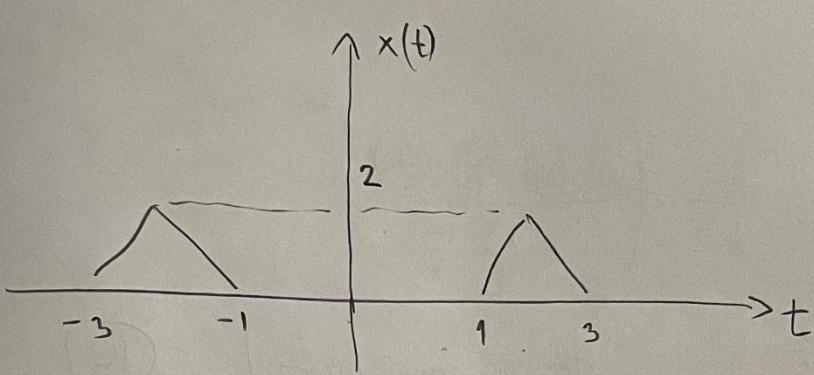


①

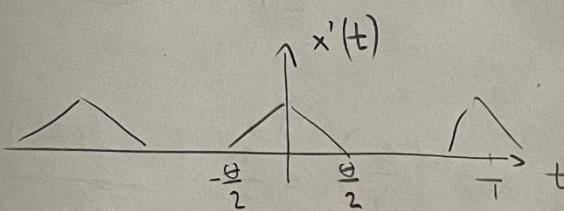


$$T = 4 \text{ ms}$$

$$\Theta = 2 \text{ ms}$$

$$\omega = \frac{\Theta}{T} = \frac{1}{2}$$

$$N = \frac{2}{\omega} = 4$$



$$x'(t) = \frac{a_0}{2} + \sum_{n=1}^{+\infty} a_n \cdot \cos(n\omega t) + \sum_{n=1}^{+\infty} b_n \cdot \sin(n\omega t) \quad ②$$

$$b_n = 0 \quad ①$$

$$a_n = \frac{2}{T} \int_{-\frac{T}{2}}^{\frac{T}{2}} x'(t) \cdot \cos(n\omega t) dt = \frac{2}{T} \int_{-\frac{\Theta}{2}}^{\frac{\Theta}{2}} x'(t) \cdot \cos(n\omega t) dt = \frac{4}{\Theta} \int_0^{\frac{\Theta}{2}} x'(t) \cos(n\omega t) dt$$

$$1^{\circ} (0, A) \quad > \quad x' = -\frac{2A}{\Theta} \left(t - \frac{\Theta}{2} \right) = -\frac{2A}{\Theta} t + A$$

$$2^{\circ} \left(\frac{\Theta}{2}, 0 \right)$$

$$a_n = \frac{4}{\Theta} \int_0^{\frac{\Theta}{2}} \left(-\frac{2A}{\Theta} t + A \right) \cos(n\omega t) dt = -\frac{8A}{\Theta T} \int_0^{\frac{\Theta}{2}} t \cos(n\omega t) dt + \frac{4A}{\Theta T} \int_0^{\frac{\Theta}{2}} \cos(n\omega t) dt$$

$\left| \begin{array}{l} u = t \quad dv = \cos(n\omega t) dt \\ du = dt \quad v = \frac{1}{n\omega} \cdot \sin(n\omega t) \end{array} \right.$

$$= -\frac{8A}{\Theta T} \cdot \left[\frac{t}{n\omega} \cdot \sin(n\omega t) + \frac{1}{(n\omega)^2} \cdot \cos(n\omega t) \right] \Big|_0^{\frac{\Theta}{2}} + \frac{4A}{n\omega \cdot T} \cdot \sin(n\omega t) \Big|_0^{\frac{\Theta}{2}} =$$

$$= -\frac{8A}{\Theta T} \left[\frac{\Theta}{2n\omega} \cdot \sin(n\omega \cdot \frac{\Theta}{2}) + \frac{1}{(n\omega)^2} \left(\cos(n\omega \cdot \frac{\Theta}{2}) - 1 \right) \right] + \frac{4A}{n\omega \cdot T} \cdot \sin(n\omega \cdot \frac{\Theta}{2}) =$$

$$= -\frac{4A}{n\omega \cdot T} \cdot \sin(n\omega \cdot \frac{\Theta}{2}) + \frac{8A}{\Theta \cdot T \cdot (n\omega)^2} \left(1 - \cos(n\omega \cdot \frac{\Theta}{2}) \right) + \frac{4A}{n\omega \cdot T} \cdot \sin(n\omega \cdot \frac{\Theta}{2}) =$$

