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FUNDAMENTALS OF COMPUTER GRAPHICS (CSIT304)

BEZIER CURVES

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PARAMETRIC CURVES

- The coefficients of an equations to have geometric meaning
- To predict the change of shape if one or more coefficients are modified.
- To do so, a system that supports users to design curves must be
 - Intuitive
 - Flexible
 - Unified Approach
 - Invariant
 - Efficiency and Numerically Stability

CURVE DESIGN

- Layouts a set of control
- Edit (Add, Delete, Move) the control points and some other characteristics for modifying the shape of the curve.
- There are very geometric, intuitive and numerically stable algorithms for finding points on the curve without knowing the equation of the curve.
- Once you know curves, the surface counterpart is a few steps away.

BEZIER CURVE

BEZIER CURVES

- Different choices of basis functions give different curves
 - Choice of basis determines how the control points influence the curve
 - In Hermite case, two control points define endpoints, and two more define parametric derivatives
- For Bezier curves, two control points define endpoints, and two control the tangents at the endpoints in a geometric way

BEZIER CURVES

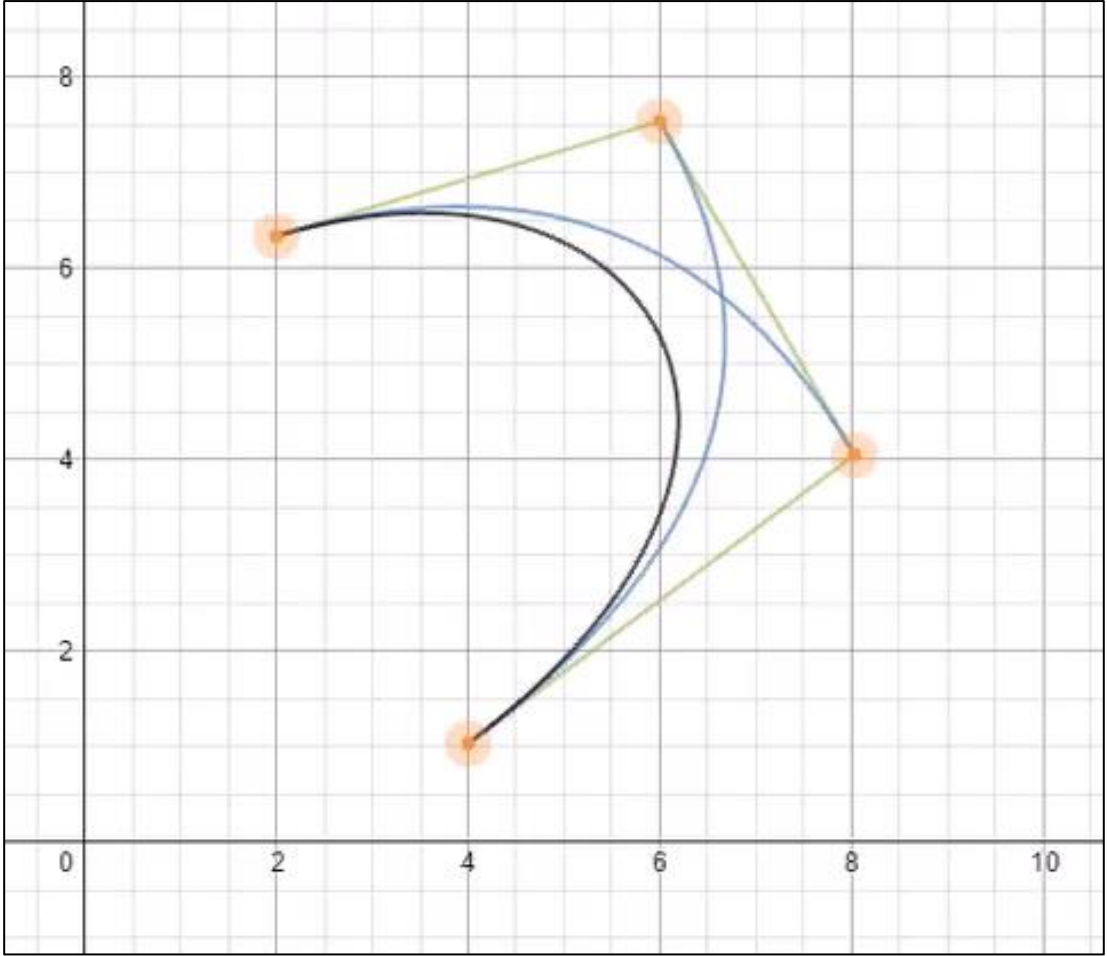
- The user supplies $d+1$ control points, \mathbf{p}_i
- Write the curve as:

$$\mathbf{x}(t) = \sum_{i=0}^d \mathbf{p}_i B_i^d(t)$$

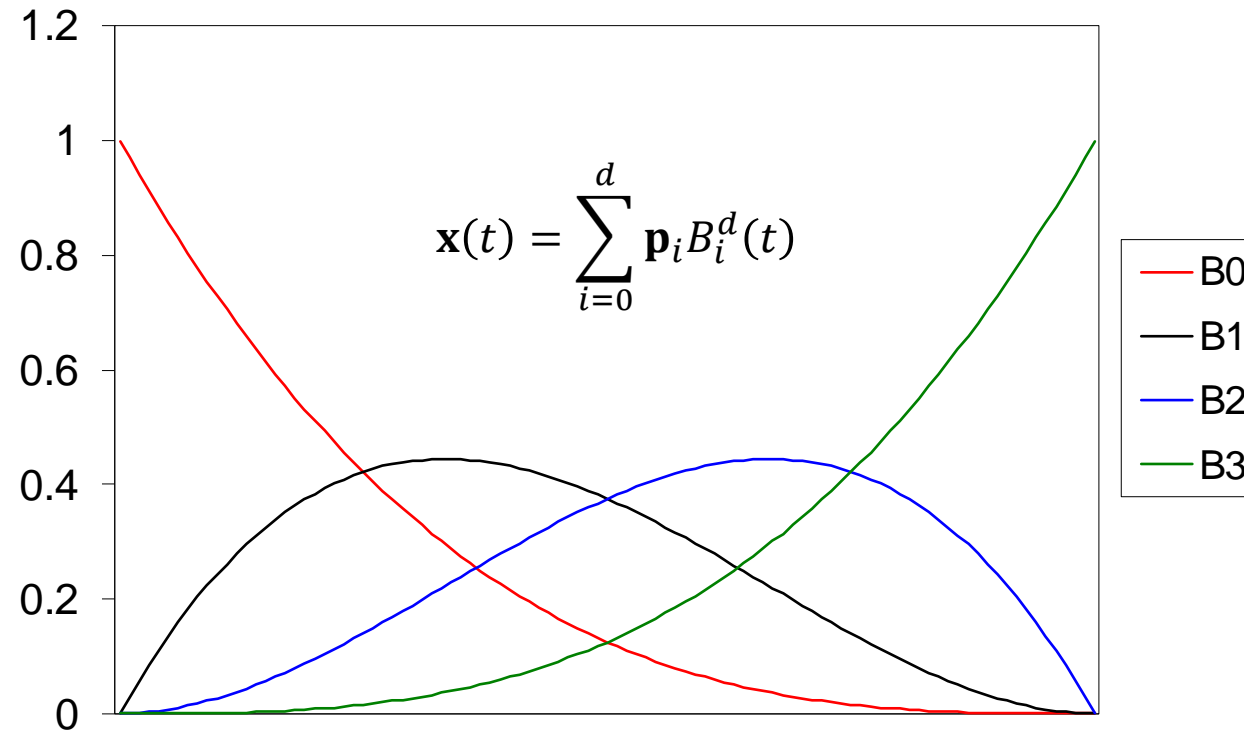
$$B_i^d(t) = \binom{d}{i} t^i (1-t)^{d-i}$$

- The functions B_i^d are the *Bernstein polynomials* of degree d
- This equation can be written as a matrix equation also

