

PRINT JOB OPTIMIZATION

JAMES JONES

Abstract. We try to formalize a print job optimization problem brought to the meetup in early March and come up with a reasonably quick way to, given a print job, determine how to print it at minimal cost.

1. Definitions and Presumptions¹

1.1. Job and Version. A job j is a pair (V, q) where V is a non-empty, finite set of versions, identically-sized images of pieces to be printed, and $q : V \rightarrow \mathbb{Z}^+$ is a function indicating how many of each version the customer wants printed. We presume that our printer can print sheets of paper large enough to let us print at least one piece. For a given job, we define U to be the number of pieces that can fit on a sheet.

1.2. Form and Run. A form is a function $f : V \rightarrow \mathbb{N}$ such that $0 < u(f) \leq U$ where $u(f) = \sum_{v \in V} f(v)$, i.e. a form must print something and fit on a sheet. $f(v)$ is the number of pieces of version v printed per sheet for form f . A form f is said to be “ $u(f)$ -up”. We call the set of possible forms for a job \mathbb{F} , and define $\pi : \mathbb{F} \rightarrow \mathcal{P}(V)$ by $\pi(f) = f^{-1}(\mathbb{Z}^+)$.

A form f corresponds to the plates that print $\pi(f)$. The printer uses process color[4], so each form requires four or eight plates for single-sided or double-sided printing respectively.

A run is the process of preparing the plates corresponding to a form and printing a number of sheets using it.

1.3. Solution. A solution for a job (V, q) is a pair (F, p) such that $\emptyset \subset F \subseteq \mathbb{F}$ and $p : F \rightarrow \mathbb{Z}^+$ satisfies $\forall v \in V, q'(v) \geq q(v)$, where $q'(v) = \sum_{f \in F} p(f)f(v)$. p maps a form to the number of sheets to be printed with it, and q' maps a version to the total number of copies that will be printed with the specified solution, so the constraint just means “we print at least as many of each version as the customer wants”. Given a solution (F, p) , for each $f \in F$, one does a run printing $p(f)$ sheets using the plates created for f .

Clearly if (F, p) solves (V, q) , $(F, v \mapsto kp(v))$ solves $(V, v \mapsto kq(v))$ for all $k \in \mathbb{Z}^+$. One can thus solve (V, q) by solving $(V, v \mapsto \frac{q(v)}{\gcd q[V]})$. If the q values tend to be round numbers (who’d order 2,457 copies of something?), the smaller job may be easier to solve.²

2. The cost function

We don’t just want solutions; we want solutions that minimize some cost function $c(F, p)$. What should the cost function reflect?

Date: April 20, 2018.

¹We have revised this document for consistency, to the extent possible, with terms used in [1] and [2]. An appendix describes possibly-unfamiliar notation.

²That property helps one work out examples by hand, but the code won’t need to bother.

2.1. Wasted paper. Wasted paper comes in two flavors: blank piece-sized spaces on sheets and excess pieces printed. There are $\sum_{f \in F} p(f)(U - u(f))$ of the former and $\sum_{v \in V} (q'(v) - q(v))$ of the latter, and their sum reflects the total wasted paper.

2.2. Wasted ink? The printer who brought us this problem said that ink wasn't a concern, so we'll ignore it; besides,

- Without detailed knowledge of what's being printed, we can't tell how much ink we're wasting anyway, but...
- ...wasted ink is ink printed on wasted paper, so minimizing wasted paper minimizes wasted ink. One could argue for weighting printed-on waste more heavily than blank waste, but that requires the detailed knowledge we lack.

2.3. Forms. Creating forms is, we're told, the resource-intensive part of an offset print job, and looking at videos of the process just for small sheets, I can believe it [4]. For double-sided printing (which the example we were first given requires), each form requires eight frames made from the CMYK separations for each side.

2.4. Weighting. The obvious cost function is, then, a weighted sum of wasted paper and the number of forms...but what are the weights, or equivalently, how many sheets would you waste to avoid another form?

