### Reticular Action Model (RAM) Notation

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### Chapter 1

## Description

This is a collection of my personal notes on the Reticular Action Model (RAM) notation that accompanies the ramR package. You can install the released version of ramR from GitHub with:

remotes::install\_github("jeksterslab/ramR")

These notes are based on the following resources:

- Boker and McArdle (2005)
- McArdle and McDonald (1984)
- McArdle (2005)

See GitHub Pages for the html deployment.

### Chapter 2

# Reticular Action Model (RAM) Matrix Notation

$$\mathbf{v} = \mathbf{A}\mathbf{v} + \mathbf{u} \tag{2.1}$$

where

- $\mathbf{v}$  is a  $t \times 1$  vector of random variables
- $u_i$  represent the residual of  $v_i$
- A is a  $t \times t$  matrix of directed or asymmetric relationship from column variable  $v_i$  to row variable  $v_i$ 
  - regression of each of the t variables on the other t-1 variables
  - diagonal  $a_{i,i}$  is zero
  - if all regression coefficients on other variables are zero, then the variable  $v_i$  is considered the same as its own residual  $u_i$

$$\Omega = \mathbb{E}\left(\mathbf{u}\mathbf{u}'\right) \tag{2.2}$$

where

•  $\Omega$  is a  $t \times t$  matrix of undirected or symmetric relationship

$$\Sigma(\theta) = (\mathbf{I} - \mathbf{A})^{-1} \Omega \left[ (\mathbf{I} - \mathbf{A})^{-1} \right]^{\mathsf{T}}$$
(2.3)

•  $\Sigma\left(\theta\right)$  is a  $t \times t$  symmetric matrix of associations between  $v_{i}$  and  $v_{j}$ 

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$$\mathbf{v}^{\mathsf{T}} = \left[\mathbf{m}, \mathbf{l}\right]^{\mathsf{T}} \tag{2.4}$$

where

- $\mathbf{m}$  are observed or manifest variables of j components
- 1 are observed or manifest variables of k components
- t = j + k

$$\mathbf{F} = \left[ \mathbf{I}_i \colon \mathbf{O}_{i \times k} \right] \tag{2.5}$$

• the **F** matrix acts as a *filter* to select the manifest variables out of the full set of manifest and latent variables

### 2.1 Model-Implied Matrices

The model-implied mean vector  $\mu(\theta)$  as a function of Reticular Action Model (RAM) matrices is given by

$$\mu\left(\theta\right) = \mathbf{F} \left(\mathbf{I} - \mathbf{A}\right)^{-1} \mathbf{M}. \tag{2.6}$$

The ramR::mutheta() function can be used to derive the model-implied mean vector.

The model-implied variance-covariance matrix  $\Sigma(\theta)$  as a function of Reticular Action Model (RAM) matrices is given by

$$\Sigma\left(\theta\right) = \mathbf{F} \left(\mathbf{I} - \mathbf{A}\right)^{-1} \Omega \left[ \left(\mathbf{I} - \mathbf{A}\right)^{-1} \right]^{\mathsf{T}} \mathbf{F}^{\mathsf{T}}.$$
 (2.7)

The ramR::Sigmatheta() function can be used to derive the model-implied variance-covariance matrix.

### 2.2 Parameters

### 2.2.1 Mean Structure

$$\mathbf{M} = \left[\mathbf{F} \left(\mathbf{I} - \mathbf{A}\right)^{-1}\right]^{-1} \mu \left(\theta\right) \tag{2.8}$$

The ramR::M() function can be used to derive the mean structure vector.

### 2.2.2 Covariance Structure

$$\Omega = (\mathbf{I} - \mathbf{A}) \Sigma (\theta) (\mathbf{I} - \mathbf{A})^{\mathsf{T}}$$
(2.9)

The ramR::Omega() function can be used to derive the symmetric matrix  $\Omega.$ 

TODO: Figure out how to isolate the A matrix

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### Chapter 3

# Simple Regression

Let  $v_1$ ,  $v_2$ , and  $v_3$  be random variables whose associations are given by the regression equation

$$\begin{split} v_1 &= m_1 + a_{1,2}v_2 + v_3 \\ &= -3.951208 + 1.269259 \cdot v_2 + v_3. \end{split} \tag{3.1}$$

 $v_1$  and  $v_2$  are observed variables and  $v_3$  is a stochastic error term which is normally distributed around zero with constant variance across values of  $v_2$ 

$$v_3 \sim \mathcal{N}\left(m_3 = 0, \omega_{3,3} = 47.659854\right).$$
 (3.2)

 $v_2$  has a mean of  $m_2=13.038328$  and a variance of  $\omega_{2,2}=7.151261.$ 

