

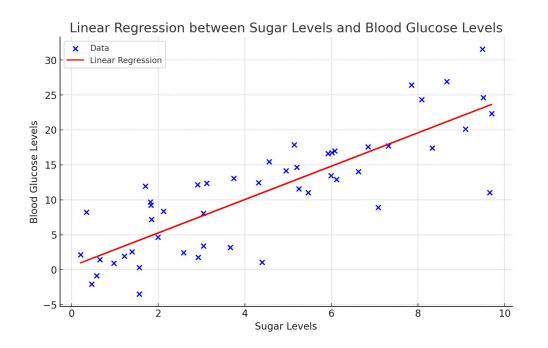




Objective: Understand the idea behind univariate linear regression

Prediction of blood sugar levels

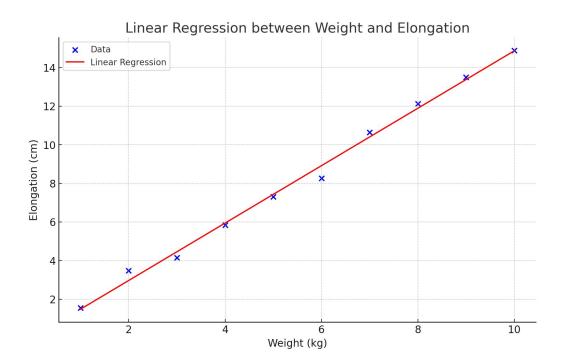




Sugar Levels	Blood Glucose Levels
3.75	13.06
9.51	24.62
7.32	17.72
5.99	13.46
1.56	-3.49

Prediction of the elongation of a spring of static size

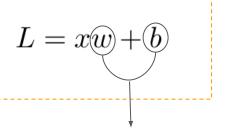




Weight (kg)	Elongation (cm)
1	1.55
2	3.48
3	4.15
4	5.84
5	7.30
6	8.27
7	10.65
8	12.13
9	13.50
10	14.88

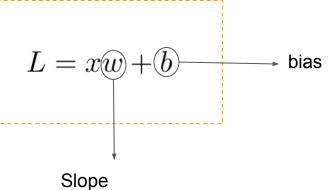
Model

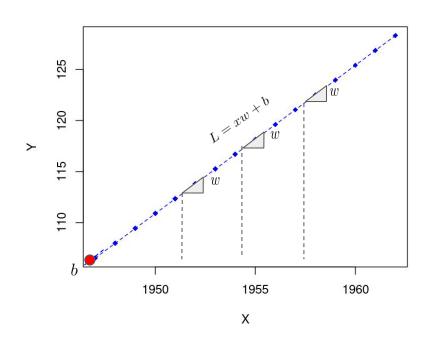




Parameters

Model



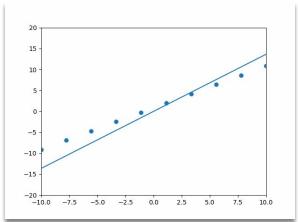


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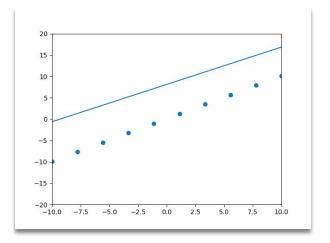