EXAMPLE

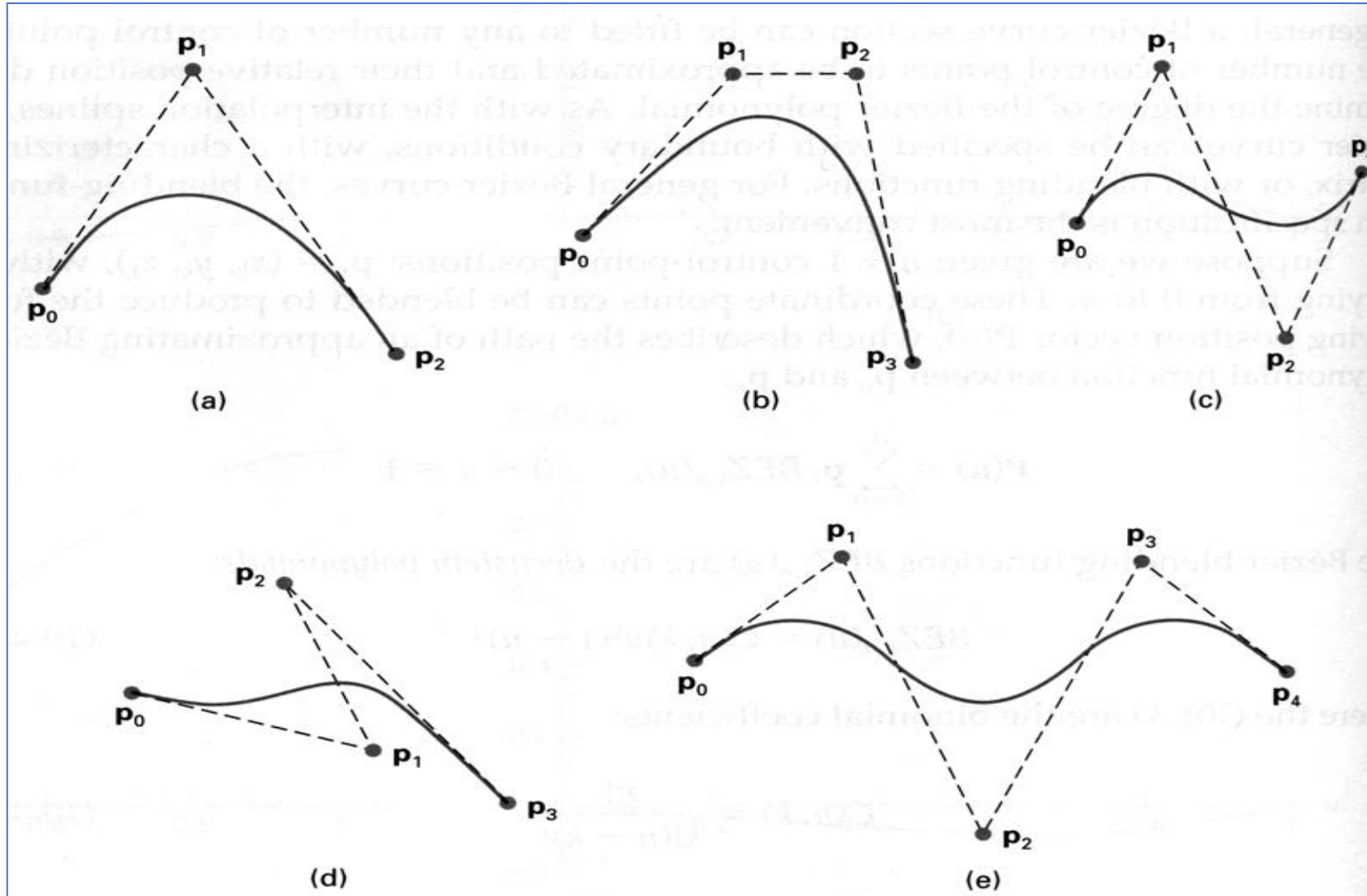


BEZIER BASIS FUNCTIONS FOR $d=3$



$$B_0^3(t) = \binom{3}{0} t^0 (1-t)^{3-0} = \frac{3!}{0! (3-0)!} \times 1 \times (1-t)^3 = (1-t)^3$$

SOME BEZIER CURVES

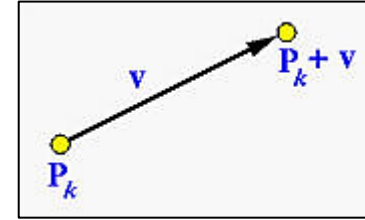


BEZIER CURVE PROPERTIES

- The first and last control points are interpolated
- Affine invariant
- The curve lies entirely within the convex hull of its control points
- The tangent to the curve at the first control point is along the line joining the first and second control points
- The tangent at the last control point is along the line joining the second last and last control points

MOVEMENT OF THE CONTROL POINT

- P_k is moved to a new position $P_k + v$



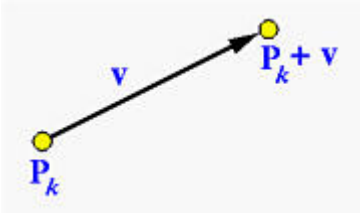
$$P(t) = \sum_{i=0}^n P_i B_i^n(t) \quad P_0, P_1, \dots, P_k, \dots, P_n \quad \longrightarrow \quad P_0, P_1, \dots, P_{k+v}, \dots, P_n$$

What can we say for the transformed curve $P'(t)$?

