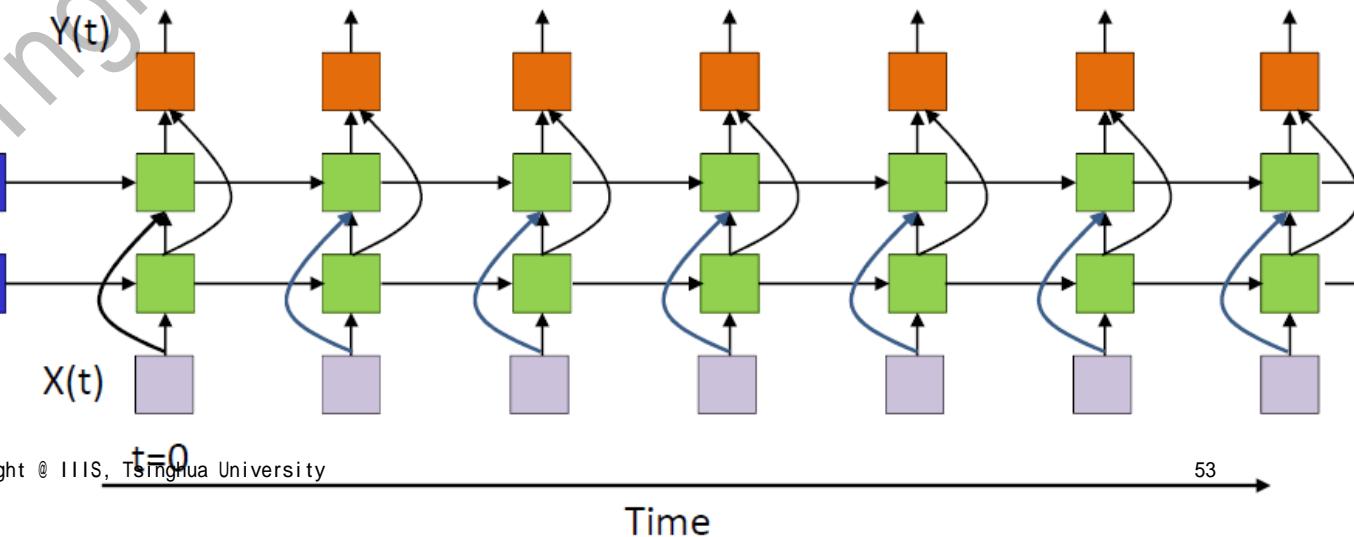
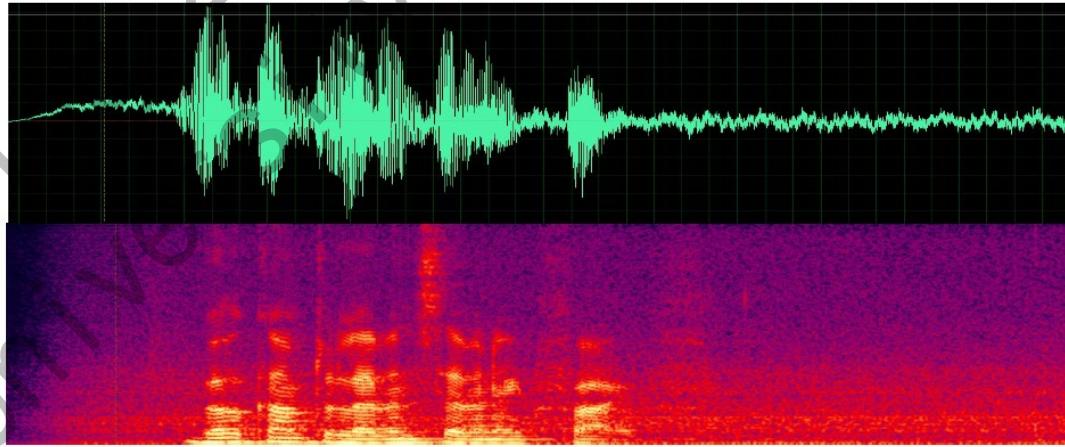
LSTM Applications

- Finding the “Welcome”
 - Input data $X_1 \dots X_L, L$ may vary
 - Whether the voice contains “Welcome”
- Solution
 - Multi-layer LSTM and max-pooling over Y_t
 - Sometimes also just use h_T to compute output for simplicity



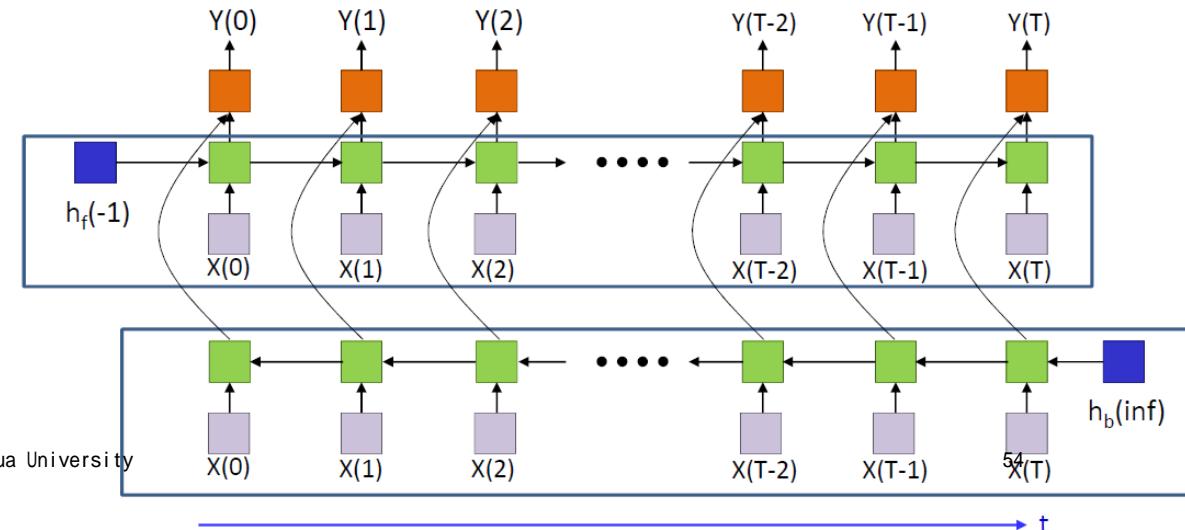
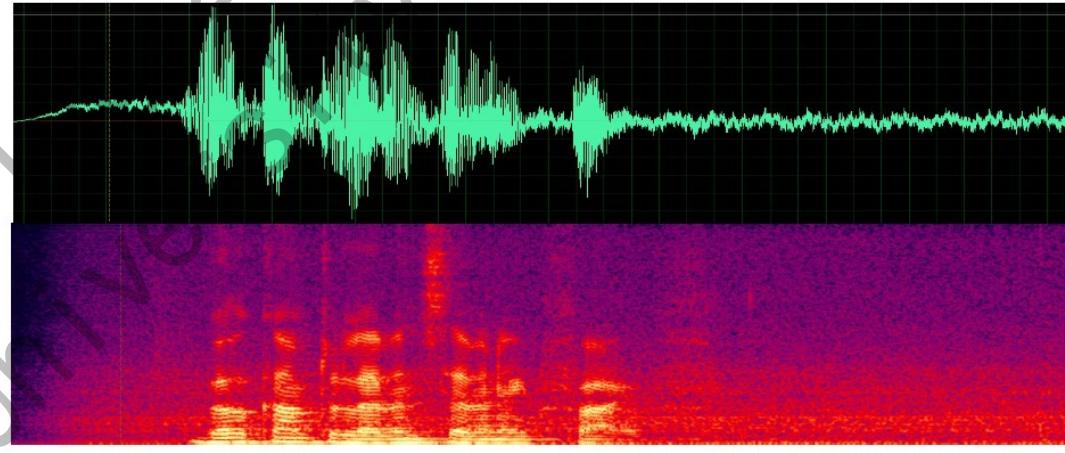
LSTM Applications

- Finding the “Welcome”
 - Input data $X_1 \dots X_L$, L may vary
 - Whether the voice contains “Welcome”
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 - Multi-layer LSTM and max-pooling over Y_t
 - Skip-connections for deeper LSTMs!



LSTM Applications

- Finding the “Welcome”
 - Input data $X_1 \dots X_L$, L may vary
 - Whether the voice contains “Welcome”
- Solution
 - Multi-layer LSTM and max-pooling over Y_t
 - Skip-connections for deeper LSTMs!
 - Bidirectional LSTMs!
 - Sometimes use $h_f(T)$ & $h_b(T)$ for output
 - Remember gradient clipping!





LSTM Applications

- What about text generation?
 - A generative model over texts
 - $p(X; \theta)$: the probability for X
 - Training data:
 - A collection of texts
 - E.g.: 诗歌全集
 - Even conditional generation!
 - Next lecture

深度之梦

在数据的海洋里遨游，
算法如风，吹散迷雾。
神经元闪烁似星辰，
连接着未来的道路。
梯度回溯千重浪，
优化求解万象生。

Deep learning is a popular area in AI.

检测语言 英语 中文 德语

Deep learning is a popular area in AI.

中文 (简体) 英语 日语

深度学习是AI的热门领域。

Shèndù xuéxí shì AI de rèmén lǐngyù.

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写一首热爱深度学习的诗歌



Language Model

- Language Model $p(X)$
 - A generative model over natural language X
- Autoregressive Language Model

$$P(X; \theta) = \prod_{t=1}^L P(X_t | X_{i < t}; \theta)$$

- The most popular model assumption

- Sequential generation & tractable likelihood

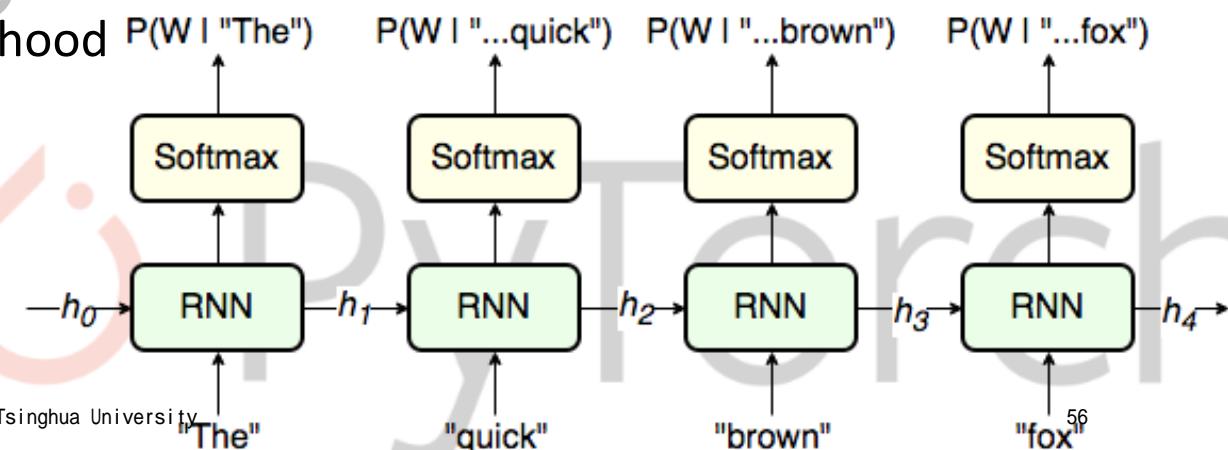
- LSTM language model

- X_t : word at position t

- $Y_t: P(X_t | X_{i < t})$, softmax over all words

- MLE Training!