$$L = xw + b$$

$$L = x w + b$$



$$L = xw + b$$



20

15

10

-10

-15

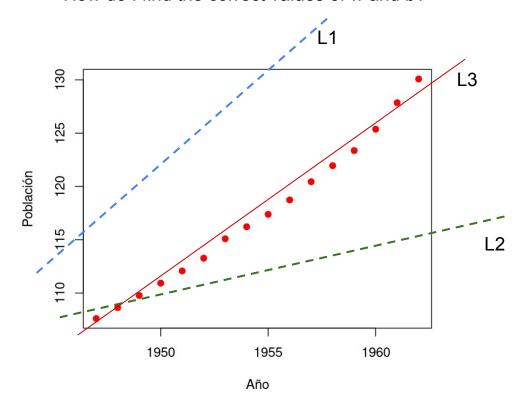
-10.0 -7.5 -5.0

-2.5 0.0

2.5 5.0

7.5

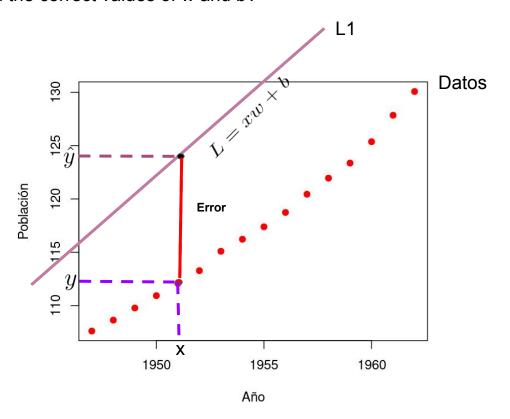












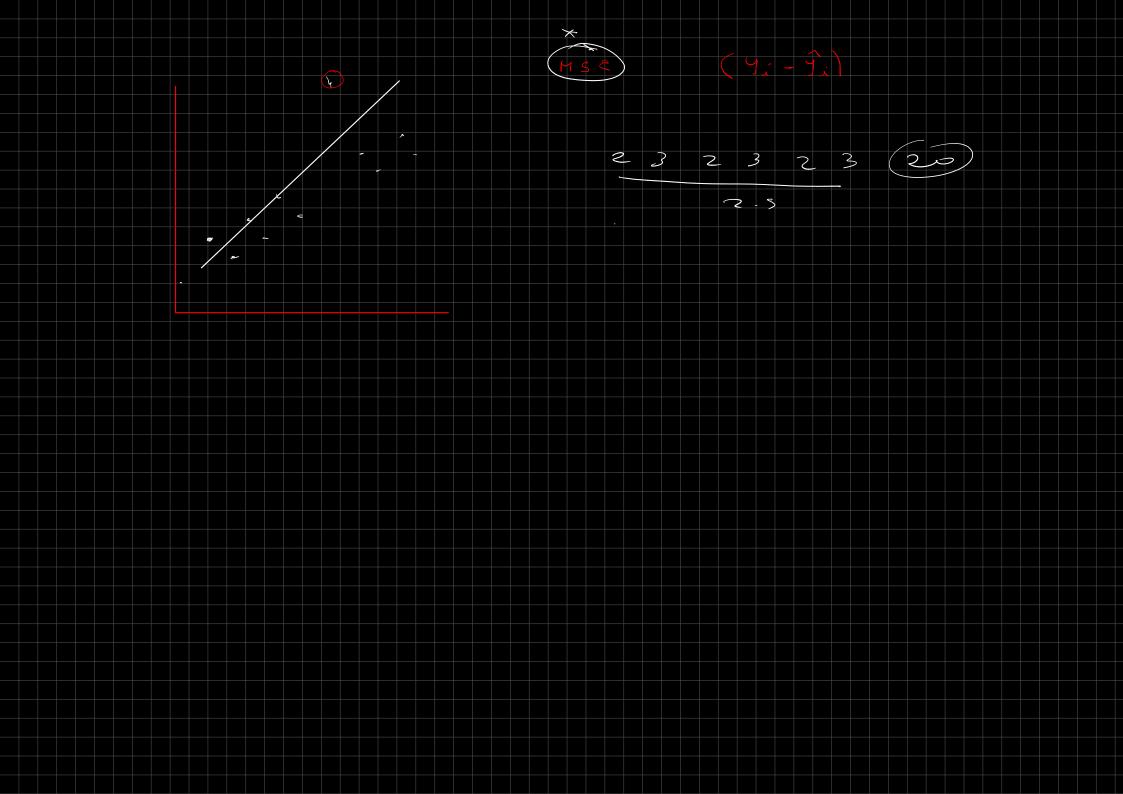


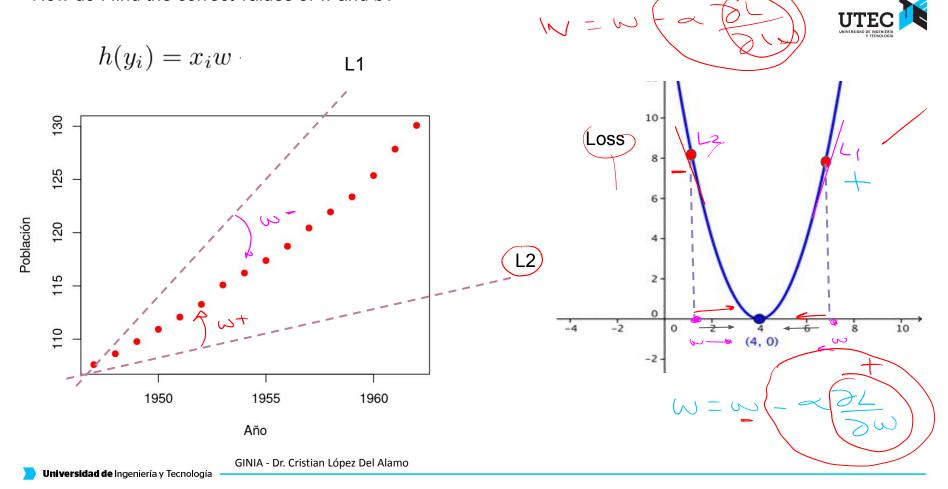
Hipótesis

$$h(y_i) = x_i w + b$$

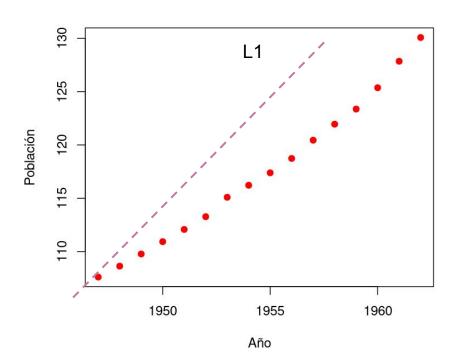
Loss Function

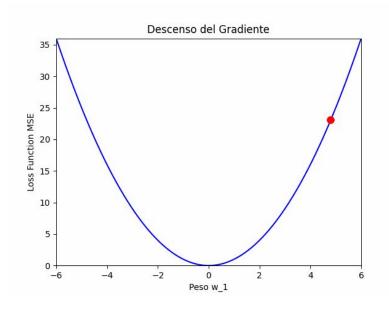
$$\mathcal{L} = \frac{1}{2n} \sum_{i=0}^{n} (y_i - \hat{y_i})^2$$



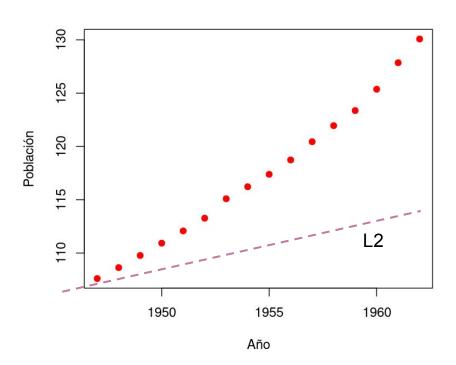