The corresponding point of t on the new curve is obtained by **translating** the corresponding point of t on the original curve in the **direction of v with a distance $B_i^n(t)$**

Show Animation

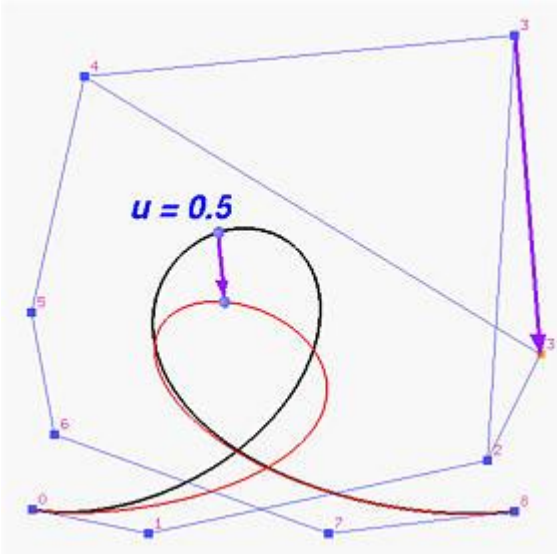
MOVING CONTROL POINTS



Since the new Bézier curve is defined by $P_0, P_1, \dots, P_k + v, \dots, P_n$, its equation $D(u)$ is

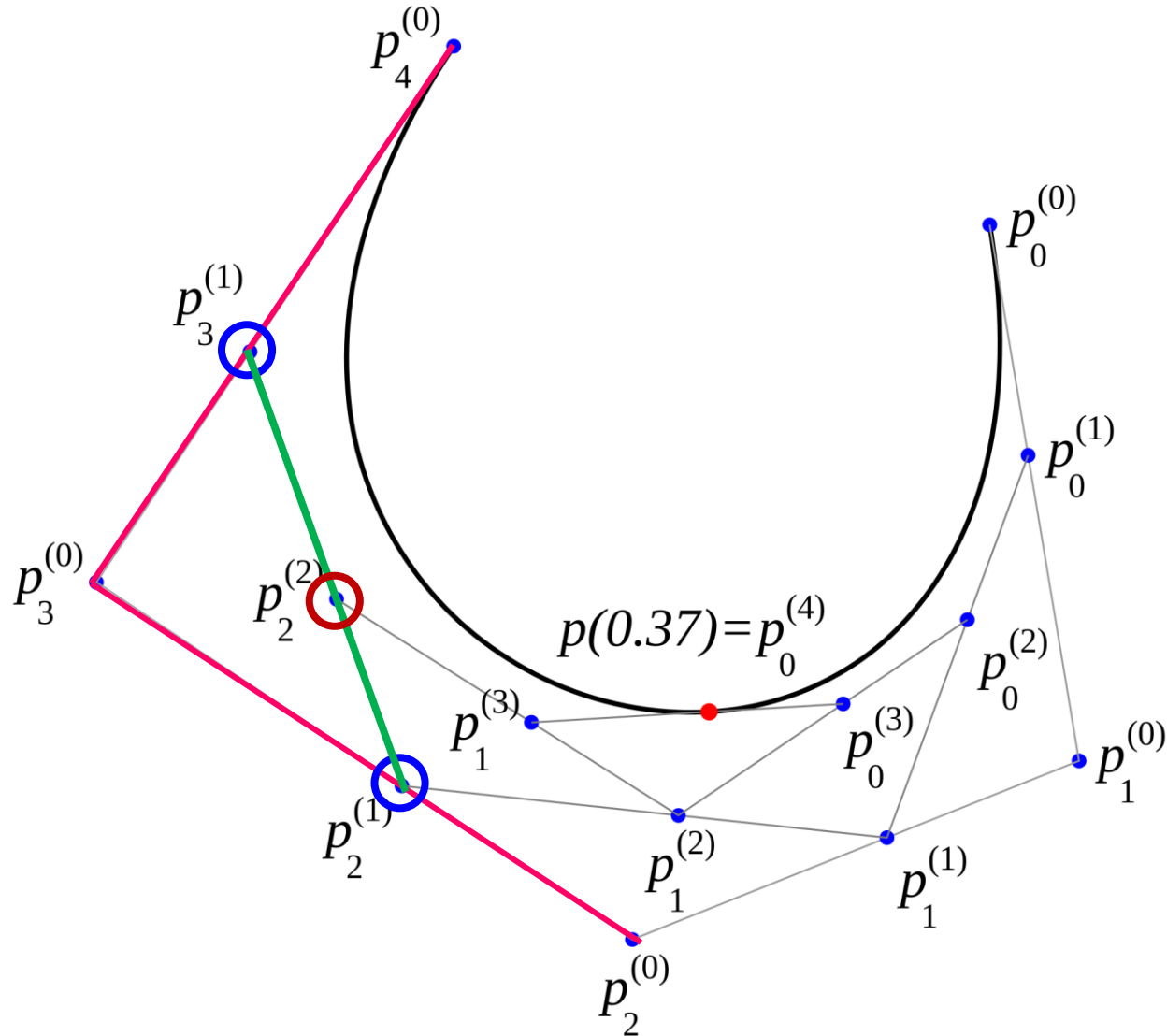
$$C(u) = \sum_{i=0}^n B_{n,i}(u) P_i$$

$$\begin{aligned} D(u) &= \sum_{i=0}^{k-1} B_{n,i}(u) P_i + B_{n,k}(u) (P_k + v) + \sum_{i=k+1}^n B_{n,i}(u) P_i \\ &= \sum_{i=0}^n B_{n,i}(u) P_i + B_{n,k}(u) v \\ &= C(u) + B_{n,k}(u) v \end{aligned}$$