Probably quite a few, from looking at how plates are prepared and the cost of plates and materials. One example of what, at least to me, seems a large job, involved printing nearly 800,000 pieces with 186 versions. It was printed 12-up and sheetwise, with thirty forms, at a cost per sheet of \$0.20 and setup cost per press run of \$475. At \$0.20/sheet, that would pay for 2,360 sheets of paper, or $2360U$ pieces, so you'd have to seriously reduce waste to make it worth another form.

2.5. Why not just use the actual cost? Maybe we should. I was trying to reflect how far away a solution is from the optimum, but there's no way to express wasted forms without actually knowing the optimal solution. (It did show what an optimal one-form solution must be.)

3. Solutions

3.1. Maximum forms. Given a job (V, q) , $(\{w \mapsto U\delta_{vw} | v \in V\}, v \mapsto \lceil \frac{q(v)}{U} \rceil)$ is a solution with $\|V\|$ forms.³ If $\|V\|=1$ or $U = 1$, that is the solution. In general, it's pretty expensive, but at least it serves as an existence proof.

3.2. Minimum forms. Every job has a solution with $\lceil \frac{\|V\|}{U} \rceil$ forms. For simplicity's sake, let's start with the simple case, and then add the minor complication.

3.2.1. $U | \|V\|$. If U divides $\|V\|$, there are $\frac{\|V\|}{U}$ forms, all stuffed to the gills. More formally, $\forall f \in F, \|\pi(f)\| = U$, so $\forall v \in f, f(v) = 1$ and hence $q'(v) = p(f) = \max q[\pi(f)]$. f thus adds $p(f) \sum_{v \in \pi(f)} (p(f) - q(v))$ to the paper portion of the cost. Note that if $\|q[\pi(f)]\| = 1$, said contribution is zero, which suggests printing versions with the same quantity together on a form.

3.2.2. $U \nmid \|V\|$. Otherwise, the forms are just as described above, plus one more with $\|\pi(f)\| < U$. This extra form and its leftover slots can be handled as described in 3.3.2.

³Here we use a flavor of the Kronecker delta[3] that compares versions rather than integers.

3.3. The one-form case. As long as $\|V\| < U$, we can print everything with one form. We'll discuss whether we should later.

3.3.1. The perfect solution. A perfect solution uses one form and prints exactly what the customer wants. If there's an integer p' such that $\forall v \in V, p' | q(v)$ and $\sum_{v \in V} \frac{q(v)}{p'} = U$, then $(\{f\}, f \mapsto p')$, where $f(v) = \frac{q(v)}{p'}$, is the perfect solution, because

- $U = \sum_{v \in V} \frac{q(v)}{p'} = \sum_{v \in V} f(v) = u(f)$, so f is U -up; all printed sheets are full.
- $\forall v \in V, q'(v) = \sum_{f \in F} p(f)f(v) = p' \frac{q(v)}{p'} = q(v)$, so no excess copies are printed and no ink is wasted.
- One form is the best we can do.

$\sum_{v \in V} \frac{q(v)}{p'} = U \Rightarrow p' = \frac{\sum_{v \in V} q(v)}{U}$, so just calculate that value. If it's an integer that divides all the quantities, you're golden. If not, there will be some waste.

3.3.2. Pretty good solution. A perfect solution may not be possible, but one can come close. Consider the example from the first meetup where we talked about the problem, with

- $V = \{v_1, v_2, v_3\}$
- $q(v_1) = 1100, q(v_2) = 1000, q(v_3) = 300$
- $U = 12$

For doing this by hand, we can turn it into a search for a solution for (11, 10, 3). I came up with $f(v_1) = 5, f(v_2) = 5, f(v_3) = 2$, so that printing three sheets gives you 15 of v_1 and v_2 and six of v_3 . Three's necessary to get eleven copies of v_1 .

We could stop there and print 300 sheets to accommodate the order—but we shouldn't. A scaled-up perfect solution is necessarily perfect. A scaled-up less-than-perfect solution gives an even less perfect solution for a larger problem, but if all versions have excess copies, there may be room to improve. 220 sheets gives us 1100 of each of v_1 and v_2 , and 440 of v_3 , resulting in 100 excess of v_2 and 140 excess of v_3 . 240 excess copies at 12-up is 20 sheets of paper, only four dollars more expensive than a perfect solution, if one even exists. I spent maybe five minutes coming up with that form, but our goal is to avoid such work, so...

