Кола са спрегнутим калемовима.

Основи електротехнике 2
Предавање: 11. блок

КОЛА СА СПРЕГНУТИМ КАЛЕМОВИМА

$$U = L\frac{di}{dt} = -e_{ind}$$

$$e_{ind} = -\frac{d\phi}{dt}$$

$$\underline{U} = j\omega L \underline{I}$$
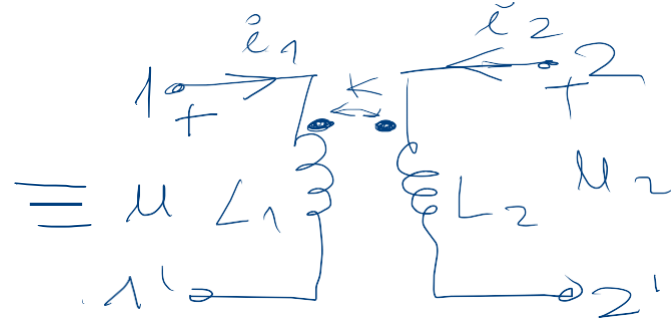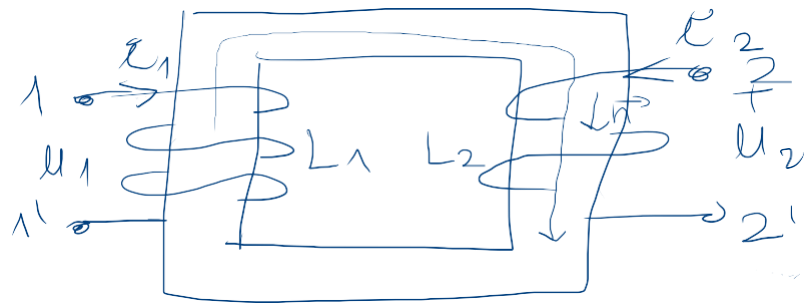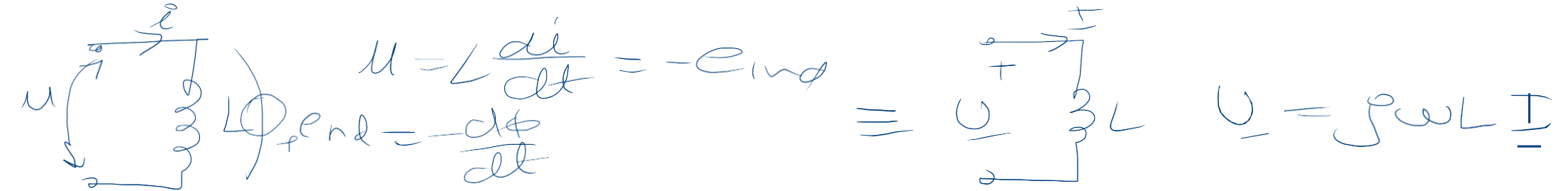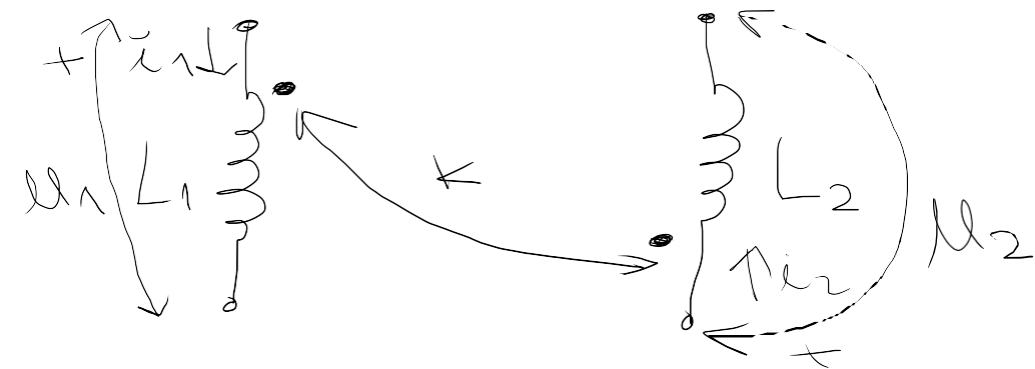
$$U_1 = L_1 \frac{di_1}{dt} + L_{12}\frac{di_2}{dt}$$

