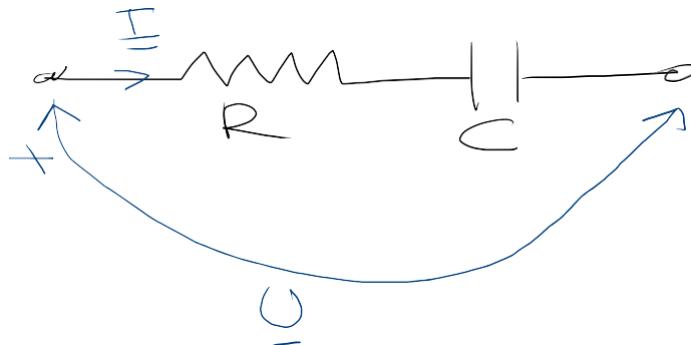


Рјешавање сложених кола у комплексном домену.

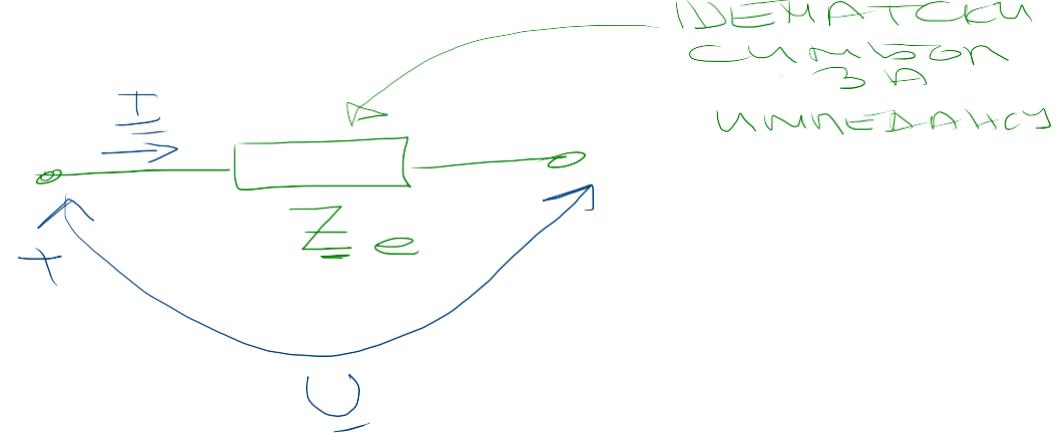
Основи електротехнике 2
Предавање: 9. блок

ЧАСТОТНЫЕ ПАРАМЕТРЫ МОСТА НА АЧИВАНИЯ ЭЛЕМЕНТА

1. параллельная схема



\equiv



IDEATSKA
СУММА
ЗАДАЧ
ИМПЕДАНС

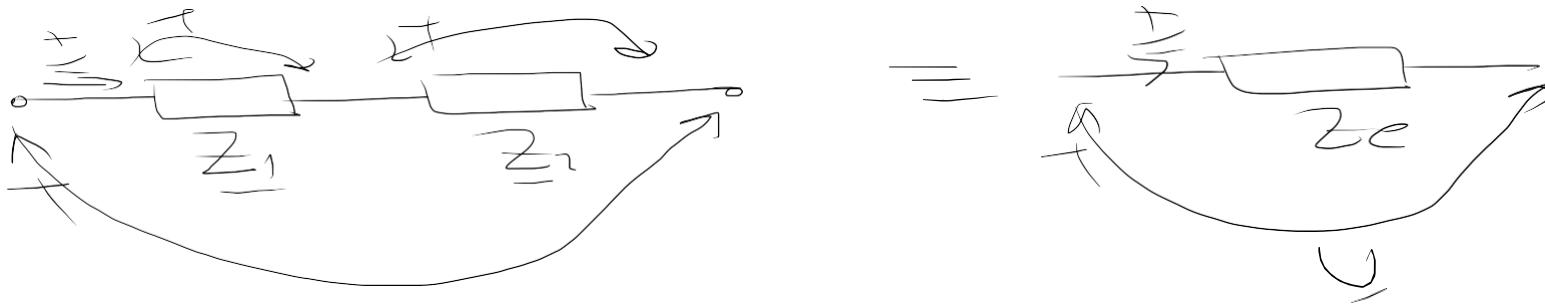
$$U = R \underline{I} + \frac{1}{j\omega C} \underline{I} = \underline{Z}_e \cdot \underline{I}$$

$$\underline{Z}_e = R + \frac{1}{j\omega C} = R - j \frac{1}{\omega C} = \sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2} e^{-j \arctg \frac{1}{\omega C}}$$

$$= \sqrt{R^2 + \left(\frac{1}{\omega C}\right)^2} e^{-j \arctg \frac{1}{\omega C}}$$

\underline{Z}_e

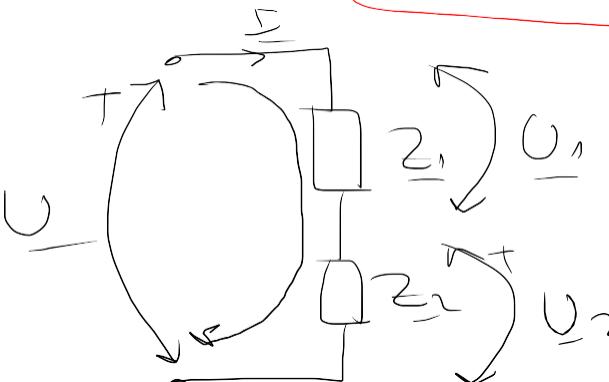
$$\phi_e = -\arctg \frac{1}{\omega C}$$



$$U = \underline{Z}_1 \cdot \underline{I} + \underline{Z}_2 \cdot \underline{I} = \underline{Z}_c \cdot \underline{I} \Rightarrow \boxed{\underline{Z}_c = \underline{Z}_1 + \underline{Z}_2}$$

$$\boxed{\underline{Z}_1 \oplus \underline{Z}_2 = \underline{Z}_1 + \underline{Z}_2}$$