The corresponding point of u on the new curve is obtained by translating the corresponding point of u on the original curve in the direction of v with a distance of $|B_{n,k}(u)v|$.

DE CASTELJAU'S ALGORITHM: ILLUSTRATION



Play Animation

DE CASTELJAU'S ALGORITHM

- Task is to find the point $P(t)$ on the curve for a particular t

Input: Array $P[0:n]$ of $n + 1$ points and real number t in $[0, 1]$

Output: Point on curve, $P(t)$

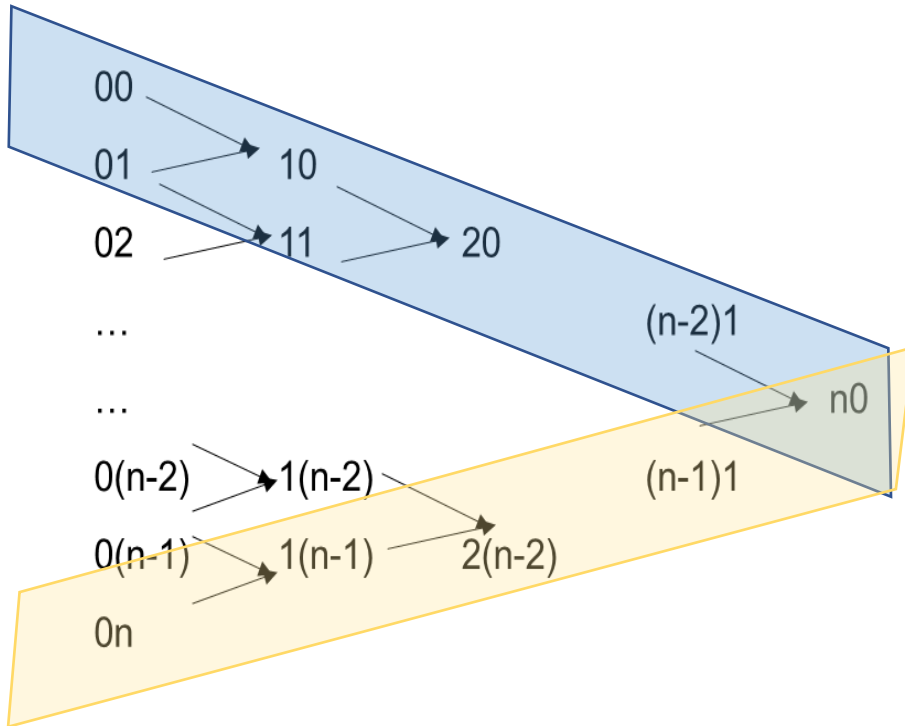
Working: Point array $Q[0:n]$

```
for i = 0 to n do
    Q[i] = P[i]; // save input
for r = 1 to n do
    for i = 0 to n - r do
        Q[i] = (1 - u)Q[i] + u Q[i + 1];
return Q[0];
```

DE CASTELJAU'S ALGORITHM: RECURRENCE

$$P_{i,j} = (1 - u)P_{i-1,j} + uP_{i-1,j+1}$$

for $i = 1, \dots, n; j = 1, \dots, n - i$



```
function deCasteljau( $i, j$ )
```

```
begin
```

```
if  $i = 0$  then
```

```
    return  $P_{0,j}$ 
```