$$U_2 = L_2 \frac{di_2}{dt} + L_{21}\frac{di_1}{dt}$$

$$\underline{U}_1 = j\omega L_1 \underline{I}_1 + j\omega L_{12}\underline{I}_2$$

$$\underline{U}_2 = j\omega L_2 \underline{I}_2 + j\omega L_{21}\underline{I}_1$$
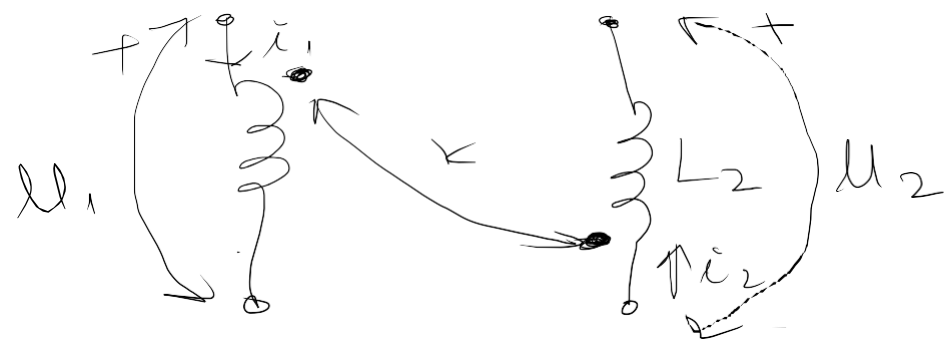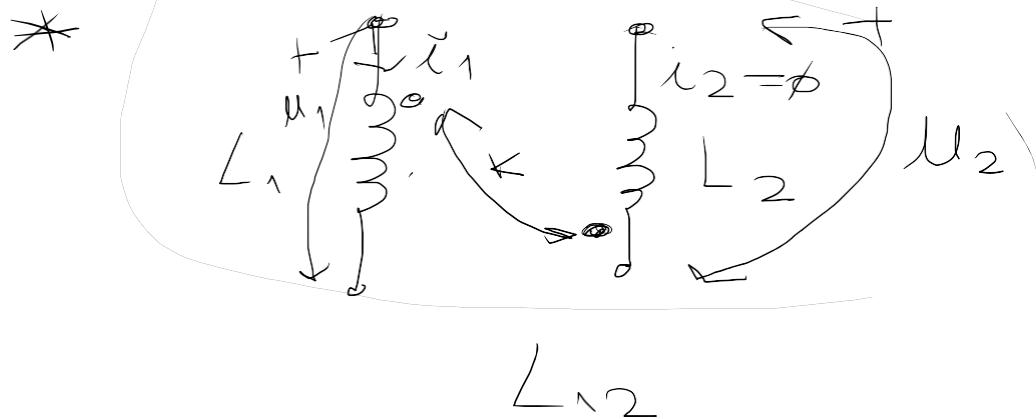
$$L_{12} = L_{21} = \pm K\sqrt{L_1 L_2} = M$$

