Algorithm 1: Serial Double Greedy Alg. 1 $A \leftarrow \emptyset, B \leftarrow V$ 2 for $i \in \{1, \dots n\}$ do

$$\begin{array}{ll} \mathbf{3} & \Delta_A \leftarrow \max\left(F(A \cup i) - F(A), 0\right) \\ \mathbf{4} & \Delta_B \leftarrow \max\left(F(B \backslash i) - F(B), 0\right) \\ \mathbf{5} & \operatorname{Draw} u_i \sim Unif(0, 1) \\ \mathbf{6} & \text{if } u_i < \frac{\Delta_A}{\Delta_A + \Delta_B} \text{ then } A \leftarrow A \cup i \end{array}$$

else $B \leftarrow B \setminus i$

7 else $B \leftarrow B \setminus i$

Algorithm 2: Parallel Double Greedy Alg.

```
1 A \leftarrow \emptyset, B \leftarrow V

2 for p \in \{1, \dots, P\} do in parallel

3 i \leftarrow p

4 while i < n do

5 (\Gamma_i, \delta_i) \leftarrow T_i(A, B)

6 (A, B) \leftarrow \text{Validate}(\delta_i, \Gamma_i)

7 i \leftarrow \text{AtomicInc}(i)
```

Algorithm 3: Validate the Transaction

```
Input: The predicate \Gamma on the state A,B
Input: The operation \delta_i on element i \in V

1 if \Gamma(A,B) is false then

2 \Delta_A = F(A \cup i) - F(A)

3 \Delta_B = F(B \setminus i) - F(B)

4 if u_i < \frac{\Delta_A}{\Delta_A + \Delta_B} then \delta_i \leftarrow +1

5 else \delta_i \leftarrow -1

6 if \delta_i = +1 then A \leftarrow A \cup i
```

Algorithm 4: Coordinate Free Transaction T_i

```
1 \Delta_A \leftarrow \max \left( F(A \cup i) - F(A), 0 \right)

2 \Delta_B \leftarrow \max \left( F(B \setminus i) - F(B), 0 \right)

3 Draw u_i \sim Unif(0, 1)

4 if u_i < \frac{\Delta_A}{\Delta_A + \Delta_B} then (True, +1)

5 else (True, -1)
```

Algorithm 5: Concurrency Control T_i

4 CF2G Bidirectional Greedy Algorithm

[XP: Provide more intuition for what the CF2G algorithm is doing.]

Algorithm 6 is the CF2G parallel bidirectional greedy algorithm for unconstrained submodular maximization. The CF2G algorithm closely resembles the serial algorithm, but the elements $e \in V$ are no longer processed in a fixed order. Thus, the sets A,B are replaced by "bounds" \hat{A},\hat{B} , where \hat{A} is a subset of the "true" A and \hat{B} is a superset of the "actual" B on each iteration. These bounding sets allow us to compute bounds Δ_+^{\max} , Δ_-^{\max} which approximate Δ_+ , Δ_- from the serial algorithm. We now formalize this idea.

We order the elements $e \in V$ according to the time at which Algorithm 6 line 7 is executed. Let $\iota(e)$ be the position of e in this total ordering on elements. This ordering allows us to define monotonically non-decreasing sets $A^i = \{e' : e' \in A, \iota(e') < i\}$, and monotonically non-increasing sets $B^i = A^i \cup \{e' : \iota(e') \geq i\}$. These "true" sets A^i, B^i provide a serialization against which we can compare the CF2G algorithm; in this serialization, Algorithm 1 computes:

$$\Delta_+(e) = F(A^{\iota(e)-1} \cup i) - F(A^{\iota(e)-1}), \qquad \Delta_-(e) = F(B^{\iota(e)-1} \backslash e) - F(B^{\iota(e)-1}) \,.$$

Note that in Algorithm 6, lines 5 and 6 may be executed in parallel with lines 9 and 10. Hence, $\Delta_{+}^{\max}(e)$ and $\Delta_{-}^{\max}(e)$ (lines 5 and 6) may be computed with conflicting versions of \hat{A} and \hat{B} . Denoting these versions by \hat{A}_e and \hat{B}_e , Algorithm 6 computes:

$$\Delta_{+}^{\max}(e) = F(\hat{A}_e \cup e) - F(\hat{A}_e), \qquad \Delta_{-}^{\max}(e) = F(\hat{B}_e \setminus e) - F(\hat{B}_e).$$

¹We present only the parallelized probabilistic versions of [1]. Both parallel algorithms can be easily extended to the deterministic version of [1]; the CF2G algorithm can also be extended to the multilinear version of [1].