- MLE over a training corpus D



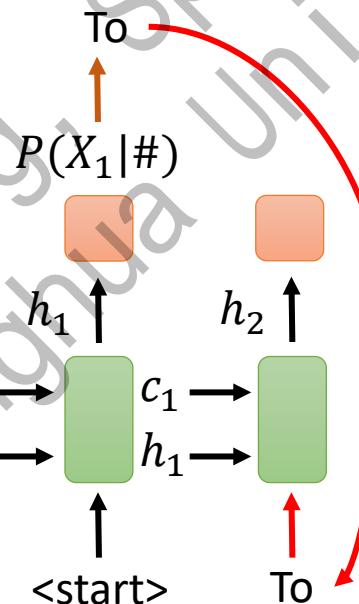
Language Model

- LSTM language model
 - $Y_t = \text{softmax}(h_t) = P(X_t | X_{i < t})$
 - $h_t, c_t = \text{LSTM}(X_{t-1}, h_{t-1}, c_{t-1})$
- Language generation
 - Draw $X \sim P(X; \theta)$
 - Sample $X_1 \sim Y_1(h_0, c_0, \#; \theta)$



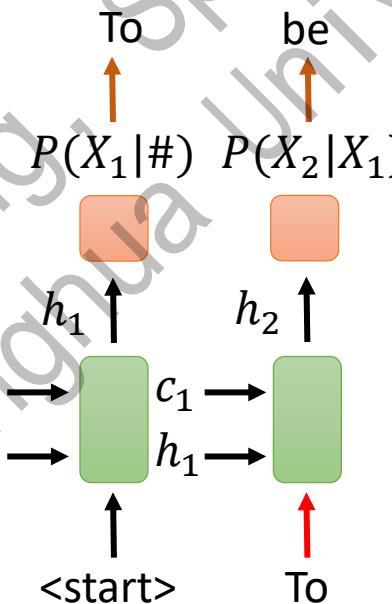
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 - $h_t, c_t = \text{LSTM}(X_{t-1}, h_{t-1}, c_{t-1})$
- Language generation
 - Draw $X \sim P(X; \theta)$
 - Sample $X_1 \sim Y_1(h_0, c_0, \#; \theta)$
 - Generate X_2
 - Feed X_1 into LSTM
 - Compute Y_2



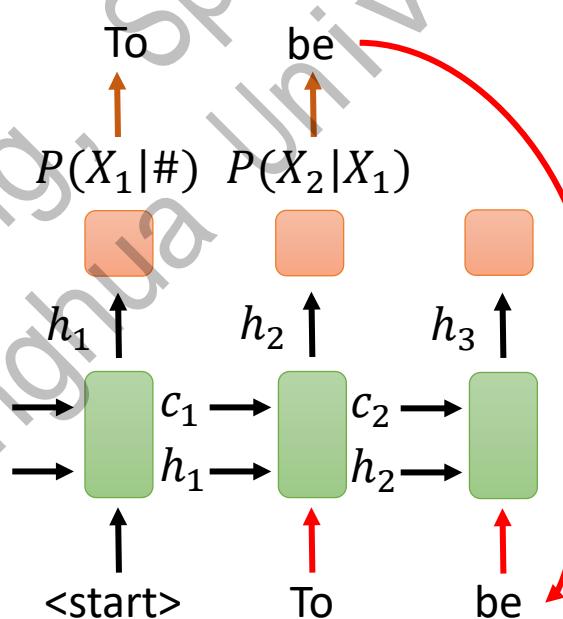
Language Model

- LSTM language model
 - $Y_t = \text{softmax}(h_t) = P(X_t | X_{i < t})$
 - $h_t, c_t = \text{LSTM}(X_{t-1}, h_{t-1}, c_{t-1})$
- Language generation
 - Draw $X \sim P(X; \theta)$
 - Sample $X_1 \sim Y_1(h_0, c_0, \#; \theta)$
 - Generate X_2
 - Feed X_1 into LSTM
 - Compute Y_2
 - Sample $X_2 \sim Y_2(h_1, c_1, X_1; \theta)$



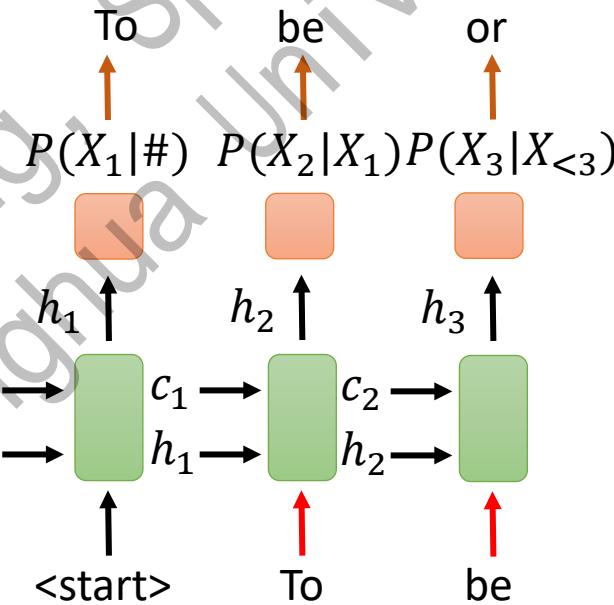
Language Model

- LSTM language model
 - $Y_t = \text{softmax}(h_t) = P(X_t | X_{i < t})$
 - $h_t, c_t = \text{LSTM}(X_{t-1}, h_{t-1}, c_{t-1})$
- Language generation
 - Draw $X \sim P(X; \theta)$
 - Sample $X_1 \sim Y_1(h_0, c_0, \#; \theta)$
 - Generate X_2
 - Generate X_3
 - LSTM forward step



Language Model

- LSTM language model
 - $Y_t = \text{softmax}(h_t) = P(X_t | X_{i < t})$
 - $h_t, c_t = \text{LSTM}(X_{t-1}, h_{t-1}, c_{t-1})$
- Language generation
 - Draw $X \sim P(X; \theta)$
 - Sample $X_1 \sim Y_1(h_0, c_0, \#; \theta)$
 - Generate X_2
 - Generate X_3
 - LSTM forward step
 - Sample $X_3 \sim Y_3(c_2, h_2, X_2; \theta)$

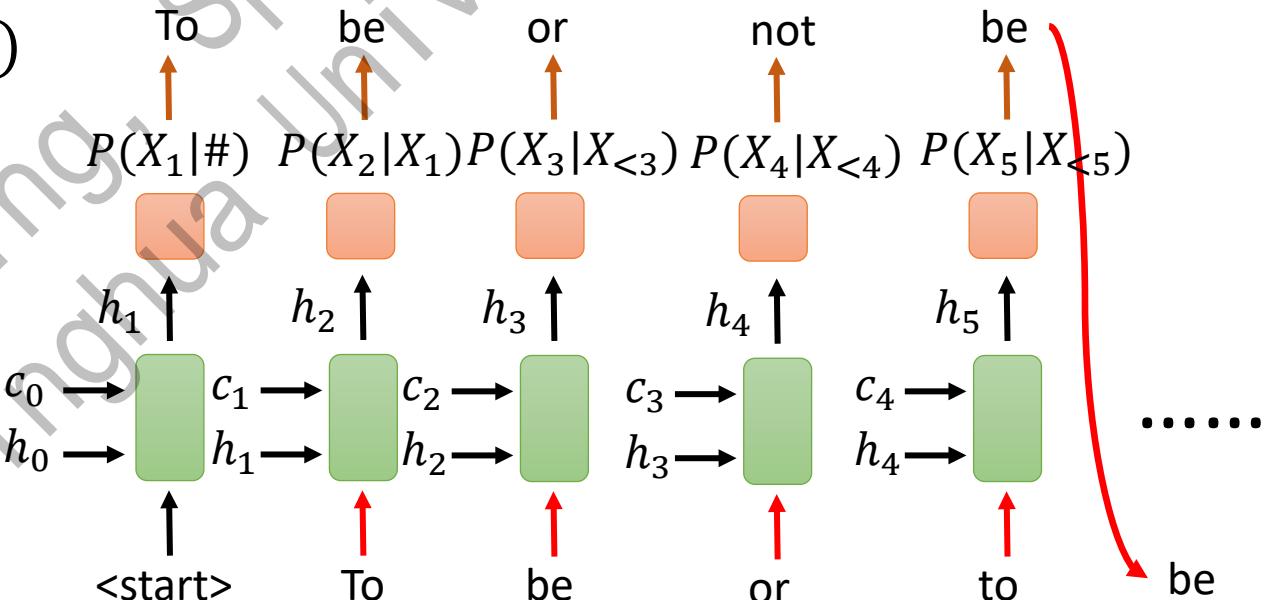


Language Model

- LSTM language model
 - $Y_t = \text{softmax}(h_t) = P(X_t | X_{i < t})$
 - $h_t, c_t = \text{LSTM}(X_{t-1}, h_{t-1}, c_{t-1})$

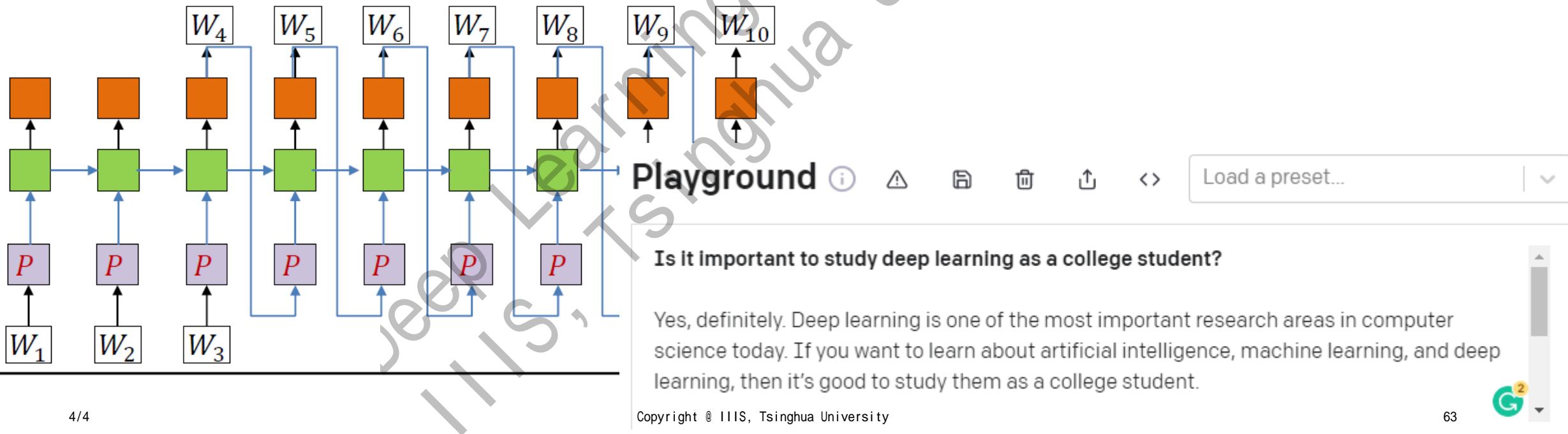
- Language generation
 - Draw $X \sim P(X; \theta)$
 - Sample $X_1 \sim Y_1(h_0, c_0, \#; \theta)$
 - Generate X_2
 - Generate X_3
 - Repeat

- Remark
 - Ensure 1 position shift at training time!



