

BS Formula : Theory and Application

一、Brownian Motion

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(1) randn('state',100) % set the state of randn
T = 1; N = 500; dt = T/N;
dw = zeros(1,N); % preallocate arrays for efficiency
W = zeros(1,N);
dw(1) = sqrt(dt)*randn; % prepare the iteration W(j) = W(j-1) + dw(j)
W(1) = dw(1);
for j = 2:N % start the iteration
    dw(j) = sqrt(dt)*randn; % general increment
    W(j) = W(j-1) + dw(j);
end
plot([0:dt:T],[0,W],'r-') % plot W against t
xlabel('t','FontSize',16)
ylabel('W(t)','FontSize',16,'Rotation',0)

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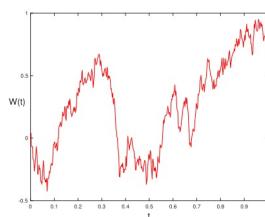


Figure 3.1: Discretized Brownian path

Time series

$B(t)$, $X(t)$, $U(t)$

B_t , X_t , W_t

The time series of BM is similar to stock price time series.

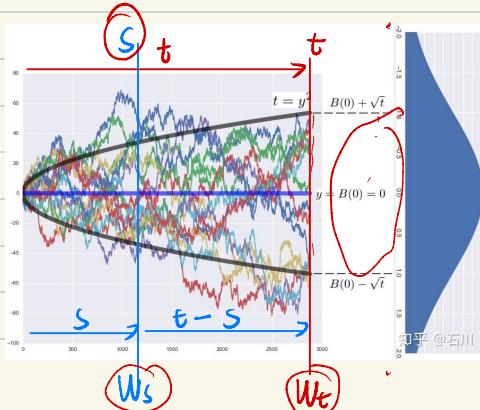
(2) def. $\{W_t, t \geq 0\}$

$$\textcircled{1} \quad W_0 = 0 \quad (\text{起点从 } 0 \text{ 开始})$$

② 平稳性: $\forall 0 \leq s < t \quad u_t - u_s \sim N(0, t-s)$

③ 独立增量 ΔB 间 $[S_i, t_i]$, not overlapping

$\Rightarrow U_{ti} - W_{si}$, a series of independent normal distribution



$$W_t - \frac{W_0}{D} \sim N(0, t)$$

$\boxed{W_0}$ + $\boxed{\frac{W_t - W_0}{D}}$ } $N(0, t-s)$

Think about it : $W_3 \sim N(0,3)$ $W_1 \sim N(0,1)$

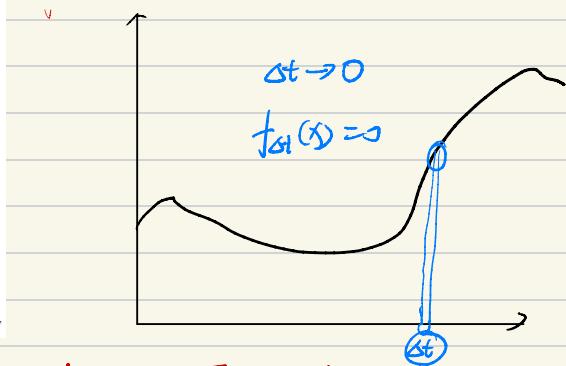
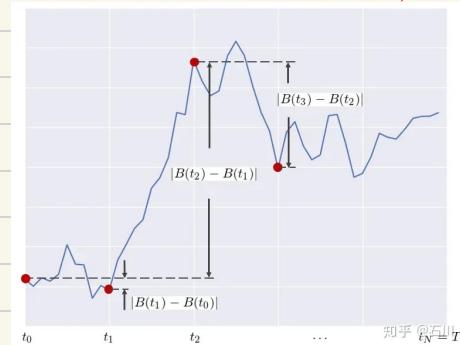
What is the distribution of $W_1 + W_3$?

(3) quadratic variation

$[0, T]$ is divided into $\Pi = \{0 = t_0 < t_1 < \dots < t_n = T\}$

$$\lim_{|\Pi| \rightarrow 0} \sum_i (W_{t_{i+1}} - W_{t_i})^2 = T$$

Explanation: $|\Pi| = \max_i |t_{i+1} - t_i| \xrightarrow{n \rightarrow \infty}$



Quadratic Variation $\Rightarrow (dW_t)^2 = dt \Rightarrow$ Ito's lemma.

