

Advanced case study options

GMSE: an R package for generalised management strategy evaluation (Supporting Information 4)

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Fine-tuning simulation conditions using `gmse_apply`

Here we demonstrate how simulations in GMSE can be more fine-tuned to specific empirical situations through the use of `gmse_apply`. To do this, we use the same scenario described in [SI3](#); we first recreate the basic scenario run in `gmse` using `gmse_apply`, and then build in additional modelling details including (1) custom placement of user land, (2) parameterisation of individual user budgets, and (3) density-dependent movement of resources. We emphasise that these simulations are provided only to demonstrate the use of GMSE, and specifically to show the flexibility of the `gmse_apply` function, not to accurately recreate the dynamics of a specific system or make management recommendations.

We reconsider the case of a protected waterfowl population that exploits agricultural land (e.g., [Fox and Madsen, 2017](#); [Mason et al., 2017](#); [Tulloch et al., 2017](#); [Cusack et al., 2018](#)). The manager attempts to keep the waterfowl at a target abundance, while users (farmers) attempt to maximise agricultural yield on the land that they own. We again parameterise our model using demographic information from the Taiga Bean Goose (*Anser fabalis fabalis*), as reported by [Johnson et al. \(2018\)](#) and [AEWA \(2016\)](#). Relevant parameter values are listed in the table below.

Table 1: GMSE simulation parameter values inspired by [Johnson et al. \(2018\)](#) and [AEWA \(2016\)](#)

Parameter	Value	Description
<code>remove_pr</code>	0.122	Goose density-independent mortality probability
<code>lambda</code>	0.275	Expected offspring production per time step
<code>res_death_K</code>	93870	Goose carrying capacity (on adult mortality)
<code>RESOURCE_ini</code>	35000	Initial goose abundance
<code>manage_target</code>	70000	Manager’s target goose abundance
<code>res_death_type</code>	3	Mortality (density and density-independent sources)

Additionally, we continue to use the following values for consistency, except in the case of `stakeholders`, where we reduce the number of farmers to `stakeholders = 8`. This is done to for two reasons. First, it speeds up simulations for the purpose of demonstration; second, it makes the presentation of our custom landscape ownership easier to visualise (see below).

Table 2: Non-default GMSE parameter values chosen by authors

Parameter	Value	Description
<code>manager_budget</code>	10000	Manager’s budget for setting policy options
<code>user_budget</code>	10000	Users’ budgets for actions
<code>public_land</code>	0.4	Proportion of the landscape that is public

Parameter	Value	Description
stakeholders	8	Number of stakeholders
land_ownership	TRUE	Users own landscape cells
res_consume	0.02	Landscape cell output consumed by a resource
observe_type	3	Observation model type (survey)
agent_view	1	Cells managers can see when conducting a survey

27 All other values are set to GMSE defaults, except where specifically noted otherwise.

28 Re-creating gmse simulations using gmse_apply

29 We now recreate the simulations in [SI3](#), which were run using the `gmse` function, in `gmse_apply`. Doing
30 so requires us to first initialise simulations using one call of `gmse_apply`, then loop through multiple time
31 steps that again call `gmse_apply`; results of interest are recorded in a data frame (`sim_sum_1`). Following the
32 protocol introduced in [SI2](#), we can call the initialising simulation `sim_old`, and use the code below to read in
33 the relevant parameter values.

```
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
  res_death_K = 93870, RESOURCE_ini = 35000,
  manage_target = 70000, res_death_type = 3,
  manager_budget = 10000, user_budget = 100000,
  public_land = 0.4, stakeholders = 8, res_consume = 0.02,
  res_birth_K = 200000, land_ownership = TRUE,
  observe_type = 3, agent_view = 1, converge_crit = 0.01,
  ga_mingen = 200);
```