$$= \frac{8A}{\Theta \cdot T \cdot (n\omega)^2} \cdot 2 \cdot \sin^2(n\omega \cdot \frac{\Theta}{2}) = \frac{16A}{\Theta \cdot T} \cdot \frac{\sin^2(n\omega \cdot \frac{\Theta}{2})}{(n\omega)^2} \cdot \frac{\Theta}{16} \cdot \frac{16}{\Theta} =$$

$$= \frac{A\Theta}{T} \cdot \left(\frac{\sin(n\omega_0 \frac{\Theta}{n})}{n\omega_0 \frac{\Theta}{n}} \right)^2$$

$$\underline{F_u}' = \frac{am - bn}{2} = \frac{am}{2} = \frac{A\Theta}{2T} \cdot \left(\frac{\sin(n \cdot \frac{2\pi}{T_0} \cdot \frac{\Theta}{4})}{n \cdot \frac{2\pi}{T_0} \cdot \frac{\Theta}{4}} \right)^2 =$$

$$= \frac{A\omega}{2} \cdot \left(\frac{\sin(n\omega \frac{1}{2})}{n\omega \frac{1}{2}} \right)^2 = \frac{A\omega}{2} \cdot \sin^2\left(n \frac{1}{2}\right) \quad (10)$$

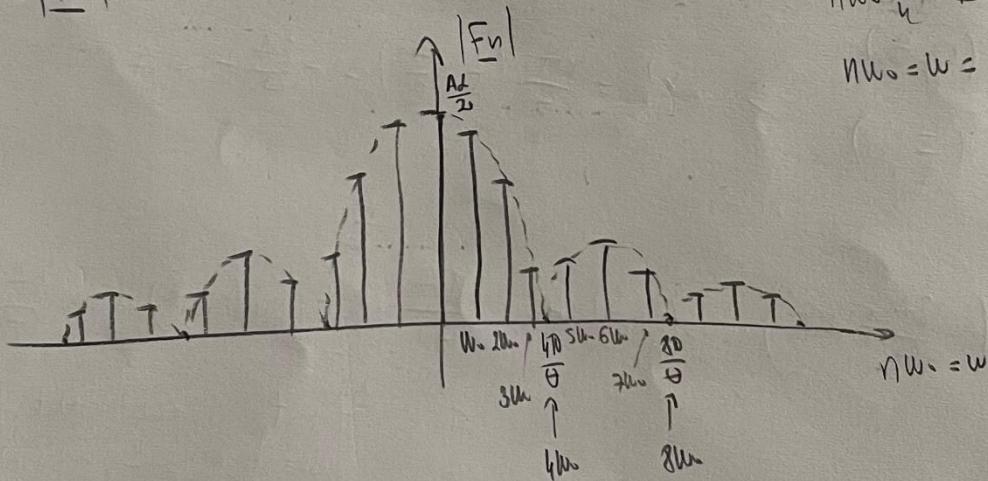
$$\left. \begin{array}{l} L = \frac{1}{2} \\ A = 2 \end{array} \right\} \Rightarrow \underline{F_u}' = \frac{1}{2} \cdot \sin^2\left(\frac{n}{4}\right) = \frac{1}{2} \cdot \left(\frac{\sin(n\pi/4)}{n\pi/4} \right)^2$$

$$\underline{F_u} = \underline{F_u}' \cdot e^{-jn\omega_0 t_0} = \frac{A\omega}{2} \cdot \sin^2\left(n \frac{1}{2}\right) \cdot e^{-jn\omega_0 t_0} \quad (5)$$