$$0 \le K \le 1$$

$$U_1 = j\omega L_1 I_1 + j\omega L_{12} I_2$$

$$L_{12} = K\sqrt{L_1 L_2} > 0$$
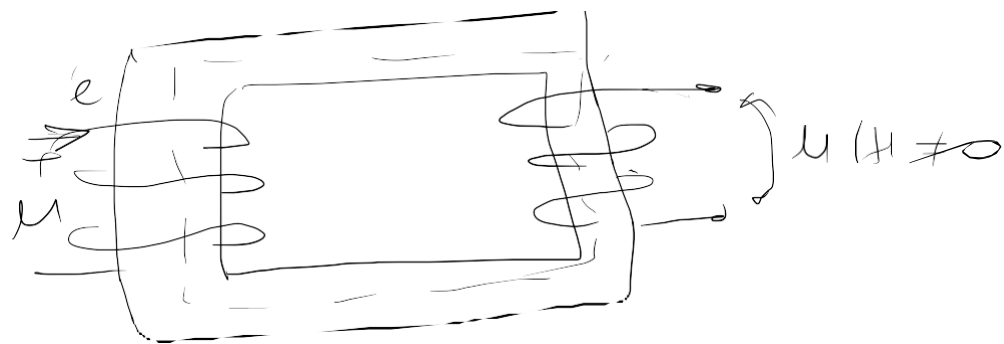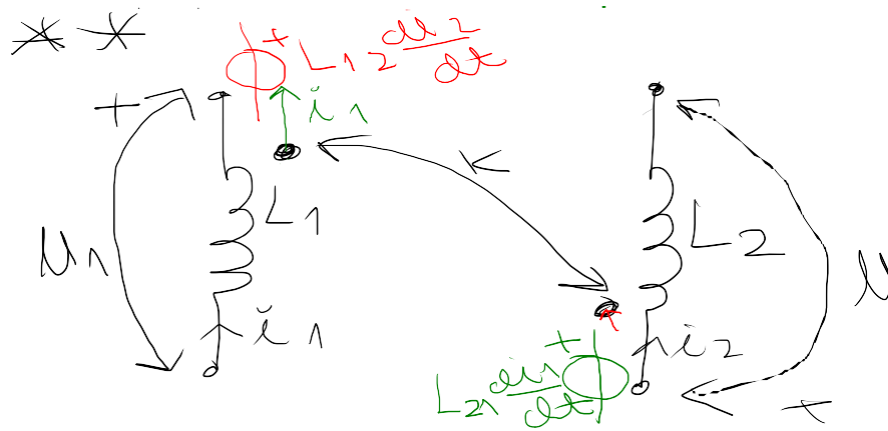
dep ode ceapje y mapuep

$$*$$

$$L_{12}$$

$$\underline{U}_1 = j\omega L_1 \underline{I}_1 + j\omega L_{12} \underline{I}_2$$

$$\underline{U}_2 = -j\omega L_2 \underline{I}_2 - j\omega L_{12} \underline{I}_1$$

$$j\omega H \neq 0$$

* *

У коммерсиям dawery

$+ L_{12}\frac{di_2}{dt}$ (in red)

i_1

U_1 L_1

i_1

K

L_2 i_2

$L_{21}\frac{di_1}{dt} +$ (in green)

$U_2 = U_1$ L_1 I_1 K L_2 U_2 I_2

$L_{21} > 0$
$L_{12} > 0$
↑
удовлетворяет
взаимность (green)

$$L\frac{di}{dt} = u$$

$$L_{12}\frac{di_2}{dt} = [V]$$

U_1 L_1 I_1 $+ j\omega L_{12} I_2$ (green)

L_2 U_2
$+ j\omega L_{21} I_1$ (red)

$L_{12} > 0$ $L_{21} > 0$ (green)

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ПРИМЈЕР:

Circuit diagram with elements: L_1, C_2, R_2, E_1, E_2, R_3, L_5, R_5, L_6, C_6, E_6, currents I_1, I_2, I_3, I_4, I_5, I_6, I_{g4}, nodes ①②③④, contours K_1, K_2, K_3, couplings K_{15}, K_{56}, and label $j\omega K_{15}\sqrt{L_1 L_5} I_5$.
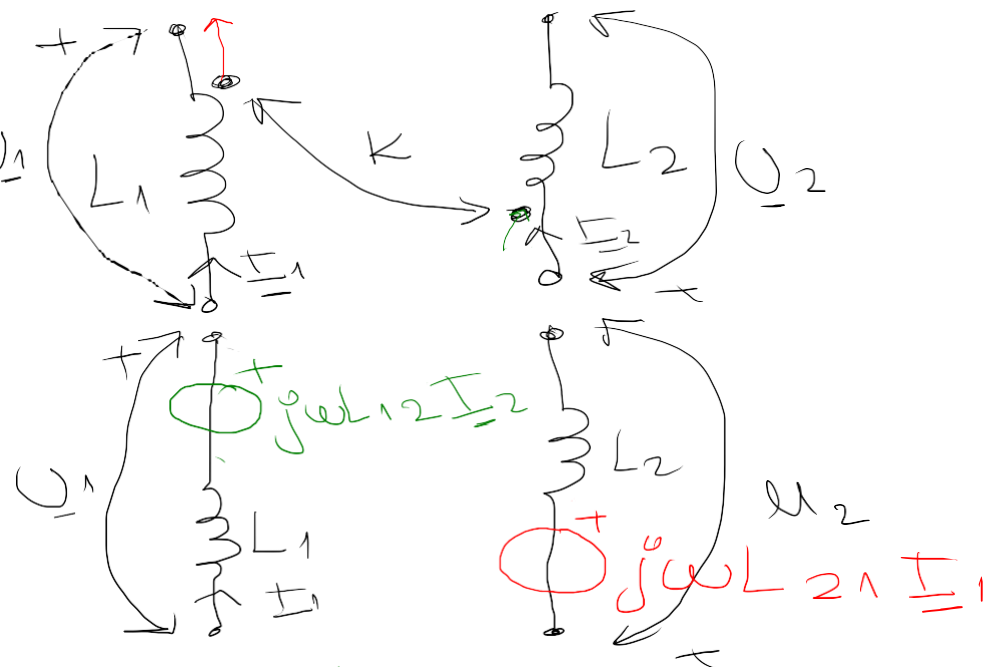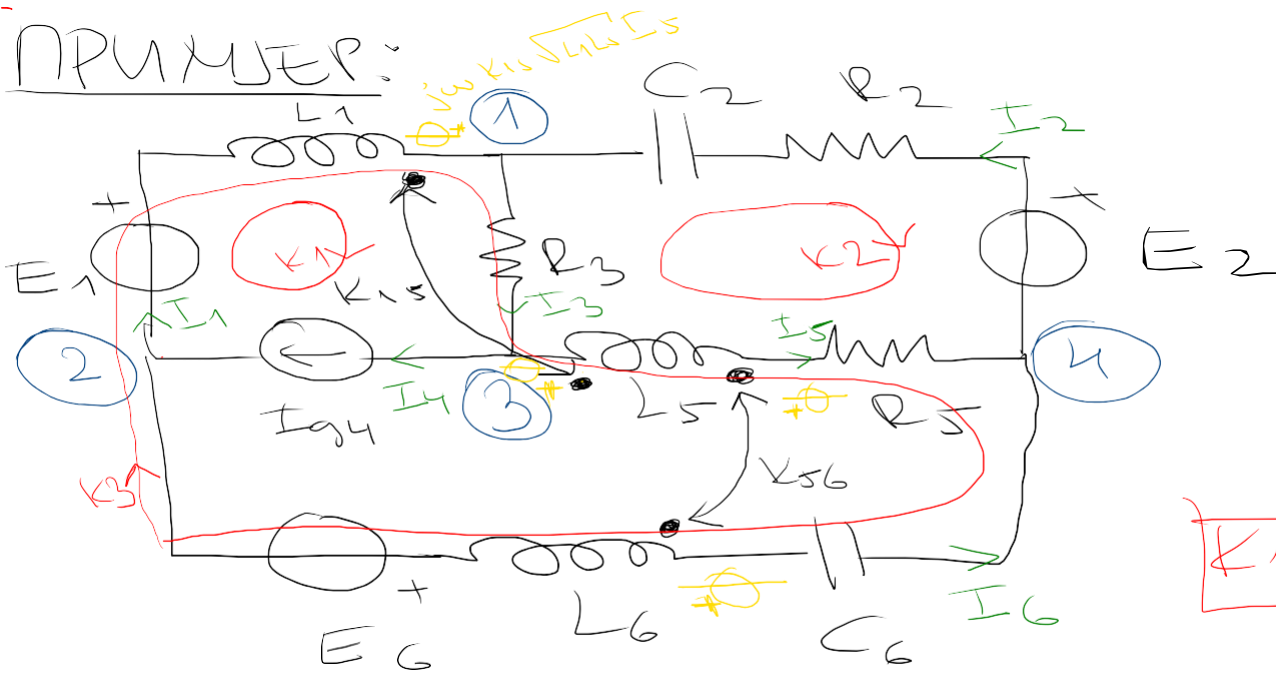
$$n_{\check{c}} - 1 = 3$$

① $\quad I_1 + I_2 = I_3$

② $\quad I_4 = I_1 + I_6$

③ $\quad I_3 = I_4 + I_5$

$$n_k = n_g - (n_{\check{o}} - 1) = \boxed{3}$$

$$\boxed{K_1:} \quad I_4 = I_{g4}$$

$\boxed{K_2:} \quad -R_2 I_2 - \dfrac{1}{j\omega C_2} I_2 + E_2 - R_5 I_5 - j K_{56} \omega \sqrt{L_5 L_6} \, I_6$