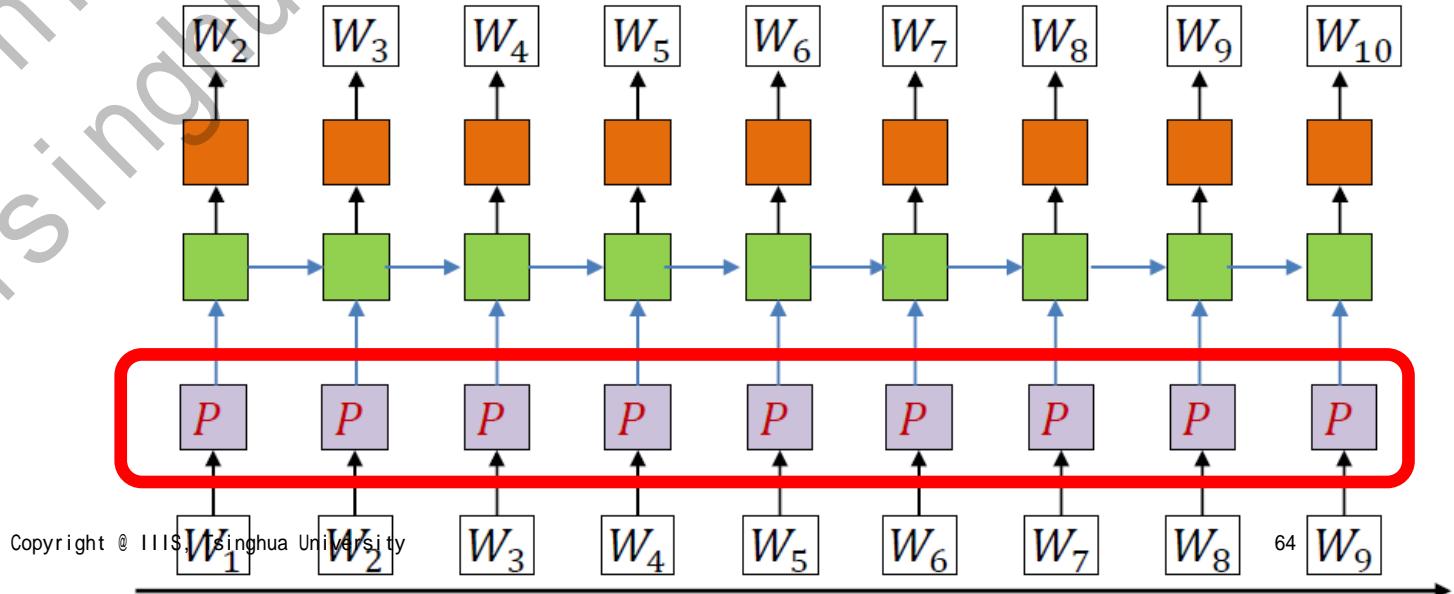
Language Model

- We can also generate a language with any given prefix
 - Given $w_{1 \sim 3}$, we can sample $P(W|w_{1 \sim 3}; \theta)$
 - E.g.: question answering



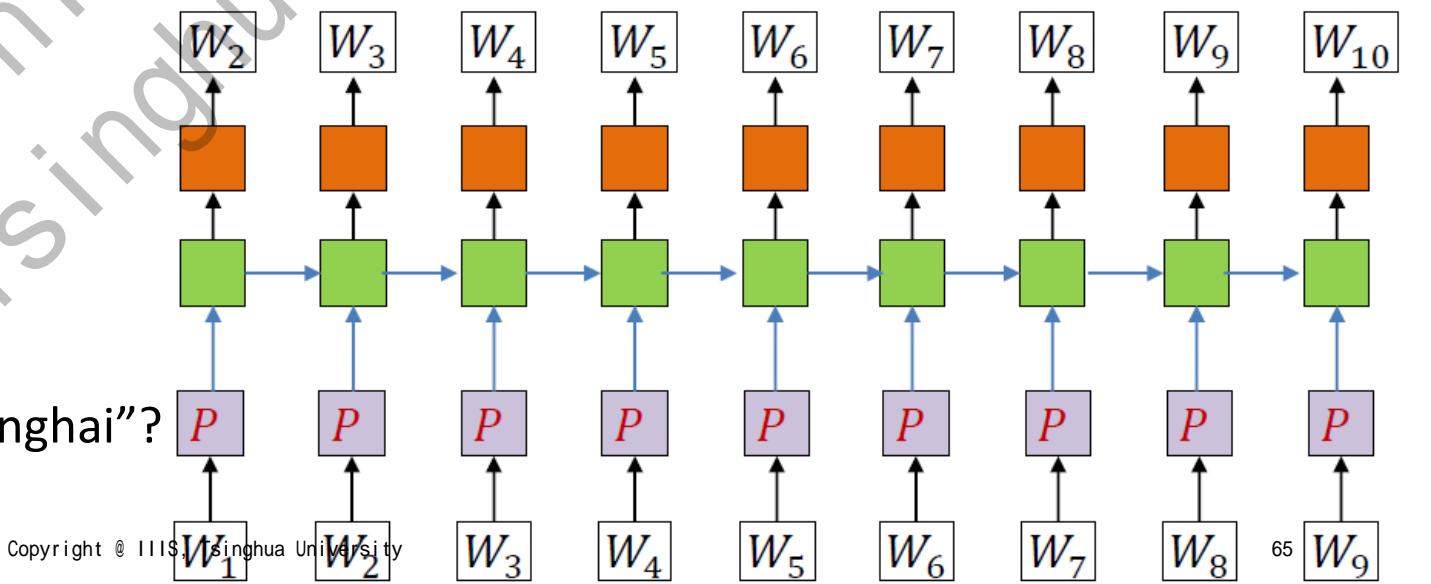
Language Model

- LSTM language model
 - $Y_t = \text{softmax}(h_t) = P(X_t | X_{i < t})$
 - $h_t, c_t = \text{LSTM}(X_{t-1}, h_{t-1}, c_{t-1})$
- MLE training and autoregressive generation
- Input projection
 - “to be or not to be ...”
 - w_t are discrete tokens
 - *LSTM* requires vector input
 - Trivial solution:
 - One-hot vector
 - $X_t = [0, 0, \dots, 1, \dots, 0]$
 - Issue?



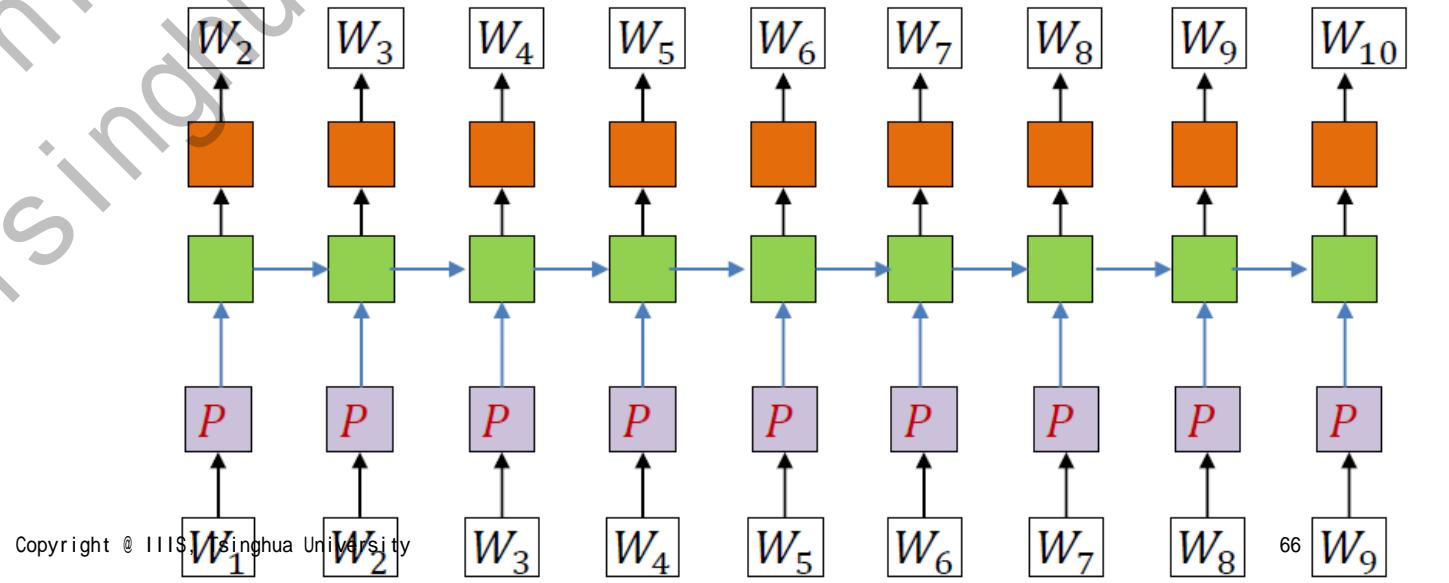
Language Model

- LSTM language model
 - $Y_t = \text{softmax}(h_t) = P(X_t | X_{i < t})$
 - $h_t, c_t = \text{LSTM}(X_{t-1}, h_{t-1}, c_{t-1})$
- Trivial input projection: one-hot encoding
 - Change a word to an ID
 - “To be or not to be ...”
 - [123, 444, 8, 91, 123, 444, ...]
 - No semantic meaning
 - $P(I \text{ live in Beijing}) = 0.3$
 - $P(I \text{ live in Shanghai}) = ?$
 - What if corpus D has no “Shanghai”?



Language Model

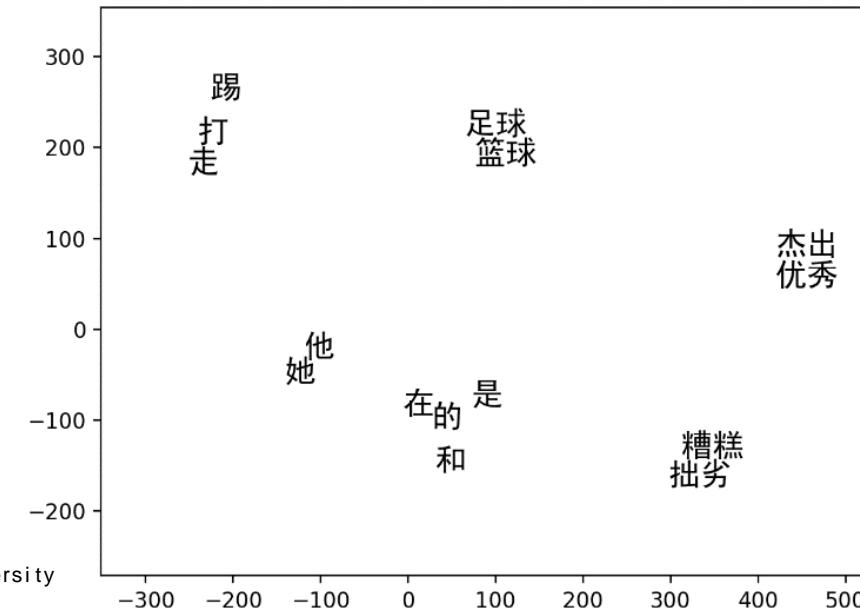
- LSTM language model
 - $Y_t = \text{softmax}(h_t) = P(X_t | X_{i < t})$
 - $h_t, c_t = \text{LSTM}(X_{t-1}, h_{t-1}, c_{t-1})$
- Goal: learn meaningful continuous representation for words
 - E.g., “Beijing”
 - It is a city in China
 - It is a noun
 - It is a capital
 - Close to “Shanghai”
 - Different from “deep”
 - Word embeddings



Word Embedding

- A semantic vector representation for words
 - Proposed in the book, “The Measurement of Meaning” 1957
 - Manually propose a few features and scores
 - **Let's learn word embeddings!**

few many those these These
couple some A a another such
any some The a the da
any some My Our our
any some their his
any some my ur your
any some her
any some me him us
any some them em
daily everyday yo yo
Every each
every each
everyday



Word Embedding

- Distributional Hypothesis
 - A word's meaning is given by the words that frequently appear close-by
 - “You shall know a word by the company it keeps” (J. R. Firth 1957: 11)
- How to measure the “similarity” of two words?
 - Given word vector w_1 and w_2
 - We use cosine distance
- Learning objective
 - If two words are close to each other, their word embeddings have small distance
 - Otherwise, the distance should be large

$$D(w_1, w_2) = \cos \langle w_1, w_2 \rangle = \frac{w_1^T w_2}{\|w_1\| \|w_2\|}$$

Word Embedding

- Word2Vec (Mikolov, et al, Google, 2013, NeurIPS 2023 test-of-time)
 - An efficient toolbox for learning word embeddings
 - Formulation
 - Given $2k$ context (上下文) vectors $c_{-k} c_{-k+1} \dots c_{-1} ? c_1 c_2 \dots c_k$
 - $P(w|c_{-k} \dots c_k)$: Predict which word should appear in the position of “?”
 - Independence assumption $P(w|c) = \prod_i P(w|c_i)$
 - $P(w|c_i)$: a softmax distribution over all words
 - There are a lot of words!!
 - We can convert multi-class classification to binary-class classification

Word Embedding

- Word2Vec (Mikolov, et al, Google, 2013)
 - An efficient toolbox for learning word embeddings
 - Simplified formulation
 - Given $2k$ context (上下文) vectors and a word w : $c_{-k} c_{-k+1} \dots c_{-1} w c_1 c_2 \dots c_k$
 - $P(+|c_{-k} \dots w \dots c_k)$: the probability of w should appear with c
 - Independence assumption $P(+|w, c) = \prod_i P(+|w, c_i)$
 - $P(+|w, c_i)$: a value between 0 and 1
 - Sigmoid function over $D(w, c_i)$
 - Assume all the vectors have unit norm

$$P(+|w, c_i) = \sigma(w, c_i) = \frac{1}{1 + \exp(-w^T c_i)}$$

$$P(-|w, c_i) = 1 - P(+|w, c_i)$$

$$\log P(+|w, c) = \sum_i \log P(+|w, c_i)$$

Word Embedding

- Word2Vec (Mikolov, et al, Google, 2013)
 - An efficient toolbox for learning word embeddings
 - Simplified formulation (CBOW, continuous bag-of-word model)
 - Given $2k$ context (上下文) vectors and a word w : $c_{-k} c_{-k+1} \dots c_{-1} w c_1 c_2 \dots c_k$
 - $P(+|c_{-k} \dots w \dots c_k)$: the probability of w should appear with c
- MLE Training!
 - Positive (w, c) pairs: all the text chunks of length $2k + 1$ from training corpus D
 - All set?
 - Identical vectors maximize the learning objective!