$t_0 = 2 \text{ ms}$

$$|\underline{F_u}'| = |\underline{F_u}|$$

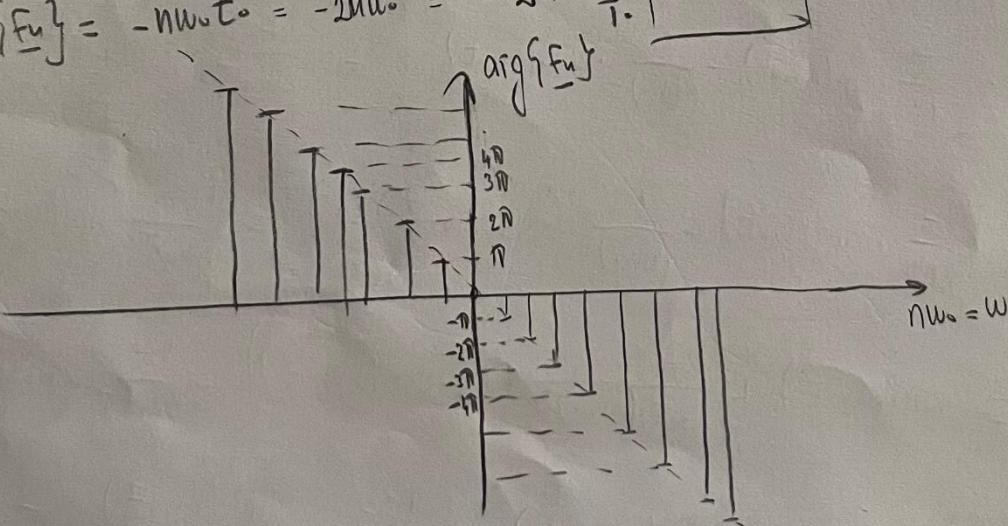
(5)



$$\begin{aligned} n\omega_0 &= \omega = \frac{4\pi}{\Theta} \cdot k = \frac{4\pi}{T} \cdot \frac{1}{\Theta} \cdot k = \\ &= 2\omega_0 \cdot \frac{1}{2} \cdot k = \\ &= 4\omega_0 \cdot k \end{aligned}$$

$$\arg\{\underline{F_u}\} = -n\omega_0 t_0 = -2n\omega_0 = -2n \cdot \frac{2\pi}{T} = -\frac{4\pi}{T} \quad (5)$$

(5)



$$F_0 = \frac{AL}{2} = \frac{1}{2}$$

$$F_1 = \frac{AL}{2} \cdot \frac{8\sin^2(\frac{\pi}{4})}{(\frac{\pi}{4})^2} = \frac{1}{2} \cdot \frac{\frac{1}{2}}{\frac{\pi^2}{16}} = \frac{4}{\pi^2}$$

$$F_2 = \frac{AL}{2} \cdot \frac{8\sin^2(\frac{\pi}{2})}{(\frac{\pi}{2})^2} = \frac{1}{2} \cdot \frac{1}{\frac{\pi^2}{4}} = \frac{2}{\pi^2}$$

$$F_3 = \frac{AL}{2} \cdot \frac{8\sin^2(\frac{3\pi}{4})}{(\frac{3\pi}{4})^2} = \frac{1}{2} \cdot \frac{\frac{1}{2}}{\frac{9\pi^2}{16}} = \frac{4}{9\pi^2}$$

$$P' = |F_0|^2 + 2(|F_1|^2 + |F_2|^2 + |F_3|^2) =$$

$$= \frac{1}{4} + 2\left(\frac{16}{\pi^4} + \frac{4}{\pi^4} + \frac{16}{81\pi^4}\right) =$$

$$= \frac{1}{4} + 2\left(\frac{20}{\pi^4} + \frac{16}{81\pi^4}\right) = \frac{1}{4} + 2 \cdot \frac{1636}{81\pi^4} =$$

$$= \frac{1}{4} + \frac{3272}{81\pi^4} \quad \boxed{0,6646 [V^2]} \quad (3)$$

$$P' = \frac{1}{T} \int_{-\frac{\Theta}{2}}^{\frac{\Theta}{2}} x'^2(t) dt = \frac{1}{T} \int_{-\frac{\Theta}{2}}^{\frac{\Theta}{2}} x'^2(t) dt = \frac{2}{T} \int_0^{\frac{\Theta}{2}} x'^2(t) dt = \frac{2}{T} \int_0^{\frac{\Theta}{2}} (-\frac{2A}{\Theta}t + A)^2 dt =$$

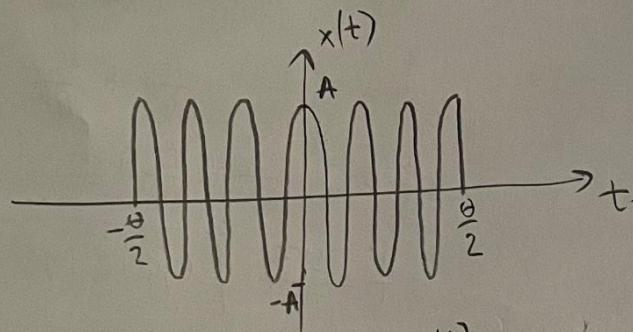
$$= \frac{2}{T} \int_0^{\frac{\Theta}{2}} \left(A^2 - \frac{4A^2}{\Theta}t + \frac{4A^2}{\Theta^2}t^2 \right) dt = \frac{2}{T} \cdot \left[A^2 \cdot t \Big|_0^{\frac{\Theta}{2}} - \frac{2A^2}{\Theta} \cdot t^2 \Big|_0^{\frac{\Theta}{2}} + \frac{4A^2}{3\Theta^2} \cdot t^3 \Big|_0^{\frac{\Theta}{2}} \right] =$$

$$= \frac{2}{T} \cdot \left[\cancel{\frac{A^2\Theta}{2}} - \cancel{\frac{A^2\Theta}{2}} + \frac{A^2\Theta}{6} \right] = \frac{A^2\Theta}{3T} \left[\cancel{\frac{A^2\Delta}{3}} \right] \boxed{= \frac{2}{3} = 0,667 [V^2]} \quad (3)$$

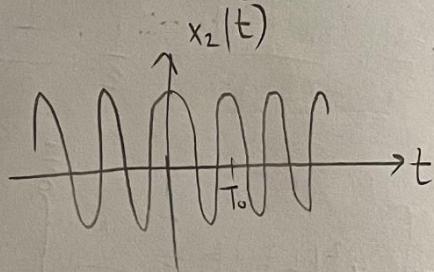
$$\eta = \frac{P'}{P} = \frac{0,6646}{0,667} \quad \boxed{\neq 0,996 = 99,6\%} \quad (1)$$

2.

a)



$$x(t) = \begin{cases} A & \text{for } -\frac{\Theta}{2} \leq t < \frac{\Theta}{2} \\ -A & \text{otherwise} \end{cases}$$



$$X_{1n} = \frac{A\Theta}{T} \cdot \frac{\sin(n\omega_0 \frac{\Theta}{2})}{n\omega_0 \frac{\Theta}{2}}$$

$$X_1(j\omega) = \lim_{T \rightarrow \infty} T \cdot X_{1n} = A\Theta \cdot \frac{\sin(\omega \frac{\Theta}{2})}{\omega \frac{\Theta}{2}}$$

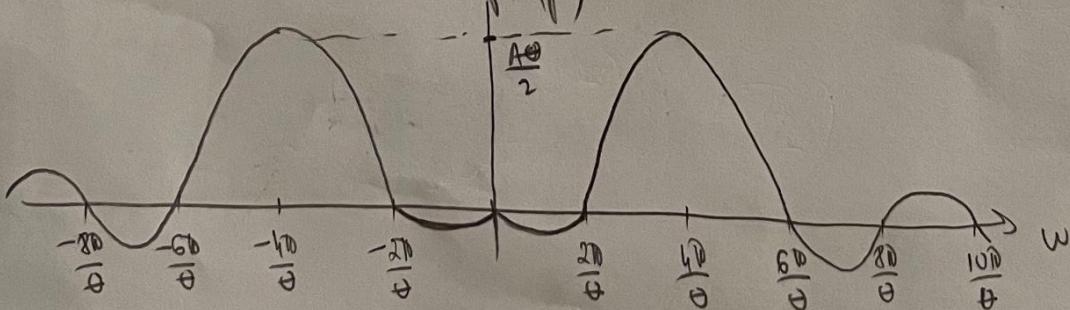
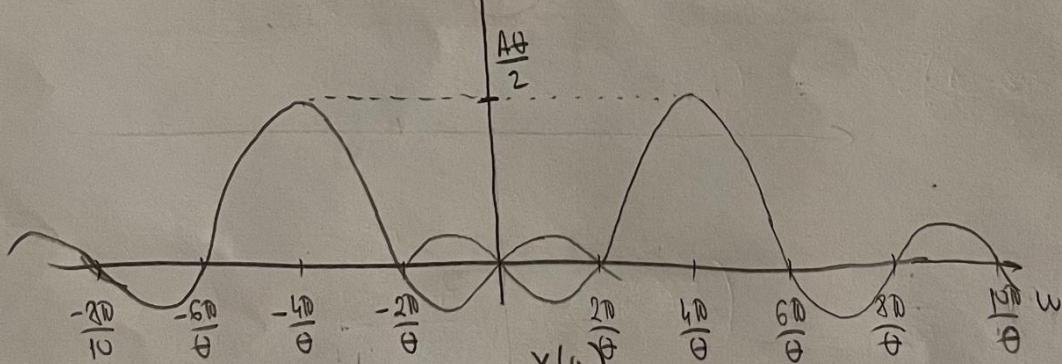
Hence: $\omega \frac{\Theta}{2} = k\pi$
 $(\omega = \frac{2\pi}{\Theta} \cdot k)$