### 3.0.1 Expectations

$$\begin{split} \mathbb{E}\left(v_{3}\right) &= m_{3} \\ &= 0 \end{split} \tag{3.3}$$

$$\begin{split} \mathbb{E}\left(v_{2}\right) &= m_{2} \\ &= 13.038328 \end{split} \tag{3.4}$$

$$\begin{split} \mathbb{E}\left(v_{1}\right) &= \mathbb{E}\left(m_{1} + a_{1,2}v_{2} + v_{3}\right) \\ &= \mathbb{E}\left(m_{1}\right) + \mathbb{E}\left(a_{1,2}v_{2}\right) + \mathbb{E}\left(v_{3}\right) \\ &= m_{1} + a_{1,2}\mathbb{E}\left(v_{2}\right) + 0 \\ &= m_{1} + a_{1,2}m_{2} \\ &= -3.951208 + 1.269259 \times 13.038328 \\ &= 12.5978072 \end{split} \tag{3.5}$$

$$\mathbb{E}\left(\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}\right) = \begin{bmatrix} m_1 + a_{1,2}m_2 \\ m_2 \\ m_3 \end{bmatrix} \\
= \begin{bmatrix} 12.5978072 \\ 13.038328 \\ 0 \end{bmatrix}$$
(3.6)

$$Cov(v_3, v_3) = Var(v_3)$$
  
=  $\omega_{3,3}$  (3.7)  
=  $47.659854$ 

$$\begin{aligned} &\operatorname{Cov}\left(v_{1},v_{3}\right) = \operatorname{Cov}\left(a_{1,2}v_{2} + v_{3},v_{3}\right) \\ &= \operatorname{Cov}\left(a_{1,2}v_{2},v_{3}\right) + \operatorname{Cov}\left(v_{3},v_{3}\right) \\ &= a_{1,2}^{2}\operatorname{Cov}\left(v_{2},v_{3}\right) + \operatorname{Var}\left(v_{3}\right) \\ &= a_{1,2}^{2} \cdot 0 + \omega_{3,3} \\ &= 0 + \omega_{3,3} \\ &= \omega_{3,3} \\ &= 47.659854 \end{aligned} \tag{3.8}$$

$$Cov\left(v_{2}, v_{3}\right) = 0\tag{3.9}$$

$$\begin{aligned} \operatorname{Cov}\left(v_{1},v_{1}\right) &= \operatorname{Cov}\left(a_{1,2}v_{2} + v_{3}, a_{1,2}v_{2} + v_{3}\right) \\ &= \operatorname{Cov}\left(a_{1,2}v_{2}, a_{1,2}v_{2}\right) + \operatorname{Cov}\left(a_{1,2}v_{2}, v_{3}\right) + \operatorname{Cov}\left(a_{1,2}v_{2}, v_{3}\right) + \operatorname{Cov}\left(v_{3}, v_{3}\right) \\ &= a_{1,2}^{2}\operatorname{Cov}\left(v_{2}, v_{2}\right) + a_{1,2}\operatorname{Cov}\left(v_{2}, v_{3}\right) + a_{1,2}\operatorname{Cov}\left(v_{2}, v_{3}\right) + \operatorname{Var}\left(v_{3}\right) \\ &= a_{1,2}^{2}\operatorname{Var}\left(v_{2}\right) + a_{1,2} \cdot 0 + a_{1,2} \cdot 0 + \omega_{3,3} \\ &= a_{1,2}^{2}\operatorname{Var}\left(v_{2}\right) + 0 + 0 + \omega_{3,3} \\ &= a_{1,2}^{2}\omega_{2,2} + \omega_{3,3} \\ &= 1.269259^{2} \times 7.151261 + 47.659854 \\ &= 59.1806671 \end{aligned} \tag{3.10}$$

$$\begin{aligned} &\operatorname{Cov}\left(v_{2},v_{1}\right) = \operatorname{Cov}\left(v_{2},a_{1,2}v_{2} + v_{3}\right) \\ &= \operatorname{Cov}\left(v_{2},a_{1,2}v_{2}\right) + \operatorname{Cov}\left(v_{2},v_{3}\right) \\ &= a_{1,2}\operatorname{Cov}\left(v_{2},v_{2}\right) + 0 \\ &= a_{1,2}\operatorname{Var}\left(v_{2}\right) \\ &= a_{1,2}\omega_{2,2} \\ &= 1.269259 \times 7.151261 \\ &= 9.0768024 \end{aligned} \tag{3.11}$$

$$\begin{split} \operatorname{Cov}\left(v_{2},v_{2}\right) &= \operatorname{Var}\left(v_{2}\right) \\ &= \omega_{2,2} \\ &= 7.151261 \end{split} \tag{3.12}$$

$$\operatorname{Cov}\left(\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}\right) = \begin{bmatrix} a_{1,2}^2 \omega_{2,2} + \omega_{3,3} & a_{1,2} \omega_{2,2} & \omega_{3,3} \\ a_{1,2} \omega_{2,2} & \omega_{2,2} & 0 \\ \omega_{3,3} & 0 & \omega_{3,3} \end{bmatrix} \\
= \begin{bmatrix} 59.1806671 & 9.0768024 & 47.659854 \\ 9.0768024 & 7.151261 & 0 \\ 47.659854 & 0 & 47.659854 \end{bmatrix}$$
(3.13)

Below are two ways of specifying this model. The first specification includes the error term  $v_3$  as a latent variable. The second specification only includes the observed variables.

