

# Jake Eichinger

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<b>Objective</b>	Soon to be college graduate double majoring in Electrical Engineering and Computer Science. Seeking a position in Software Engineering that will allow me to continue to grow, and build upon my existing academic knowledge and internships.
<b>Education</b>	<b>B.S. Electrical Engineering and B.S. Computer Science, Dec. 2017</b> <i>University of Wisconsin-Madison</i> Overall GPA: 3.265/4.00 Major GPA: 3.761/4.00 Overall Last Two Semesters: 4.00/4.00
<b>Work Experience</b>	<div><div><b>John Deere, Dubuque, IA</b></div><div>May 2017-Sept 2017</div><div><i>Computer Engineering Intern</i></div><ul style="list-style-type: none"><li>• Created a database tool using PostgreSQL that consolidates hundreds of files into one single database.</li><li>• Implemented a new software feature that allows for automated testing on excavators. Involved developing an SRD, creating a Simulink model, as well as writing the code to implement the feature.</li><li>• Developed electrical benches for multiple models that will be used for testing purposes. Involved creating wiring harnesses, as well as designing a setup for the benches.</li></ul></div> <div><div><b>John Deere, Des Moines, IA</b></div><div>May 2016-Sept 2016</div><div><i>Computer Engineering Intern</i></div><ul style="list-style-type: none"><li>• Implemented a new feature for one of their latest iOS products. This consisted of designing a mobile architecture, developing functional documentation, as well as actually implementing the new feature in the application.</li><li>• Worked directly with the embedded systems and mobile application teams.</li><li>• Skills Obtained: iOS programming(swift), Functional Reactive Programming(ReactiveCocoa), embedded systems practices, Sqlite and Realm database manipulation.</li></ul></div>
<b>Projects</b>	<div><div><b>Obstacle Avoiding Robot</b></div><div>Summer 2016</div><ul style="list-style-type: none"><li>• An Obstacle avoiding robot designed and built from scratch. This robot utilizes ultrasonic sensors to traverse its environment freely.</li><li>• Developed an iPhone app that allows the user to either control the robot with an on-screen controller, or command the robot to go into its "Obstacle Avoiding Self Drive" mode.</li></ul></div> <div><div><b>Arduino Quadcopter Drone</b></div><div>Summer 2015</div><ul style="list-style-type: none"><li>• Designed, built, and programmed a drone using multiple Arduinos, wireless transmitters and receivers, a flight controller and an improvised controller from an old RC helicopter.</li><li>• Currently working on improving drone for live video feed and GPS navigation.</li></ul></div> <div><b>See website provided at top for older projects.</b></div>
<b>Activities/Clubs</b>	<div><b>IEEE</b></div> <div>September 2015-Present</div> <ul style="list-style-type: none"><li>• Actively involved in tech talks, social events, as well as mini tech workshops.</li></ul>