$\qquad - j\omega L_5 I_5 + j\omega K_{15}\sqrt{L_1 L_5}\, I_1 - R_3 I_3 = 0$

$\boxed{K_3:} \quad -E_1 + j\omega L_1 I_1 - j\omega K_{15}\sqrt{L_1 L_5}\, I_5 + R_3 I_3 - j\omega K_{15}\sqrt{L_1 L_5}\, I_1$

$\qquad + j\omega L_5 I_5 + j\omega K_{56}\sqrt{L_5 L_6}\, I_6 + R_5 I_5 - \dfrac{1}{j\omega C_6} I_6$

$\qquad - j\omega K_{56}\sqrt{L_5 L_6}\, I_5 - j\omega L_6 I_6 + E_6 = 0$

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L_1 $j\omega L_{15} I_5$ $\boxed{K_{15}\sqrt{L_1 L_5}}$ C_2 R_2

$+$

E_1 $+$ I_1 K_1 $+$ I_3 K_2 $+$ I_2 E_2

R_3

K_3 $j\omega K_{15}\sqrt{L_1 L_5} I_1$ $+$ $j\omega K_{56}\sqrt{L_5 L_6} I_6$ I_5

I_{5M} I_4 L_5 R_5

$+ j\omega K_{56}\sqrt{L_5 L_6} I_6$

E_6 $+$ L_6 I_6 C_6

$*\ j\omega L$
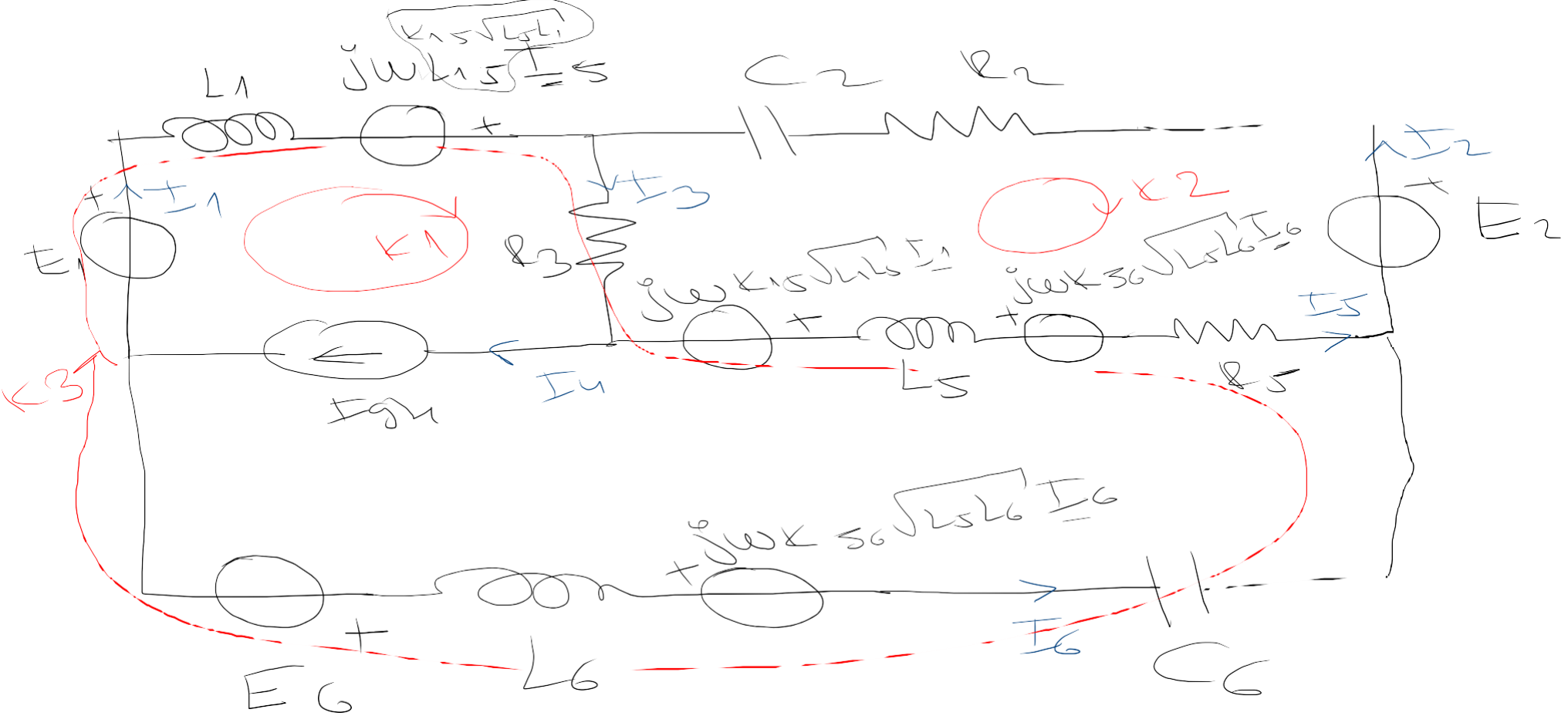
$\Rightarrow j\omega K_{15} L_{15}$ $\boxed{\sqrt{L_1 L_5}}$
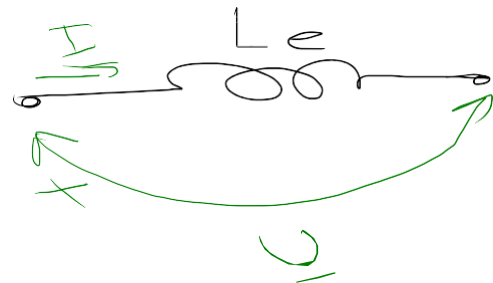
$\boxed{j\omega K_{15}\sqrt{L_1 L_5}}$