# 3.1 Specification 1 - Includes Error Term as a Latent Variable

#### 3.1.1 Matrix Notation

$$\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \tag{3.14}$$

$$\mathbf{A} = \begin{bmatrix} 0 & a_{1,2} & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1.269259 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$
(3.15)

$$\Omega = \begin{bmatrix}
0 & 0 & 0 \\
0 & \omega_{2,2} & 0 \\
0 & 0 & \omega_{3,3}
\end{bmatrix} 
= \begin{bmatrix}
0 & 0 & 0 \\
0 & 7.151261 & 0 \\
0 & 0 & 47.659854
\end{bmatrix}$$
(3.16)

$$\mathbf{M} = \begin{bmatrix} m_1 \\ m_2 \\ m_3 \end{bmatrix}$$

$$= \begin{bmatrix} -3.951208 \\ 13.038328 \\ 0 \end{bmatrix}$$
(3.17)

To filter the observed variables, use the following filter matrix

$$\mathbf{F} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}. \tag{3.18}$$

To include all variables, use the following filter matrix

$$\mathbf{F} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} . \tag{3.19}$$

#### 3.1. SPECIFICATION 1 - INCLUDES ERROR TERM AS A LATENT VARIABLE15

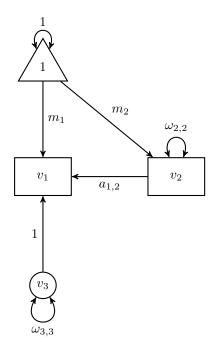


Figure 3.1: The Simple Linear Regression Model (with  $v_3$ )

Table 3.1:  $\mu(\theta)$ 

	$\mu$
$v_1$	12.59781
$v_2$	13.03833
$\overline{v_3}$	0.00000

### 3.1.1.1 Using the ramR Package

```
knitr::kable(
  ramR::mutheta(
    M = M,
    A = A,
    filter = filter
),
  col.names = "$\\boldsymbol{\\mu}$",
  caption = "$\\boldsymbol{\\mu} \\left( \\boldsymbol{\\theta} \\right)$",
  escape = FALSE
)
```

Table 3.2:  $\Sigma(\theta)$ 

	$v_1$	$v_2$	$v_3$
$v_1$	59.180667	9.076802	47.65985
$v_2$	9.076802	7.151261	0.00000
$\overline{v_3}$	47.659854	0.000000	47.65985

```
knitr::kable(
  ramR::Sigmatheta(
    A = A,
    Omega = Omega,
    filter = filter
),
  caption = "$\\boldsymbol{\\Sigma} \\left( \\boldsymbol{\\theta} \\right)$",
  escape = FALSE
)
```

### 3.2 Specification 2 - Observed Variables

### 3.2.1 Matrix Notation

$$\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \tag{3.20}$$

$$\mathbf{A} = \begin{bmatrix} 0 & a_{1,2} \\ 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1.269259 \\ 0 & 0 \end{bmatrix}$$
(3.21)

$$\Omega = \begin{bmatrix} \omega_{1,1} & 0 \\ 0 & \omega_{2,2} \end{bmatrix} \\
= \begin{bmatrix} 47.659854 & 0 \\ 0 & 7.151261 \end{bmatrix}$$
(3.22)

$$\mathbf{M} = \begin{bmatrix} m_1 \\ m_2 \end{bmatrix}$$

$$= \begin{bmatrix} -3.951208 \\ 13.038328 \end{bmatrix}$$
(3.23)

Table 3.3:  $\mu(\theta)$ 

	$\mu$
$v_1$	12.59781
$v_2$	13.03833

$$\mathbf{F} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \tag{3.24}$$

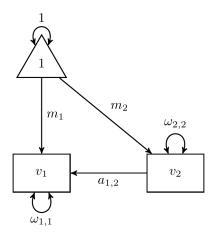


Figure 3.2: The Simple Linear Regression Model (without  $v_3$ )

### 3.2.1.1 Using the ram() Package

```
knitr::kable(
  ramR::mutheta(
    M = M,
    A = A,
    filter = filter
),
  col.names = "$\\boldsymbol{\\mu}$",
  caption = "$\\boldsymbol{\\mu} \\left( \\boldsymbol{\\theta} \\right)$",
  escape = FALSE
)
```

Table 3.4:  $\Sigma(\theta)$ 

	$v_1$	$v_2$
$\overline{v_1}$	59.180667	9.076802
$v_2$	9.076802	7.151261

```
knitr::kable(
  ramR::Sigmatheta(
    A = A,
    Omega = Omega,
    filter = filter
),
  caption = "$\\boldsymbol{\\Sigma} \\left( \\boldsymbol{\\theta} \\right)$",
  escape = FALSE
)
```

# Bibliography

- Boker, S. M. and McArdle, J. J. (2005). Path analysis and path diagrams. In Everitt, B. S. and Howell, D. C., editors, *Encyclopedia of Statistics in Behavioral Science*, pages 1529–1531. John Wiley & Sons, Ltd, Chichester, UK.
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