Concordia University Department of Electrical and Computer Engineering COEN 316 Computer Architecture Lab 5 - Datapath/Control Unit Integration and system testing Fall 2018

Introduction

The datapath designed in the previous lab contains 10 control signals. The function of the control unit, which is the focus of this lab, is to produce the correct values for all the control signals at the proper point in time. Tables 1 and 2 lists the 10 control signals and summarizes their operation.

Table 1: Single bit control signals.

Control signal	value = 0	value = 1
reg_write	do not write into register file	write into register file
reg_dst	rt is the destination register	rd is the destination register
reg_in_src	d_out of data_cache is the d_in to the register file	ALU output is the d_in to the register file
alu_src	out_b of register file (rt) is the y input of the ALU	sign extended immediate is the y input of the ALU
add_sub	ALU operation = addition	ALU operation = subtraction
data_write	do not write into data cache	write into data cache

Table 2: Two bit control signals.

Control signal	value = 00	value = 01	value =10	value = 11
logic_func	AND	OR	XOR	NOR
func	load upper immediate	set less	arithmetic	logic
branch_type	no branch	beq	bne	bltz
pc_sel	no jump (PC+1, or PC+target address if branch condition is true)	jump (PC = target address)	jump register (PC = rs)	not used

Table 3 lists the 20 instructions implemented by the CPU together with the values of the 6 bit opcode field and the 6 bit func field (contained within the instruction as per Figure 1 of Lab 4) together with the 10 control signals. Table 3 is **partially** completed, you are to **complete** the table by deriving the values of the 10 control signals based upon Tables 1 and 2 and knowledge of which control signals need to be activated during a particular instruction in order to achieve correct execution of the instruction. Refer to your datapath of Lab 4 to assist in completing the table.

Table 3: 20 instructions with opcode and function fields and control signals. [1]

Inst.	op	func	reg_wr ite	reg_dst	reg_in _src	alu_src	add_su b	data_w rite	logic_f unc	func	branch _type	pc_sel
lui	001111		1	0	1	1	0 (don't care)	0	00 (don't care)	00	00	00
add	000000	100000	1	1	1	0	0	0	00	10	00	00
sub	000000	100010	1	1	1	0	1	0	00	10	00	00
slt	000000	101010	1	1	1	0	1	0	00	01	00	00
addi	001000		1	0	1	1	0	0	00	10	00	00
slti	001010		1	0	1	1	1	0	00	01	00	00
and	000000	100100	1	1	1	0	1	0	00	11	00	00
or	000000	100101	1	1	1	0	1	0	01	11	00	00
xor	000000	100110	1	1	1	0	1	0	10	11	00	00
nor	000000	100111	1	1	1	0	1	0	11	11	00	00
andi	001100		1	0	1	1	1	0	00	11	00	00
ori	001101		1	0	1	1	1	0	01	11	00	00
xori	001110		1	1	1	1	1	0	10	11	00	00
lw	100011		1	0	0	1	0	0	10 (don't care)	10	00	00
sw	101011		0	0	0	1	0	1	00	10	00	00
j	000010		00	00	00	00	00	00	00	00	00	01
jr	000000	001000	0	0	0	0	0	0	00	00	00	10
bltz	000001											
beq	000100		0	0	0	0	0	0	00	00	01	00
bne	000101		0	0	0	0	0	0	00	00	10	00

Note that Table 3 has some entries which are "don't care" values which have arbitrarily assigned with values.

Procedure

Complete Table 3 by deriving all the remaining values of the control signals. Design the control unit using VHDL. The control unit in this implementation is a combinational logic circuit whose inputs are the opcode and function fields of the instruction and the outputs are the 10 control signals. Test your control unit (through simulation) to ensure that it generates the correct values for the 10 control signal for each of the 20 instructions. You may either use a VHDL process for the control unit which will be added to your datapath designed in Lab 4, or you may design the control unit as a separate entity and use it as an additional component to be added with a port map statement to your existing datapath. Alternatively, the datapath of Lab 4 may be added as a component together with an instance of your control unit to create a new top level entity (with name cpu).

Use the following VHDL entity specification for the final CPU design:

You will note that in the cpu entity, the top-level ports consist of the out_a (rs) and out_b (rt) ports of the register file and the PC register (with negated outputs to account for the active-low LEDs on the XUPV2Pro FPGA board. There is an asynchronous reset (which will be constrained to a switch input) and a clock input (constrained to the debounced clock input switch on the expansion IO board of the FPGA board). It is important that you use the above entity specification, as it is the one which will be used during the lab test.

Test your complete CPU by writing different test programs into the I-cache and verify correct operation of your CPU on the XUPV2Pro FPGA development board.

Requirements

- 1. Modelsim simulation results for the complete CPU showing execution of one example of each class of instruction: arithmetic and logic with and without immediate operands, conditional branches, unconditional jumps, and memory access instructions.
- 2. RTL schematic diagram of the synthesized circuit.
- 3. Synthesis log file (precision.log) as generated by Precision RTL.
- 4. You are not required to demonstrate your downloaded design to the lab TA as this is the last lab of the session and there is no subsequent lab session two weeks henceforth. Although you are not required to demonstrate the working design, you are required to submit as part of the written lab report the following:
- the _impact.log file created by the Xilinx Impact software.
- a listing of the directory contents containing the System ACE file generated by the Xilinx Impact software for Lab 5. Include in the listing the present working directory (obtained with the Linux 'pwd' command). For example:

Report Submission

Please note that the due date for Lab 5 is **Monday, Dec. 10, 2018** Submit (before 5 PM) a **hard-copy** printout of your lab report to the mailbox of T. Obuchowicz in room EV5.139. Please ask the receptionist at the front desk in EV5.139 to place it in my mailbox. CLEARLY INDICATE ON THE FRONT COVER OF YOUR LAB REPORT YOUR LAB SECTION.

References

1. *Computer Architecture, From Microprocessors to Supercomputers*, Behrooz Parhami, Oxford University Press, ISBN 0-19-515455-x, 2006, p251.

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Ted Obuchowicz
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