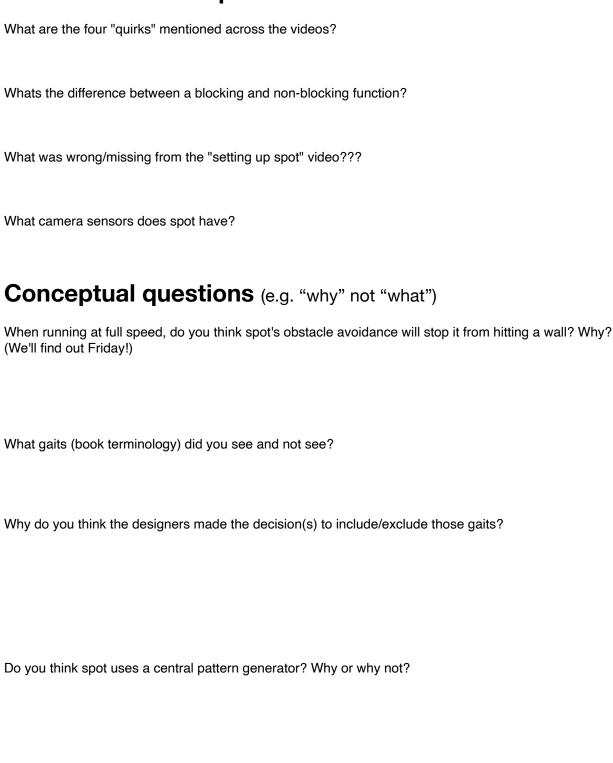
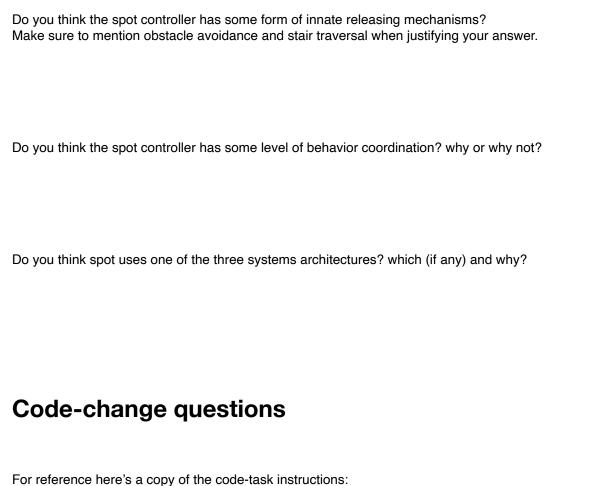
"Correct answer" questions





i or reference here a depy or the code tack met

- · Download this hello_spot.py file
- Change #1: go to the "Robot standing twisted." part
 - Find the `command_client.robot_command(` part
 - 1. Duplicate the whole function call, and edit the one further down
 - 2. Inside of it change 'yaw' to be 0 and 'pitch' to be 0.4
- Change #2: go to the section that mentions "absolute body control"
 - change the `z` value of the second `math_helpers.Quat(` object to `0.4`
 - · within that section there are time durations for each movement
 - double the amount of time between those movements
- Upload the modified code to canvas

Why do you think the second time.sleep(3) is in the code? What would removing it probably do?

What do you think change #1 will do?

What do you think change #2 would do?