$K = \dfrac{|L_{12}|}{\sqrt{L_1 L_2}}$

$\boxed{L_{12} = \pm K \sqrt{L_1 L_2}}$

ЕКВИВАЛЕНТНА ИНДУКТИВНОСТ
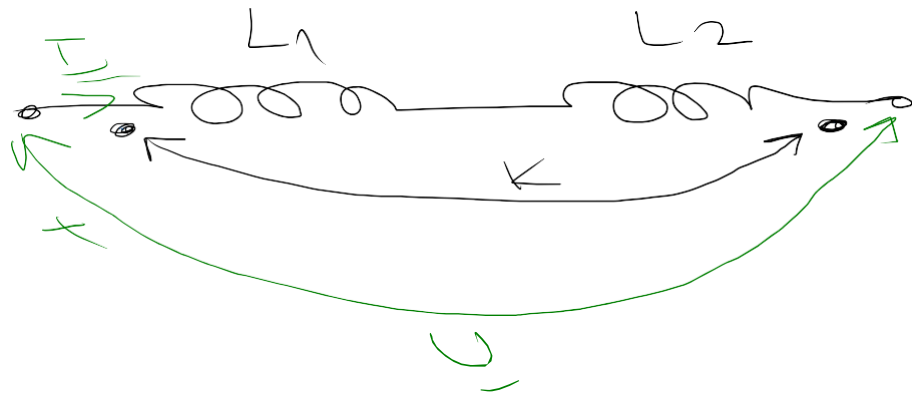
$$U = j\omega L_e \cdot I$$

$$U = j\omega L_1 I - j\omega L_{12} I + j\omega L_2 I - j\omega L_{12} I$$
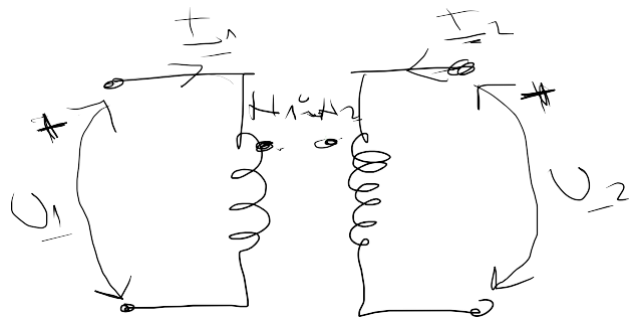
$$U = j\omega (L_1 + L_2 - 2L_{12}) I$$

$$\Rightarrow L_e = L_1 + L_2 - 2L_{12}$$

$$L_e = L_1 + L_2 - 2 \cdot (\pm k\sqrt{L_1 L_2})$$

убијек оо коренито секен ракитана јер-
кри ако
отреан

$$\boxed{L_e = L_1 + L_2 - 2k\sqrt{L_1 L_2}}$$

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ИДЕАЛНИ ТРАНСФОРМАТОР

I_1 I_2

$N_1 \ddot{}N_2$

U_1 U_2

$$\frac{U_1}{U_2} = \pm \frac{N_1}{N_2}$$

$N_1 : N_2$ $1 : N_2$

$\boxed{\dfrac{N_1}{N_2}} : 1$

$m : 1$

преносни однос (oxнос)

