CSC473 Assignment 1: Randomized k-Path

Jeff Blair: 1002177057 jeffrey.blair@mail.utoronto.ca

Jaryd Hunter: 1002725893 jaryd.hunter@mail.utoronto.ca

February 2020

Introduction:

A well-studied problem in graph theory is the Hamiltonian Path Problem (HAMPATH): Deciding whether there exists a simple path on a graph G that visits every node exactly once. This paper provides an efficient, randomized approach to solving the HAMPATH problem on a graph G.

Randomized k-PATH

We see that the HAMPATH problem on n vertices is a special case of the k-PATH problem where k = n. For our k-PATH problem, we will consider a k-Coloring of the graph G where each vertex is assigned a color $c(v) \in \{1, \ldots, k\}$ uniformly at random. Using this coloring we can define the following recurrence:

Let PATH(S, v) be a boolean function that returns 1 iff there is a path on G ending at vertex v that contains each color in the set S exactly once. Then

```
(v_1, v_2) \in G : S \subset [k] : c(v_1) \in S : c(v_2) \notin S : PATH(S \cup c(v_2), v_2) = PATH(S, v_1)
```

Using this recurrence, we can use dynamic programming to efficiently compute solutions to the k-PATH problem.

```
def ColouredPath (G(V, E), K = \{1, ..., k\}):
    @typedef PATH[K, v]:
        Hashtable (set, vertex) -> bool
        If PATH[K, v] returns 1 then there is a path that ends at vertex v
        and contains every colour in K exactly once
    PATH <- 0 # All entries initiated to zero
    For v in V: # Base case
        PATH[c(v), v] = 1
    For k in Powerset(K):
        # Powerset(K) returns the set of all subsets of K in O(k2^k),
        # in increasing order. The set returned contains 2 k elements
        For v_1 in V:
             For each neighbour v<sub>-2</sub> of v<sub>-1</sub>:
                 if c(v_1) not in k: \# O(k) by assumption
                     k' = k.join(\{c(v_1)\}) \# join with 1 element is O(1)
                     PATH[k', v_1] = PATH[k, v_2] \# where 'x = y' equates to
                                                      \# 'x = x OR v'
    return ANY(PATH[K, v] \text{ for } v \text{ in } V) \# O(n)
```

Correctness:

Claim 1:

It is possible to return (in increasing order) Powerset(K) in $O(2^k k)$

Proof:

Represent $K=\{1,...,k\}$ as a binary integer with k bits, where the i-th bit represents the i-th entry in the set K. Enumerate Powerset(K) by incrementing the integer by 1. There are a total of 2^k elements in Powerset(K), so enumerating every element takes $O(2^k)$. Then sort in $O(2^k \log 2^k) = O(2^k k)$

Claim 2:

There is a path P that contains every colour in K exactly once $\iff \exists v \in V : PATH[K, v]$

Proof:

Suppose $\exists v \in V : PATH[K, v] = 1$ \implies a path P hits every colour in K exactly once by definition

Suppose a path exists that hits every colour in K exactly once and ends in vertex v. Then there must exist a path to a neighbour of v that hits every color in $K \setminus c(v)$ exactly once.

Base case: $\forall k \in K : \exists v \in P \mid PATH[k, v] = 1$ from the first loop Inductive Step: $\forall k \in 2^K$:

If k is a colouring along the path P and k' is the set of colours when the next vertex along P is considered:

$$\exists (v, v') \in P \mid k = k' \setminus c(v') \text{ and } PATH[k, v] \implies PATH[k', v'].$$

Since the algorithm considers all pairs of neighbouring vertices and considers each subset of K in increasing order, we are guaranteed to find (v, v').

Claim 3:

The total running time of the algorithm is $O(2^k kn^2)$

Proof:

Preprocessing the Powerset of K: $O(2^k k)$ by Claim 1. Initializing PATH is constant time assignments to n elements $\to O(n)$ Main loop is $O(2^k) \cdot O(n) \cdot O(n) \cdot O(k) = O(2^k k n^2)$ $\Longrightarrow T(n) = O(2^k k) + O(n) + O(2^k k n^2) = O(2^k k n^2)$

Assume a path P of length k, and vertex colouring is performed uniformly at random. Then for vertices $v_1, ..., v_k \in P$:

$$P(c(v_1) \neq ... \neq c(v_k)) = 1 \cdot P(c(v_1) \neq c(v_2)) \cdot ... \cdot P(c(v_1) \neq ... \neq c(v_k) \mid c(v_1) \neq ... \neq c(v_{k-1}))$$

$$= \frac{k}{k} \cdot \frac{k-1}{k} \cdot ... \cdot \frac{1}{k}$$

$$= \frac{k!}{k^k}$$

If there exists no Path of length k in G, kPath always returns NO. If there does exist a path, kPath returns YES with probability $\frac{k!}{k^k}$ in $O(2^k kn^2)$.

$$P(Success) = \frac{k!}{k^k} \ge e^{-k} = \frac{1}{e^k}$$

Running the algorithm $T = e^k \log(\frac{1}{\delta})$ many times gives us

$$\begin{split} P(\text{Failure}) &\leq \left(1 - \frac{1}{e^k}\right)^T \\ &\leq e^{-\frac{1}{e^k}T} \\ &\leq e^{-\frac{1}{e^k} \cdot T} \\ &\leq e^{-\frac{1}{e^k} \cdot (-e^k \log(\delta))} \\ &\leq \delta \\ P(\text{Success}) &\geq 1 - \delta \end{split}$$

This gives us a probability of returning YES of at least $\frac{2}{3}$ in $T(n)=\log(3)\cdot e^k\cdot O(2^kkn^2)=O(e^k2^kkn^2)=O((2e)^kkn^2)$

Setting k = n, we see an algorithm that computes HAMPATH with time complexity $O((2e)^n n^3)$, which is an improvement over the brute force complexity O(n!).