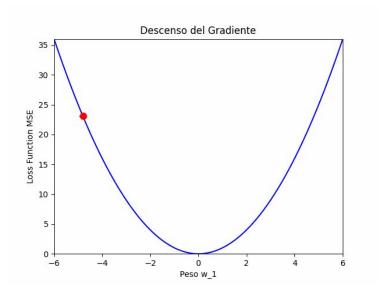






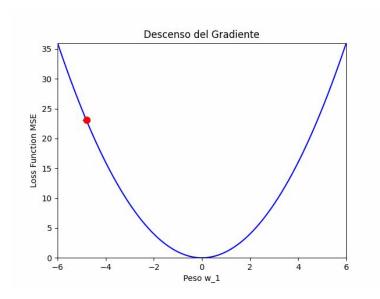






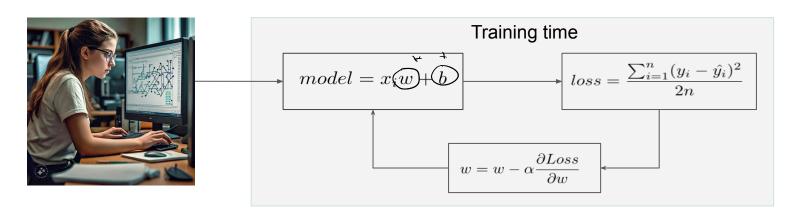
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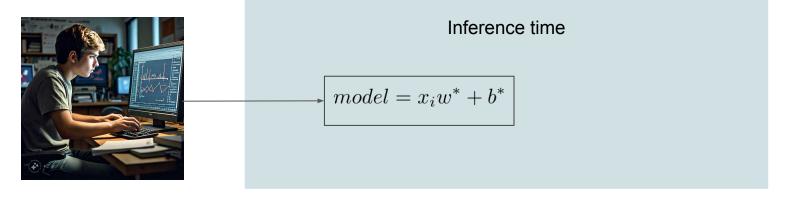




$$w = w - \alpha \frac{\partial Loss}{\partial w}$$



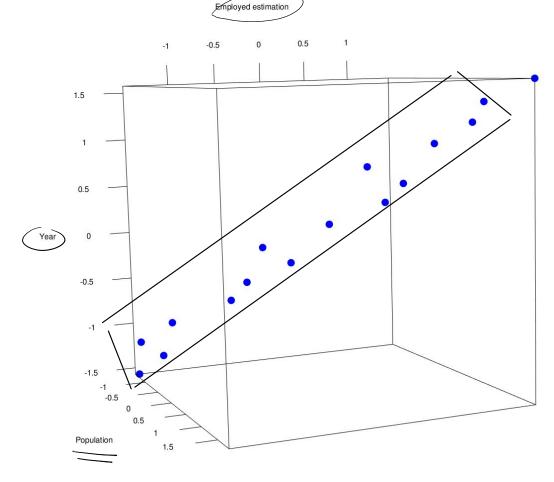






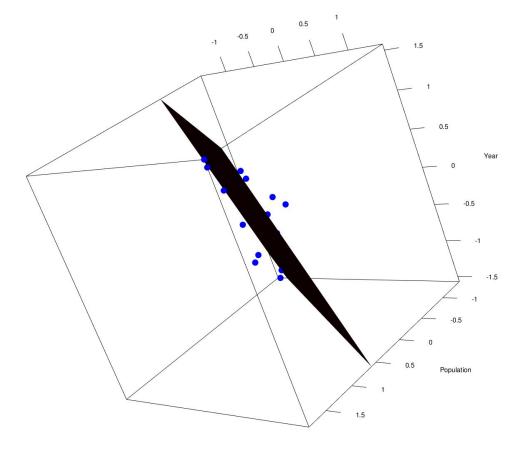
Objective: Understand the idea behind multivariable linear regression

How do we approach this set of points to **predict employability** based on **population** and **year**?