$$\begin{aligned} x(t) &= x_1(t) - \cos(\omega_0 t) = x_1(t) - \frac{1}{2} (e^{j\omega_0 t} + e^{-j\omega_0 t}) \\ &= \frac{1}{2} x_1(t) e^{j\omega_0 t} + \frac{1}{2} x_1(t) e^{-j\omega_0 t} \end{aligned} \quad (5)$$

$$X(j\omega) = \frac{1}{2} X_1(\omega - \omega_0) + \frac{1}{2} X_1(\omega + \omega_0)$$

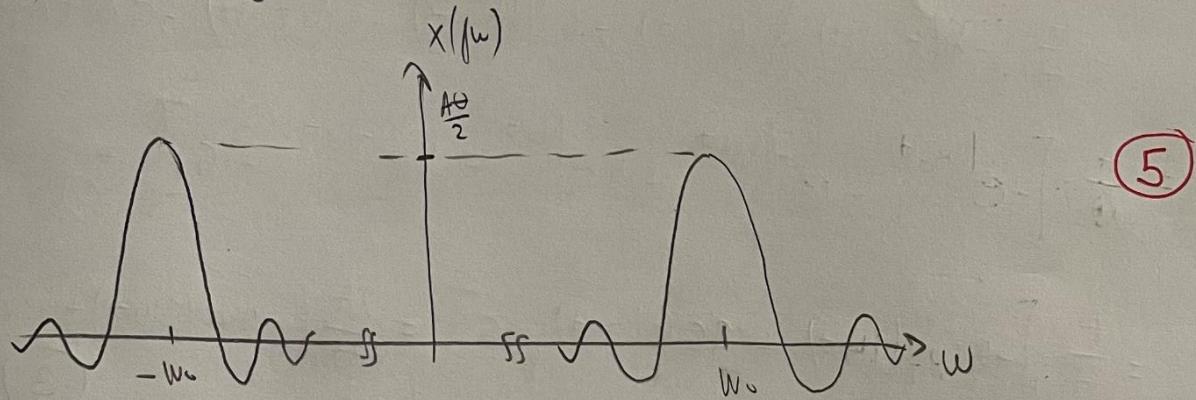
$$\text{i)} \omega_0 = \frac{4\pi}{\Theta}$$

$$X(j\omega)$$

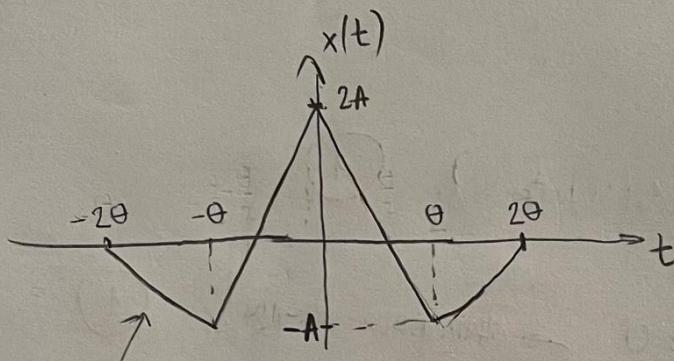


(5)

$$\text{ii) } \omega_0 > \frac{2\pi}{\theta}$$



5)