$$\boxed{\underline{Z}_c = \sum_{k=1}^n \underline{Z}_k}$$

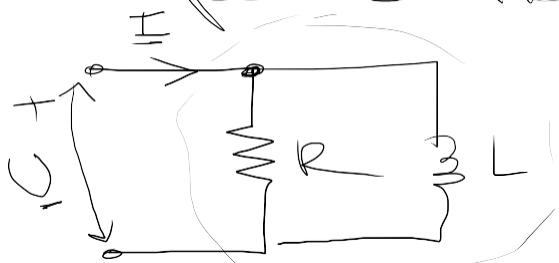


Wektorielle
Parallelschaltung

$$\begin{aligned} U &= U_1 + U_2 && \text{3a H} \\ U_1 &= \underline{Z}_1 \cdot \underline{I} && \text{umgekehrt} \\ U_2 &= \underline{Z}_2 \cdot \underline{I} \end{aligned}$$

$$\begin{aligned} U &= (\underline{Z}_1 + \underline{Z}_2) \cdot \underline{I} \Rightarrow \underline{I} = \frac{U}{\underline{Z}_1 + \underline{Z}_2} \\ U_1 &= \frac{\underline{Z}_1}{\underline{Z}_1 + \underline{Z}_2} U \\ U_2 &= \frac{\underline{Z}_2}{\underline{Z}_1 + \underline{Z}_2} U \end{aligned}$$

→ dieparanenken löschen



$$\underline{I} = \underline{I}_R + \underline{I}_L$$

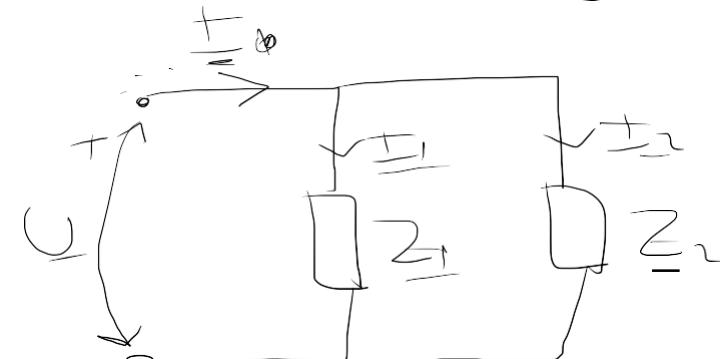
$$\underline{I}_R = \frac{\underline{U}}{R} \quad \underline{I}_L = \frac{\underline{U}}{j\omega L}$$

$$\underline{I} = \frac{\underline{U}}{R} + \frac{\underline{U}}{j\omega L} = \underline{U} \frac{R + j\omega L}{j\omega L \cdot R}$$



$$\underline{U} = \frac{R \cdot j\omega L}{R + j\omega L} \quad \underline{I} = Z_e \cdot \underline{I}$$

$$Z_e = \frac{R \cdot j\omega L}{R + j\omega L}$$



$$\underline{I} = \underline{I}_1 + \underline{I}_2 = \frac{\underline{U}}{Z_1} + \frac{\underline{U}}{Z_2} = \underline{U} \frac{Z_1 + Z_2}{Z_1 \cdot Z_2}$$

$$\underline{I} = \frac{\underline{U}}{Z_e}$$

$$\Rightarrow Z_e = \frac{Z_1 \cdot Z_2}{Z_1 + Z_2}$$

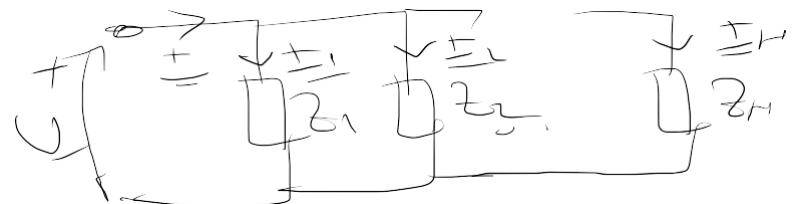
$Z_1 \parallel Z_2$

Gesuchtes Programm:

$$\underline{I}_1 = \frac{Z_2}{Z_1 + Z_2} \cdot \underline{I}$$

$$\underline{I}_2 = \frac{Z_1}{Z_1 + Z_2} \cdot \underline{I}$$

За A непарома берасць:

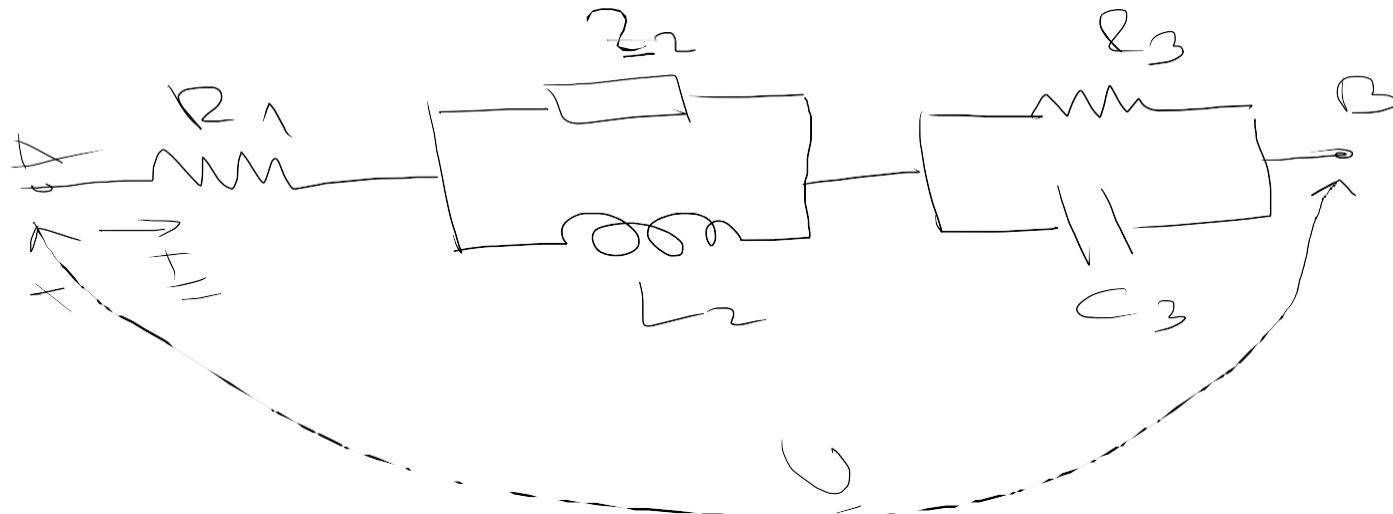


$$\begin{aligned}I &= I_1 + I_2 + \dots + I_n \\&= \frac{Q}{C_1} + \frac{Q}{C_2} + \dots + \frac{Q}{C_n}\end{aligned}$$