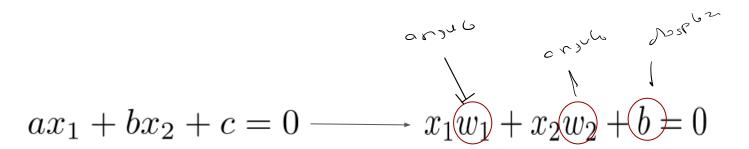
Artificial Intelligence Employed estimation

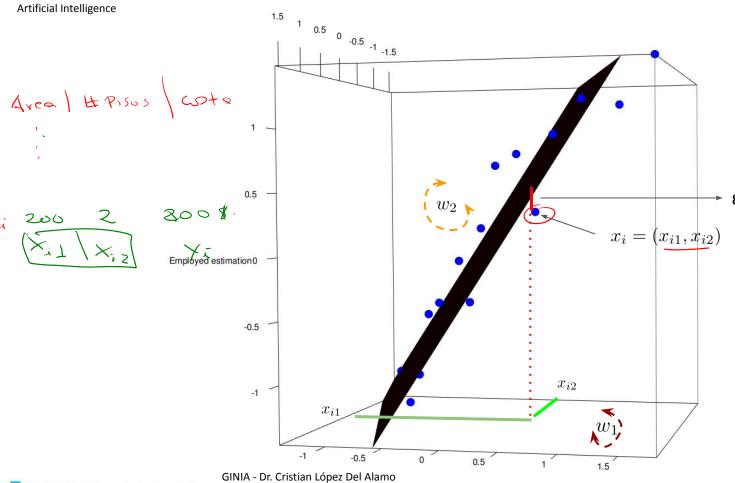
How can we create the plane that best fits this set of points?





Plane Equation









Hypothesis for univariate linear regression

$$h(x_i) = x_i \widehat{w} + \widehat{b}$$

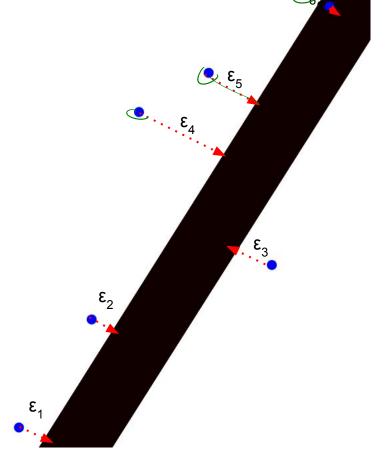
Hypothesis for multivariate linear regression

$$h(x_i) = x_{i1} \underbrace{w_1} + \underbrace{x_{i2} \underbrace{w_2}} + \underbrace{b}$$

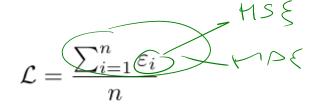


$$h(x_i) = x_{i1} \underbrace{w_1} + x_{i2} \underbrace{w_2} + \underbrace{b}$$





$$\mathcal{L} = \frac{\varepsilon_1 + \varepsilon_2 + \dots + \varepsilon_6}{6}$$





$$(h(x_i)) = x_{i1}w_1 + (x_{i2}w_2) + b$$

$$\mathcal{L} = \frac{\sum_{i=1}^{n} (y_i - h(x_i))^2}{2n}$$

Derivatives

$$\begin{array}{c|c}
\hline
\frac{\partial Loss}{\partial b} & \overline{\frac{\partial Loss}{\partial w_1}} & \overline{\frac{\partial Loss}{\partial w_2}}
\end{array}$$

Change parameters
$$\left(w_i = w_i - \alpha \frac{\partial loss}{\partial w_i}\right)^{\varsigma}$$

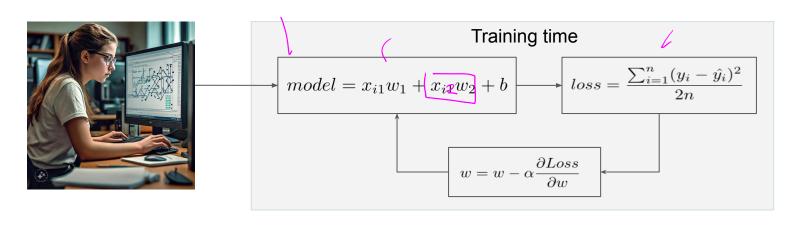
$$\frac{\partial L}{\partial b} = \underbrace{\mathbb{E}\left(y_i \circ h(x_i)\right)}_{i \neq 0} \cdot \left(-L\right)$$