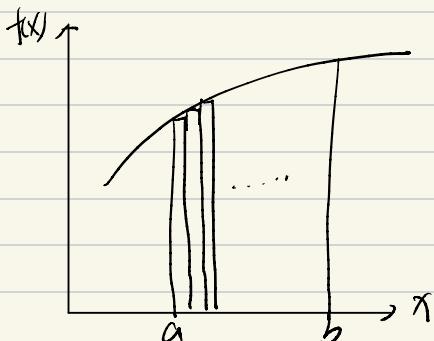
$$\int f(t) dt = F(t) + C \quad \checkmark$$

$$\int f(W_t) dW_t ? \quad (\text{带 } W_t \text{ 的 } \int dt \text{ 何解?})$$

2. Ito integral

(1) How to do integration on dW_t

Key point: Return to the definition of Riemann Integral



$$\int_a^b f(x) dx = \sum_{i=0}^{n-1} f(x_i) (x_{i+1} - x_i)$$

where $x_0 = a$, $x_n = b$

$$dt = \left(\int_a^c dm \right) dx$$

$$\text{Therefore : } \int_0^T f(u_{t_i}) du_{t_i} = \sum_{i=0}^{n-1} f(u_{t_i}) (u_{t_{i+1}} - u_{t_i})$$

Example 1

Guess : $E\left(\int_0^T f(u_{t_i}) du_{t_i}\right) = ?$

$f(s, u_t)$
 $f(s)$

$X_t = \int_0^t f(u_s) du_s$

$E(X_t)$

Example 2

$$\int_0^t w_s ds = \frac{1}{2}w_t^2 - \frac{1}{2}t$$

$$\text{证明 : } \int_0^t s ds = \frac{1}{2}s^2 \Big|_0^t$$

$$\begin{aligned} \int_0^t w_s ds &= \lim_{\delta t \rightarrow 0} \sum_i w_{t_i} (w_{t_{i+1}} - w_{t_i}) \\ &= \lim_{\delta t \rightarrow 0} \left(\sum_i \frac{1}{2}(w_{t_{i+1}}^2 - w_{t_i}^2) \right) - \sum_i (w_{t_{i+1}} - w_{t_i})^2 \\ &= \frac{1}{2}w_t^2 - \frac{1}{2}t \end{aligned}$$

quadratic variation

(2) Ito Isometry:

$$E\left[\int_0^T f(t, w) dt \quad \int_0^T g(t, w) dt\right] = E\left[\int_0^T f(t, w) g(t, w) dt\right]$$

proof: $E\left[\sum_{i=0}^{n-1} f_{t_i} (w_{t_{i+1}} - w_{t_i}) \cdot \sum_{i=0}^{n-1} g_{t_i} (w_{t_{i+1}} - w_{t_i})\right]$

Note: $E((w_{t_{i+1}} - w_{t_i})(w_{t_{i+1}} - w_{t_i})) = 0$ for any $i \neq j$

iid normal distribution

$$= E\left(\sum_{i=1}^{n-1} f_{t_i} g_{t_i} (w_{t_{i+1}} - w_{t_i})^2\right) \quad \frac{i \neq j}{(w_{t_{i+1}} - w_{t_i})(w_{t_{i+1}} - w_{t_j})}$$

$$= E \left[\int_0^t f(t, w) g(t, w) \frac{dt}{(dw_t)^2} \right]$$

$$\frac{df(t, s)}{d(t, w_t)} = \frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial s} ds$$

3. Ito lemma

Target: how to solve $df(t, s)$

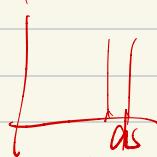
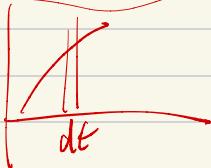
We have learned chain rule: $df(t, s) = \frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial s} ds$

And what about: $df(t, w_t) = \frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial w_t} dw_t$ TRUE or False?