$$\frac{1}{Z_e} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} + \dots + \frac{1}{C_n}$$

$$Y_e = Y_1 + Y_2 + \dots + Y_n$$

Mitgliederauslöser



$$Z_{AB} = \frac{U}{I}$$



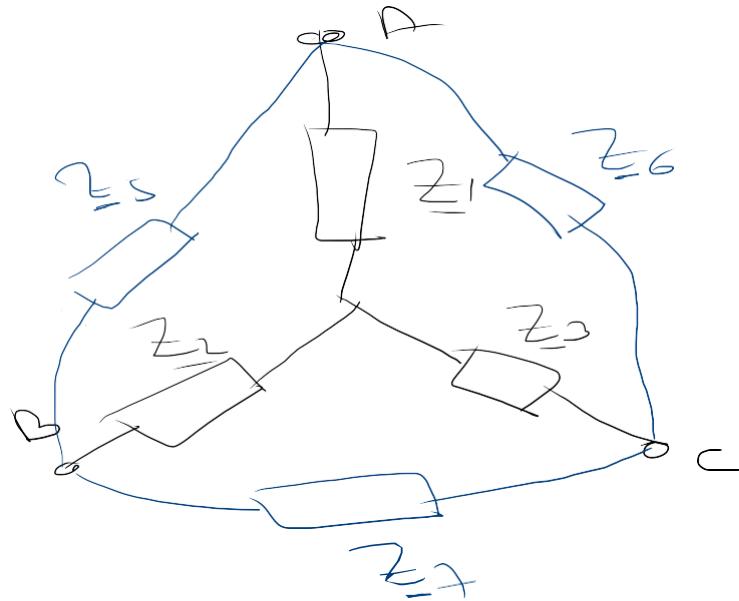
$$Z_e = R_1 + \frac{j\omega L_2 \cdot Z_2}{j\omega L_2 + Z_2} + \frac{R_3 \cdot \frac{1}{j\omega C_3}}{R_3 + \frac{1}{j\omega C_3}}$$

$$Z_e = R_1 \oplus (L_2 \parallel Z_2) \oplus (R_3 \parallel C_3)$$

$$R_1 \oplus (j\omega L_2 \parallel Z_2) \oplus (R_3 \parallel \frac{1}{j\omega C_3}) \quad \checkmark$$

ТРАНСФОРМАЦИЈЕ ЗВУЕЗДА - ПРОСТАР НАСИВНИХ ЕЛЕМЕНТА

① Трансформације меѓусите зглоби



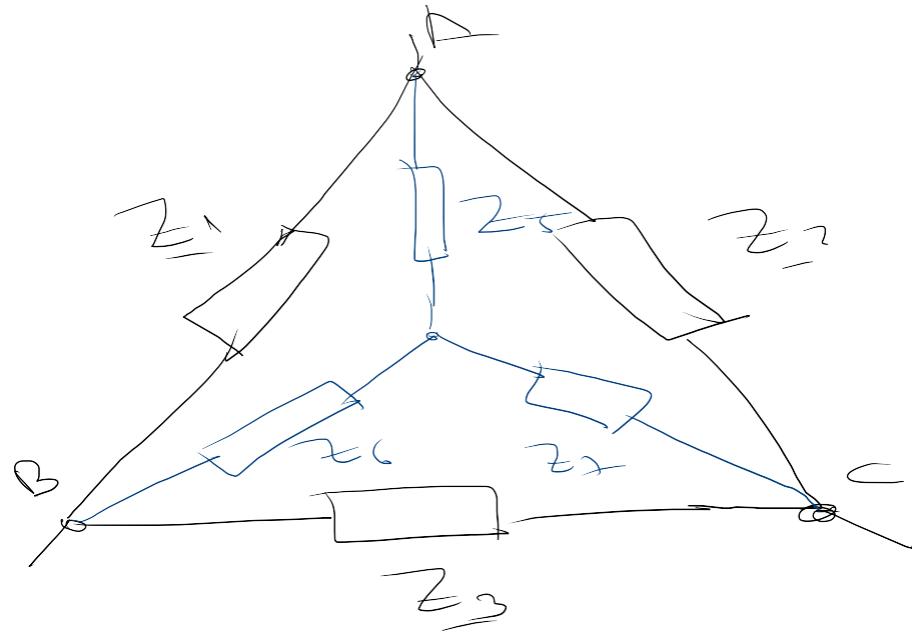
$\underline{z}_1, \underline{z}_2, \underline{z}_3 \rightarrow$ меѓусите
зглоби

$$\underline{z}_5 = \underline{z}_1 + \underline{z}_2 + \frac{\underline{z}_1 \cdot \underline{z}_2}{\underline{z}_3}$$

$$\underline{z}_6 = \underline{z}_1 + \underline{z}_3 + \frac{\underline{z}_1 \cdot \underline{z}_3}{\underline{z}_2}$$

$$\underline{z}_7 = \underline{z}_2 + \underline{z}_3 + \frac{\underline{z}_2 \cdot \underline{z}_3}{\underline{z}_1}$$

2. ~~regolare~~ unegare regola $\underline{z}_1, \underline{z}_2, \underline{z}_3 \rightarrow Y$



$$\underline{z}_5 = \frac{\underline{z}_1 + \underline{z}_2}{\underbrace{\underline{z}_1 + \underline{z}_2 + \underline{z}_3}_{\underline{z}_\Delta}}$$

$$\underline{z}_6 = \frac{\underline{z}_1 \cdot \underline{z}_3}{\underline{z}_\Delta}$$

$$\underline{z}_7 = \frac{\underline{z}_2 \cdot \underline{z}_3}{\underline{z}_\Delta}$$