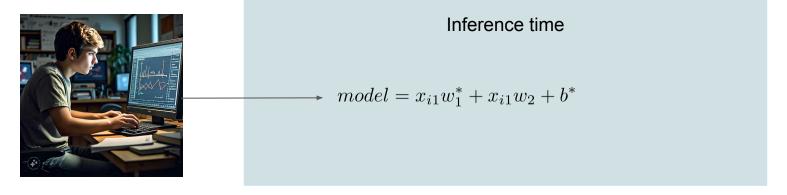
$$L = \begin{cases} 0 \\ 0 \\ 1 \end{cases} - \left[\frac{2}{x} \right]^{2}$$

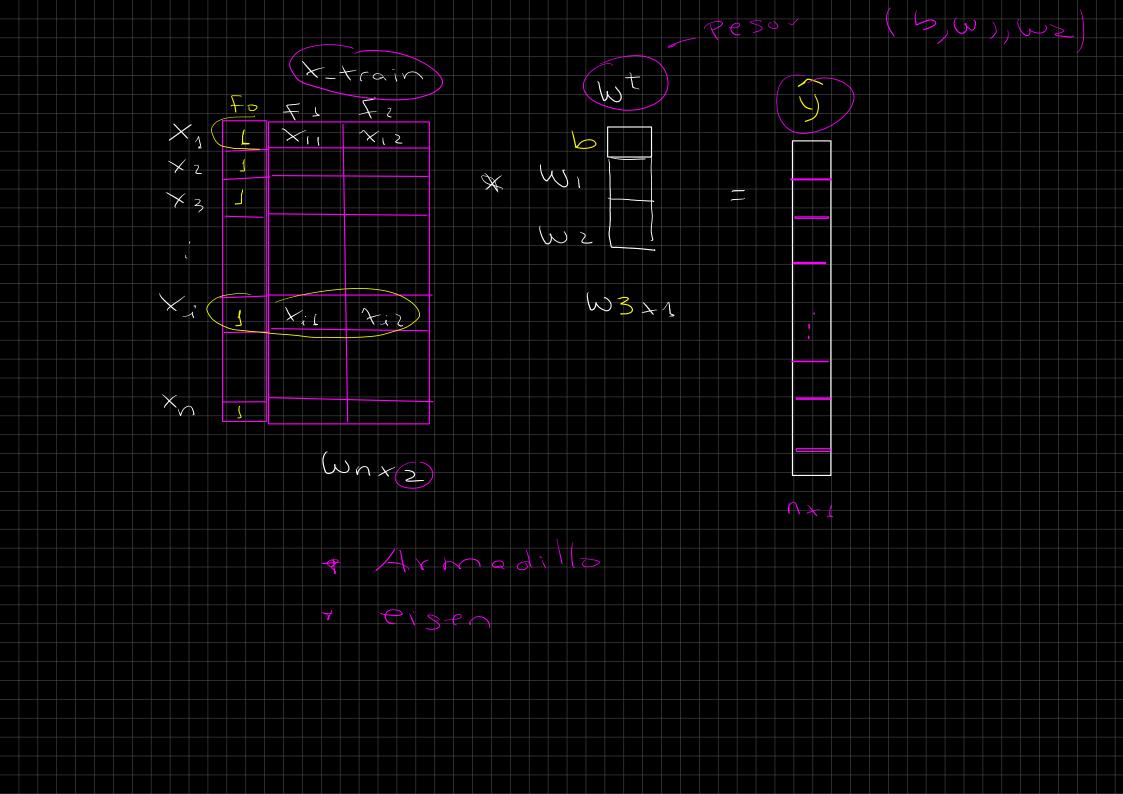
$$\frac{\partial L}{\partial w_1} = \frac{1}{128} \left(\frac{y_1 \cdot y_1}{y_1 \cdot y_2} \right) \left(\frac{y_1 \cdot y_1}{y_2 \cdot y_2} \right)$$

$$\frac{\partial L}{\partial \omega_{2}} = \frac{1}{1} \left(\frac{y_{1} \cdot h_{1}(x_{1})}{h_{1}(x_{1})} \right) \left(\frac{1}{1} \cdot \frac{y_{1}}{y_{2}} \right)$$