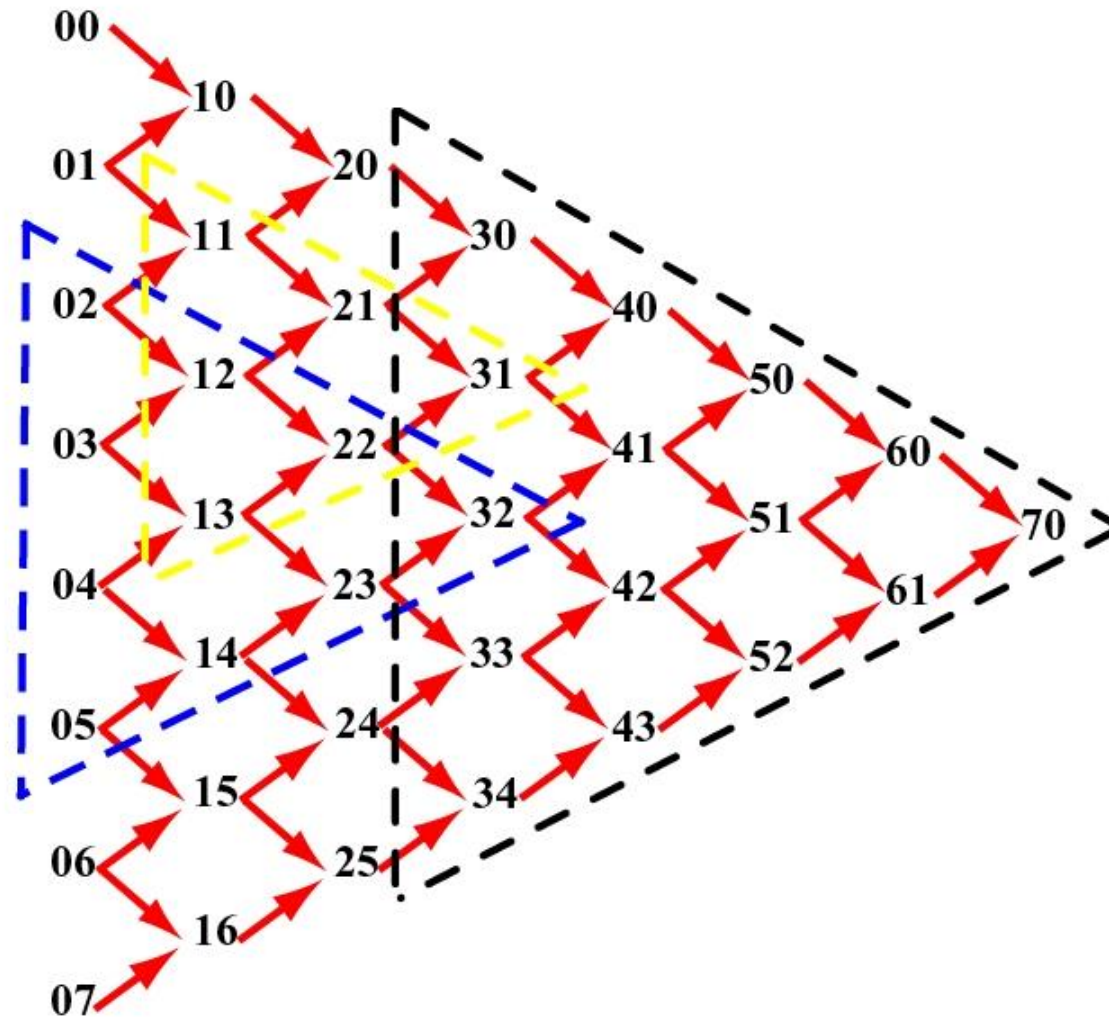
```
else
```

```
    return  $(1 - u) *$ 
```

```
    deCasteljau( $i - 1, j$ ) +  $u *$  deCasteljau( $i - 1, j + 1$ )
```

```
end
```

DE CASTELJAU'S ALGORITHM



SUBDIVIDING A BÉZIER CURVE

- Cut a given Bézier curve at $\mathbf{P}(t)$ for some t into two curve segments
- Each of which is still a Bézier curve.
- What happens to the control point?
- What about the degree of the resultant curves?

