sheet09

December 16, 2018

1 Support Vector Machines

In this exercise sheet, you will experiment with training various support vector machines on a subset of the MNIST dataset composed of digits 5 and 6. First, download the MNIST dataset from http://yann.lecun.com/exdb/mnist/, uncompress the downloaded files, and place them in a data/ subfolder. Install the optimization library CVXOPT (python-cvxopt package, or directly from the website www.cvxopt.org). This library will be used to optimize the dual SVM in part A.

1.1 Part A: Kernel SVM and Optimization in the Dual

We would like to learn a nonlinear SVM by optimizing its dual. An advantage of the dual SVM compared to the primal SVM is that it allows to use nonlinear kernels such as the Gaussian kernel, that we define as:

$$k(x, x') = \exp\left(-\frac{\|x - x'\|^2}{\sigma^2}\right)$$

The dual SVM consists of solving the following quadratic program:

$$\max_{\alpha} \sum_{i=1}^{N} \alpha_i - \frac{1}{2} \sum_{ij} \alpha_i \alpha_j y_i y_j k(x_i, x_j)$$

subject to:

$$0 \le \alpha_i \le C$$
 and $\sum_{i=1}^N \alpha_i y_i = 0$.

Then, given the alphas, the prediction of the SVM can be obtained as:

$$f(x) = \begin{cases} 1 & \text{if } \sum_{i=1}^{N} \alpha_i y_i k(x, x_i) + \theta > 0 \\ -1 & \text{if } \sum_{i=1}^{N} \alpha_i y_i k(x, x_i) + \theta < 0 \end{cases}$$

where

$$\theta = \frac{1}{\#SV} \sum_{i \in SV} \left(y_i - \sum_{j=1}^N \alpha_j y_j k(x_i, x_j) \right)$$

1

and SV is the set of indices corresponding to the unbound support vectors.

1.1.1 Implementation (25 P)

We will solve the dual SVM applied to the MNIST dataset using the CVXOPT quadratic optimizer. For this, we have to build the data structures (vectors and matrices) to must be passed to the optimizer.

- *Implement* a function gaussianKernel that returns for a Gaussian kernel of scale σ , the Gram matrix of the two data sets given as argument.
- Implement a function getQPMatrices that builds the matrices P, q, G, h, A, b (of type cvxopt.matrix) that need to be passed as argument to the optimizer cvxopt.solvers.qp.
- *Run* the code below using the functions that you just implemented. (It should take less than 3 minutes.)

```
In [2]: import utils,numpy,cvxopt,cvxopt.solvers
                             #import solutions
                             import numpy as np
                            Xtrain,Ttrain,Xtest,Ttest = utils.getMNIST56()
                             cvxopt.solvers.options['show_progress'] = False
                            def gaussianKernel(X1,X2,sigma):
                                          n1 = X1.shape[0]
                                          n2 = X2.shape[0]
                                          d = X1.shape[1]
                                          K = np.empty((n1,n2))
                                           for i in numpy.arange(n1):
                                                         Xi=np.dot(np.ones((n2,1)),X1[i].reshape((1,d)))
                                                         K[i] = np.exp(-(np.linalg.norm(Xi-X2,axis=1)**2/sigma**2))
                                          return K
                            def getQPMatrices(K,Y,C):
                                          n=K.shape[0]
                                          P = np.dot(np.dot(np.diag(Y),K),np.diag(Y))
                                           q= - np.ones(n)
                                           G= - np.identity(n)
                                          h= np.zeros(n)
                                           A=Y.reshape((1,n))
                                          b = [0.0]
                                           return cvxopt.matrix(P),cvxopt.matrix(q),cvxopt.matrix(G),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h),cvxopt.matrix(h)
                            for scale in [10,30,100]:
                                           for C in [1,10,100]:
                                                         # Prepare kernel matrices
                                                         Ktrain = gaussianKernel(Xtrain, Xtrain, scale)
```

Ktest = gaussianKernel(Xtest, Xtrain, scale)

```
# Prepare the matrices for the quadratic program
               P,q,G,h,A,b = getQPMatrices(Ktrain,Ttrain,C)
               # Train the model (i.e. compute the alphas)
               alpha = numpy.array(cvxopt.solvers.qp(P,q,G,h,A,b)['x']).flatten()
               # Get predictions for the training and test set
               SV = (alpha>1e-6)
               uSV = SV*(alpha<C-1e-6)
               theta = 1.0/sum(uSV)*(Ttrain[uSV]-numpy.dot(Ktrain[uSV,:],alpha*Ttrain)).sum()
               Ytrain = numpy.sign(numpy.dot(Ktrain[:,SV],alpha[SV]*Ttrain[SV])+theta)
               Ytest = numpy.sign(numpy.dot(Ktest [:,SV],alpha[SV]*Ttrain[SV])+theta)
               # Print accuracy and number of support vectors
               Atrain = (Ytrain==Ttrain).mean()
               Atest = (Ytest ==Ttest ).mean()
               print('Scale=%3d C=%3d SV: %4d Train: %.3f Test: %.3f'%(scale,C,sum(SV),At:
           print('')
Scale= 10 C= 1 SV: 1000 Train: 1.000 Test: 0.937
Scale= 10 C= 10 SV: 1000 Train: 1.000 Test: 0.937
Scale= 10 C=100 SV: 1000 Train: 1.000 Test: 0.937
Scale= 30 C= 1 SV: 256 Train: 1.000 Test: 0.986
Scale= 30 C= 10 SV: 256 Train: 1.000 Test: 0.986
Scale= 30 C=100 SV: 256 Train: 1.000 Test: 0.986
Scale=100 C= 1 SV: 134 Train: 1.000 Test: 0.975
Scale=100 C= 10 SV: 134 Train: 1.000 Test: 0.975
Scale=100 C=100 SV: 134 Train: 1.000 Test: 0.975
```