- Eks. mægarca ma her. peamun gus
 - ke arawa za appoyx n matem
 jne frysantem am undan
 buan ga ce mægarca ke
 mone peamun leus tely R, L n C
 evenewen

- $Z_D = \phi$

$$\begin{aligned}
 Z_D &= j\omega L_1 + j\omega L_2 + \frac{1}{j\omega C_2} \\
 &= j(\omega(L_1 + L_2) - \frac{1}{\omega C_2})
 \end{aligned}$$

$$w(L_1 + L_2) = \frac{1}{\omega C_2}$$

КОМПЛЕКСНАЯ УМОЛЧАТЕЛЬНАЯ (РЕЗИСТАТИВНАЯ, РЕАКТИВНАЯ)
І КОМП. АДДИТИВНАХ (КОДАКТИВНАЯ, СУСЛУГИВА-
ННАЯ)

За схемаю RC тано:

$$\underline{Z}_e = R + j\omega L$$

За схемаю RC сано

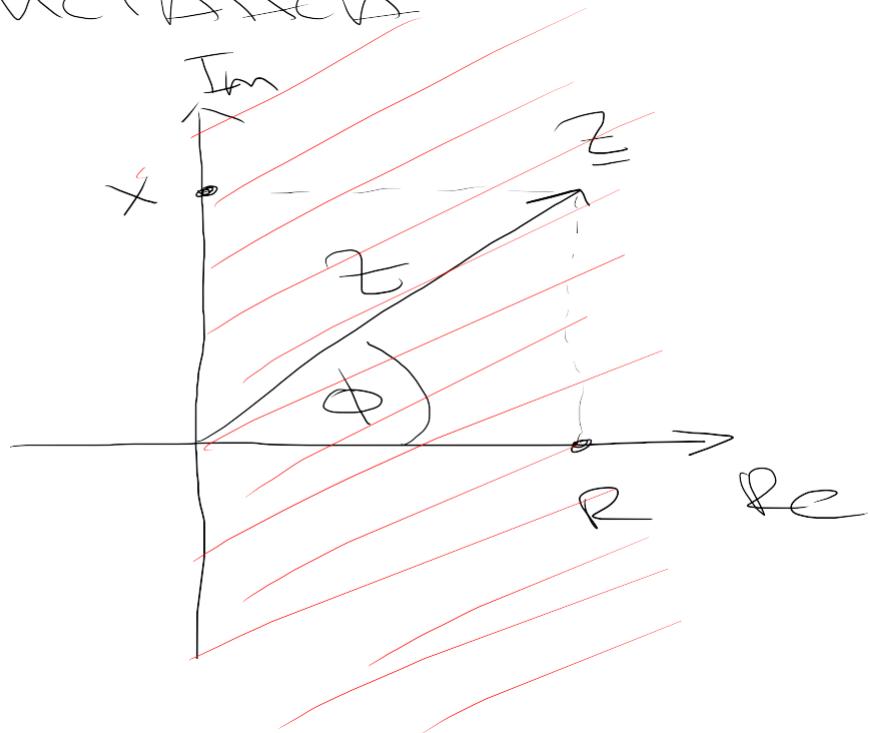
$$\underline{Z}_e = R + \frac{1}{j\omega C} = R - j\frac{1}{\omega C} = \underbrace{R}_{\text{real part}} + j\left(-\frac{1}{\omega C}\right)$$

За діаграмою RC тано

$$\begin{aligned} \underline{Z}_e &= \frac{R - j\omega C}{R + j\omega C} = \frac{R}{1 + j\omega RC} \cdot \frac{1 - j\omega RC}{1 - j\omega RC} = \frac{R}{1 + (\omega RC)^2} + \\ &\quad j \frac{-\omega R^2 C}{1 + (\omega RC)^2} \end{aligned}$$

$$z = R + jX$$

~~PEBUNCIANNA~~



PEAKTAHCA

$$R = \text{Re}\{z\} \quad [\Omega]$$

$$X = \text{Im}\{z\} \quad [\Omega]$$

$R > 0$
 $X < 0, X \neq 0, X = \emptyset$

BAHKO !

$$Z = R + jX = \sqrt{R^2 + X^2} e^{j \arctg \frac{X}{R}} = Z e^{j\phi} = Z \cdot \cos\phi + j Z \sin\phi$$

$$R = Z \cdot \cos\phi$$

$$X = Z \cdot \sin\phi$$

$$-\frac{\pi}{2} \leq \phi \leq \frac{\pi}{2}$$

$$\cos\phi > 0$$

\Rightarrow

$$\phi = \begin{cases} \arctg \frac{X}{R}, & R > 0 \\ \frac{\pi}{2}, & R = 0 \text{ and } X > 0 \\ -\frac{\pi}{2}, & R = 0 \text{ and } X < 0 \\ 0, & R = 0 \text{ and } X = 0 \end{cases}$$

$$Y = \operatorname{Re}\{Z\} + j \operatorname{Im}\{Z\} = G + jB$$

[S] [s]

KONSTRUKTIVA

CYKLENTHAUA

$$Z = Z e^{j\phi} = \frac{1}{2} e^{j\phi} = G \cos \phi - j B \sin \phi$$

$$G = Y \cdot \cos \phi$$

$$B = Y \cdot \sin \phi$$

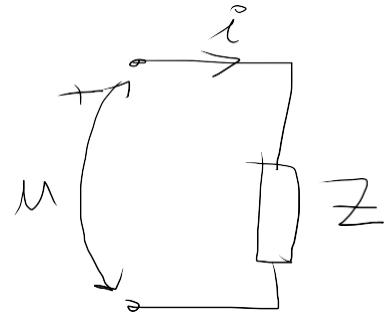
$$Y = \sqrt{G^2 + B^2}$$

$$\phi = \begin{cases} -\operatorname{arg} \frac{B}{G}, & G > 0 \\ \frac{\pi}{2}, & G = 0 \wedge B > 0 \\ \frac{3\pi}{2}, & G = 0 \wedge B < 0 \\ 0, & G = B = 0 \end{cases}$$

$G > 0$
 $B > 0$
 $B < 0$
 $B = 0$

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ЧИАТЕ \Rightarrow ПРОЦЕДУРА ПОЛУЧЕНИЯ РЕЗУЛЬТАТОВ



$$P(t) = U(t) \cdot i(t)$$

$$U(t) = \sqrt{2}U \cos(\omega t + \theta)$$

$$i(t) = \sqrt{2}I \cos(\omega t + \psi)$$

$$\Rightarrow P(t) = 2UI \cos(\omega t + \theta) \cdot \cos(\omega t + \psi)$$

~~также~~ же $\phi = \theta - \psi \Rightarrow \psi = \theta - \phi$ $\cos\phi > \phi$

$$P(t) = UI \cos\phi + UI \cos\phi \cos(2\omega t + 2\theta) +$$
$$UI \sin\phi \cdot \sin(2\omega t + 2\theta)$$

$$P = UI \cos\phi \quad [\text{W}] \geq \phi \quad \text{активная (согласованная)}$$

$$Q = UI \sin\phi \quad [\text{Var}] \quad \text{ПАКТИЧЕСКАЯ ЧАСТЬ}$$

$$S = UI \quad [\text{VA}] \quad \text{безразмеренная}$$

Фактор чисте привеска

$$k = \cos \phi = \frac{P}{S}, \quad 0 \leq k \leq 1$$

Фактор реалності

$$k_r = \sin \phi = \frac{Q}{S}, \quad -1 \leq k_r \leq 1$$

$k_r < 0$ позитивна характеристика привеска

$k_r > 0$ негативна характеристика привеска

$$k^2 + k_r^2 = 1 = \cos^2 \phi + \sin^2 \phi \Rightarrow k^2 = 1 - k_r^2$$

$$k_r = \pm \sqrt{1 - k^2}$$

$$g_k = \pm \sqrt{1 - k_r^2}$$

гружа

KOMPLEXNA CHATA NAPRJEMNICA

$$S = P + jQ = UI \cos \phi + jUI \sin \phi \quad [\text{VA}]$$

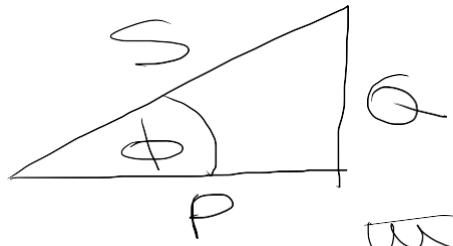
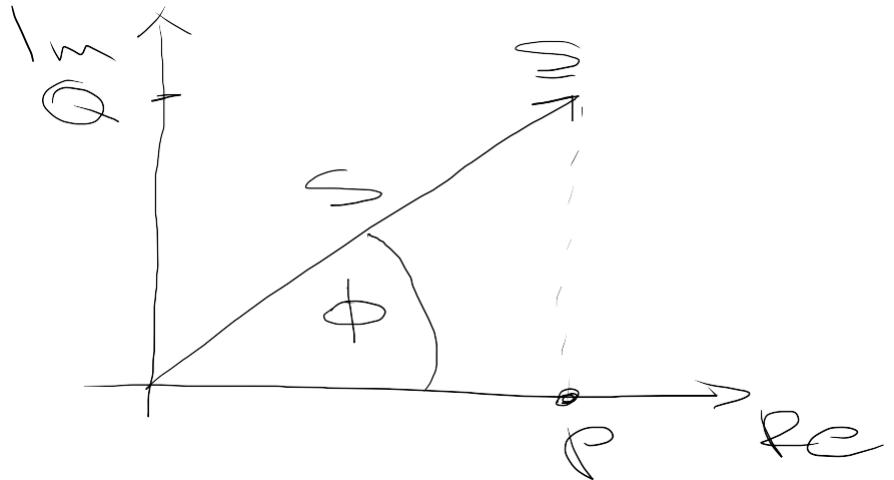
$$S = UI(\cos \phi + j \sin \phi) = UI e^{j\phi} = S e^{j\phi}$$

$$U \cdot I = U e^{j\theta} I e^{j\psi} = U I e^{j(\theta + \psi)} \neq U I e^{j\phi}$$

$$\phi = \theta - \psi$$

$$U \cdot I^* = U e^{j\theta} I e^{-j\psi} = U I e^{j(\theta - \psi)} \quad \checkmark$$