Word Embedding

- Word2Vec (Mikolov, et al, Google, 2013)
 - An efficient toolbox for learning word embeddings
 - Simplified formulation (CBOW, continuous bag-of-word model)
 - Given $2k$ context (上下文) vectors and a word w : $c_{-k} c_{-k+1} \dots c_{-1} w c_1 c_2 \dots c_k$
 - $P(+|c_{-k} \dots w \dots c_k)$: the probability of w should appear with c
- MLE Training!
 - Positive (w, c) pairs: all the text chunks of length $2k + 1$ from training corpus D
 - **We need negative pairs!**
 - Choose a context c , and select **random** negative words w'
 - *This training method is called **negative sampling***

Word Embedding

- Word2Vec (Mikolov, et al, Google, 2013)

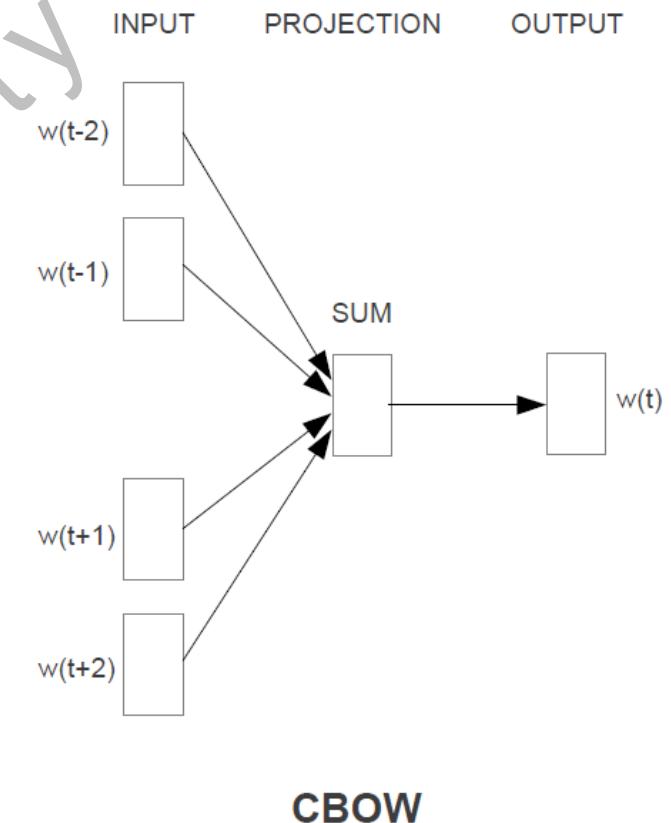
$$P(+|w, c_i) = \sigma(w, c_i) = \frac{1}{1 + \exp(-w^T c_i)}$$

$$\log P(+|w, c) = \sum_i \log P(+|w, c_i)$$

- CBOW Training corpus D
 - For every text chunks $(c_{-k}, \dots, w, \dots, c_k)$ in D
 - Collect positive data pair (c, w) , add to D^+
 - Random choose a word w' , add (c, w') to D^-
- MLE Training

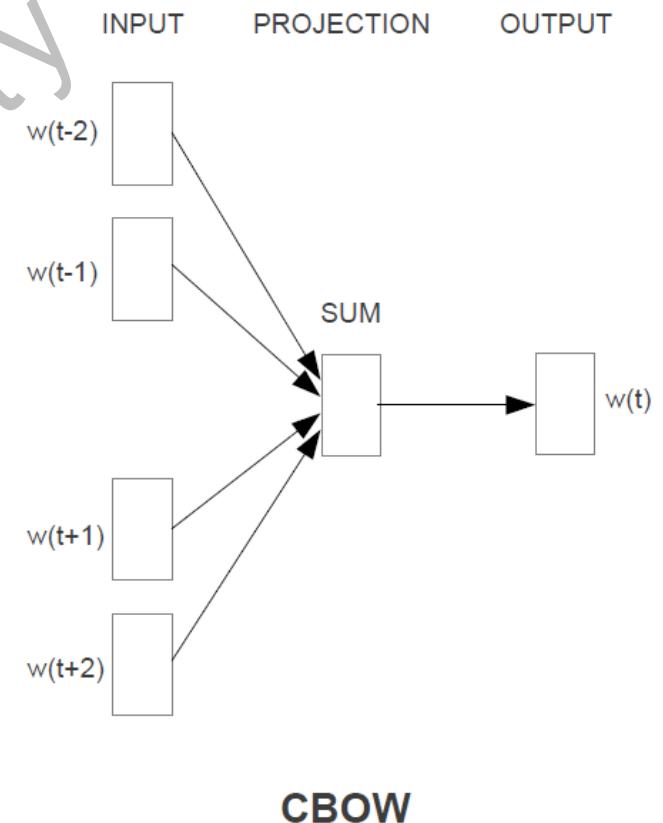
$$L(W, C) = \sum_{(c, w) \in D^+} \log P(+|w, c) + \sum_{(c, w') \in D^-} \log P(-|w', c)$$

- Use w_i as the word embedding for the i -th word
 - We can also use $[c_i, w_i]$, or simply ignore c_i



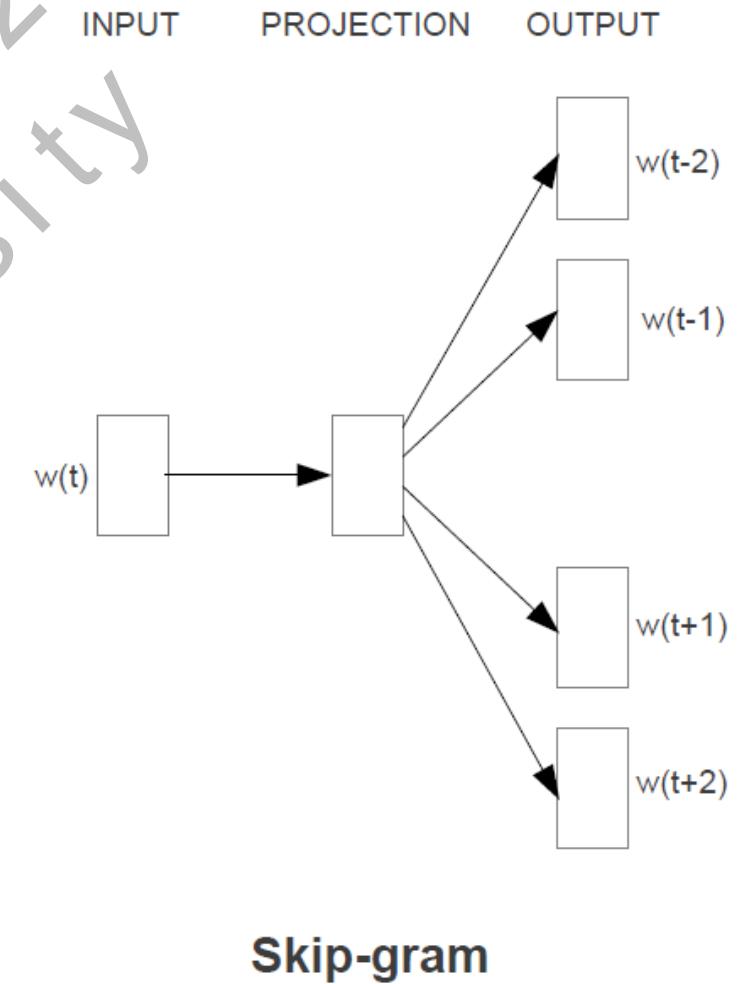
Word Embedding

- Word2Vec (Mikolov, et al, Google, 2013)
 - Continuous Bag-of-Words (CBOW)
 - Objective $\log P(w|c_i)$
 - Use contexts c to predict center word w
 - Alternative: use w to predict surrounding words c



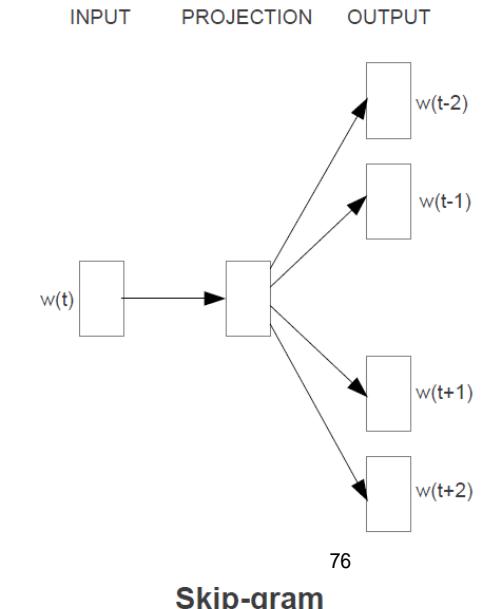
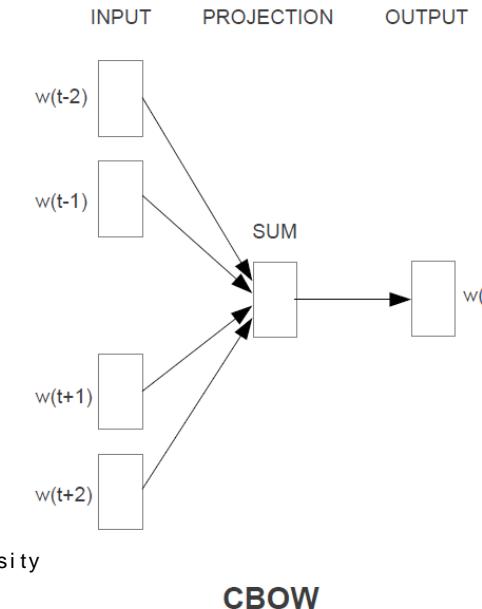
Word Embedding

- Word2Vec (Mikolov, et al, Google, 2013)
 - Continuous Bag-of-Words (CBOW)
 - Objective $\log P(w|c_i)$
 - Use contexts c to predict center word w
 - Skip-Gram Model
 - Use a single center word c to predict $w_{-k}, \dots, w_{-1}, *, w_1, \dots, w_k$
 - Objective $\log P(w_i|c)$
 - Skip-Grams
 - Randomly choose sample $2R$ positions from $-k \dots -1, 1, \dots, k$
 - Training Corpus D
 - For every text chunks $(w_{-k}, \dots, c, \dots, w_k)$ in D
 - select a subset of $2R$ words from $\tilde{w} \subseteq w_{-k} \dots w_k$
 - Collect positive data pair (c, \tilde{w}) , add to D^+
 - Random choose $2R$ words \tilde{w} , add (c, \tilde{w}) to D^-



