```
In [1]:
u=2.5+3j
v=2
w=u+v
In [2]:
from math import sin
r=sin(w)
TypeError
                                           Traceback (most recent call last)
<ipython-input-2-f2478e858a9e> in <module>()
      1 from math import sin
----> 2 r=sin(w)
TypeError: can't convert complex to float
In [20]:
from cmath import sin, sinh
from numpy.lib.scimath import *
from cmath import *
from math import sqrt
from cmath import sqrt
import numpy
r=sin(w)
r
Out[20]:
(-9.841442815345065-2.1117259539209345j)
In [11]:
r1=sin(8j)
r1
Out[11]:
1490.4788257895502j
In [12]:
r2=1j*sinh(8)
r2
Out[12]:
1490.4788257895502j
In [15]:
q=8
exp(1j*q)
Out[15]:
(-0.14550003380861354+0.9893582466233818j)
```

```
In [16]:
cos(q)+1j*sin(q)
Out[16]:
(-0.14550003380861354+0.9893582466233818j)
In [19]:
sqrt(-1)
                                            Traceback (most recent call last)
ValueError
<ipython-input-19-e94865f03ce3> in <module>()
----> 1 sqrt(-1)
ValueError: math domain error
In [21]:
sqrt(-1)
Out[21]:
1j
Type Markdown and LaTeX: \alpha^2
In [8]:
import numpy as np
In [11]:
x=np.array([[1,2],[4,5]])
y=np.array([[1,3],[5,6]])
print(np.add(x,y))
[[ 2 5]
 [ 9 11]]
In [12]:
print(np.subtract(x,y))
[[ 0 -1]
[-1 -1]]
In [13]:
print(np.divide(x,y))
[[ 1.
               0.66666667]
               0.8333333]]
 [ 0.8
```

```
In [14]:
print(np.multiply(x,y))
[[ 1 6]
[20 30]]
In [15]:
print(np.dot(x,y))
[[11 15]
[29 42]]
In [1]:
import numpy as np
matrix = np.matrix([[1,4],[2,0]])
det=np.linalg.det(matrix)
print(det)
-8.0
In [2]:
A=([[1,5,6,7],[8,9,1,0],[2,3,4,5],[4,5,2,3]])
A_det=np.linalg.det(A)
print(A)
print(A_det)
[[1, 5, 6, 7], [8, 9, 1, 0], [2, 3, 4, 5], [4, 5, 2, 3]]
-86.0
In [3]:
inverse=np.linalg.inv(matrix)
A_inv=np.linalg.inv(A)
print(inverse)
print(A_inv)
B=np.linalg.inv(A_inv)
print(B)
[[ 0.
          0.5
 [ 0.25 -0.125]]
[[-0.39534884 0.09302326 0.65116279 -0.1627907 ]
 [ 0.34883721 -0.02325581 -0.6627907
                                        0.29069767]
 [ 0.02325581  0.46511628  0.75581395 -1.31395349]
 [-0.06976744 -0.39534884 -0.26744186 0.94186047]]
   1.00000000e+00
                     5.00000000e+00
                                       6.00000000e+00
                                                        7.00000000e+001
ГΓ
    8.0000000e+00
                     9.00000000e+00
                                       1.00000000e+00
                                                        2.35922393e-16]
    2.00000000e+00
                     3.00000000e+00
                                       4.00000000e+00
                                                        5.00000000e+001
                                                        3.00000000e+00]]
    4.00000000e+00
                     5.00000000e+00
                                       2.00000000e+00
```

```
In [4]:
```

```
A=([[1,3,2],[2,3,1],[4,2,1]])
B=([[2,4,6],[3,2,1],[7,6,2]])
det_A=np.linalg.det(A)
det_B=np.linalg.det(B)
print(det_A)
print(det_B)
inv_A=np.linalg.inv(A)
inv_B=np.linalg.inv(B)
print(inv_A)
print(inv B)
AB=np.dot(A,B)
AB_INV=np.linalg.inv(AB)
B_INV_A_INV=np.dot(inv_B,inv_A)
print(B_INV_A_INV)
print(AB_INV)
-9.0
24.0
[[-0.11111111 -0.11111111 0.33333333]
 [ 0.88888889 -1.11111111 0.33333333]]
[[-0.08333333 1.16666667 -0.333333333]
[ 0.04166667 -1.58333333  0.66666667]
1.28703704 -0.52777778]
[[-0.5462963
[ 0.93981481 -1.97685185  0.76388889]
[-0.46296296 0.87037037 -0.27777778]]
[[-0.5462963
              1.28703704 -0.52777778]
 [ 0.93981481 -1.97685185 0.76388889]
 [-0.46296296  0.87037037  -0.27777778]]
In [5]:
A=([[1,3],[4,9]])
B=([[4,5],[6,8]])
C=([[6,7],[8,1]])
A B=np.dot(A,B)
B_C=np.dot(B,C)
A_BC=np.dot(A,B_C)
AB_C=np.dot(A_B,C)
print(A BC)
print(AB_C)
[[ 364
       183]
[1156
       582]]
[[ 364
       183]
[1156
       582]]
In [6]:
E=np.matrix([[1,4,7],[9,1,9],[0,0,1]])
eigvals=np.linalg.eigvals(E)
print(eigvals)
[7.-5.1.]
```

```
In [7]:
a=np.array([[1,2,3],[4,5,6],[7,8,9]])
print(a)
tri_upper_diag=np.triu(a,k=0)
print(tri_upper_diag)
tri_upper_diag_no_diag=np.triu(a,k=1)
print(tri_upper_diag_no_diag)
tri_upper_diag_no_diag=np.triu(a,k=2)
print(tri_upper_diag_no_diag)
tri_upper_diag_no_diag=np.triu(a,k=3)
print(tri_upper_diag_no_diag)
[[1 2 3]
[4 5 6]
 [7 8 9]]
[[1 2 3]
[0 5 6]
[0 0 9]]
[[0 2 3]
 [0 0 6]
 [0 0 0]]
[[0 0 3]
 [0 0 0]
[0 0 0]]
[[0 0 0]]
 [0 0 0]
 [0 0 0]]
In [8]:
A=np.array([[3,1],[1,2]])
B=np.array([9,8])
X=np.linalg.solve(A,B)
print(X)
[ 2. 3.]
```

In []: