Asymptotie analysis provides basic vocabulary for discussing the design and analysis of algorithms.

Often referred to as "big O"

"Dweet spot" for high level reasoning about algorithms

- Coarse enough to suppress computer architecture / programming language / Scompiler-Merch details
- Sharp enough to make useful comparisons between different algorithms, sespecially on large sets of imputs

The point of asymptotic analysis is to suppress constant factors and lower order telms.

IRRELEVANT FOR LARGE NUMBER OF INPUTS

TOO SYSTEM
DEPENDENT

## EXAMPLE :

From previous work on merge sort analysis the estimated runtime of the algorithm was 5n(g(n) + 5n)

Suppress constant factors: In Ign + In -> n Ig(n) + n

REMOVE LOWER ORDER TERMS: nlg(n)+n -> nlg(n)

RUNNING TIME IS: (Xn)= nlgn, O of nlgn, where

n = input size (length of input arrays)

EXAMPLE; ONE LOOP

Does arbitrary array, A. of length or contain the target

for i=1 to n: if A[i] == t: return True

return False

In the worst case t may be in the last position or not in the array. The entire array will be seamed and compared once or n times before ending.

Therefore, O(n) = n or linear runtime

Two LOOPS IN SEQUENCE

Mirenianays A and B, both containing n elements a target value, t,

Does either away A or away B contain E?

for i=1 to n: if A[i] == t: return True

for i=1 to n: if BIiT == E: return True

return False

Similar to the one loop example t will be in the last position or not in one of the arrays. Therefore, there will be a comparisons in the worst-case per loop.

Since there are two loops in sequence, there are n+n comparisons or 2n.

Suppressing constant factors 2n -> n

... O(n) = n for two loops in sequence.

Two NESTED LOOPS

Liven arrays A and B, both with a elements

Do arrays A and B have a value in common?

for i=1 to ni for i=1 to n: if A[i] == B[j]: return True return False For every iteration of the outer loop the inner loop does noterations.

Thurspare, n toops " n iterations = nº iterations

O(n) = n2 for two nested loops

Two NESTED LOOPS: PART DEUX

Miver an array A of length 1

Does array A have duplicate elements?

for i=1 to n-1:

for i=1 to n-1:

for i=1 to n-1:

return True

return True

return False

For every iteration of the outer loop, the inner loop closs one less iteration. That is on the outer loops ken iteration the inner loop does n-k iterations, effectively halving the number of comparisons compared to the previous example.

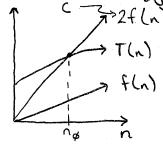
n Loops ·  $\frac{n}{2}$  iterations =  $\frac{n^2}{2}$  iterations  $(2n) = n^2$  since the  $\frac{1}{2}$  is suppressed

BIG · O FORMAL DEFINITION

Let T(n), a function on an input quantity of n, n=1,2,...Usually n is selected such that it will represent the worst case running time or input quantity to the algorithm. When is T(n) = O(F(n))?

This occurs for all sufficiently large n,  $n_0 \le n$ , where  $n_0$  is the minimum input admitty I to estisfy the above requirement, and T(n) is bounded above by a constant multiple of F(n).

Iderès a picture to clarify -



T(n) is bounded by f(n) and a constant times f(n), 2F(n), so
T(n) = O(f(n))

T(n) = O(f(n)) if and only if there exists constants C and  $n_{\emptyset}$  both quester than zero; C,  $n_{\emptyset} > \emptyset$ ; such that  $T(n) \leq C \cdot f(n)$  for all  $n \geq n_{\emptyset}$ , where C and  $n_{\emptyset}$  are independent of the number of elements put into the function.

BIG OMEGA, IL, and BIG THETA, O Big Omega and Big Thata are both notations to describe an algorithms runtime.

- A represents the best time an about on run, whereas big O is concerned with worst case runtime
  - D' represents both big O and hig I a bound on the upper and lowed mutimes for an algorithm

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BIG- 12 AND BIG O (cont)

BIG A PICTURE

f(n)

T(n)

1/2 f(n)

C

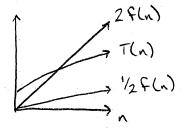
n

n

T(n) is bounded by a constant times f(n) on the low side,  $\frac{1}{2}f(n)$ , so  $T(n) = \mathcal{N}(f(n))$ 

T(n) = A(f(n)) if and only if there exists constants c and no where C,  $n_{\phi} > \emptyset$ ; such that  $T(n) \ge C \cdot f(n)$  for all  $n \ge n_{\phi}$ , where C and  $n_{\phi}$  are independent of the number of elements put into the function, n.

BIG O PICTURE



T(n) is bounded by both 2 f(n) and  $\frac{1}{2} f(n)$ , so  $T(n) = \Theta(f(n))$ 

While Big I provides the best case in the real world we prepare for the worst case (factor of safety)

additionally Big O provides for a more exact definition on the bounds, of an algorithm's nuntime, but in practice we do not generally need the righter tolerance because we are only construed with reducing the upper bound, big O, of the runtime.