$$h(x_i) = x_{iL} w_i + x_{i2} w_i + b$$

$$L = \frac{1}{2} \left(y_i - h(x_i) \right)^2 / 2n$$

$$\frac{2L}{2b} = \frac{1}{2} \left(y_i - h(x_i) \right) (-1)$$

$$\frac{2L}{2b} = \frac{1}{2} \left(y_i - h(x_i) \right) (-x_i)$$

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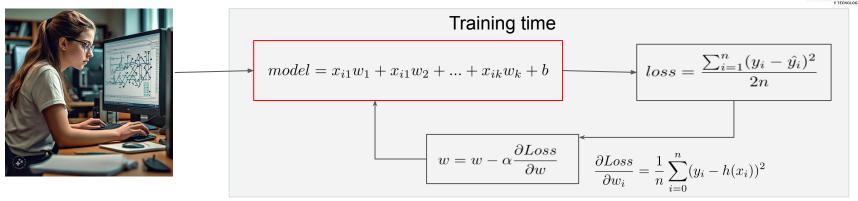






Generalizing to a k-dimensional space





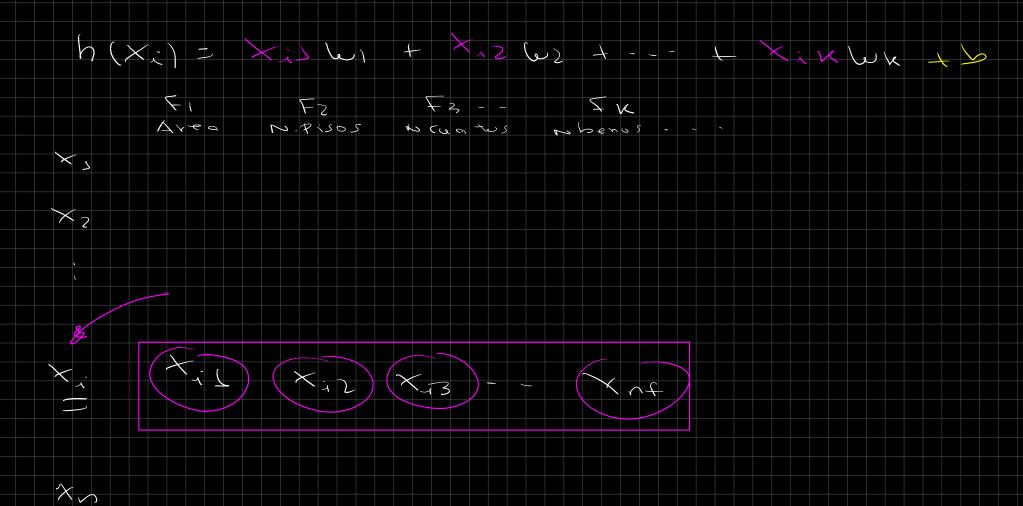


Inference time

$$model = x_{i1}w_1 + x_{i1}w_2 + \dots + x_{ik}w_k + b$$



```
1 def train(x, y, umbral, alfa):
      w = [np.random.rand() for i in range(1:k)]
      b = np.random.rand()
      L = Error(x, y, w, b)
      loss = []
      while (L > umbral):
          db, dw = derivada(x, y, w, b)
8
          b, w = update(w, b, alfa, db, dw)
9
          L = Error(x, y, w, b)
10
          print(L)
11
           loss.append(L)
12
      return b, w
13
```



$$h(x_i) = x_i \times w_1 + x_2 \times w_2 + \dots + x_n \times w_n + x_n \times w_n$$

$$h(x_i) = x_i \times w_1 + x_2 \times w_2 + \dots + x_n \times w_n$$

$$h(x_i) = (y_0) + x_1 \times (w_1) + x_2 \times (w_2) + \dots + x_n \times (w_n)$$

$$h(x_i) = (1 \times x_1 \times x_2 \times x_1) \cdot [w_0 w_1 \cdot w_1]$$

$$h(x_i) = x_i \times w_1 \times w_2 \cdot w_2 \cdot w_3 \cdot w_4 \cdot w_4 \cdot w_6$$

$$h(x_i) = (1 \times x_1 \times x_2 \times x_1) \cdot [w_0 w_1 \cdot w_1]$$

$$h(x_i) = x_i \cdot w_1 \cdot w_2 \cdot w_3 \cdot w_4 \cdot w_4 \cdot w_6$$

$$h(x_i) = (1 \times x_1 \times x_2 \times x_3) \cdot [w_0 w_1 \cdot w_1]$$

$$h(x_i) = x_i \cdot w_1 \cdot w_2 \cdot w_3 \cdot w_4 \cdot w_4 \cdot w_6$$

$$h(x_i) = x_i \text{ Wt}$$

$$L = \left\{ \left(y_i - h(x_i) \right)^2 - hs \right\}$$

$$i = 1 \quad zh$$

$$2h = \left\{ \left(y_i - h(x_i) \right) \left(-1 \right) \right\}$$

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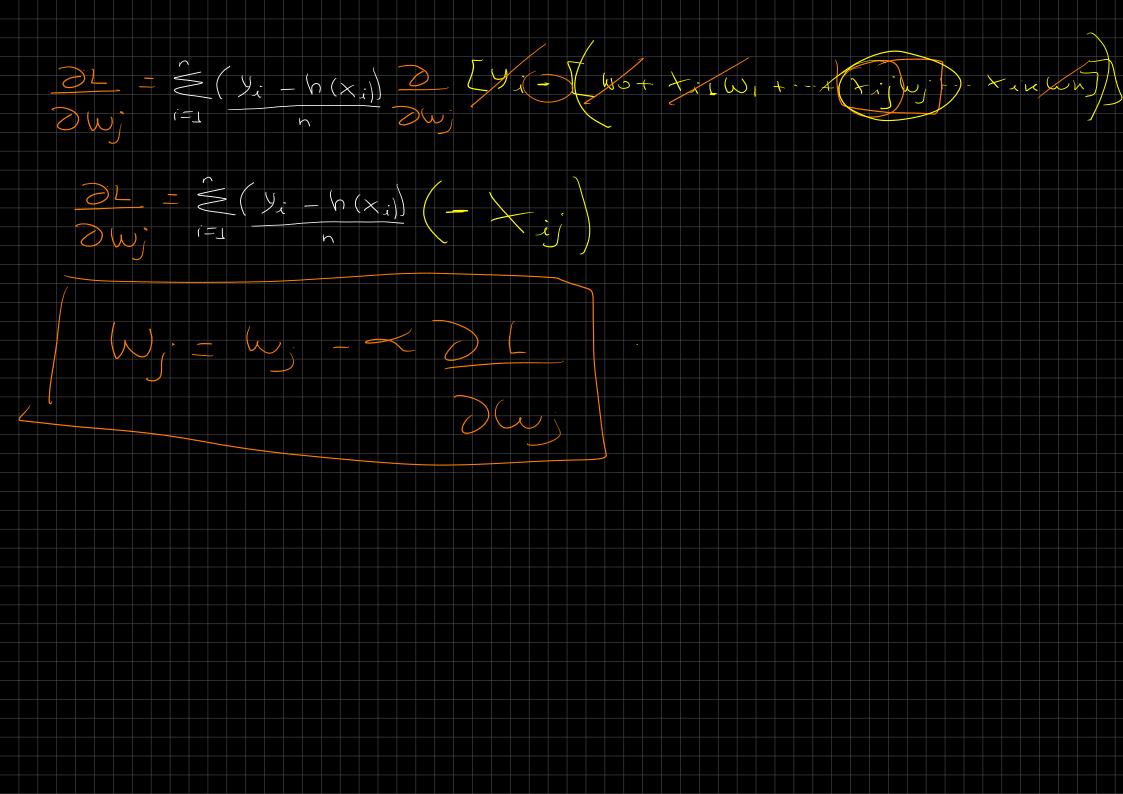
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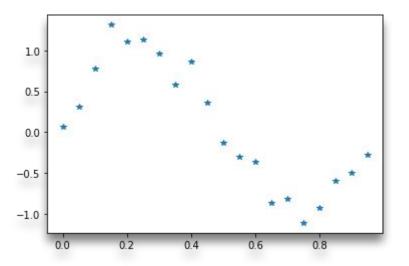


Linear Regression

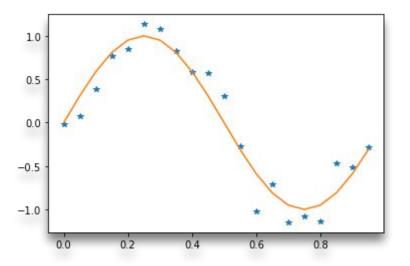


Objective: Understand the idea behind nonlinear



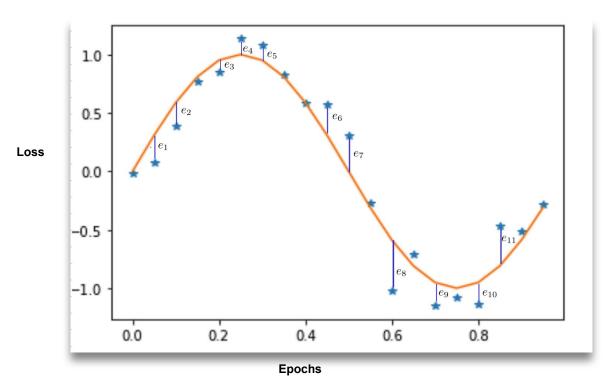








Loss Function



Loss Function

$$\mathcal{L} = \frac{\sum_{i=0}^{n} (y_i - h(x_i))^2}{2n}$$



What would be missing?