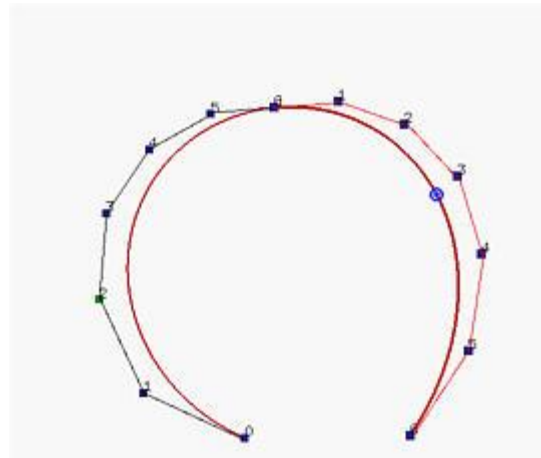
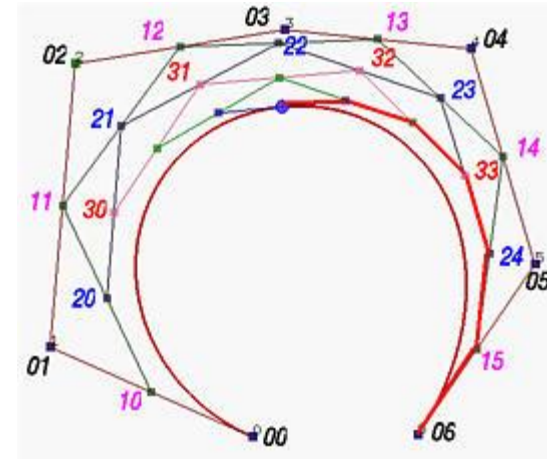
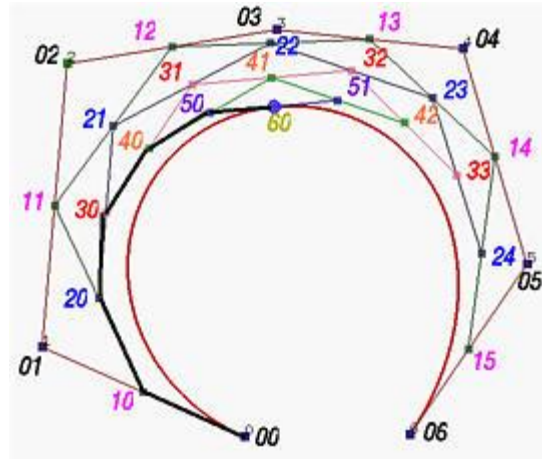
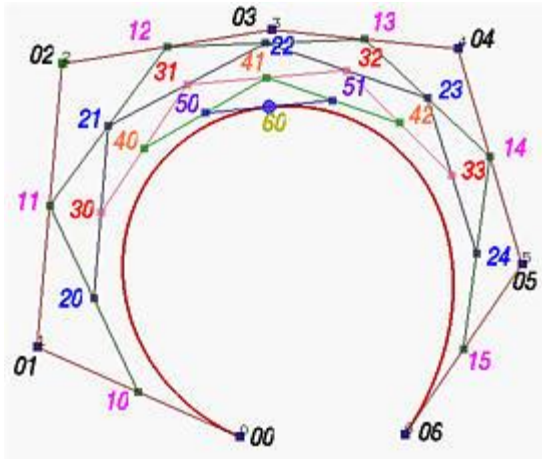
PROBLEM STATEMENT

Given a set of $n + 1$ control points $P_0, P_1, P_2, \dots, P_n$ and a parameter value t in $[0, 1]$,

We want to find two sets of $n + 1$ control points $Q_0, Q_1, Q_2, \dots, Q_n$ and $R_0, R_1, R_2, \dots, R_n$ such that

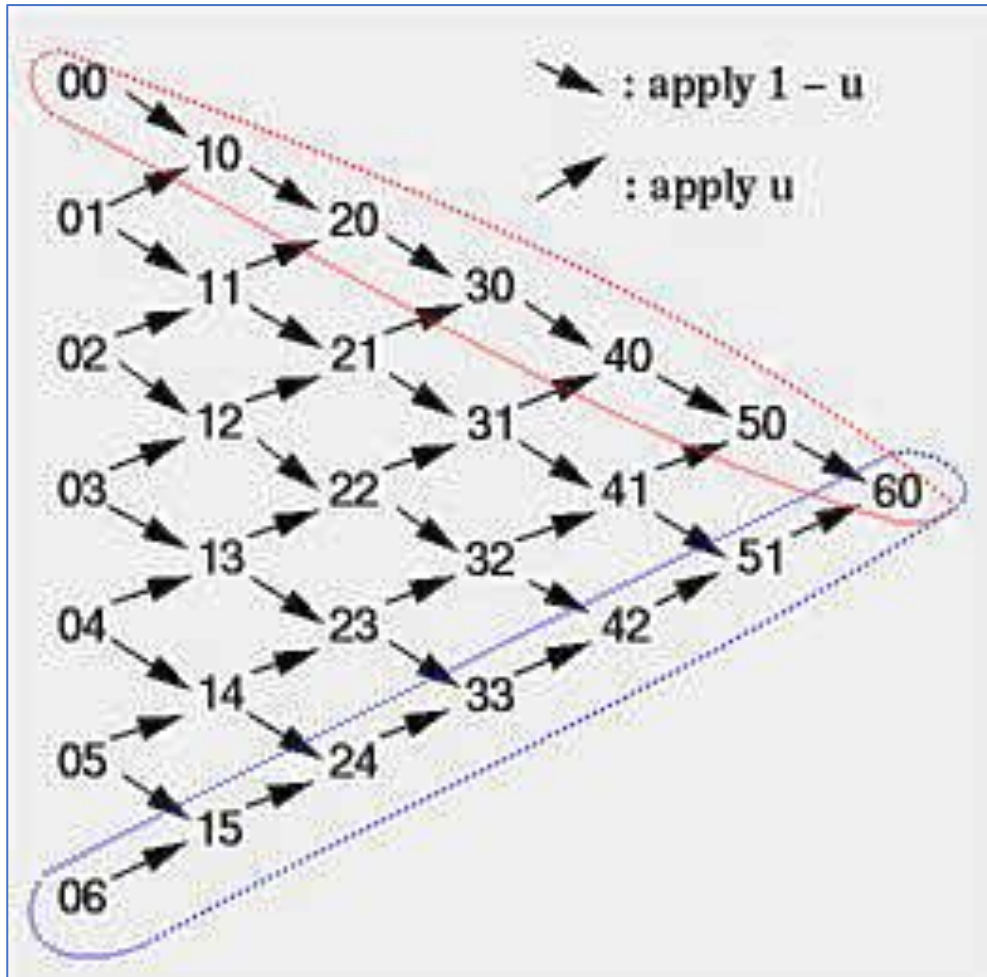
The Bézier curve defined by Q_i 's (resp., R_i 's) is the piece of the original Bézier curve on $[0, t]$ (resp., $[t, 1]$).