$$S = U \cdot I^*$$

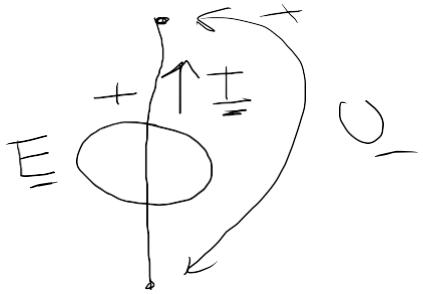


hypotenuse

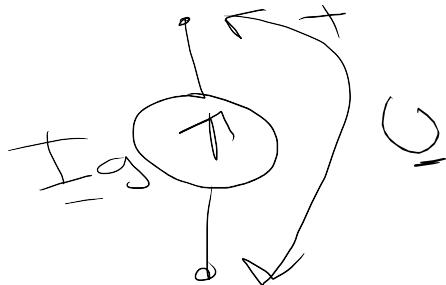
$$S = \sqrt{P^2 + Q^2}$$

— Gitter Abhängigkeit

Chata tverpravopon



$$\underline{S} = \underline{E} \cdot \underline{I}_+^*$$

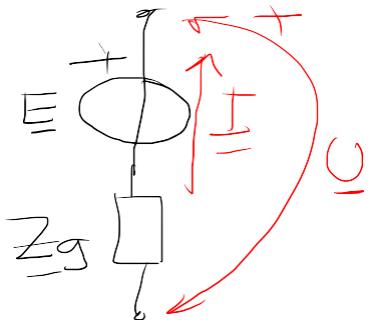


$$\underline{S} = \underline{U}_- \cdot \underline{I}_g^+$$

$$\underline{\pi} \leq \phi \leq \underline{\pi}$$

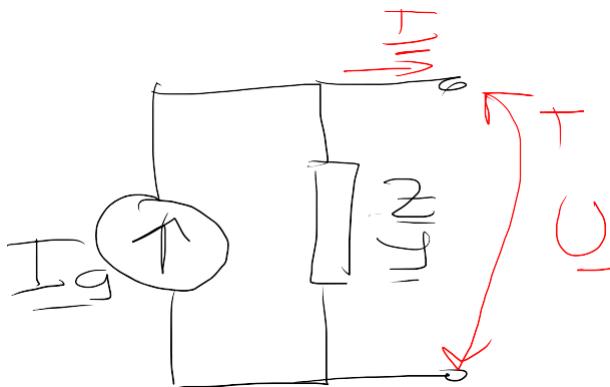
$$P > 0$$

$$P < 0$$



$$\underline{S} = \underline{U}_- \cdot \underline{I}_+^*$$

$$\underline{U}_- = \underline{E} - \underline{Z}_g \cdot \underline{I}_-$$



$$\underline{S} = \underline{U}_- \cdot \underline{I}_-^*$$

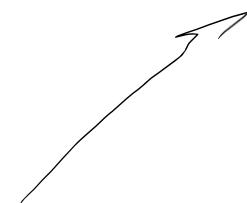
$$\underline{I}_-^* = \underline{I}_g - \frac{\underline{U}_-}{\underline{Z}_g}$$

РЕДУЦИРУЕМЫЕ СОВХЕМЫ КОМПЛексНОМ ДОМЕНЫ

$$\sum I = \phi \text{ на } n_0 - 1$$

но - для
вершин

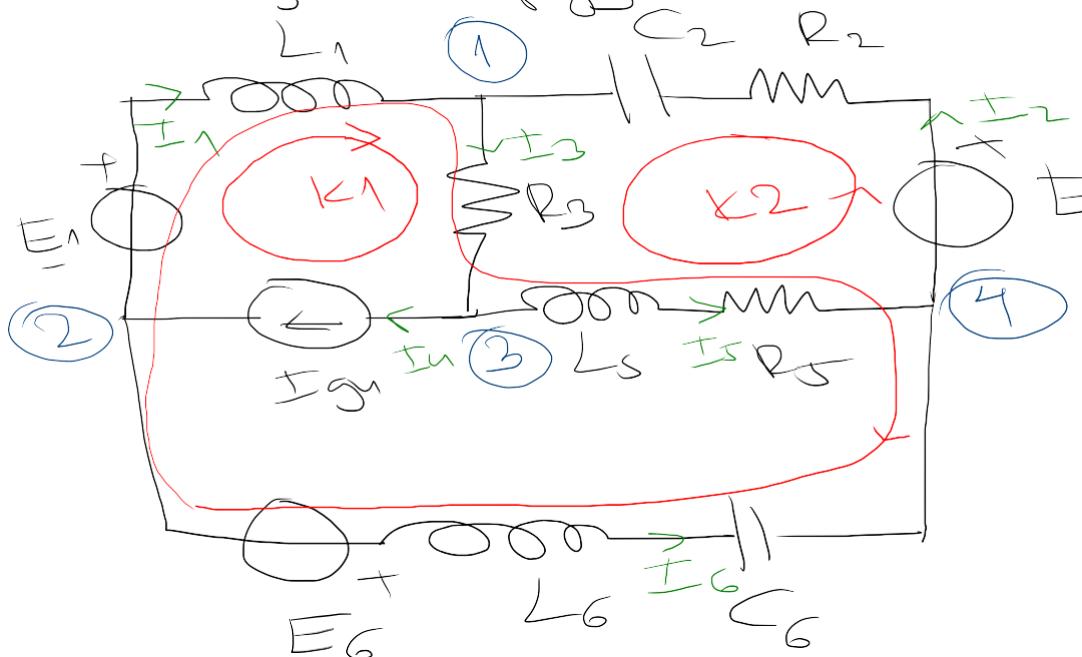
$$\sum U = \phi \text{ на } n_{ik} = n_0 - (n_0 - 1)$$



но
для
ребра

для вершин
комплекса

→ Tandaan ang tanong: Mga pagkakaroon je ng transients
n ng circuito



$$Ng - (Nz - 1) = 6 - 3 = 3 \quad \text{baseline known}$$

$$K1: \underline{V}_{21} + \underline{V}_{13} + \underline{V}_{32} = 0$$

$$K2: \underline{V}_{41} + \underline{V}_{13} + \underline{V}_{34} = 0$$

$$K3: \underline{V}_{13} + \underline{V}_{34} + \underline{V}_{42} + \underline{V}_{21} = 0$$

$$\begin{aligned} Nz - 1 &= 3 \\ (1) - I_1 - I_2 + I_3 &= 0 \\ (2) I_1 - I_4 + I_6 &= 0 \\ (3) -I_3 + I_4 - I_5 &= 0 \end{aligned}$$

$$\underline{V}_{21} = -\underline{V}_{12} = -E_1 + j\omega L_1 I_1$$

$$\underline{V}_{13} = R_3 I_3 = -\underline{V}_{31}$$

$$\underline{V}_{41} = -\underline{V}_{14} = E_2 - I_2 (R_2 + \frac{1}{j\omega C_2})$$