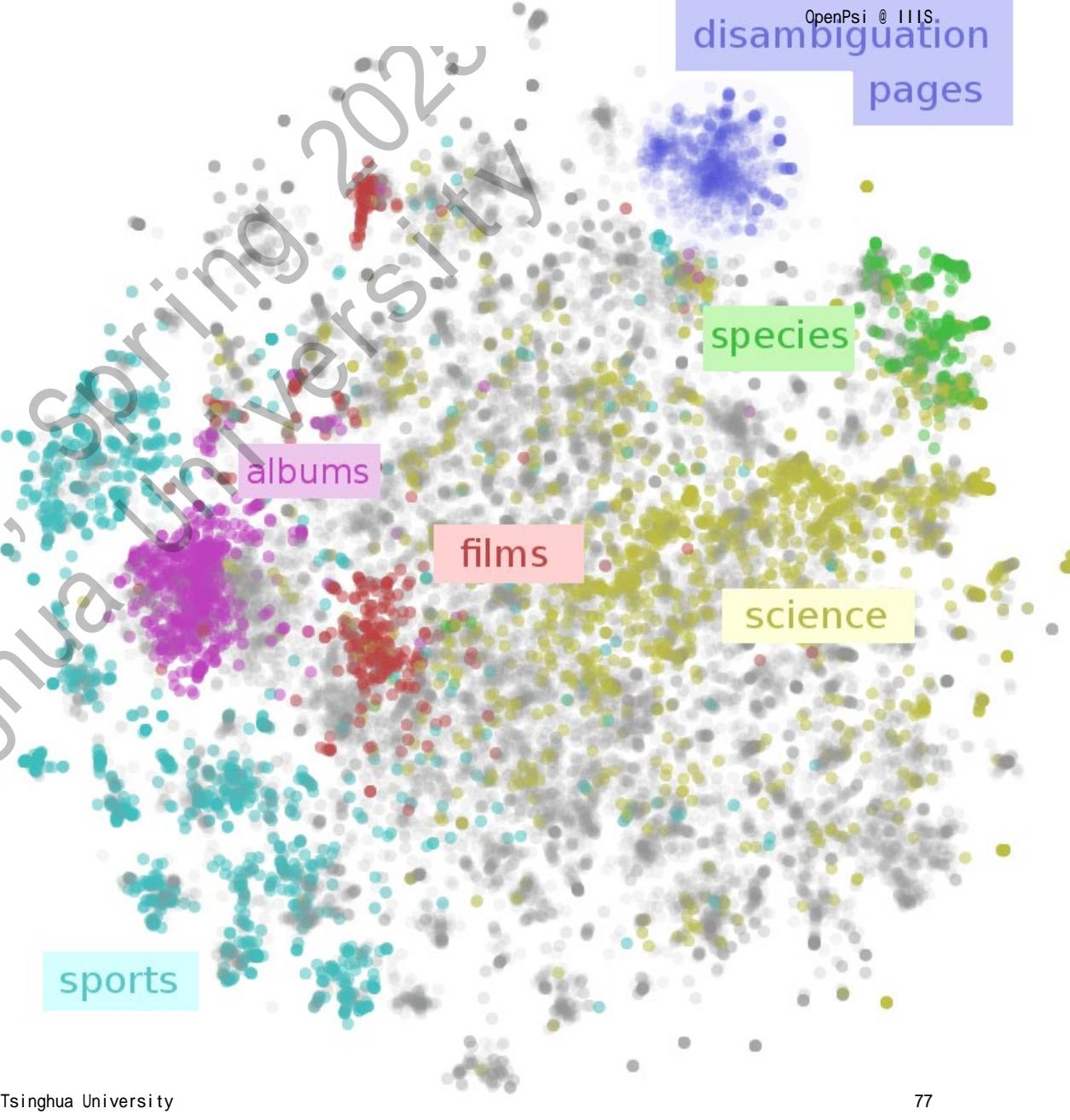
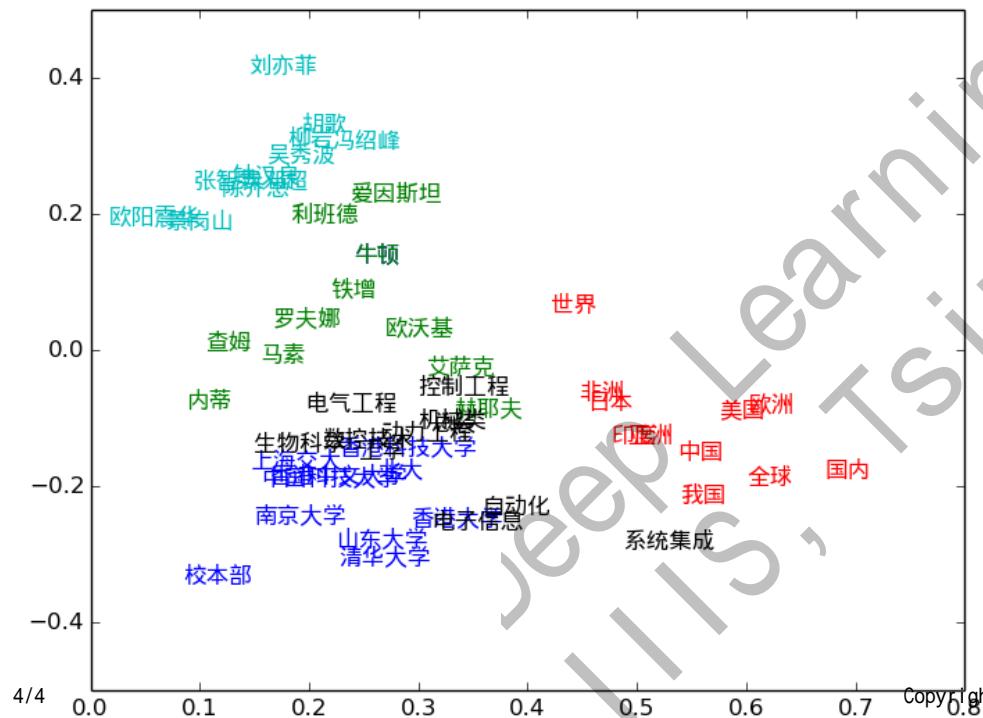
Word Embedding

- Word2Vec (Mikolov, et al, Google, 2013)
 - Continuous Bag-of-Words (CBOW)
 - Use contexts c to predict center word w
 - Skip-Gram Model
 - Use a single center word c to predict $w_{-k}, \dots, w_{-1}, *, w_1 \dots w_k$
- Remark
 - CBOW trains faster than Skip-Gram
 - Skip-Gram is a harder problem
 - Harder to overfit
 - Skip-Gram performs better
 - Particularly for rare words



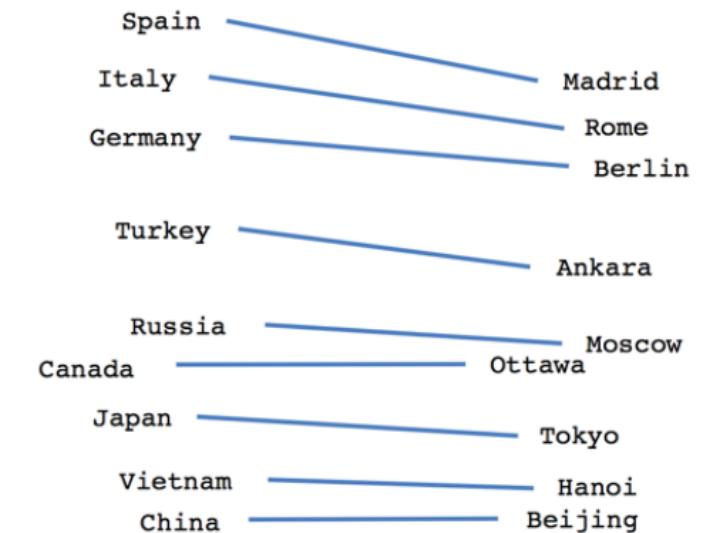
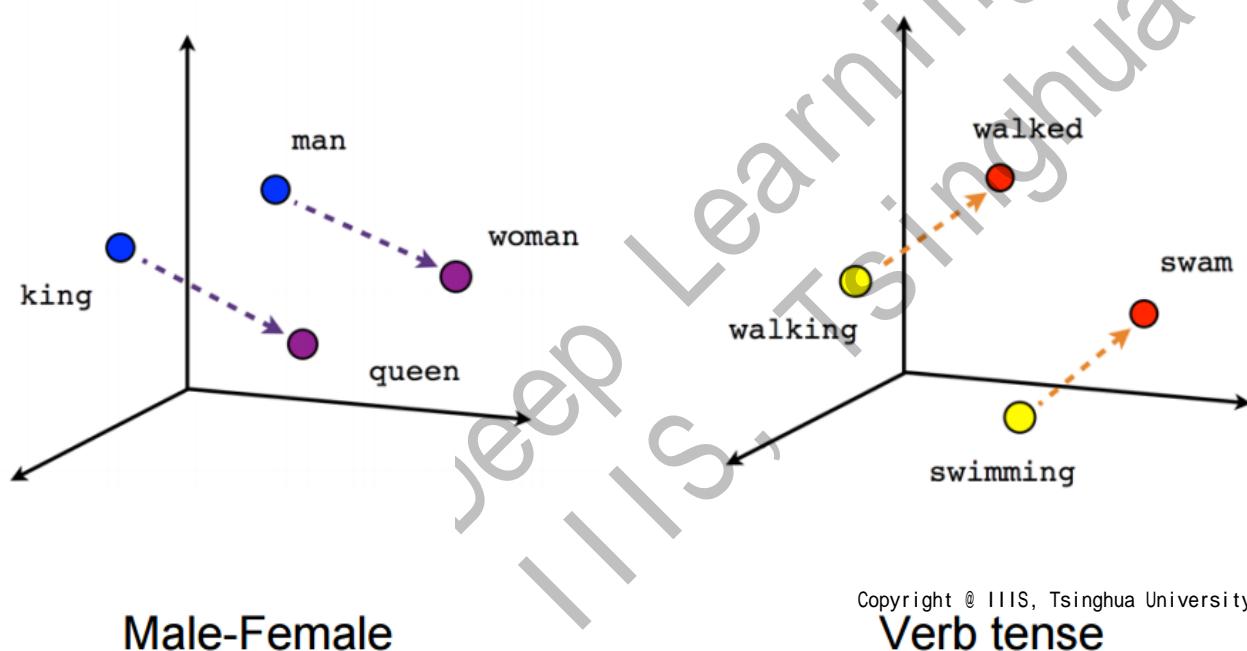
Word Embedding

- Word2Vec Visualization
 - t-SNE projection in 2D
 - Similar topics cluster together



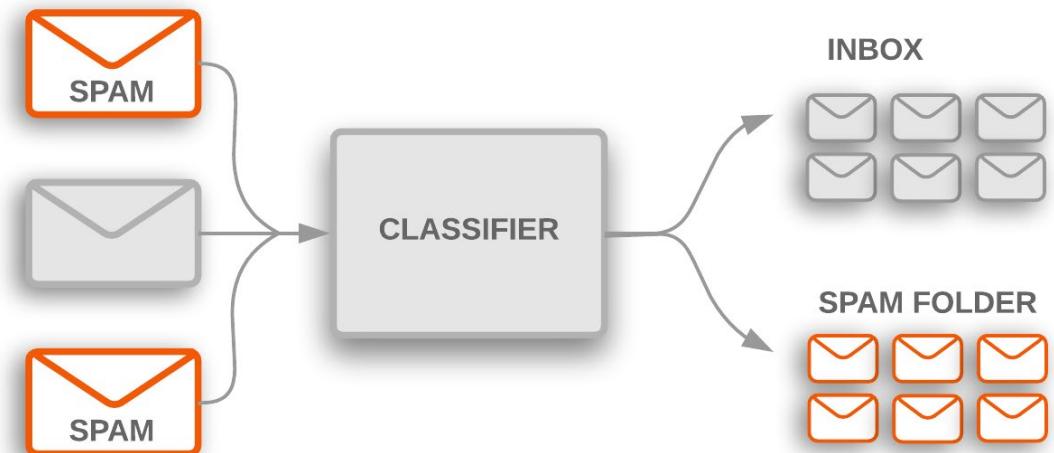
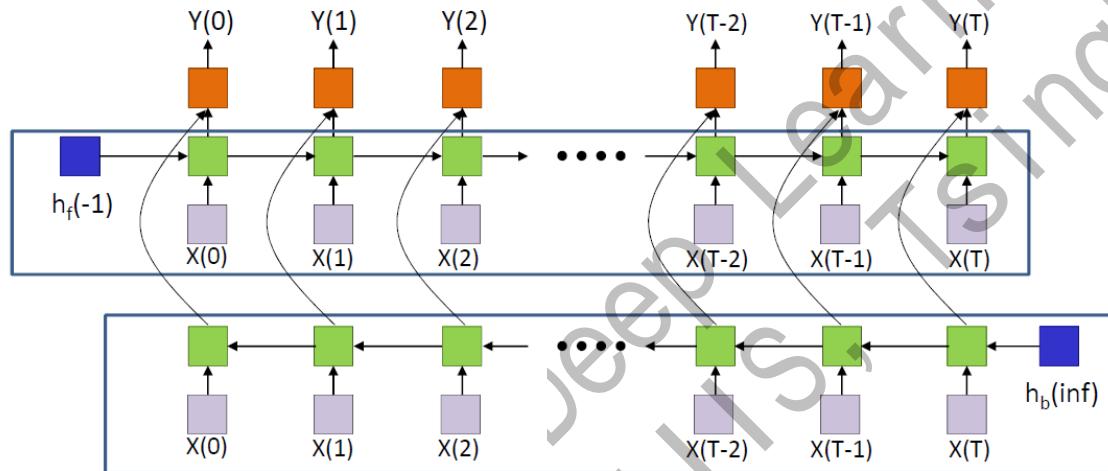
Word Embedding