$$1^{\circ} (-2\theta, 0)$$

$$(-\theta, -A)$$

$$2^{\circ} (-\theta, -A)$$

$$(0, 2A)$$

$$x_1 = \frac{-A}{\theta} (t + 2\theta) = -\frac{A}{\theta} t - 2A$$

$$x_1 + A = \frac{3A}{\theta} (t + \theta) = \frac{3A}{\theta} t + 2A$$

$$3^{\circ} (0, 2A)$$

$$(\theta, -A)$$

$$x_1 + A = \frac{-3A}{\theta} (t - \theta) = -\frac{3A}{\theta} t + 2A$$

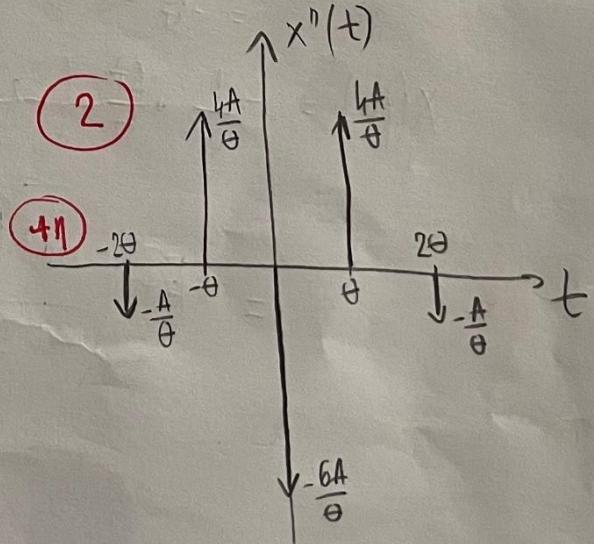
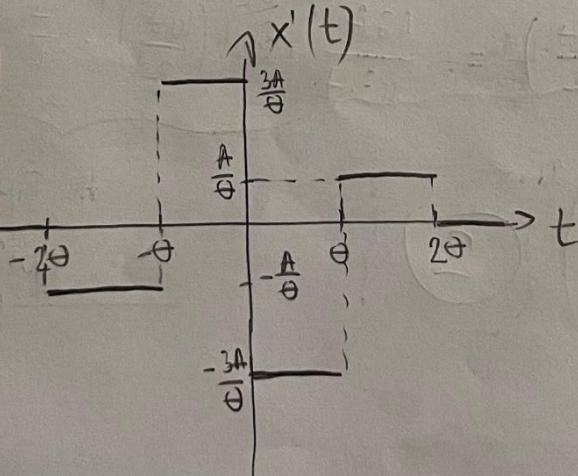
$$4^{\circ} (\theta, -A)$$

$$(2\theta, 0)$$

$$x_1 = \frac{-A}{\theta} (t - 2\theta) = \frac{A}{\theta} t - 2A$$

(2)

(+1)



$$x''(t) = x_2(t) = -\frac{A}{\Theta} \cdot \delta(t+2\Theta) + \frac{4A}{\Theta} \delta(t+\Theta) - \frac{6A}{\Theta} \cdot \delta(t) + \frac{4A}{\Theta} \cdot \delta(t-\Theta) - \frac{A}{\Theta} \cdot \delta(t-2\Theta)$$

$$= \frac{A}{\Theta} \left[-\delta(t+2\Theta) - \delta(t-2\Theta) + 4\delta(t+\Theta) + 4\delta(t-\Theta) - 6\delta(t) \right]$$

$$X_2(j\omega) = \frac{A}{\Theta} \cdot \left[-e^{j\omega 2\Theta} - e^{-j\omega 2\Theta} + 4e^{j\omega \Theta} + 4e^{-j\omega \Theta} - 6 \right] =$$

$$= \frac{A}{\Theta} \left[-2\cos(2\omega\Theta) + 8\cos(\omega\Theta) - 6 \right] = \frac{2A}{\Theta} \left(-\cos(2\omega\Theta) + 4\cos(\omega\Theta) - 3 \right) \quad (3)$$

$$x_2(0) = 0 \quad (1)$$

$$X_1(j\omega) = \frac{1}{j\omega} \cdot X_2(j\omega) \quad (1)$$

$$X(j\omega) = \frac{1}{j\omega} \cdot X_1(j\omega) + D \cdot x_1(0) \cdot \delta(j\omega) \quad (1)$$

$$X_1(0) = \int_{-\infty}^{\infty} x_1(t) dt = 0 \rightarrow \text{Неважка}\ \delta(j\omega)! \quad (1)$$

$$\Rightarrow X(j\omega) = \frac{1}{(j\omega)^2} \cdot X_2(j\omega) = -\frac{1}{\omega^2} \cdot \frac{2A}{\Theta} \left(-\cos(2\omega\Theta) + 4\cos(\omega\Theta) - 3 \right) \quad (2)$$

$$\cos 2x = \cos^2 x - \sin^2 x = 2\cos^2 x - 1$$

$$-\cos 2x + 4\cos x - 3 = 1 - 2\cos^2 x + 4\cos x - 3 = -2\cos^2 x + 4\cos x - 2 =$$

$$= -2(\cos^2 x - 2\cos x + 1) = -2 \cdot (1 - \cos x)^2 = -2 \cdot \left(2 \cdot \sin^2 \frac{x}{2}\right)^2 =$$