$$\underline{V}_{34} = -\underline{V}_{43} = (j\omega L_5 + R_5) I_5$$

$$\underline{V}_{23} \leftarrow \text{NCF?} \Rightarrow I_4 = I_{g4}$$

$$\underline{V}_{42} = E_6 - j\omega L_6 I_6 - \frac{1}{j\omega C_6} I_6$$

Peggy's Lawer circuit

→ Ng yegmene y kewna oy ~~veo yane~~ andje
spaser

$$n_C - 1 = 3$$

① $\underline{I_1} + \underline{I_2} = \underline{I_3}$

② $\underline{I_1} + \underline{I_6} = \underline{I_4}$

③ $\underline{I_4} + \underline{I_5} = \underline{I_3}$

$$Ng - (n_C - 1) = 3$$

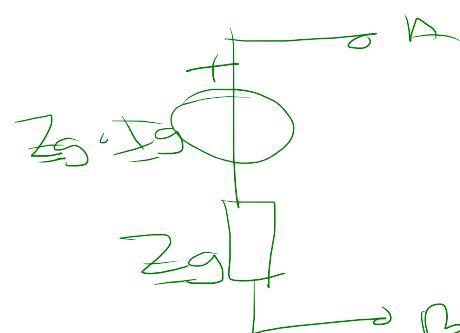
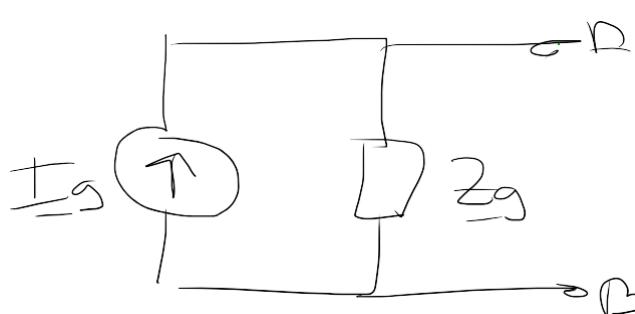
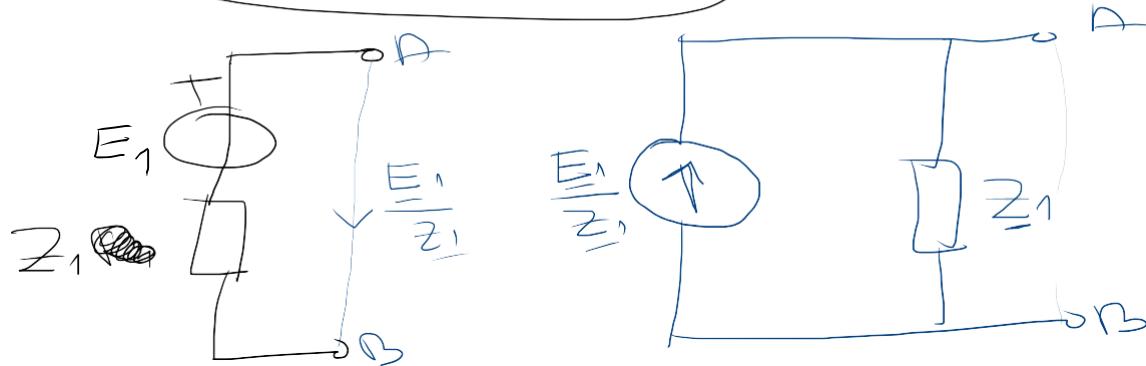
(1) $-E_1 + jwL_1 \underline{I_1} + R_3 \underline{I_3} + \boxed{U_{32}} = \emptyset \quad \text{VCT}$ $\underline{I_4} = \underline{I_5}$

(2) $-E_2 + R_2 \underline{I_2} + \frac{1}{jwC_2} \underline{I_2} + R_5 \underline{I_5} + jwL_5 \underline{I_5} + R_5 \underline{I_5} = \emptyset$

(3) $-E_1 + jwL_1 \underline{I_1} + R_3 \underline{I_3} + jwL_3 \underline{I_3} + R_5 \underline{I_5} - \frac{1}{jwC_6} \underline{I_6} - jwL_6 \underline{I_6} - \frac{1}{jwC_6} \underline{I_6} = \emptyset$

ЕКВИВАЛЕНТНАЯ МАНОБАСТ И СПОСОБЫ ТЕМПЕРАТУР

PHT и PCT



МЕТОДА КОНСРУХ СПІВА ІЗ КОМНЕЧНОМ ОСТАУХ

$$n_k = n_g - (n_c - 1)$$

$$\underline{Z}_{11} \cdot \underline{I}_{k1} + \underline{Z}_{12} \underline{I}_{k2} + \dots + \underline{Z}_{1n_c} \cdot \underline{I}_{kn_c} = \underline{E}_{k1}$$

$$\underline{Z}_{21} \underline{I}_{k1} + \underline{Z}_{22} \underline{E}_{k2} + \dots + \underline{Z}_{2n_c} \underline{I}_{kn_c} = \underline{E}_{k2}$$

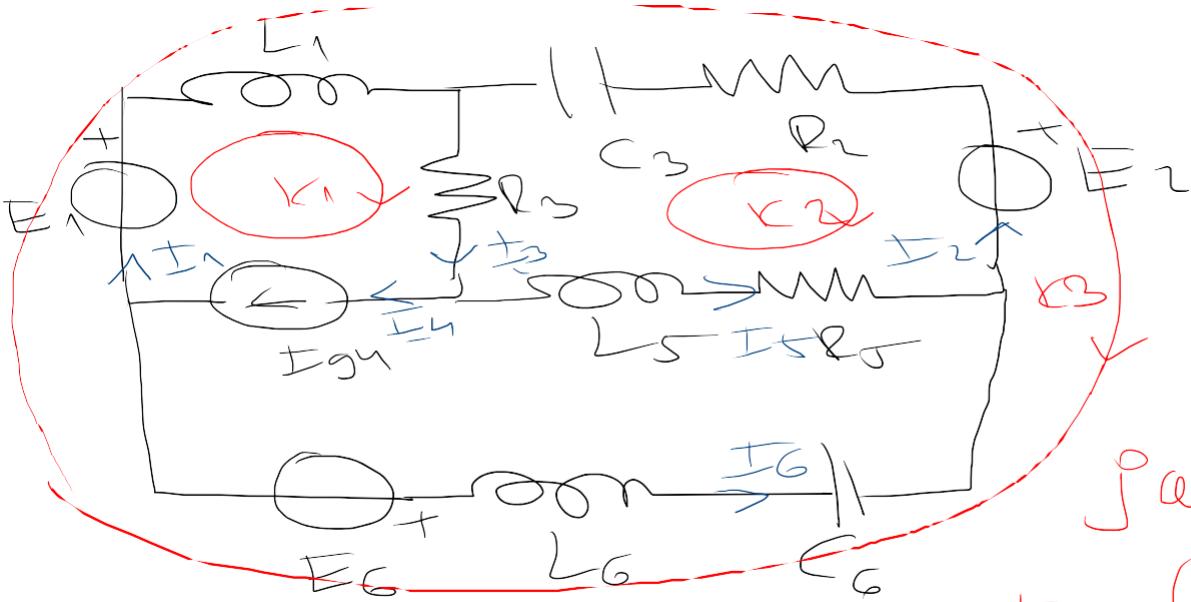
⋮

$$\underline{Z}_{n_c 1} \underline{I}_{k1} + \underline{Z}_{n_c 2} \underline{I}_{k2} + \dots + \underline{Z}_{n_c n_c} \underline{I}_{kn_c} = \underline{E}_{kn_c}$$