- Word2Vec Vector Arithmetic
 - Emergent analogies
 - $\text{king} - \text{man} + \text{woman} \approx \text{queen}$
 - $\text{Beijing} - \text{China} + \text{France} \approx \text{Paris}$



LSTM Applications

- Pre-processing
 - Collect a large corpus and learn word embeddings (word2vec)
- Text classification
 - Bi-directional LSTM and then run Softmax on final hidden states



LSTM Applications

- Pre-processing
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 - For the specific training domain, learn an autoregressive model $P(X)$



LSTM Applications

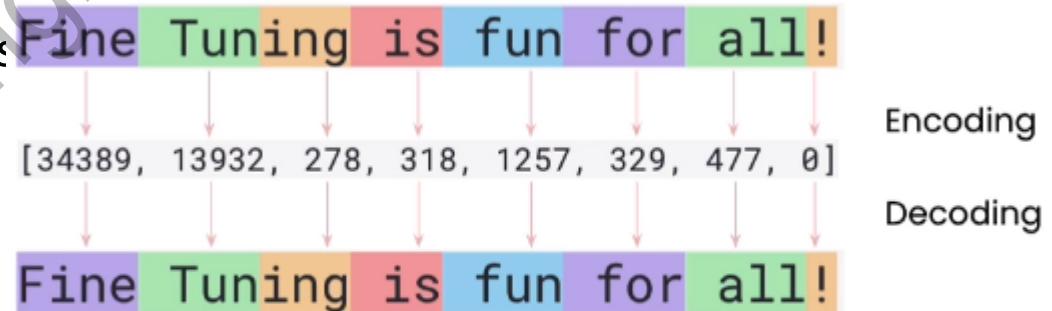
- Pre-processing
 - Collect a large corpus and learn word embeddings (word2vec)
- Text classification
 - Bi-directional LSTM and then run Softmax on final hidden states
- Text generation
 - For the specific training domain, learn an autoregressive model $P(X)$
- Text correction (文本改错)
 - MCMC over $P(X)$ to improve X
 - $-\log P(\text{文学是一种医术形式}) = 1484.5$
 - $-\log P(\text{文学是一种艺术形式}) = 234.5$

LSTM Applications

- English v.s. 中文
 - Word v.s. character
 - We typically use word models for English & character model for Chinese
 - A huge number of words in English! (“pneumonoultramicroscopicsilicovolcanoconiosi”)
 - Use <unk> for very rare words
 - Dictionary is much smaller for pure Chinese (your homework ☺)
 - 分词 word segmentation
 - An issue in Chinese if you want to use word model: 中关村北大街
 - 词干化 stemming
 - Has → have; running → run
 - Apples → apple
 - 词条化(令牌化) tokenization
 - A 11-year-old boy; 12345*54321=670592745 **(still critical in modern LMs)**

LSTM Applications

- English v.s. 中文
 - Word v.s. character
 - We typically use word models for English & character model for Chinese
 - A huge number of words in English! (“pneumonoultramicroscopicsilicovolcanoconiosi”)
 - Use <unk> for very rare words
 - Dictionary is much smaller for pure
 - Tokenize the data
 - 分词 word segmentation
 - An issue in Chinese if you want to us
 - 词干化 stemming
 - Has → have; running → run
 - Apples → apple
 - 词条化(令牌化) tokenization
 - A 11-year-old boy; 12345*54321=67 There are multiple popular tokenizers:
 - Subword tokenization

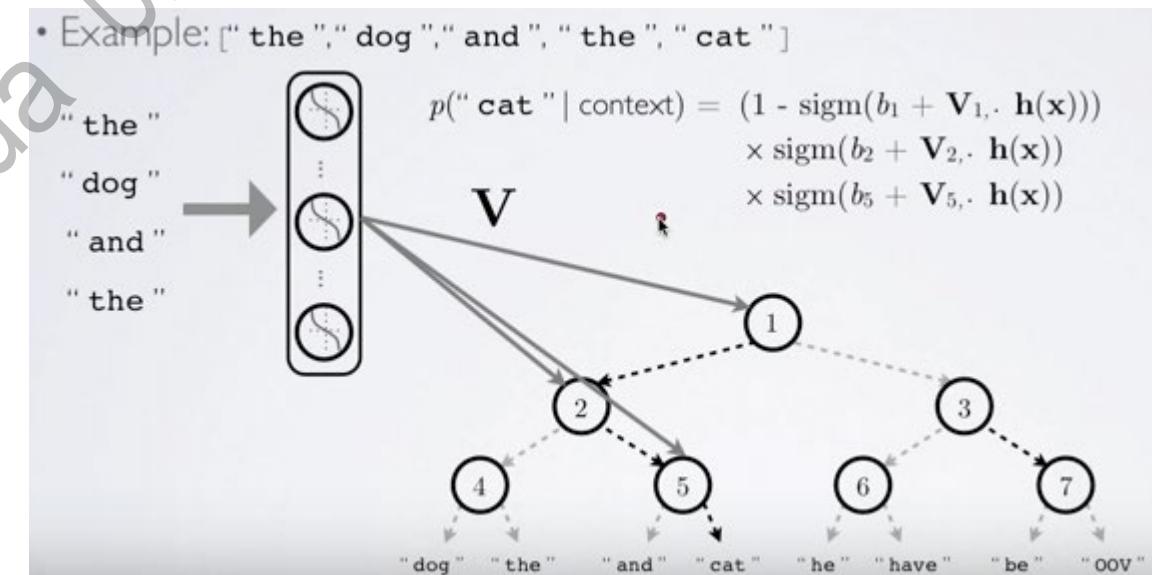


Computation Techniques

- Language Model Learning
 - MLE learning: $P(X_t | X_{i < t})$
 - The expensive Softmax operator
 - Objective $P_\theta(w|h) = \text{softmax}(w^T h) \propto \exp(w^T h)$ for $w \in V$
 - h is the hidden state of LSTM language model output
 - Equivalent: $P_\theta(w|h) \propto u_\theta(w, h)$, $u_\theta(w, h)$ is exponential logit for w given h
 - Loss
 - $L(w; \theta) = \log P_\theta(w) = \log u_\theta(w) - \log Z = \log u_\theta(w) - \log(\sum_{w'} u_\theta(w'))$
 - Partition function Z
 - Monte Carlo Estimate!
 - $\nabla L(w; \theta) = \nabla \log u_\theta(w) - \mathbb{E}_{w' \sim P_\theta} [\nabla \log u_\theta(w')]$
 - How to sample?
 - *Note: this is a categorical distribution over words...*

Computation Techniques

- Language Model Learning
 - MLE learning: $P(X_t | X_{i < t})$
 - The expensive Softmax operator
 - Hierarchical Softmax
 - Build a binary tree: $O(V) \rightarrow O(\log V)$
 - For node j , $P(\text{left} | n_j, h) = \sigma(n_j^T h)$
 - $P(w) = \prod_j \sigma(h^T n_j)$
 - #Params = $2V$
 - $2V$ operators to calculate all probabilities
 - Remark:
 - Each word has different frequency
 - *Optimal tree structure?*

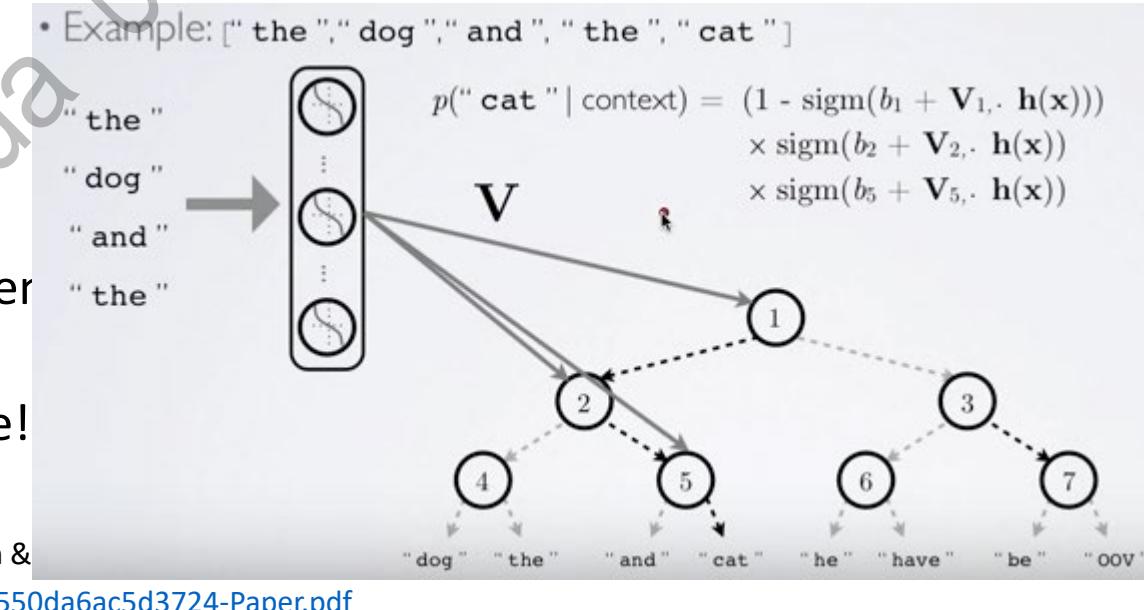


Computation Techniques

- Language Model Learning

- MLE learning: $P(X_t | X_{i < t})$
- The expensive Softmax operator
- Hierarchical Softmax

- Computation cost $H = \sum_w P(w)I(w)$
 - H is also referred to as entropy
- $P(w)$: the frequency of word w
- $I(w)$: the tree depth (or information content)
 - In a complete binary tree, $I(w) = \log_2 V$
- The optimal tree structure is Huffman tree!
- We can also utilize semantic information
 - E.g., A Scalable Hierarchical Distributed Language Model. Mnih &
 - <https://papers.nips.cc/paper/2008/file/1e056d2b0ebd5c878c550da6ac5d3724-Paper.pdf>



Advanced Techniques

- Language Model Learning
 - Hierarchical Softmax
 - Non-sampling, tree-based probability computation
 - Remark
 - Use full softmax when possible for the best performance (GPU memory allowed)
- Q: what if we want the *best* output?
 - $X = \arg \max_X P(X)$
 - Greedy solution: for each $P(X_t | X_{i < t})$, select the optimal X_t
 - *Optimal?*

Advanced Techniques

- Language Model Inference

- Goal: find $X^* = \arg \max_X P(X) = \prod_t P(X_t | X_{i < t})$
- Greedy Solution:
 - For each t , $X_t^* = \arg \max_{X_t} P(X_t | X_{i < t}^*)$ (i.e., keep the best partial candidate)
- Better Solution: Beam Search
 - Idea: keep top K candidates for each t
 - K is called the beam size (in practice $k = 5 \sim 10$)
 - At each time step t , compute K^2 expansions and keep the top K for $t + 1$
 - For each candidate $\tilde{X}_{i < t}$, find the top- K X_t based on $P(X_t | \tilde{X}_{i < t})$
 - Rank K^2 candidates by their partial probability $P(\tilde{X}_{i \leq t})$
 - No guarantee to find the optimal solution
 - Trade-off between accuracy (exhaustive search) and efficiency (greedy)

Advanced Techniques

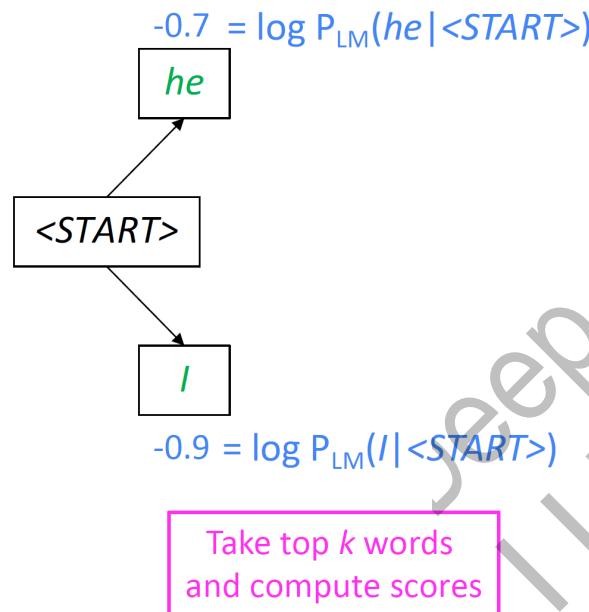
- Beam Search
 - Example: $K = 2$, score = $\log P(X) = \sum_t \log P(X_t | X_{i < t})$

<START>

Calculate prob
dist of next word

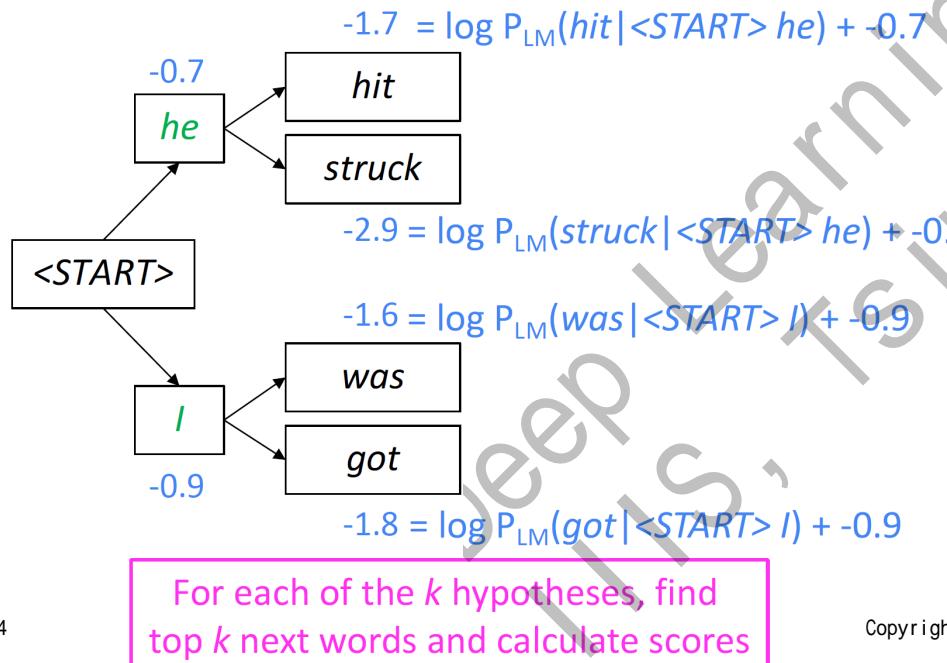
Advanced Techniques

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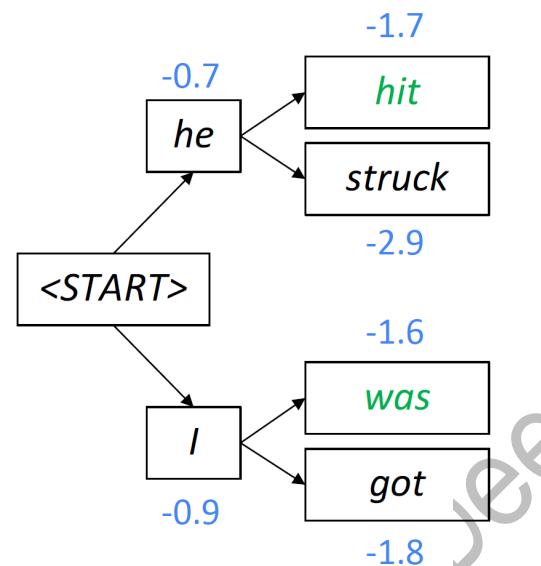
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Advanced Techniques

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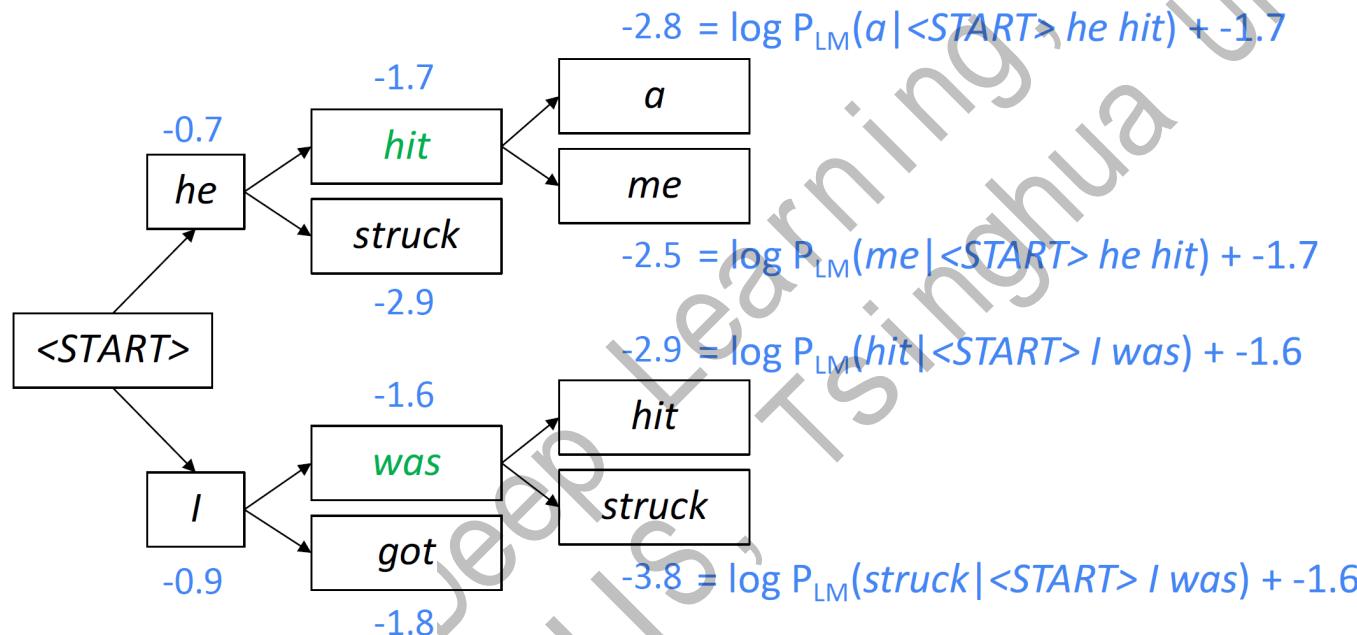


Of these k^2 hypotheses,
just keep k with highest scores

Advanced Techniques

- Beam Search

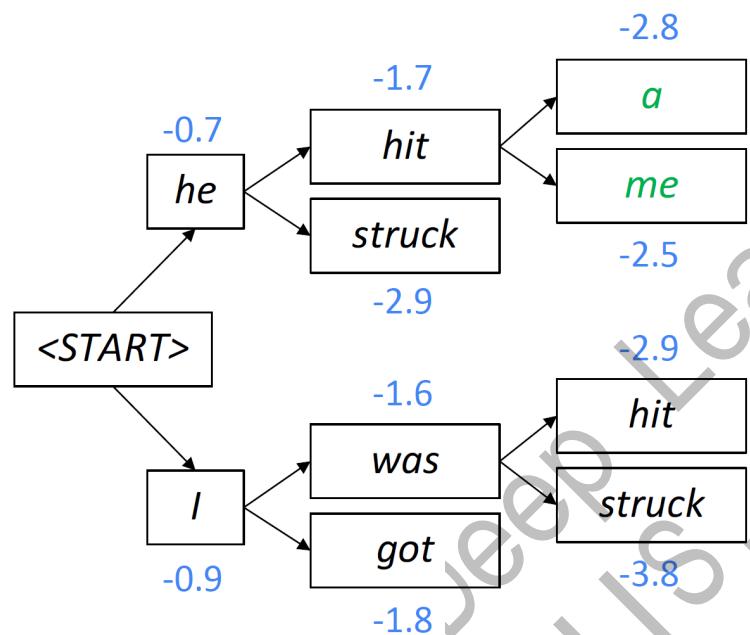
- Example: $K = 2$, score = $\log P(X) = \sum_t \log P(X_t | X_{i < t})$



For each of the k hypotheses, find
top k next words and calculate scores

Advanced Techniques

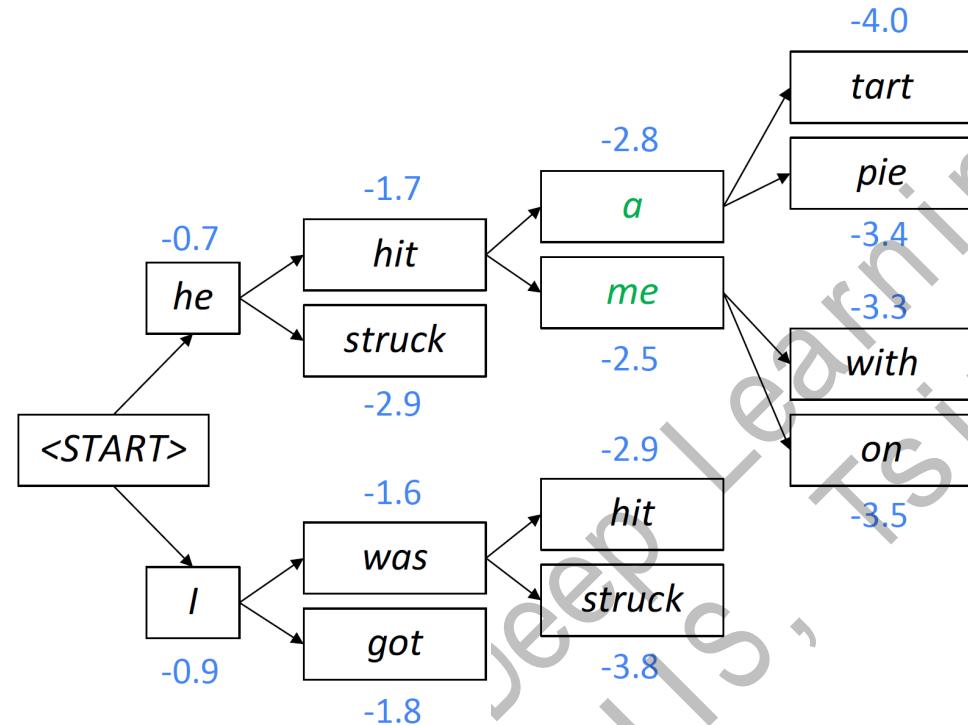
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Of these k^2 hypotheses
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Advanced Techniques