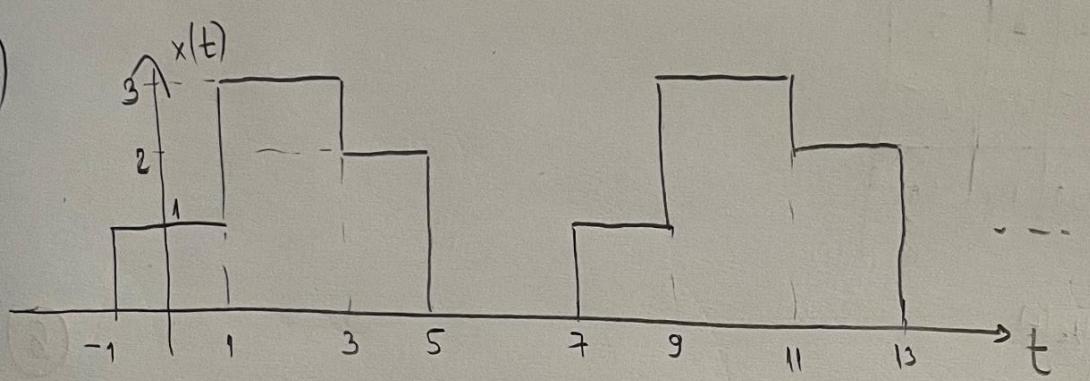
$$= -8 \cdot \sin^4 \frac{x}{2}$$

$$X(j\omega) = -\frac{1}{\omega^2} \cdot \frac{2A}{\Theta} \cdot \left(-8 \cdot \sin^4 \frac{\omega\Theta}{2} \right) = \frac{16A}{\omega^2 \cdot \Theta} \cdot \underbrace{\sin^4 \left(\frac{\omega\Theta}{2} \right)}_{\text{не тупеда}} \cdot \underbrace{\frac{\Theta}{4} \cdot \frac{4}{\Theta}}_{\text{среднебольшое}} =$$

$$= 4A\Theta \cdot \left(\frac{\sin^2 \left(\frac{\omega\Theta}{2} \right)}{\frac{\omega\Theta}{2}} \right)^2 \quad (2)$$

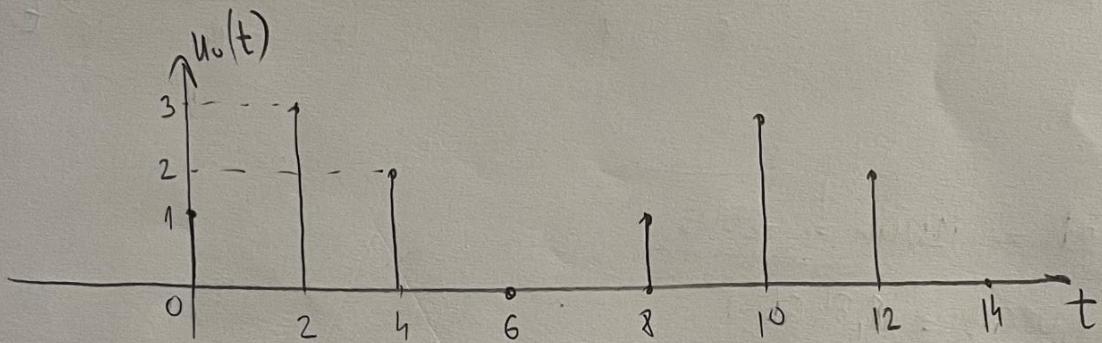
не тупеда
среднебольшое

3.) a)