34 Note that the argument `get_res = "Full"` causes `sim_old` to retain all of the relevant data structures for
35 simulating a new time step and recording simulation results. This includes the key simulation output, which
36 is located in `sim_old$basic_output`, which is printed below.

```
37 ## $resource_results
38 ## [1] 34092
39 ##
40 ## $observation_results
41 ## [1] 34092
42 ##
43 ## $manager_results
44 ##      resource_type scaring culling castration feeding help_offspring
45 ## policy_1          1      NA      524          NA      NA          NA
46 ##
47 ## $user_results
48 ##      resource_type scaring culling castration feeding help_offspring
49 ## Manager          1      NA      0          NA      NA          NA
50 ## user_1            1      NA     190          NA      NA          NA
51 ## user_2            1      NA     190          NA      NA          NA
52 ## user_3            1      NA     190          NA      NA          NA
53 ## user_4            1      NA     190          NA      NA          NA
54 ## user_5            1      NA     190          NA      NA          NA
55 ## user_6            1      NA     190          NA      NA          NA
56 ## user_7            1      NA     190          NA      NA          NA
57 ## user_8            1      NA     190          NA      NA          NA
58 ##      tend_crops kill_crops
```

```

59 ## Manager      NA      NA
60 ## user_1       NA      NA
61 ## user_2       NA      NA
62 ## user_3       NA      NA
63 ## user_4       NA      NA
64 ## user_5       NA      NA
65 ## user_6       NA      NA
66 ## user_7       NA      NA
67 ## user_8       NA      NA

```

68 We can then loop over 30 time steps to recreate the simulations from [SI3](#). In these simulations, we are
 69 specifically interested in the resource and observation outputs, as well as the manager policy and user actions
 70 for culling, which we record below in the data frame `sim_sum_1`. The inclusion of the argument `old_list`
 71 tells `gmse_apply` to use parameters and values from the list `sim_old` in the new time step.

```

sim_sum_1 <- matrix(data = NA, nrow = 30, ncol = 5);
for(time_step in 1:30){
  sim_new <- gmse_apply(get_res = "Full", old_list = sim_old);
  sim_sum_1[time_step, 1] <- time_step;
  sim_sum_1[time_step, 2] <- sim_new$basic_output$resource_results[1];
  sim_sum_1[time_step, 3] <- sim_new$basic_output$observation_results[1];
  sim_sum_1[time_step, 4] <- sim_new$basic_output$manager_results[3];
  sim_sum_1[time_step, 5] <- sum(sim_new$basic_output$user_results[,3]);
  sim_old <- sim_new;
}
colnames(sim_sum_1) <- c("Time", "Pop_size", "Pop_est", "Cull_cost",
                        "Cull_count");
print(sim_sum_1);

```

```

72 ##      Time Pop_size Pop_est Cull_cost Cull_count
73 ## [1,]    1    32300   32300     1010        792
74 ## [2,]    2    31957   31957     1010        791
75 ## [3,]    3    32000   32000     1009        792
76 ## [4,]    4    32781   32781     1010        792
77 ## [5,]    5    36993   36993     1010        792
78 ## [6,]    6    38008   38008     1009        792
79 ## [7,]    7    39292   39292     1010        792
80 ## [8,]    8    40907   40907     1010        791
81 ## [9,]    9    42956   42956     1010        792
82 ## [10,]  10    45249   45249     1010        792
83 ## [11,]  11    47810   47810     1009        792
84 ## [12,]  12    50111   50111     1010        792
85 ## [13,]  13    52515   52515     1009        792
86 ## [14,]  14    55241   55241     1010        792
87 ## [15,]  15    58084   58084     1009        792
88 ## [16,]  16    61102   61102     1010        792
89 ## [17,]  17    64699   64699     1010        792
90 ## [18,]  18    68354   68354     1009        791
91 ## [19,]  19    72265   72265        35    18335
92 ## [20,]  20    57511   57511     1010        792
93 ## [21,]  21    60673   60673     1009        792
94 ## [22,]  22    64183   64183     1010        791
95 ## [23,]  23    67544   67544     1010        792
96 ## [24,]  24    71348   71348        59    12734
97 ## [25,]  25    62715   62715     1010        792

```

```

98 ## [26,] 26 66280 66280 1010 792
99 ## [27,] 27 69773 69773 1009 792
100 ## [28,] 28 73638 73638 22 24190
101 ## [29,] 29 52906 52906 1010 792
102 ## [30,] 30 55756 55756 1009 792

```

The above output from `sim_sum_1` shows the data frame that holds the information we were interested in pulling out of our simulation results. All of this information was available under the list element `sim_new$basic_output`, but other list elements of `sim_new` might also be useful to record. It is important to remember that this example of `gmse_apply` is using the default resource, observation, manager, and user sub-models. Custom sub-models could produce different outputs in `sim_new` (see [SI2](#) for examples). For default sub-models, there are some list elements that might be especially useful. These elements can potentially be edited *within the above loop* to dynamically adjust simulations. For more explanation of built-in GMSE data arrays, see [SI7](#).

- `sim_new$resource_array`: A table holding all information on resources. Rows correspond to discrete resources, and columns correspond to resource properties: (1) ID, (2-4) types (not currently in use), (5) x-location, (6) y-location, (7) movement parameter, (8) time, (9) density independent mortality parameter (`remove_pr`), (10) reproduction parameter (`lambda`), (11) offspring number, (12) age, (13-14) observation columns, (15) consumption rate (`res_consume`), and (16-20) recorded experiences of user actions (e.g., was the resource culled or scared?).
- `sim_new$AGENTS`: A table holding basic information on agents (manager and users). Rows correspond to a unique agent, and columns correspond to agent properties: (1) ID, (2) type (0 for the manager, 1 for users), (3-4) additional type options not currently in use, (5-6), x and y locations (usually ignored), (7) movement parameter (usually ignored), (8) time, (9) agent's viewing ability in cells (`agent_view`), (10) error parameter, (11-12) values for holding marks and tallies of resources, (13-15) values for holding observations, (16) yield from landscape cells, (17) budget (`manager_budget` and `user_budget`).
- `sim_new$observation_vector`: Estimate of total resource number from the observation model (`observation_array` also holds this information in a different way depending on `observe_type`)
- `sim_new$LAND`: The landscape on which interactions occur, which is stored as a 3D array with `land_dim_1` rows, `land_dim_2` columns, and 3 layers. Layer 1 (`sim_new$LAND[,1]`) is not currently used in default sub-models, but could be used to store values that affect resources and agents. Layer 2 (`sim_new$LAND[,2]`) stores crop yield from a cell, and layer 3 (`sim_new$LAND[,3]`) stores the owner of the cell (value corresponds to the agent's ID).
- `sim_new$manage_vector`: The cost of each action as set by the manager. For even more fine-tuning, individual costs for the actions of each agent can be set for each user in `sim_new$manager_array`.
- `sim_new$user_vector`: The total number of actions performed by each user. A more detailed breakdown of actions by individual users is held in `sim_new$user_array`.

Next, we show how to adjust the landscape to manually set land ownership in `gmse_apply`.

1. Custom placement of user land

By default, all farmers in GMSE are allocated the same number of landscape cells, which are simply placed in order of the farmer's ID. Public land is produced by placing landscape cells that are technically owned by the manager, and therefore have landscape cell values of 1. The image below shows this landscape for the eight farmers from `sim_old`.

```
image(x = sim_old$LAND[,3], col = topo.colors(9), xaxt = "n", yaxt = "n");
```

We can change the ownership of cells by manipulating `sim_old$LAND[,3]`. First we initialise a new `sim_old` below.

```
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
                     res_d4eath_K = 93870, RESOURCE_ini = 35000,
```