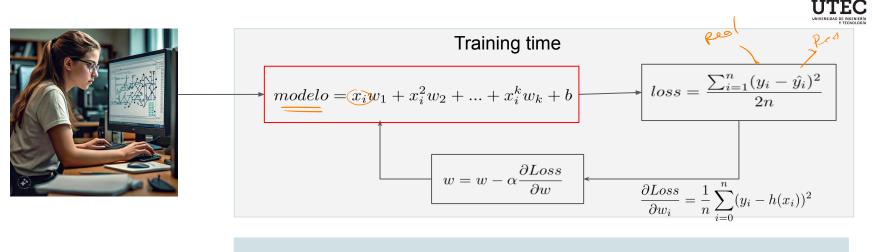


Hypothesis :
$$h(x_i) = b + x_i \underline{w_1} + x_i^2 \underline{w_2} + x_i^3 \underline{w_2} + \ldots + + x_i^p \underline{w_2}$$

Loss Function :
$$\mathcal{L} = \frac{\sum_{i=1}^{n} (y_i - h(x_i))^2}{2n}$$

Change parameters

Find derivatives of the error with respect to the parameters





Inference time

 $model = x_{i1}w_1 + x_{i1}w_2 + \dots + x_{ik}w_k + b$

$$h(x_{i}) = b + x_{i} w_{i} + x_{i}^{2} w_{2} + \cdots + x_{i}^{p} w_{p}$$

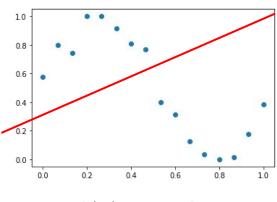
$$h(x_{i}) = x_{i}^{2} w_{i} + x_{i}^{2} w_{1} + x_{i}^{2} w_{2} + \cdots + x_{i}^{p} w_{p}$$

$$donde b = w_{0}$$

$$= [x_{i}^{2} x_{i}^{2} \times x_{i}^{2}$$

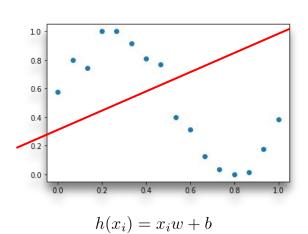
$$\frac{\partial L}{\partial w} = \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_2 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_1) \right) \frac{\partial L}{\partial w} + \frac{1}{2} \left(y_1 \cdot h(x_$$



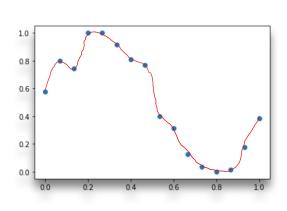


$$h(x_i) = x_i w + b$$



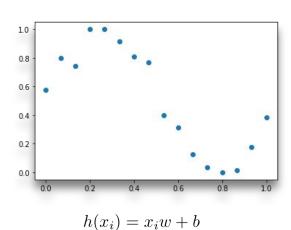


Overfitting

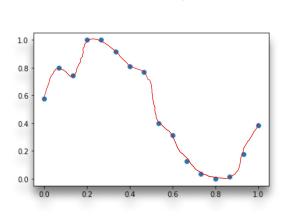


$$h(x_i) = x_i^0 w_0 + x_1^1 w_1 + \dots + x_i^{20} w_{20}$$



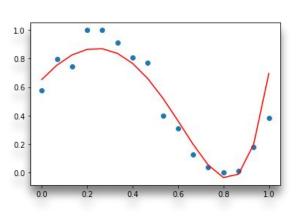


Overfitting



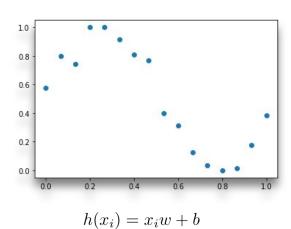
$$h(x_i) = x_i^0 w_0 + x_1^1 w_1 + \dots + x_i^{20} w_{20}$$

good



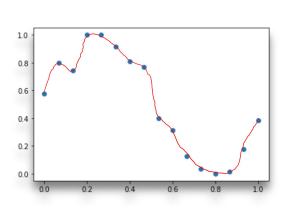
$$h(x_i) = x_i^0 w_0 + x_1^1 w_1 + \dots + x_i^3 w_3$$





- Simple Model
- Low Capacity Model

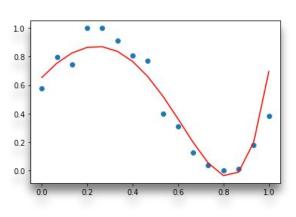
Overfitting



$$h(x_i) = x_i^0 w_0 + x_1^1 w_1 + \dots + x_i^{20} w_{20}$$

- Highly Complex Model
- High Capacity Model

good



$$h(x_i) = x_i^0 w_0 + x_1^1 w_1 + \dots + x_i^3 w_3$$

- Data-Fitting Model
- Model with Adequate Capacity



Linear No Regression