# Jeeseop Kim

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EDUCATION Ph.D. Candidate in Mechanical Engineering advisor: Prof. Kaveh Akbari Hamed Expected in 2022

M.S. in Transdisciplinary Studies (Intelligent Systems)

advisor: Prof. Jaeheung Park

March, 2017

Seoul National University, South Korea

Virginia Polytechnic Institute and State University, USA

**B.S. in Mechanical and Aerospace Engineering**March, 2014
Seoul National University, South Korea

EMPLOYMENT Graduate Research Assistant Aug. 2019 - Present

Dept. of Mechanical Engineering, Virginia Tech, Blacksburg, USA

Advisor: Prof. Kaveh Akbari Hamed

Graduate Research Assistant Aug. 2017 - Jul. 2019

Dept. of Mechanical Engineering, Virginia Tech, Blacksburg, USA

Advisor: Prof. Tomonari Furukawa

Graduate Research Assistant Jan. 2014 - Jul. 2017

Dept. of Transdisciplinary Studies, Seoul National University, South Korea

Advisor: Prof. Jaeheung Park

Undergraduate Research Assistant

Dynamic Robotic Systems Lab, Seoul National University, South Korea Jun. 2013 - Sep. 2013

Supervisor: Prof. Jaeheung Park

Research Intern Mar. 2012 - Feb. 2013

Biorobotics Lab, Seoul National University, South Korea

Supervisor: Prof. Kyu-Jin Cho

Teaching Assistant

EXPERIENCE Dept. of Mechanical Engineering, Virginia Tech, Blacksburg, USA

ME5524: Bayesian Robotics

ME5984: SS:Advanced Experimental Robotics

Teaching Assistant

Dept. of Transdisciplinary Studies, Seoul National University, South Korea

493.601: Convergent Robotics Technology

493.611: Dynamics and Control of Robot-Environment Interaction

PATENT [P2] **Jeeseop Kim**, et al, Automatic cardiopulmonary resuscitation device and control method therefor, 2019. No. 20190029919A1 (US Patent), No. 108697572A (CN Patent), No. 3409258A1

(EU Patent)

[P1] **Jeeseop Kim**, et al, Apparatus for Automatic Cardiovascular Pulmonary Resuscitation, 2016. Korea Patent No.10-2016-0172286.

## PEER-REVIEWED JOURNAL ARTICLES

- [J3] R. T. Fawcett, A. Pandala, J. Kim, and K. Akbari Hamed, Real-time planning and nonlinear control for quadrupedal locomotion with articulated tails, ASME Journal of Dynamic Systems, Measurement, and Control, Accepted to appear, Jan, 2021.
- [J2] K. A. Hamed, **J. Kim**, A. Pandala, Quadrupedal Locomotion via Event-Based Predictive Control and QP-Based Virtual Constraints, IEEE Robotics and Automation Letters, Vol. 5, No. 3, pp. 4463-4470, Jul, 2020.
- [J1] **J. Kim**, Y. Omori, A. Sifat, and T. Furukawa, Adjustably Designed Torque Controlled Humanoid Platform, International Journal of Mechanical and Production Engineering, Vol. 7, No. 2, pp. 52-57, May, 2019.

## PEER-REVIEWED CONFERENCE ARTICLES

- [C4] J. Kim, Y. Omori, A. Sifat, and T. Furukawa, Adjustably Designed Torque Controlled Humanoid Platform, International Conference on Control, Automation, Robotics and Vision Engineering, Washington DC, USA, 21-22 Nov, 2018.
- [C3] J. Kim, M. Kim, and J. Park, Improvement of Humanoid Walking Control by Compensating Actuator Elasticity, International Conference on Humanoid Robots (ICHR), Cancun, Mexico, 15-17 Nov, 2016.
- [C2] J. Jung, J. Kim, S. Kim, W. Kwon, S. Na, K. Kim, J. Lee, G. Suh, and J. Park, Application of Robot Manipulator for Cardiopulmonary Resuscitation, International Symposium on Experimental Robotics (ISER), Tokyo, Japan, 3-6 Oct, 2016.
- [C1] J. Kim, M. Kim, and J. Park, Improvement of Humanoid gait stability using reduction gear deformation model, The 31st Institute of Control, Robotics and Systems (ICROS), Seoul, Korea, 10-11 Mar, 2016.

### Honors

#### Awards

The Best Presentation Award, Institute of Control, Robotics and Systems 2016	2016
Darpa Robotics Challenge DRC Finalist	2015
The Best Presentation Award from Bachelor Thesis Presentation, Seoul National University	2012

#### Graduate Fellowship

Research Assistant Scholarships, Virginia Tech, Blacksburg, USA	Jul. 2017 - present
Gwan-ak Scholarship, Seoul National University, Seoul, South Korea	Mar. 2014 - Feb. 2015

#### Undergraduate Fellowship

National Scholarship from Korea Student Aid Foundation, South Korea Mar. 2009 - Feb. 2010

References available upon request

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