...let's try our perfect formula anyway. $11 + 10 + 3 = 24$, a multiple of 12, giving $p' = 2$. 11 and 3 are odd, so they fail the first constraint—but look at what we got for our hand-generated form. Integer division of the q 's by 2 gives us 5, 5, and 1 which add to 11, one less than U . Using that leftover for anything other than v_3 forces the full 300 sheets to get 300 of v_3 , so 5, 5, 2 looks like (and in fact is) the best we can do, suggesting that the formula can guide us even if we can't achieve perfection.

We were fortunate with that first example, because our p' did meet one constraint if not both. Let's try one that meets neither.

- $V = \{v_1, v_2, v_3\}$
- $q(v_1) = 1000, q(v_2) = 800, q(v_3) = 300$
- $U = 12$

$10 + 8 + 3 = 21$, and $12 \nmid 21$. $p' = 1$ fails, because $10 + 8 + 3 > 12$. $p' = \left\lceil \frac{\sum_{v \in V} q(v)}{U} \right\rceil$ works whether or not the sum is a multiple of U . Then we have 5, 4, 1 and two leftover slots to play with. As before, at least one must go to v_3 , or we need 300 sheets to get the needed copies of v_3 . 200 sheets of 5, 4, 2 gives us 1000 of v_1 , 800 of v_2 , and 400 of v_3 , wasting 100 printed copies and 200 blank spaces, equivalent to 25 sheets or \$5. Further improvement requires more leftovers than remain.

The key: for an imperfect solution, no one p' is best for all versions. You have to use $p' = \max \left\{ \left\lceil \frac{q(v)}{f(v)} \right\rceil \mid v \in V \right\}$, which in turn tells us where to hand out leftovers.

3.4. The general case. At the top level, we hand the one-form solver at most U versions at a time (if we don't, you can easily have all f values zero. Poof: nontermination!) and accumulate the forms it returns until we've handled all the versions.

3.5. Code and testing. About the Python code for the imperfect case: we use the Python `heapq` package, which is almost what we want. Since it implements a “min heap” and we want a “max heap”, we keep the negative of the p' value in the heap and negate it at the end.

Testing turned up some bugs:

- The first version, which did the imperfect p' calculation in integer arithmetic, led to a division by zero when a small U was combined with widely varying quantities. We solved this by staying in floating point (and working around Python raising an exception rather than returning appropriately-signed infinity when dividing by zero).
- Still wider variation in quantities led to a situation with some zero f values even after distributing the leftovers. We handle that now by not putting the corresponding versions in the form.

We've yet to find a case in which adding a form reduces waste enough to make up for the setup costs of the additional form, as opposed to adding a form because we have no choice. Until we find such a case, we won't add code to try it.

Things that remain to be done:

- Testing, testing, testing. Test data from real life print jobs and the results of human estimators to compare against would be invaluable to exercise the code and suggest improvements.
- Refactoring as needed.
- Considering how best to return the solution, or possibly adding code to display the forms visually.
- Letting the caller pass in quantities in arbitrary order and returning a solution consistent with that ordering (i.e. sorting and then renumbering at the end).

```

from typing import List, Tuple
from math import ceil, inf
from heapq import heapify, heappop, heappushpop

def solve(q: List[int], u: int) -> Tuple[List[Dict[int, int]], List[int]:
    """The general case."""
    # preconditions: q is monotonically nonincreasing; all(qv > 0 for qv in q); u > 0
    F = [] # type: List[Dict[int, int]]
    p = [] # type: List[int]
    base = 0
    while base < len(q):
        f, pf = oneForm(q[base : base + min(len(q), u)], u)
        F.append(dict(zip((base + i for i in range(len(f))), f)))
        p.append(pf)
        base += len(f)
    return F, p

def oneForm(q: List[int], u: int):
    """Given q and U, return (f, p)."""
    # precondition: len(q) <= u and all(qv > 0 for qv in q)
    def pVal(qv: int, fv: int) -> Tuple[List[int], int]:
        return inf if fv == 0 else ceil(qv / fv)

    while True:
        idealP = sum(q) / u
        p = int(ceil(idealP))
        f = [float(qv // p) for qv in q]
        if p == idealP and all(qv % p == 0 for qv in q):
            break # perfect; we're done

        uncommitted = [] # type: List[int]
        pvHeap = list(zip((-pVal(qv, fv) for qv, fv in zip(q, f)), range(len(q))))
        heapify(pvHeap)
        p, v = heappop(pvHeap)
        for _ in range(u - int(sum(f))):
            uncommitted.append(v)
            f[v] += 1
            pNew, v = heappushpop(pvHeap, (-pVal(q[v], f[v]), v))
            if pNew > p:
                uncommitted = []
                p = pNew
        # Discard uncommitted leftovers.
        for v in uncommitted:
            f[v] -= 1
        if p != -inf:
            p = int(-p)
            break # for now, we'll call it good if it's feasible
        # Discard zeroes in f and corresponding q
        # TODO: add code to test our belief that the zeroes, if present, are
        # all at the end of f. Monotonicity of q *should* imply that, but...
        q, f = zip(*[x for x in zip(q, f) if x[1] != 0])

    return ([int(fv) for fv in f], p)

