

NAAN MUDHALVAN – PROFESSIONAL READINESS FOR INNOVATION, EMPLOYMENT AND ENTREPRENEURSHIP

ASSIGNMENT – 1

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QUESTION:

Build a smart home in wokwi with minimum 2 sensors, Led, buzzer.

→ Example: pir sensor for home security, servo motor for door lock system.

→ Hint: replicate tinkercad code and connections in wokwi and integrate both codes to a single code.

LINK:

<https://wokwi.com/projects/364513583711177729>

CODE:

```
#define BLYNK_TEMPLATE_ID "TMPLgCeV0y1b"
#define BLYNK_DEVICE_NAME "Home"
#define BLYNK_AUTH_TOKEN "93h-1b23ewlQooDTdB2y2COGacfYkbdO"

#include<LiquidCrystal_I2C.h>
LiquidCrystal_I2C lcd(0x27, 20, 4);

#define BLYNK_PRINT Serial

#include<WiFi.h>
#include<WiFiClient.h>
#include<BlynkSimpleEsp32.h>
#include "DHTesp.h"

BlynkTimer timer;

char auth[] = BLYNK_AUTH_TOKEN;
char ssid[] = "Wokwi-GUEST"; char pass[] = ""; int val = 0,
va1, va2, va3, va4, va5, ge, t = 15; float tmp, hum = 0;
int ledPin = 33;
int inputPin = 27;
int pirState, k;      int v
= 0;

//temp symbol
byte t1[8] = {B00000, B00001, B00010, B00100, B00100, B00100, B00100, B00111,}; byte
t2[8] = {B00111, B00111, B00111, B01111, B11111, B11111, B01111, B00011,}; byte t3[8] = {B00000,
B10000, B01011, B00100, B00111, B00100, B00111, B11100,}; byte t4[8] = {B11111, B11100, B11100,
B11110, B11111, B11111, B11110, B11000,};
//humidity symbol byte hum1[8] = {B00000, B00001, B00011, B00011, B00111, B01111, B01111,
B11111,}; byte hum2[8] = {B11111, B11111, B11111, B01111, B00011, B00000, B00000, B00000,}; byte
hum3[8] = {B00000, B10000, B11000, B11000, B11100, B11110, B11110, B11111,};
byte hum4[8] = {B11111, B11111, B11111, B11110, B11100, B00000, B00000,
B00000,};

//Home Symbol
byte house1[8] = {B00000, B00001, B00011, B00011, B00111, B01111, B01111, B11111,};
byte house2[8] = {B11111, B11111, B11100, B11100, B11100, B11100, B11100, B11100,};
byte house3[8] = {B00000, B10010, B11010, B11010, B11110, B11110, B11110, B11111,};
```

```
byte house4[8]={B11111,B11111,B11111,B10001,B10001,B10001,B11111,B11111,}; byte d[8] =
{0b00011,0b00011,0b00000,0b00000,0b00000,0b00000,0b00000,0b00000}; byte Lck[]={
B01110,B10001,B10001,B11111,B11011,B11011,B11111,B00000};
```

```
DHTesp temps;
```

```
BLYNK_WRITE(V0){ va1 =
param.asInt();
digitalWrite(5,va1);
```

```
}
BLYNK_WRITE(V1){ va2 =
param.asInt();
digitalWrite(18,va2);
}
```

```
BLYNK_WRITE(V2){ va3 =
param.asInt();
digitalWrite(19,va3);
}
BLYNK_WRITE(V3){ va4 =
param.asInt();
digitalWrite(4,va4);
}
```

```
BLYNK_WRITE(V4){ va5 =
param.asInt();
digitalWrite(2,va5);
}
```

```
BLYNK_WRITE(V7){ pirState = param.
asInt(); if(pirState == 0){
digitalWrite(ledPin,LOW); k = 1;
    ge = 0;
} else{
    digitalWrite(ledPin,HIGH); k = 0;
ge = 1; }
} void myTimer()
{
    Blynk.virtualWrite(V5,tmp);
    Blynk.virtualWrite(V6,hum);
```

```
}
```

```
void setup()
```

```
{
```

```
  Serial.begin(115200);
```

```
  Blynk.begin(auth,ssid,pass);
```

```
  pinMode(5,OUTPUT);pinMode(18,
```

```
  OUTPUT);pinMode(19,OUTPUT);
```

```
  pinMode(4,OUTPUT);
```

```
  pinMode(23,INPUT);
```

```
  pinMode(2,OUTPUT); temps.setup(t,
```

```
  DHTesp::DHT22);pinMode(ledPin,
```

```
  OUTPUT);    pinMode(inputPin,
```

```
  INPUT_PULLUP);
```

```
  lcd.init();lcd.backlight();
```

```
  digitalWrite(5,LOW);
```

```
  digitalWrite(18,LOW);
```

```
  digitalWrite(19,LOW);
```

```
  digitalWrite(21,LOW);
```

```
  lcd.setCursor(0,0);
```

```