Return to its definition ★ Taylor.

$$f(t, s) = f(0, 0) + \frac{\partial f}{\partial t} t + \frac{\partial f}{\partial s} s + \frac{1}{2} \frac{\partial^2 f}{\partial t^2} t^2 + \frac{1}{2} \frac{\partial^2 f}{\partial s^2} s^2 + \frac{1}{3} \frac{\partial^3 f}{\partial t \partial s} ts + \dots$$

$$df(t, s) = \left(\frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial s} ds + \frac{1}{2} \frac{\partial^2 f}{\partial t^2} (dt)^2 + \frac{1}{2} \frac{\partial^2 f}{\partial s^2} (ds)^2 + \frac{1}{2} \frac{\partial^3 f}{\partial t \partial s} dt \cdot ds + \dots \right)$$



dt

$$df(t, w_t) = \frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial w_t} dw_t + \frac{1}{2} \frac{\partial^2 f}{\partial t^2} dt^2 + \frac{1}{2} \frac{\partial^2 f}{\partial w_t^2} (dw_t)^2 + \frac{1}{2} \frac{\partial^3 f}{\partial t \partial w_t} dt \cdot dw_t + \dots$$

$$= \left(\frac{\partial f}{\partial t} + \frac{1}{2} \frac{\partial^2 f}{\partial w_t^2} \right) dt + \frac{\partial f}{\partial w_t} dw_t$$

四. BS formula

It



(1) 刻画标的资产 St

Use Geometric Brownian Motion

$$dSt = uSt dt + \sigma St dWt \quad \ln St = f(St, t) \text{ - Ito lemma}$$

$$d\ln St = (u - \frac{\sigma^2}{2}) dt + \sigma dWt$$

$$St = S_0 \exp((u - \frac{\sigma^2}{2})t + \sigma W_t)$$

(2) BS Assumptions

$W_t \sim$

$N(0, \sigma_t)$

- 期权的行权方式为欧式，即只有到期日才可以行权。T
- 股票的价格符合几何布朗运动，即股票的不确定性满足对数正态分布。
- 可以做空证券，且证券可以被分割（如可以买卖半手股票）。
- 市场无摩擦，即不存在交易费用和税收。
- 在期权期限内，标的股票不支付股息。
- 在期权期限内，标的股票年收益率的标准差 σ 已知且保持不变。
- 市场不存在无风险套利机会。
- 标的资产交易是连续的（如股票市场始终开市）。
- 短期无风险利率（由 r 表示）为常数并已知。

Suppose call option price function: $C(St, t)$

$$\underline{dC(St, t)} = \frac{\partial C}{\partial St} dSt + \frac{\partial C}{\partial t} dt + \frac{1}{2} \frac{\partial^2 C}{\partial St^2} dSt^2 \quad \text{Ito lemma}$$

$(dSt)^2$

$$\Rightarrow (dSt) = uSt dt + \sigma St dWt$$

$$= [\dots] dt + [\dots] dWt$$

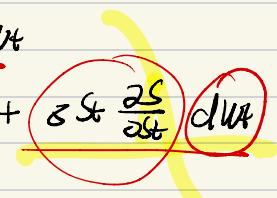
$$[\frac{\partial C}{\partial t} + uSt \frac{\partial C}{\partial St} + \frac{1}{2} \sigma^2 St^2 \frac{\partial^2 C}{\partial St^2}] dt +$$

$\sigma St \frac{\partial C}{\partial St} dWt$

$\approx \frac{\partial C}{\partial St}$ by stock

$+ \frac{\partial C}{\partial St}$

$\frac{\partial C}{\partial St}$



$$-d(C(St, t)) + \frac{\partial C}{\partial St} dSt \rightarrow \text{dive term 去掉}$$

对冲风险

Thus construct a portfolio: $d\bar{I}I_t(S_t, t) = dC(S_t, t) - \frac{\partial C}{\partial S_t} S_t$

$$d\bar{I}I_t(S_t, t) = d(C(S_t, t)) - \frac{\partial C}{\partial S_t} dS_t$$

risk neutral $d\bar{I}I_t(S_t, t) = r\bar{I}I_t(S_t, t) dt$

\Rightarrow BS 偏微方程

$$\frac{\partial C}{\partial t} + rS_t \frac{\partial C}{\partial S_t} + \frac{1}{2} \sigma^2 S_t^2 \frac{\partial^2 C}{\partial S_t^2} = rC$$

解偏微方程：



BS Formula:

$$\begin{cases} C = S N(d_1) - K e^{-r(T-t)} N(d_2) \\ P = K e^{rt} N(-d_2) - S N(-d_1) \end{cases}$$

$$C + K e^{-rt} = P + S$$

$$d_1 = \frac{\ln(S/K) + (r + \frac{1}{2}\sigma^2)(T-t)}{\sigma \sqrt{T-t}}$$

$$d_2 = d_1 - \sigma \sqrt{T-t}$$

Call

put