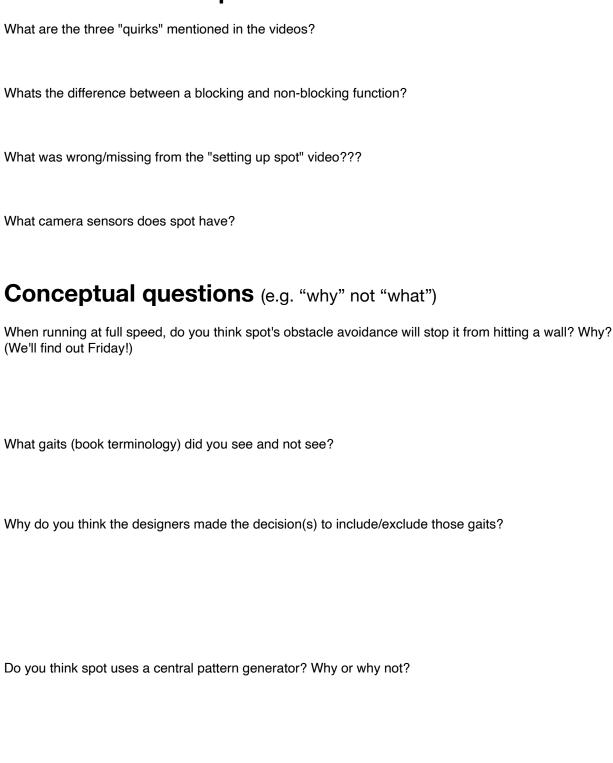
"Correct answer" questions



Do you think the spot controller has some form of innate releasing mechanisms? Make sure to mention obstacle avoidance and stair traversal when justifying your answer.
Do you think the spot controller has some level of behavior coordination? why or why not?
Do you think spot uses one of the three systems architectures? which (if any) and why?

Code-change questions

For reference here's a copy of the code-task instructions:

- · Download this hello spot.py file
- Change #1: go to the "Robot standing twisted." part
 - Find the `command_client.robot_command(` part
 - 1. Duplicate the whole function call, and edit the one further down
 - 2. Inside of it change 'yaw' to be 0 and 'pitch' to be 0.4
- Change #2: go to the section that mentions "absolute body control"
 - change the `z` value of the second `math_helpers.Quat(` object to `0.4`
 - within that section there are time durations for each movement
 - double the amount of time between those movements
- Upload the modified code to canvas

Why do you think there is there a time.sleep(3) in the code?

What do you think change #1 will do?

What do you think change #2 would do?