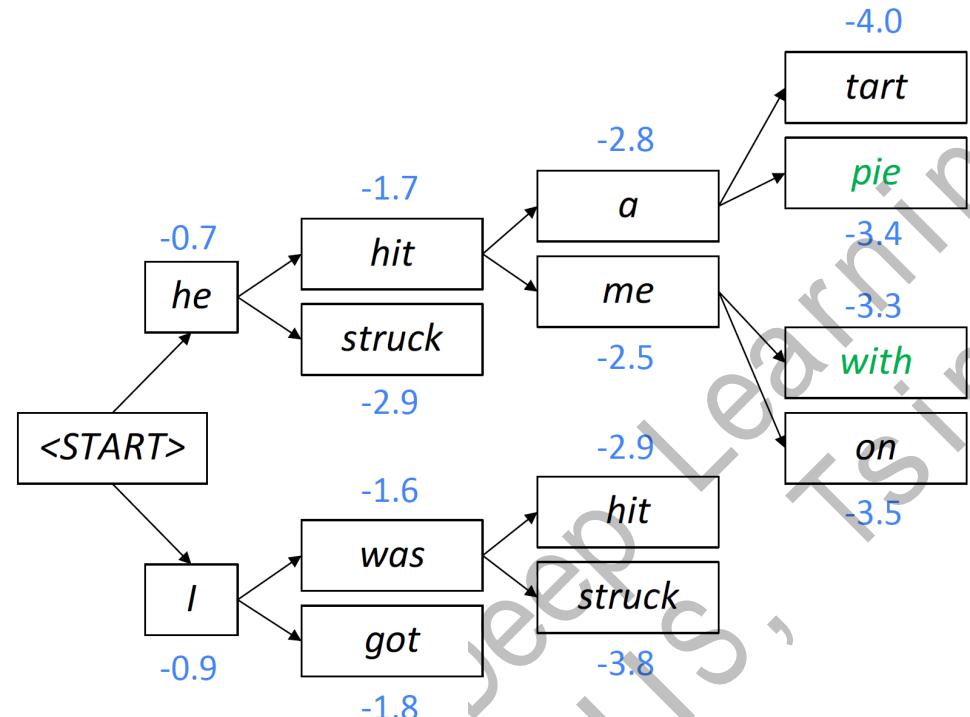
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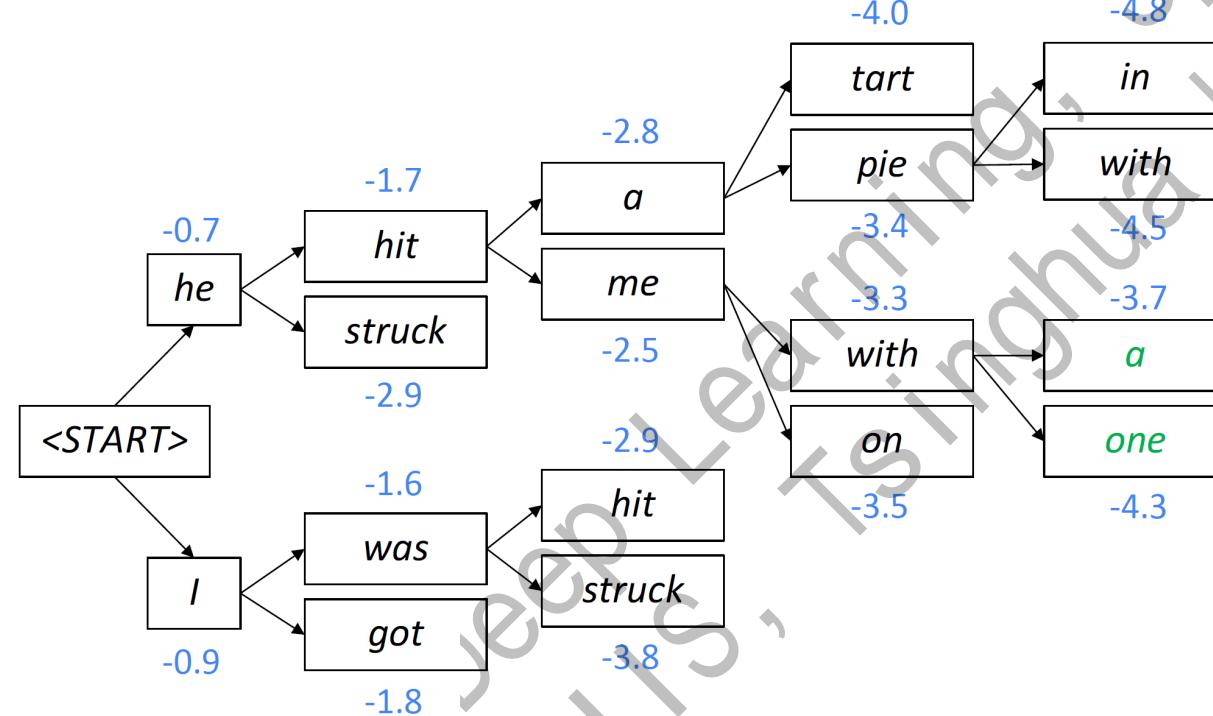
- Beam Search
 - Example: $K = 2$, score = $\log P(X) = \sum_t \log P(X_t | X_{i < t})$



Of these k^2 hypotheses
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Advanced Techniques

- Beam Search
 - Example: $K = 2$, score = $\log P(X) = \sum_t \log P(X_t | X_{i < t})$

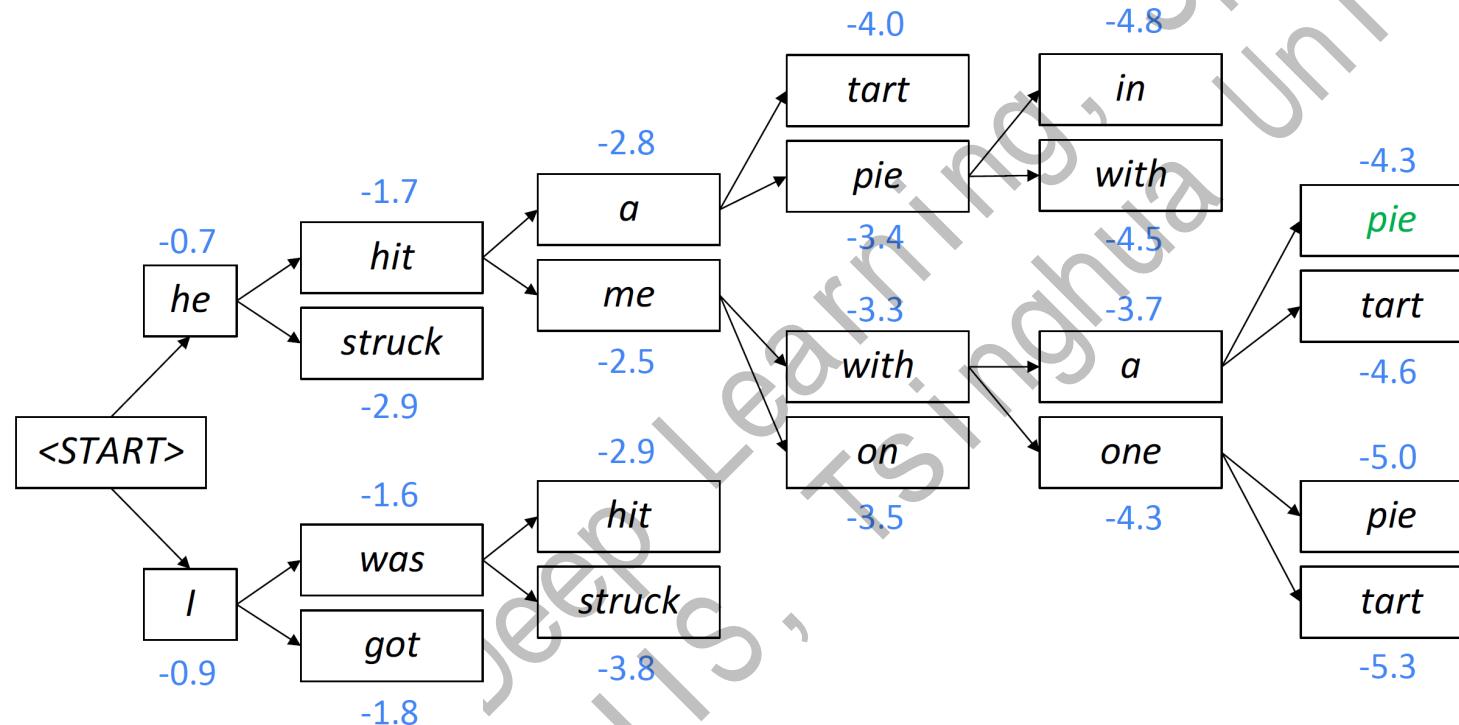


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Of these 12 hypotheses,
just keep k with highest scores

Advanced Techniques

- Beam Search

- Example: $K = 2$, score = $\log P(X) = \sum_t \log P(X_t | X_{i < t})$



Advanced Techniques

- Language Model Inference

- Goal: find $X^* = \arg \max_X P(X) = \prod_t P(X_t | X_{i < t})$

- Greedy Solution:

- For each t , $X_t^* = \arg \max_{X_t} P(X_t | X_{i < t}^*)$ (i.e., keep the best partial candidate)

- Better Solution: Beam Search

- Idea: keep top K candidates for each t
 - When to terminate (sequences may have varying lengths)?
 - We typically include a <end> token to indicate a text sequence is ended
 - L_{\max} words reached or n completed sequences obtained (<end> token produced)
 - Which sequence to choose?
 - Issue: longer sequences tend to have lower scores!
 - Adjusted metric: $X^* = \arg \max_X \frac{1}{L_X} \sum_t \log P(X_t | X_{i < t})$ (normalized by its length)

Advanced Techniques

- Language Model Learning
 - The expensive softmax operator
- Language Model Inference
 - Beam search for the best generated sequence
 - You can also include a temperature parameter in score if you want diverse texts
- Improving the word representation
 - So far, we assume a static (pretrained) embedding
 - Issue: the same word in different contexts may have different meaning
 - Teddy **bear** v.s. I cannot **bear** him any more
 - A nice **weather** v.s. I'm under the **weather** today
 - 荀富贵, 毋相忘 v.s. 荀全性命于乱世
- Word embeddings should be **context-aware!**

Advanced Techniques

- Deep contextualized word representations (EMNLP2018)
 - Idea: a word feature should be related to the whole contexts
 - Including both previous words and future words
 - ELMo
 - (Optional) Use word2vec to pretrain static word embeddings w_s
 - Train a (stacked) bidirectional RNN language model $g_f(w, h)$ and $g_b(w, h)$ use w_s
 - Fix the RNN model g_f and g_b
 - For a sequence for a specific task, for the t -th word
 - Run g_f and g_b on the sentence to get h_t^f and h_t^b
 - Use $[w_t, h_t^f, h_t^b]$ as embedding
 - Remark:
 - Bidirectional LSTM is critical!

TASK	PREVIOUS SOTA	OUR BASELINE		ELMo + BASELINE	INCREASE (ABSOLUTE/RELATIVE)
		BASELINE	BASELINE		
SQuAD	Liu et al. (2017)	84.4	81.1	85.8	4.7 / 24.9%
SNLI	Chen et al. (2017)	88.6	88.0	88.7 ± 0.17	0.7 / 5.8%
SRL	He et al. (2017)	81.7	81.4	84.6	3.2 / 17.2%
Coref	Lee et al. (2017)	67.2	67.2	70.4	3.2 / 9.8%
NER	Peters et al. (2017)	91.93 ± 0.19	90.15	92.22 ± 0.10	1.06 / 21%
SST-5	McCann et al. (2017)	53.7	51.4	54.7 ± 0.5	3.3 / 6.8%

Advanced Techniques

- Language Model Learning
 - The expensive softmax operator
- Language Model Inference
 - Beam search for the best generated sequence
 - You can also include a temperature parameter in score if you want diverse texts
- Contextualized Word Embedding
 - ELMo: use contexts to compute features of a word
- More techniques in your NLP course ☺

Summary

- Recurrent neural network (RNN) for sequence data
 - Vanishing/exploding gradients/value
- Long Short-Term Memory networks (LSTM)
 - An RNN architecture for long-term dependency
- Language Model
 - Auto-regressive model over texts & LSTM applications
 - Word2vec for word representation
 - Hierarchical Softmax for more efficient softmax
 - Beam search for the best output
 - Elmo for contextualized representation
- Next lecture: more advanced sequence modeling techniques

Thanks!

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