$$\frac{I_1}{I_2} = \mp \frac{N_2}{N_1}$$

$$\sum_{dlg} N I = 0 \quad \text{"+" дно смерб yнym y маргер}$$

$$N_1 I_1 + N_2 I_2 = 0$$

$$N_1 I_1 = - N_2 I_2$$

$$\frac{I_1}{I_2} = - \frac{N_2}{N_1}$$

Свойства трансформатора замена Z_P на следующую

Z_{UL}

$m = \dfrac{U_1}{U_2}$
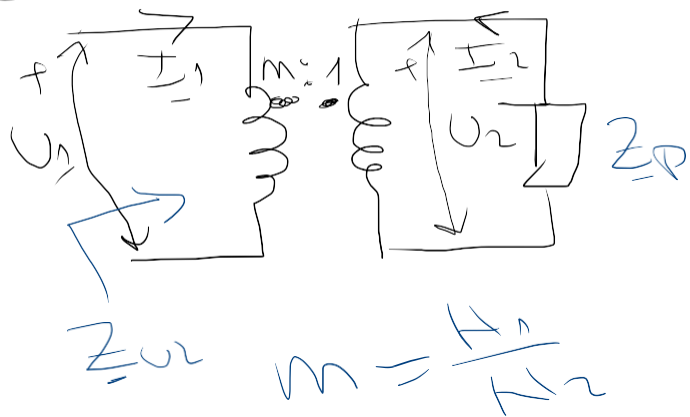
$$Z_{UL} = \dfrac{U_1}{I_1} = \dfrac{m U_2}{-\dfrac{1}{m} I_2} = -m^2 \dfrac{U_2}{I_2}$$
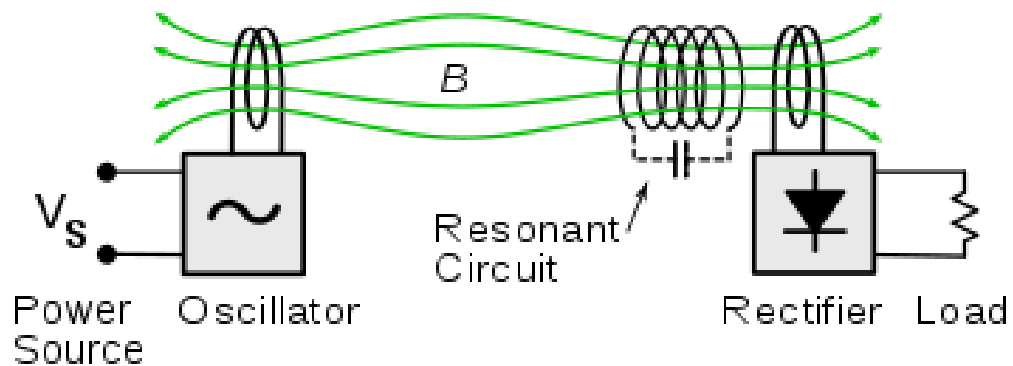
$$Z_{UL} = -m^2 \dfrac{-I_2 \cdot Z_P}{I_2} = m^2 Z_P$$

$$\boxed{Z_{UL} = m^2 Z_P}$$

$Z_P = R \quad \longrightarrow \quad Z_{UL} = m^2 R$

$Z_P = \dfrac{1}{j\omega C} \quad \Longrightarrow \quad Z_{UL} = \dfrac{m^2}{j\omega C} = \dfrac{1}{j\omega \boxed{\dfrac{C}{m^2}}}$

$Z_P = j\omega L \quad \longrightarrow \quad Z_{UL} = j\omega \boxed{m^2 L}$

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Power Source Oscillator V_S B Resonant Circuit Rectifier Load

(a) Source Drain Power Load d

(b) Γ_S $\kappa(t)$ Γ_D $C_S(t)$ $L_S(t)$ $L_D(t)$ $C_D(t)$ d

Readout Coil LC Sensor (a)

i_o k i_s R_s Z_R U_0 U_s Z_{in} L_0 L_s C_s L_0
Readout Coil LC Sensor Equivalent Input Impedance (b)

$Re(Z_{in})$ $f_{max(Re)}$ Frequency $Phase(Z_{in})$ $f_{phase-dip}$ Frequency (c)