SUBDIVIDING BEZIER CURVE



Play Animation

SUBDIVIDING BEZIER CURVE



- For a given u , it takes n iterations to compute $C(u)$.
- Collect the first and the last points on each column
- The collection of the first (resp., last) points gives the subdivision corresponding to the piece of the original curve defined on $[0, u]$ (resp., $[u, 1]$).
- The control points of the first curve segments
 - The top edge in the direction of the arrows
- The control points of the last curve segments
 - The lower edge in the reversed direction of the arrows

DEGREE ELEVATION

- In an application it is desired that all involved curves to have the same degree
- Increase the degree of a Bézier curve *without* changing its shape.
- Degree elevation
- Existing degree = n ; elevated degree = $n+1$
- Existing control points = $\{P_0, \dots, P_n\}$; New control points = $\{Q_0, \dots, Q_{n+1}\}$, such that $P_0 = Q_0$ & $P_n = Q_{n+1}$

$$Q_i = \frac{i}{n+1} P_{i-1} + \left(1 - \frac{i}{n+1}\right) P_i; 1 \leq i \leq n$$

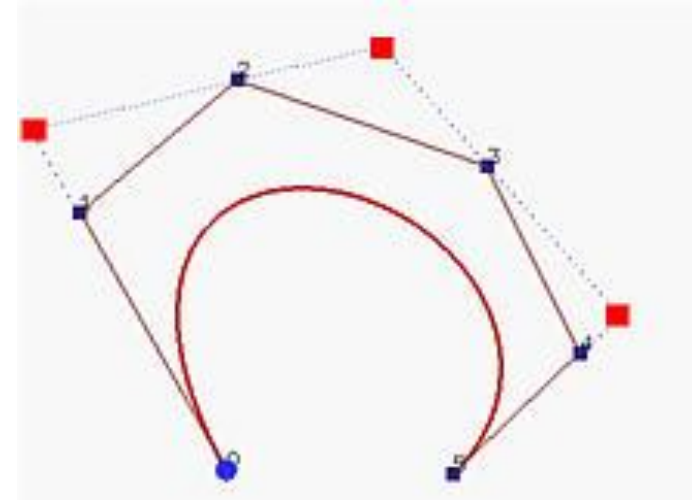


DEGREE ELEVATION OF A BÉZIER CURVE

$$Q_i = \frac{i}{n+1}P_{i-1} + \left(1 - \frac{i}{n+1}\right)P_i; 1 \leq i \leq n$$

$$\begin{aligned} Q_1 &= \frac{1}{n+1}P_0 + \left(1 - \frac{1}{n+1}\right)P_1 \\ Q_2 &= \frac{2}{n+1}P_1 + \left(1 - \frac{2}{n+1}\right)P_2 \\ Q_3 &= \frac{3}{n+1}P_2 + \left(1 - \frac{3}{n+1}\right)P_3 \\ &\vdots \\ Q_{n-1} &= \frac{n-1}{n+1}P_{n-2} + \left(1 - \frac{n-1}{n+1}\right)P_{n-1} \\ Q_n &= \frac{n}{n+1}P_{n-1} + \left(1 - \frac{n}{n+1}\right)P_n \end{aligned}$$

- Each leg of the original polyline contains exactly one new control point.
- This computation is very similar to that of de Casteljau's algorithm, though.
- Once the new set of control points is obtained, the original set can be discarded.





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