$$T_S = 2s$$

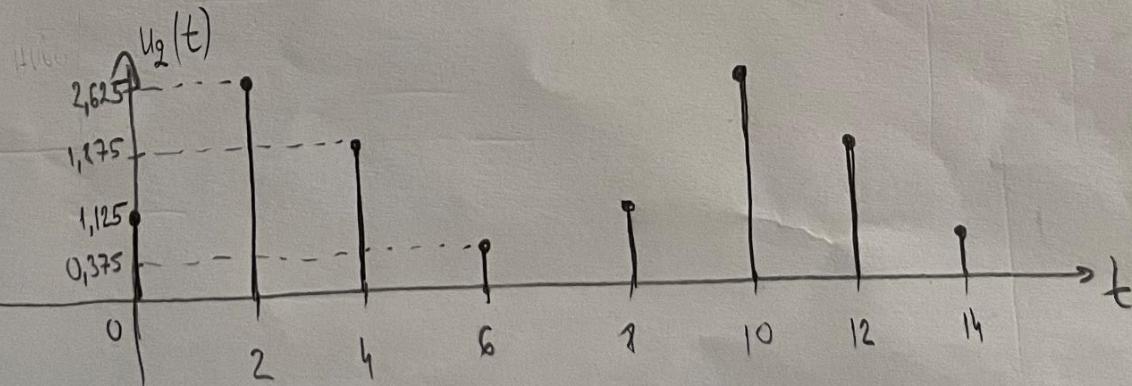
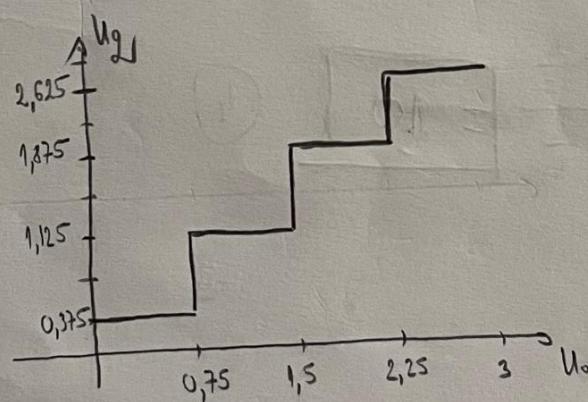
(6)



$$\Delta = 0,75V$$

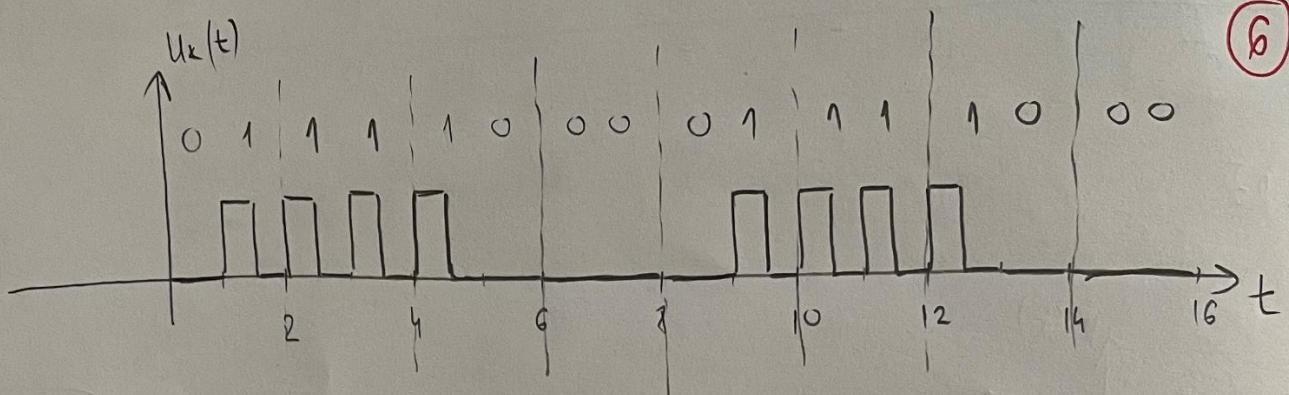
$$\Delta = \frac{x_{\max} - x_{\min}}{2} = \frac{3 - 0}{2} = \frac{3}{2} \Rightarrow 2 = \frac{3}{0,75} \boxed{= 4} \quad \boxed{1} \Rightarrow \boxed{u = 2}$$

(6)



(6)

Hibu	0	1	2	3
amün.	0,375	1,125	1,875	2,625
Kodifier pufex	00	01	10	11



$$b) \quad t = 2h = 120 \text{ min} \neq 7200 \text{ s}$$

$$J = 1,08 \text{ GB} = 8,64 \text{ Gb}$$

$$\mathcal{V}_b' = \frac{J}{t} = \frac{8,64 \cdot 10^9 \text{ b}}{7,2 \cdot 10^3 \text{ s}} = 1,2 \frac{\text{Mb}}{\text{s}}$$

$$\mathcal{V}_b' = 1,25 \mathcal{V}_b \Rightarrow \mathcal{V}_b = \frac{\mathcal{V}_b'}{1,25} = 0,96 \frac{\text{Mb}}{\text{s}}$$

$$f_0 = 48 \cdot 10^3 \text{ Hz}$$

$$n = \frac{\mathcal{V}_b}{2 \cdot f_0} = \frac{960 \cdot 10^3 \frac{\text{b}}{\text{s}}}{2 \cdot 48 \cdot 10^3 \frac{1}{\text{s}}} = 10$$