$$\underline{Z}_{\tau i}, \tau = 1, \dots, n_c$$

$$\underline{Z}_{i j}, i, j = 1, \dots, n_c, i \neq j$$

$$\underline{E}_{\tau i}, \tau = 1, \dots, n_c$$



$$\begin{aligned}
 \underline{I}_{k1} &= \underline{I}_{g4} \\
 -R_3 \underline{I}_{k1} + (R_2 + D_3 + R_J + j\omega L_5 \\
 + \frac{1}{j\omega C_3}) \underline{I}_{k2} + (D_2 + \frac{1}{j\omega C_2}) \underline{I}_{k3} \\
 &= -\underline{E}_2
 \end{aligned}$$

$$\begin{aligned}
 j\omega L_1 \underline{I}_{k1} + (R_2 + \frac{1}{j\omega C_2}) \underline{I}_{k2} + \\
 \underline{I}_{k3} (R_2 + j\omega L_1 + j\omega L_6 + \frac{1}{j\omega C_6}) = \\
 \underline{E}_1 - \underline{E}_2 - \underline{E}_6
 \end{aligned}$$

$$\Rightarrow \underline{I}_1 = \underline{I}_{k1} + \underline{I}_{k3}$$

$$\underline{I}_5 = -\underline{I}_{k2}$$

$$\underline{I}_2 = -\underline{I}_{k2} - \underline{I}_{k3}$$

$$\underline{I}_6 = -\underline{I}_{k3}$$

$$\underline{I}_3 = \underline{I}_{k1} - \underline{I}_{k2}$$

$$\underline{I}_4 = \underline{I}_{k1} - \underline{I}_{g4}$$

Metoda konwertująca wektor w kolumnę odnies

$n-1$

$$\underline{y}_{11} \underline{v}_1 + \underline{y}_{12} \underline{v}_2 + \dots + \underline{y}_{1(n-1)} \cdot \underline{v}_{n-1} = \underline{t}_{\bar{c}_1}$$

$$\underline{y}_{21} \underline{v}_1 + \underline{y}_{22} \underline{v}_2 + \dots + \underline{y}_{2(n-1)} \cdot \underline{v}_{n-1} = \underline{t}_{\bar{c}_2}$$

:

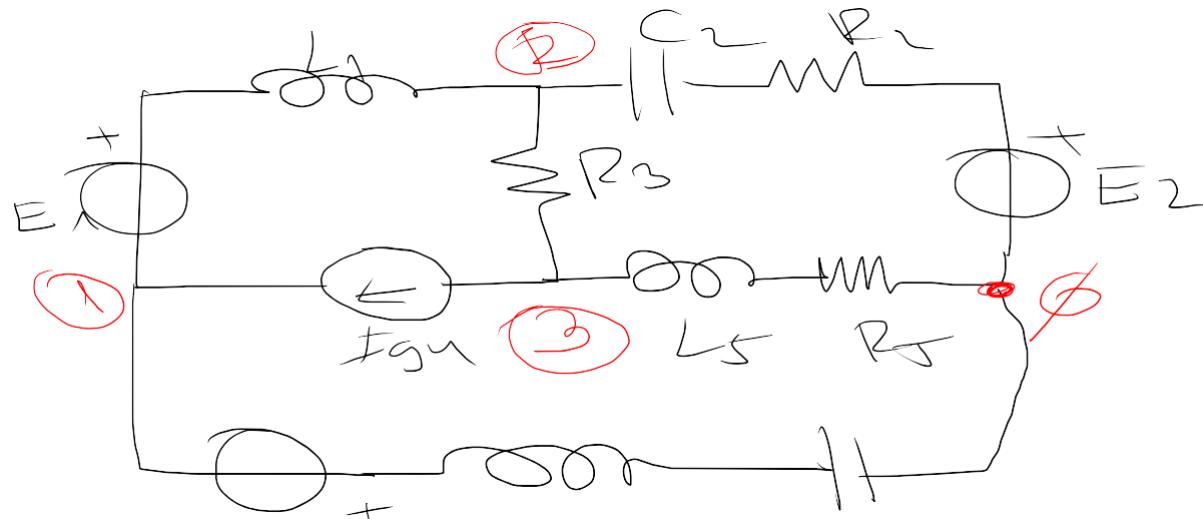
$$\underline{y}_{(n-1)1} \cdot \underline{v}_1 + \underline{y}_{(n-1)2} \underline{v}_2 + \dots + \underline{y}_{(n-1)(n-1)} \underline{v}_{n-1} = \underline{t}_{\bar{c}_{(n-1)}}$$

$$\underline{y}_{ii}, i=1, \dots, n-1$$

$$\underline{y}_{ij}, i, j=1, \dots, n-1, i \neq j$$

$$I_{\bar{c}i}, i=1, \dots, n-1$$

$$\Xi | \underline{x}, \underline{z}$$



$$V_1 \left(\frac{1}{j\omega L_1} + \frac{1}{j\omega L_6 + \frac{1}{j\omega C_6}} \right) - \frac{1}{j\omega L_1} V_2 = -\frac{E_1}{j\omega L_1} + I_4 - \frac{E_6}{j\omega L_1 + j\omega C_6}$$

$$V_2 \left(\frac{1}{j\omega L_1 + R_3} + \frac{1}{R_2 + \frac{1}{j\omega C_2}} \right) - \frac{1}{j\omega L_1} V_1 - \frac{1}{R_3} V_3 = \frac{E_1}{j\omega L_1} + \frac{E_2}{R_2 + \frac{1}{j\omega C_2}}$$

$$-\frac{1}{R_3} V_2 + V_3 \left(\frac{1}{R_3} + \frac{1}{R_5 + j\omega L_5} \right) = -\cancel{E_4} + \cancel{I_5} I_4$$