1.1.2 Analysis (10 P)

- *Explain* which combinations of parameters σ and C lead to good generalization, underfitting or overfitting?
- best generalization: σ = 30 and C=100
- overfit: $\sigma = 10$
- underfit: $\sigma = 100$
- *Explain* which combinations of parameters *σ* and *C* produce the fastest classifiers (in terms of amount of computation needed at prediction time)?
- σ = 10, C=100 is the fastest classifier, because it has less support vectors

1.2 Part B: Linear SVMs and Gradient Descent in the Primal

The quadratic problem of the dual SVM does not scale well with the number of data points. For large number of data points, it is generally more appropriate to optimize the SVM in the primal. The primal optimization problem for linear SVMs can be written as

$$\min_{w,\theta} ||w||^2 + C \sum_{i=1}^N \xi_i \quad \text{where} \quad \forall_{i=1}^N : y_i(w \cdot x_i + \theta) \ge 1 - \xi_i \quad \text{and} \quad \xi_i \ge 0.$$

It is common to incorporate the constraints directly into the objective and then minimizing the unconstrained objective

$$J(w,\theta) = ||w||^2 + C\sum_{i=1}^{N} \max(0, 1 - y_i(w \cdot x_i + \theta))$$

using simple gradient descent.

1.2.1 Implementation (15 P)

- *Implement* the function J computing the objective $I(w, \theta)$
- *Implement* the function DJ computing the gradient of the objective $J(w, \theta)$ with respect to the parameters w and θ .
- *Run* the code below using the functions that you just implemented. (It should take less than 1 minute.)

```
In [3]: import utils, numpy
        #import solutions
        import numpy as np
        C = 10.0
        lr = 0.001
        Xtrain,Ttrain,Xtest,Ttest = utils.getMNIST56()
        n,d = Xtrain.shape
        w = numpy.zeros([d])
        theta = 1e-9
        def J(w,theta,C,X,Y):
            n = X.shape[0]
            d = X.shape[1]
            Theta = theta*np.ones(n)
            return np.linalg.norm(w)**2 + C * np.sum(np.maximum(np.zeros(n) , np.ones(n)-Y*(np
        def DJ(w,theta,C,X,Y):
            n = X.shape[0]
```

```
d = X.shape[1]
           Theta = theta*np.ones(n)
           ma = np.maximum(np.zeros(n), np.ones(n)-Y*(np.dot(X,w) + Theta))
           Ma = np.dot(ma.reshape((n,1)),np.ones((1,d)))
           dJdw = 2*w + C*np.sum(np.where(Ma==0,np.zeros((n,d)),-Y.reshape((n,1))*X),axis=0)
           dJdtheta = C* np.sum( np.where(ma==0,np.zeros(n),-Y))
           return dJdw,dJdtheta
       for it in range(0,101):
           # Monitor the training and test error every 5 iterations
           if it%5==0:
               Ytrain = numpy.sign(numpy.dot(Xtrain,w)+theta)
               Ytest = numpy.sign(numpy.dot(Xtest ,w)+theta)
               Obj
                      = J(w,theta,C,Xtrain,Ttrain)
               Etrain = (Ytrain==Ttrain).mean()
               Etest = (Ytest ==Ttest ).mean()
               print('It=%3d J: %9.3f Train: %.3f Test: %.3f'%(it,Obj,Etrain,Etest))
           dw,dtheta = DJ(w,theta,C,Xtrain,Ttrain)
           w = w - lr*dw
           theta = theta - lr*dtheta
        J: 10000.000 Train: 0.471 Test: 0.482
It= 0
It= 5
        J: 68520.417
                      Train: 0.961 Test: 0.958
        J: 49918.674 Train: 0.973 Test: 0.961
It= 10
It= 15
        J: 37473.229 Train: 0.973 Test: 0.963
It= 20
        J: 28590.129 Train: 0.974 Test: 0.965
Tt=25
        J: 21746.877 Train: 0.977 Test: 0.967
It=30
        J: 16987.200 Train: 0.980 Test: 0.968
It=35
        J: 13646.095 Train: 0.986 Test: 0.967
It=40
        J: 11187.127 Train: 0.986 Test: 0.967
            9182.940 Train: 0.991 Test: 0.967
It=45
        J:
It=50
        J:
            7692.273 Train: 0.990 Test: 0.968
It=55
            6437.609 Train: 0.988 Test: 0.966
It= 60
            5253.071 Train: 0.995 Test: 0.966
        J:
It= 65
            4515.520 Train: 0.992 Test: 0.967
        J:
It=70
        J:
           4016.851 Train: 0.996 Test: 0.966
It=75
            3647.983 Train: 0.997 Test: 0.965
        J:
It= 80
        J:
            3497.204 Train: 0.998 Test: 0.966
It= 85
        J: 3404.280 Train: 1.000 Test: 0.966
```

It= 90 J: 3336.804 Train: 1.000 Test: 0.966
It= 95 J: 3270.665 Train: 1.000 Test: 0.966
It=100 J: 3205.837 Train: 1.000 Test: 0.966