Figure 1: Default position of land ownership by farmers.

```
manage_target = 70000, res_death_type = 3,
manager_budget = 10000, user_budget = 10000,
public_land = 0.4, stakeholders = 8, res_consume = 0.02,
res_birth_K = 200000, land_ownership = TRUE,
observe_type = 3, agent_view = 1, converge_crit = 0.01,
ga_mingen = 200);
```

Because we have not specified landscape dimensions in the above, the landscape reverts to the default size of 100 by 100 cells. We can then manually assign landscape cells to the eight farmers, whose IDs range from 2-9 (ID value 1 is the manager). Below we do this to make eight different sized farms.

```
sim_old$LAND[1:20, 1:20, 3] <- 2;
sim_old$LAND[1:20, 21:40, 3] <- 3;
sim_old$LAND[1:20, 41:60, 3] <- 4;
sim_old$LAND[1:20, 61:80, 3] <- 5;
sim_old$LAND[1:20, 81:100, 3] <- 6;
sim_old$LAND[21:40, 1:50, 3] <- 7;
sim_old$LAND[21:40, 51:100, 3] <- 8;
sim_old$LAND[41:60, 1:100, 3] <- 9;
sim_old$LAND[61:100, 1:100, 3] <- 1; # Public land
image(x = sim_old$LAND[, , 3], col = topo.colors(9), xaxt = "n", yaxt = "n");
```

The above image shows the modified landscape stored in `sim_old`, which can now be incorporated into simulations using `gmse_apply`. We can think of all the plots on the left side of the landscape as farms of various sizes, while the blue area of the landscape on the right is public land.

2. Parameterisation of individual user budgets

Perhaps we want to assume that farmers have different budgets, which are correlated in some way to the number of landscape cells that they own. Custom user budgets can be set by manipulating `sim_old$AGENTS`, the last column of which (column 17) holds the budget for each user. Agent IDs (as stored on the landscape above) correspond to rows of `sim_old$AGENTS`, so individual budgets can be directly input as desired. We can do this manually (e.g., `sim_old$AGENTS[2, 17] <- 4000`), or, alternatively, if farmer budget positively

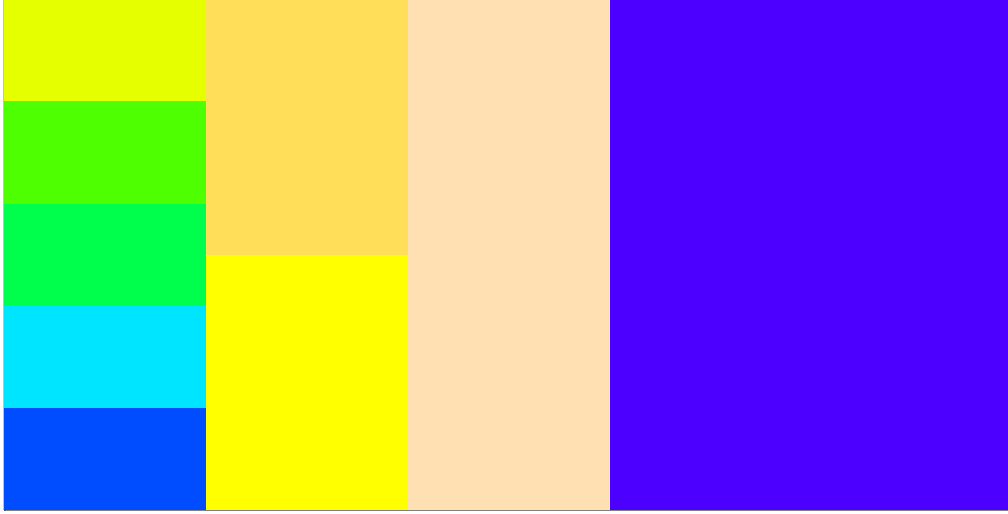


Figure 2: Land ownership by farmers as customised in `gmse_apply`.

correlates to landscape owned, we can use a loop to input values as below.

```
for(ID in 2:9){
  cells_owned      <- sum(sim_old$LAND[,3] == ID);
  sim_old$AGENTS[ID, 17] <- 10 * cells_owned;
}
```

The number of cells owned by the manager (1) and each farmer (2-8) is therefore listed in the table below.

ID	1	2	3	4	5	6	7	8	9
Budget	10000	4000	4000	4000	4000	4000	10000	10000	20000

As with `sim_old$LAND` values, changes to `sim_old$AGENTS` will be retained in simulations looped through `gmse_apply`.

3. Density-dependent movement of resources

Lastly, we consider a more nuanced change to simulations, in which the rules for movement of resources are modified to account for density-dependence. Assume that geese tend to avoid aggregating, such that if a goose is located on the same cell as too many other geese, then it will move at the start of a time step. Programming this movement rule can be accomplished by creating a new function to apply to the resource data array `sim_old$resource_array`. Below, a custom function is defined that causes a goose to move up to 5 cells in any direction if it finds itself on a cell with more than 10 other geese. As with default GMSE simulations, movement is based on a torus landscape (where no landscape edge exists, so that if resources move off of one side of the landscape they appear on the opposite side). We will use this custom function to modify `sim_old$resource_array` prior to running `gmse_apply`, thereby modelling a custom-built process affecting resource distribution that is integrated into GMSE.

```

avoid_aggregation <- function(sim_resource_array, land_dim_1 = 100,
                              land_dim_2 = 100){
  goose_number <- dim(sim_resource_array)[1] # How many geese are there?
  for(goose in 1:goose_number){ # Loop through all rows of geese
    x_loc <- sim_resource_array[goose, 5];
    y_loc <- sim_resource_array[goose, 6];
    shared <- sum( sim_resource_array[,5] == x_loc &
                  sim_resource_array[,6] == y_loc);
    if(shared > 10){
      new_x <- x_loc + sample(x = -5:5, size = 1);
      new_y <- y_loc + sample(x = -5:5, size = 1);
      if(new_x < 0){ # The 'if' statements below apply the torus
        new_x <- land_dim_1 + new_x;
      }
      if(new_x >= land_dim_1){
        new_x <- new_x - land_dim_1;
      }
      if(new_y < 0){
        new_y <- land_dim_2 + new_y;
      }
      if(new_y >= land_dim_2){
        new_y <- new_y - land_dim_2;
      }
      sim_resource_array[goose, 5] <- new_x;
      sim_resource_array[goose, 6] <- new_y;
    }
  }
  return(sim_resource_array);
}

```

169 With the above function written, we can apply the new movement rule along with our [custom farm placement](#)
 170 and [custom farmer budgets](#) to the simulation of goose population dynamics.

171 Simulation with custom farms, budgets, and goose movement

172 Below shows an example of `gmse_apply` with custom landscapes, farmer budgets, and density-dependent
 173 goose movement rules.

```

# First initialise a simulation
sim_old <- gmse_apply(get_res = "Full", remove_pr = 0.122, lambda = 0.275,
                     res_death_K = 93870, RESOURCE_ini = 35000,
                     manage_target = 70000, res_death_type = 3,
                     manager_budget = 10000, user_budget = 10000,
                     public_land = 0.4, stakeholders = 8, res_consume = 0.02,
                     res_birth_K = 200000, land_ownership = TRUE,
                     observe_type = 3, agent_view = 1, converge_crit = 0.01,
                     ga_mingen = 200, res_move_type = 0);

# By setting `res_move_type = 0`, no resource movement will occur in gmse_apply
# Adjust the landscape ownership below
sim_old$LAND[1:20, 1:20, 3] <- 2;
sim_old$LAND[1:20, 21:40, 3] <- 3;
sim_old$LAND[1:20, 41:60, 3] <- 4;
sim_old$LAND[1:20, 61:80, 3] <- 5;

```

```

sim_old$LAND[1:20, 81:100, 3] <- 6;
sim_old$LAND[21:40, 1:50, 3] <- 7;
sim_old$LAND[21:40, 51:100, 3] <- 8;
sim_old$LAND[41:60, 1:100, 3] <- 9;
sim_old$LAND[61:100, 1:100, 3] <- 1;
# Change the budgets of each farmer based on the land they own
for(ID in 2:9){
  cells_owned <- sum(sim_old$LAND[, ,3] == ID);
  sim_old$AGENTS[ID, 17] <- 10 * cells_owned;
}
# Begin simulating time steps for the system
sim_sum_2 <- matrix(data = NA, nrow = 30, ncol = 5);
for(time_step in 1:30){
  # Apply the new movement rules at the beginning of the loop
  sim_old$resource_array <- avoid_aggregation(sim_resource_array =
                                              sim_old$resource_array);
  # Next, move on to simulate (old_list remembers that res_move_type = 0)
  sim_new <- gmse_apply(get_res = "Full", old_list = sim_old);
  sim_sum_2[time_step, 1] <- time_step;
  sim_sum_2[time_step, 2] <- sim_new$basic_output$resource_results[1];
  sim_sum_2[time_step, 3] <- sim_new$basic_output$observation_results[1];
  sim_sum_2[time_step, 4] <- sim_new$basic_output$manager_results[3];
  sim_sum_2[time_step, 5] <- sum(sim_new$basic_output$user_results[,3]);
  sim_old <- sim_new;
}
colnames(sim_sum_2) <- c("Time", "Pop_size", "Pop_est", "Cull_cost",
                        "Cull_count");
print(sim_sum_2);

```

```

174 ##      Time Pop_size Pop_est Cull_cost Cull_count
175 ## [1,]    1   34087   34087     1008         52
176 ## [2,]    2   34542   34542     1010         52
177 ## [3,]    3   35613   35613     1009         52
178 ## [4,]    4   37423   37423     1010         52
179 ## [5,]    5   43128   43128     1002         52
180 ## [6,]    6   45194   45194     1005         52
181 ## [7,]    7   47748   47748     1007         52
182 ## [8,]    8   50782   50782     1008         52
183 ## [9,]    9   54253   54253     1010         52
184 ## [10,]   10   58082   58082     1005         52
185 ## [11,]   11   62405   62405     1006         52
186 ## [12,]   12   66669   66669     1008         52
187 ## [13,]   13   71400   71400         10      5465
188 ## [14,]   14   70450   70450         12      4721
189 ## [15,]   15   69981   69981     1007         52
190 ## [16,]   16   74369   74369         10      5455
191 ## [17,]   17   73187   73187         10      5430
192 ## [18,]   18   72135   72135         10      5440
193 ## [19,]   19   70901   70901         10      5381
194 ## [20,]   20   69717   69717     1003         52
195 ## [21,]   21   74185   74185         10      5453
196 ## [22,]   22   73309   73309         10      5448
197 ## [23,]   23   72410   72410         10      5441
198 ## [24,]   24   71444   71444         10      5430

```


199	##	[25,]	25	70613	70613	10	5449
200	##	[26,]	26	70721	70721	10	5421
201	##	[27,]	27	72428	72428	10	5454
202	##	[28,]	28	74123	74123	10	5409
203	##	[29,]	29	76740	76740	10	5444
204	##	[30,]	30	79292	79292	10	5482

205 Conclusions

206 In this example, we showed how the built-in resource, observation, manager, and user sub-models can be
207 customised by manipulating the data within the data structures that they use. The goal was to show how
208 software users can work with these existing sub-models and data structures to customise GMSE simulations.
209 Readers seeking even greater flexibility (e.g., replacing an entire built-in sub-model with a custom sub-model)
210 should refer to [SI2](#) that introduces `gmse_apply` more generally. Future versions of GMSE are likely to
211 expand on the built-in options available for simulation; requests for such expansions, or contributions, can be
212 submitted to [GitHub](#).

213 References

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