```

Appendix A. Notation

Predicate calculus. We use \Rightarrow for implication, and \forall and \exists for the universal (“for all”) and existential (“there exists”) quantifiers respectively.

Sets. We use upper case italic letters for sets, with some exceptions:

- \mathbb{N} , the set of natural numbers $\{0, 1, 2, 3, 4, \dots\}$

- \mathbb{Z} , the set of integers, and \mathbb{Z}^+ , the set of positive integers
- \mathbb{F} , the set of possible forms for a given job

Given a set S , $\|S\|$ is S 's cardinality (number of elements), and $\mathcal{P}(S) = \{S' | S' \subseteq S\}$ is the power set of S .

Functions. $f : A \rightarrow B$ means f is a function with domain A and codomain (aka “range”) B . If we’re defining a set of functions, as when we define forms, we give constraints the functions must meet. If we’re defining a particular function, we specify how to determine the element of the codomain corresponding to a given element of the domain.

If the domain and codomain are clear from context, we needn’t explicitly state them. For example, in the definition of forms, $u : \mathbb{F} \rightarrow \mathbb{Z}^+$ because u maps forms to necessarily positive (given the constraints on forms) sums of natural numbers.

We use \mapsto instead of lambda notation, e.g. $v \mapsto \left\lceil \frac{q(v)}{U} \right\rceil$ for the anonymous form in the maximum forms solution.

Given $f : X \rightarrow Y$, we define $f^{-1} : \mathcal{P}(Y) \rightarrow \mathcal{P}(X)$ as $f^{-1}(S) = \{x | f(x) \in S\}$ and the potentially confusing $f : \mathcal{P}(X) \rightarrow \mathcal{P}(Y)$ as $f[S] = \{f(s) | s \in S\}$. The latter maps subsets of X to their “images” under f . The brackets help distinguish the two; think of it as polymorphism, “map f ”, or the equivalent in your language of choice.

Some functions can be extended via folds to operate on sets of values as well as pairs of values, e.g. min, max, and gcd. In that case we will omit the parentheses, e.g. $\gcd \{q(v) | v \in V\}$ or, thanks to the preceding paragraph, $\gcd q[V]$.

Miscellanea.

- For $m, n \in \mathbb{Z}$, we write $m|n$ or $m \nmid n$ to indicate that m does (or doesn’t, respectively) divide n .
- $\lceil x \rceil$ is the “ceiling” of x , i.e. $\min \{z \in \mathbb{Z} | z \geq x\}$
- $\lfloor x \rfloor$ is the “floor” of x , i.e. $\max \{z \in \mathbb{Z} | z \leq x\}$

References

- [1] <https://github.com/edwja/gang-problem/gang.pdf>
- [2] PrintWiki, http://printwiki.org/Front_Page
- [3] PrintWiki, http://printwiki.org/Offset_Printing
- [4] PrintWiki, http://printwiki.org/Process_Color
- [5] https://en.wikipedia.org/wiki/Kronecker_delta
- [6] “Intro Platemaking”, <https://www.youtube.com/watch?v=7hNXFG1oi-Q&t=325s>
- [7] PrintWiki, <http://printwiki.org/Sheetwise>