  lcd.print("CircuitDesignContest");
```

```
  lcd.setCursor(8,1);lcd.print("2022");
```

```
  lcd.setCursor(0,2);lcd.print("-----");
```

```
  lcd.setCursor(9,3);lcd.print("-eDiYLaBs");
```

```
  delay(3000);lcd.clear();lcd.createChar(6,
```

```
  Lck);lcd.createChar(1,house1);
```

```
  lcd.createChar(2,house2);lcd.createChar(3,
```

```
  house3);lcd.createChar(4,house4);
```

```
  lcd.setCursor(1,2);lcd.write(1);
```

```
  lcd.setCursor(1,3);lcd.write(2);
```

```
  lcd.setCursor(2,2);lcd.write(3);
```

```
  lcd.setCursor(2,3);lcd.write(4);
```

```
  lcd.setCursor(17,2);lcd.write(1);
```

```
  lcd.setCursor(17,3);lcd.write(2);
```

```
  lcd.setCursor(18,2);lcd.write(3);
```

```
  lcd.setCursor(18,3);lcd.write(4);
```

```
  lcd.setCursor(19,0); lcd.write(6);
```

```
  lcd.setCursor(9,0);lcd.print("connected-");
```

```
  lcd.setCursor(2,1);lcd.print("HOME  
AUTOMATION");lcd.setCursor(6,2);
```

```
  lcd.print("USING IOT");delay(3000);
```

```
Blynk.virtualWrite(V7,pirState);timer.setInterval(1000L,myTimer);
```

```
}
```

```
void loop(){ Blynk.run();  
timer.run(); val=  
digitalRead(23); if(val== 1)  
{  
    digitalWrite(2,va5); }
```

```
else{    digitalWrite(2,LOW);  
}
```

```
TempAndHumidity x=temps.getTempAndHumidity();tmp=  
x.temperature;hum=x.humidity;  
v=digitalRead(inputPin); if(v== HIGH){ if  
(k== 1) {    digitalWrite(ledPin,LOW);  
k=0;    ge=0; } elseif(k==0) {  
digitalWrite(ledPin,HIGH);    k=1;    ge  
=1;  
}  
}
```

```
if(va1== 1){ lcd.clear();  
lcd.setCursor(19,0);  
lcd.write(6); lcd.setCursor(0,1);  
lcd.print("SW_1=");  
lcd.print("ON "); } else{  
lcd.clear();  
lcd.setCursor(19,0);  
lcd.write(6);    lcd.setCursor(0,  
1); lcd.print("SW_1=");  
lcd.print("OFF"); } if(va2==  
1){  
    lcd.setCursor(11,1);  
lcd.print("SW_2=");  
lcd.print("ON ");  
}  
else{    lcd.setCursor(11,1);  
lcd.print("SW_2=");  
lcd.print("OFF");} if(va3==1){  
lcd.setCursor(0,2);
```

```

lcd.print("SW_3= "); lcd.print("ON
"); } else{      lcd.setCursor(0,
2); lcd.print("SW_3= ");
lcd.print("OFF"); }    if(va4==
1){      lcd.setCursor(11,2);
lcd.print("SW_4= "); lcd.print("ON
"); } else{      lcd.setCursor(11,
2); lcd.print("SW_4= ");
lcd.print("OFF"); }    if(va5==
1){      lcd.setCursor(0,3);
lcd.print("OD_L= "); lcd.print("ON
"); } else{      lcd.setCursor(0,
3); lcd.print("OD_L= ");
lcd.print("OFF"); }    if(ge==1){
lcd.setCursor(11,3);
lcd.print("WR_L= "); lcd.print("ON
"); } else{
      lcd.setCursor(11,3);
lcd.print("WR_L= ");lcd.print("OFF");}
delay(1500);  lcd.clear();
lcd.createChar(1,t1);
lcd.createChar(2,t2);
lcd.createChar(3,t3);
lcd.createChar(4,t4);
lcd.createChar(5,d);
lcd.createChar(6,Lck);
lcd.setCursor(19,0);  lcd.write(6);
lcd.setCursor(1,1);  lcd.write(1);
lcd.setCursor(1,2);  lcd.write(2);
lcd.setCursor(2,1);  lcd.write(3);
lcd.setCursor(2,2);  lcd.write(4);
lcd.setCursor(4,1);
lcd.print("Temperature:");
lcd.setCursor(7,2);  lcd.print(tmp);
lcd.setCursor(11,2);  lcd.write(5);
lcd.setCursor(12,2);  lcd.print("C");
delay(750);  lcd.clear();
lcd.createChar(1,hum1);
lcd.createChar(2,hum2);
lcd.createChar(3,hum3);
lcd.createChar(4,hum4);
lcd.setCursor(19,0);  lcd.write(6);
lcd.setCursor(3,1);  lcd.write(1); lcd.

```



```

setCursor(3,2); lcd.write(2);
lcd.setCursor(4,1);lcd.write(3);
lcd.setCursor(4,2);lcd.write(4);
lcd.setCursor(6,1);
lcd.print("Humidity:");
  lcd.setCursor(7,2);
lcd.print(hum);
lcd.setCursor(12,2);
lcd.print("%"); delay(750);
}

```

CIRCUIT DIAGRAM:

