

TERMIN 4 - zadaci za samostalan rad - rješenja



Zadatak 1.

Dopuniti skup vektora $\{(1, 1, 1, 2), (1, 2, 3, -3)\}$ do ortogonalne baze vektorskog prostora \mathbb{R}^4 .

Rješenje

Neka je $V = \text{Lin}\{(1, 1, 1, 2), (1, 2, 3, -3)\}$. Kako je prostor kolona matrice A ortogonalan na nula prostor matrice A^T , iz stepenaste forme

$$\left[\begin{array}{cc|cccc} \boxed{1} & 1 & 1 & 0 & 0 & 0 \\ 1 & 2 & 0 & 1 & 0 & 0 \\ 1 & 3 & 0 & 0 & 1 & 0 \\ 2 & -3 & 0 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\begin{array}{l} R_1 \cdot (-1) + R_2 \\ R_1 \cdot (-1) + R_3 \\ R_1 \cdot (-2) + R_4 \end{array}} \left[\begin{array}{cc|cccc} \boxed{1} & 1 & 1 & 0 & 0 & 0 \\ 0 & \boxed{1} & -1 & 1 & 0 & 0 \\ 0 & 2 & -1 & 0 & 1 & 0 \\ 0 & -5 & -2 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\begin{array}{l} R_2 \cdot (-2) + R_3 \\ R_2 \cdot 5 + R_4 \end{array}} \left[\begin{array}{cc|cccc} \boxed{1} & 1 & 1 & 0 & 0 & 0 \\ 0 & \boxed{1} & -1 & 1 & 0 & 0 \\ 0 & 0 & 1 & -2 & 1 & 0 \\ 0 & 0 & -7 & 5 & 0 & 1 \end{array} \right]$$

dobijamo $V^\perp = \text{Lin}\{(1, -2, 1, 0), (-7, 5, 0, 1)\}$.

Da bismo skup $\{(1, 1, 1, 2), (1, 2, 3, -3)\}$ doveli do ortogonalne baze prostora \mathbb{R}^4 , potrebno je da bazni vektori prostora V i V^\perp budu međusobno ortogonalni. Za ortogonalizaciju tih vektora iskoristićemo Gram-Šmitov postupak. Imamo da je:

$$\begin{aligned} \vec{y}_1 &= \vec{x}_1, \\ \vec{y}_2 &= \vec{x}_2 - \frac{(\vec{x}_2, \vec{y}_1)}{(\vec{y}_1, \vec{y}_1)} \cdot \vec{y}_1, \\ \vec{y}_3 &= \vec{x}_3, \\ \vec{y}_4 &= \vec{x}_4 - \frac{(\vec{x}_4, \vec{y}_3)}{(\vec{y}_3, \vec{y}_3)} \cdot \vec{y}_3, \end{aligned}$$

odakle dobijamo

$$\begin{aligned} \vec{y}_1 &= (1, 1, 1, 2), \\ \vec{y}_2 &= (1, 2, 3, -3) - \frac{0}{7} \cdot (1, 1, 1, 2) \\ &= (1, 2, 3, -3), \\ \vec{y}_3 &= (1, -2, 1, 0), \\ \vec{y}_4 &= (-7, 5, 0, 1) - \frac{(-17)}{6} \cdot (1, -2, 1, 0) \\ &= \left(-\frac{25}{6}, -\frac{4}{6}, \frac{17}{6}, 1\right) \\ &= \frac{1}{6} \cdot (-25, -4, 17, 6). \end{aligned}$$

Dakle, jedna od ortogonalnih baza prostora \mathbb{R}^4 je

$$B_{\mathbb{R}^4} = \{(1, 1, 1, 2), (1, 2, 3, -3), (1, -2, 1, 0), (-25, -4, 17, 6)\}.$$

Zadatak 2.

Neka je

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 3 \\ -1 & 1 \\ 0 & 0 \\ -1 & 1 \end{bmatrix}.$$

Odrediti baze fundamentalnih potprostora matrice A pa provjeriti da li su ispunjeni odgovarajući uslovi njihove ortogonalnosti.

Rješenje

Iz proširene stepenaste forme matrice A :

$$\left[\begin{array}{cc|ccccc} 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & 3 & 0 & 1 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ -1 & 1 & 0 & 0 & 0 & 0 & 1 \end{array} \right] \xrightarrow{R_1 \leftrightarrow R_2} \left[\begin{array}{cc|ccccc} \boxed{1} & 3 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ -1 & 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ -1 & 1 & 0 & 0 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\substack{R_1+R_3 \\ R_1+R_5}} \left[\begin{array}{cc|ccccc} \boxed{1} & 3 & 0 & 1 & 0 & 0 & 0 \\ 0 & \boxed{1} & 1 & 0 & 0 & 0 & 0 \\ 0 & 4 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 4 & 0 & 1 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\substack{R_2 \cdot (-4) + R_3 \\ R_2 \cdot (-4) + R_5}} \left[\begin{array}{cc|ccccc} \boxed{1} & 3 & 0 & 1 & 0 & 0 & 0 \\ 0 & \boxed{1} & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & -4 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & -4 & 1 & 0 & 0 & 1 \end{array} \right]$$

dobijamo

$$B_{C(A)} = \left\{ \begin{bmatrix} 0 \\ 1 \\ -1 \\ 0 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 1 \\ 0 \\ 1 \end{bmatrix} \right\}, \quad B_{C(A^T)} = \left\{ \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\} = \mathbb{R}^2, \quad B_{N(A^T)} = \left\{ \begin{bmatrix} -4 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -4 \\ 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

Kako je $\mathcal{A} : \mathbb{R}^2 \rightarrow \mathbb{R}^5$, zaključujemo da je

$$\dim(C(A)) + \dim(N(A)) = 2.$$

Kako je $\dim(C(A)) = 2$, zaključujemo da je $\dim(N(A)) = 0$ pa je

$$B_{N(A)} = \left\{ \begin{bmatrix} 0 \\ 0 \end{bmatrix} \right\}.$$

Neka je

$$\vec{x}_1 = \begin{bmatrix} 1 \\ 3 \end{bmatrix}, \vec{x}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \vec{x}_3 = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \text{i} \quad \vec{y}_1 = \begin{bmatrix} 0 \\ 1 \\ -1 \\ 0 \\ -1 \end{bmatrix}, \vec{y}_2 = \begin{bmatrix} 1 \\ 3 \\ 1 \\ 0 \\ 1 \end{bmatrix}, \vec{y}_3 = \begin{bmatrix} -4 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \vec{y}_4 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \\ 0 \end{bmatrix}, \vec{y}_5 = \begin{bmatrix} -4 \\ 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}.$$

Kako vrijedi

$$(\vec{x}_1, \vec{x}_3) = 0 \quad \text{i} \quad (\vec{x}_2, \vec{x}_3) = 0$$

zaključujemo da je $C(A^T) \perp N(A)$.

Sa druge strane, kako vrijedi

$$(\vec{y}_1, \vec{y}_3) = 0, \quad (\vec{y}_1, \vec{y}_4) = 0, \quad (\vec{y}_1, \vec{y}_5) = 0, \quad (\vec{y}_2, \vec{y}_3) = 0, \quad (\vec{y}_2, \vec{y}_4) = 0 \quad \text{i} \quad (\vec{y}_2, \vec{y}_5) = 0$$

zaključujemo da je $C(A) \perp N(A^T)$.

Ovim smo pokazali ortogonalnost fundamentalnih potprostora matrice A .



Zadatak 3.

Neka je

$$A = \begin{bmatrix} 1 & -2 & a \\ -2 & 1 & b \\ -2 & -2 & c \end{bmatrix}.$$

Odrediti $a, b, c \in \mathbb{R}$ tako da matrica A ima ortogonalne kolone.

Rješenje

Kako su kolone $A_{\bullet 1}$ i $A_{\bullet 2}$ ortogonalne jer je $A_{\bullet 1}^T \cdot A_{\bullet 2} = 0$, matrica A će imati ortogonalne kolone ako vrijedi $A_{\bullet 1}^T \cdot A_{\bullet 3} = 0$ i $A_{\bullet 2}^T \cdot A_{\bullet 3} = 0$, tj. ako je

$$\begin{cases} a - 2b - 2c = 0 \\ -2a + b - 2c = 0 \end{cases} \Leftrightarrow \begin{cases} a - 2b = 2c \\ -2a + b = 2c \end{cases}$$

čije je rješenje $a = -2c$ i $b = -2c$. Dakle, da bi matrica A imala ortogonalno rješenje, potrebno je da vrijedi

$$(a, b, c) = (-2c, -2c, c).$$

Odabiranjem proizvoljne vrijednosti parametra c dobijamo jedno rješenje sistema. Npr. za $c = -1$ dobijamo da je

$$(a, b, c) = (2, 2, -1).$$

Zadatak 4.

Odrediti jednu ortonormiranu bazu prostora kolona matrice

$$A = \begin{bmatrix} 1 & 3 & 8 \\ 1 & 3 & 0 \\ 1 & -1 & 0 \\ 1 & -1 & 0 \end{bmatrix}$$

a onda odrediti ortogonalnu dopunu od $C(A)$.

Rješenje

Iz proširene stepenaste forme matrice A :

$$\begin{aligned} \left[\begin{array}{ccc|cccc} \boxed{1} & 3 & 8 & 1 & 0 & 0 & 0 \\ 1 & 3 & 0 & 0 & 1 & 0 & 0 \\ 1 & -1 & 0 & 0 & 0 & 1 & 0 \\ 1 & -1 & 0 & 0 & 0 & 0 & 1 \end{array} \right] & \xrightarrow{\substack{R_1 \cdot (-1) + R_2 \\ R_1 \cdot (-1) + R_3 \\ R_1 \cdot (-1) + R_4}} \left[\begin{array}{ccc|cccc} \boxed{1} & 3 & 8 & 1 & 0 & 0 & 0 \\ 0 & 0 & -8 & -1 & 1 & 0 & 0 \\ 0 & -4 & -8 & -1 & 0 & 1 & 0 \\ 0 & -4 & -8 & -1 & 0 & 0 & 1 \end{array} \right] & \xrightarrow{R_2 \leftrightarrow R_3} \left[\begin{array}{ccc|cccc} \boxed{1} & 3 & 8 & 1 & 0 & 0 & 0 \\ 0 & \boxed{-4} & -8 & -1 & 0 & 1 & 0 \\ 0 & 0 & -8 & -1 & 1 & 0 & 0 \\ 0 & -4 & -8 & -1 & 0 & 0 & 1 \end{array} \right] \\ & \xrightarrow{R_2 \cdot (-1) + R_4} \left[\begin{array}{ccc|cccc} \boxed{1} & 3 & 8 & 1 & 0 & 0 & 0 \\ 0 & \boxed{-4} & -8 & -1 & 0 & 1 & 0 \\ 0 & 0 & \boxed{-8} & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 & 1 \end{array} \right] \end{aligned}$$

dobijamo da je

$$C(A) = \{\vec{x}_1, \vec{x}_2, \vec{x}_3\}$$

pri čemu je

$$\vec{x}_1 = \begin{bmatrix} 1 & 1 & 1 & 1 \end{bmatrix}^T, \quad \vec{x}_2 = \begin{bmatrix} 3 & 3 & -1 & -1 \end{bmatrix}^T, \quad \vec{x}_3 = \begin{bmatrix} 8 & 0 & 0 & 0 \end{bmatrix}^T.$$

Koristeći Gram-Šmitov postupak ortogonalizacije, ortogonalne vektore \vec{y}_1 , \vec{y}_2 i \vec{y}_3 dobijamo iz formula:

$$\begin{aligned} \vec{y}_1 &= \vec{x}_1, \\ \vec{y}_2 &= \vec{x}_2 - \frac{(\vec{x}_2, \vec{y}_1)}{(\vec{y}_1, \vec{y}_1)} \cdot \vec{y}_1, \\ \vec{y}_3 &= \vec{x}_3 - \frac{(\vec{x}_3, \vec{y}_1)}{(\vec{y}_1, \vec{y}_1)} \cdot \vec{y}_1 - \frac{(\vec{x}_3, \vec{y}_2)}{(\vec{y}_2, \vec{y}_2)} \cdot \vec{y}_2. \end{aligned}$$

Računanjem dobijamo

$$\begin{aligned} \vec{y}_1 &= \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \\ \vec{y}_2 &= \begin{bmatrix} 3 \\ 3 \\ -1 \\ -1 \end{bmatrix} - \frac{4}{4} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \\ -2 \\ -2 \end{bmatrix}, \\ \vec{y}_3 &= \begin{bmatrix} 8 \\ 0 \\ 0 \\ 0 \end{bmatrix} - \frac{8}{4} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} - \frac{16}{16} \cdot \begin{bmatrix} 2 \\ 2 \\ -2 \\ -2 \end{bmatrix} = \begin{bmatrix} 4 \\ -4 \\ 0 \\ 0 \end{bmatrix}. \end{aligned}$$

Kako je

$$\|\vec{y}_1\| = 2, \quad \|\vec{y}_2\| = 4 \text{ i } \|\vec{y}_3\| = 4\sqrt{2},$$

tražena ortonormirana baza prostora $C(A)$ je

$$B_{C(A)} = \left\{ \frac{1}{2} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \frac{1}{4} \cdot \begin{bmatrix} 2 \\ 2 \\ -2 \\ -2 \end{bmatrix}, \frac{1}{4\sqrt{2}} \cdot \begin{bmatrix} 4 \\ -4 \\ 0 \\ 0 \end{bmatrix} \right\}$$

odnosno

$$B_{C(A)} = \left\{ \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \\ -\frac{1}{2} \end{bmatrix}, \begin{bmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \\ 0 \\ 0 \end{bmatrix} \right\}.$$

Kako je $C(A) \perp N(A^T)$, iz stepenaste forme matrice A dobijamo da je ortogonalna dopuna prostora $C(A)$:

$$N(A^T) = \text{Lin} \left\{ \begin{bmatrix} 0 \\ 0 \\ -1 \\ 1 \end{bmatrix} \right\}.$$

Zadatak 5.

Da li postoji ortogonalna matrica $Q \in \mathcal{M}_3$ čija je prva kolona $\vec{q}_1 = \begin{bmatrix} \frac{3}{5} & 0 & -\frac{4}{5} \end{bmatrix}^T$? Obrazložiti odgovor.

Rješenje

Neka su $\vec{q}_1, \vec{q}_2, \vec{q}_3$ kolone matrice Q . Da bi matrica Q bila ortogonalna, potrebno je da vrijedi

$$\vec{q}_1 \perp \vec{q}_2, \quad \vec{q}_1 \perp \vec{q}_3 \quad \text{i} \quad \vec{q}_2 \perp \vec{q}_3.$$

Neka je

$$\vec{q}_2 = \begin{bmatrix} x_2 \\ y_2 \\ z_2 \end{bmatrix}.$$

Kako je $\vec{q}_1 \perp \vec{q}_2$ imamo da je $(\vec{q}_1, \vec{q}_2) = 0$ odnosno

$$\frac{3}{5} \cdot x_2 + 0 \cdot y_2 - \frac{4}{5} \cdot z_2 = 0.$$

Odaberimo proizvoljan vektor \vec{q}_2 tako da vrijedi prethodna jednakost. Neka je

$$\vec{q}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}.$$

Kako je $\vec{q}_1 \perp \vec{q}_3$ i $\vec{q}_2 \perp \vec{q}_3$, vrijedi $(\vec{q}_1, \vec{q}_3) = 0$ i $(\vec{q}_2, \vec{q}_3) = 0$. Ako je

$$\vec{q}_3 = \begin{bmatrix} x_3 \\ y_3 \\ z_3 \end{bmatrix}$$

imamo da je

$$\begin{aligned} \frac{3}{5} \cdot x_3 + 0 \cdot y_3 - \frac{4}{5} \cdot z_3 &= 0 \\ 0 \cdot x_3 + 1 \cdot y_3 + 0 \cdot z_3 &= 0. \end{aligned}$$

Iz prethodnog sistema dobijamo $y_3 = 0$ i $x_3 = \frac{4}{3}z_3$.

Izborom proizvoljne vrijednosti z_3 dobijamo vektor \vec{q}_3 koji je ortogonalan na vektore \vec{q}_1 i \vec{q}_2 . Npr. za $z_3 = 1$ dobijamo

$$\vec{q}_3 = \begin{bmatrix} \frac{4}{3} \\ 0 \\ 1 \end{bmatrix}.$$

Konačno, matrica

$$Q = \begin{bmatrix} \frac{3}{5} & 0 & \frac{4}{3} \\ 0 & 1 & 0 \\ -\frac{4}{5} & 0 & 1 \end{bmatrix}$$

je jedna ortogonalna matrica čija je prva kolona \vec{q}_1 . Važno je napomenuti da ovakvih matrica ima beskonačno mnogo, a gore navedena matrica Q je samo jedna od njih.

Zadatak 6.

Neka je

$$V = \text{Lin} \left\{ \begin{bmatrix} 0 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 4 \\ 5 \end{bmatrix} \right\}.$$

Odrediti ortonormiranu bazu prostora V^\perp .

Rješenje

Ako bazne vektore prostora V predstavimo kao kolone matrice A , koristeći činjenicu da je $C(A) \perp N(A^T)$ iz stepenaste forme proširene matrice A

$$\left[\begin{array}{cc|cccc} 0 & 1 & 1 & 0 & 0 & 0 \\ 2 & 3 & 0 & 1 & 0 & 0 \\ 3 & 4 & 0 & 0 & 1 & 0 \\ 4 & 5 & 0 & 0 & 0 & 1 \end{array} \right] \xrightarrow{R_1 \leftrightarrow R_2} \left[\begin{array}{cc|cccc} \boxed{2} & 3 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 \\ 3 & 4 & 0 & 0 & 1 & 0 \\ 4 & 5 & 0 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\begin{array}{l} R_1 \cdot (-\frac{3}{2}) + R_3 \\ R_1 \cdot (-2) + R_4 \end{array}} \left[\begin{array}{cc|cccc} \boxed{2} & 3 & 0 & 1 & 0 & 0 \\ 0 & \boxed{1} & 1 & 0 & 0 & 0 \\ 0 & -\frac{1}{2} & 0 & -\frac{3}{2} & 1 & 0 \\ 0 & -1 & 0 & -2 & 0 & 1 \end{array} \right] \xrightarrow{\begin{array}{l} R_2 \cdot \frac{1}{2} + R_3 \\ R_2 + R_4 \end{array}} \left[\begin{array}{cc|cccc} \boxed{2} & 3 & 0 & 1 & 0 & 0 \\ 0 & \boxed{1} & 1 & 0 & 0 & 0 \\ 0 & 0 & \frac{1}{2} & -\frac{3}{2} & 1 & 0 \\ 0 & 0 & 1 & -2 & 0 & 1 \end{array} \right]$$

dobijamo da je

$$V^\perp = \text{Lin} \left\{ \begin{bmatrix} \frac{1}{2} \\ \frac{3}{2} \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

Da bismo odredili ortogonalnu bazu prostora V^\perp koristimo Gram-Šmitov postupak ortogonalizacije:

$$\begin{aligned} \vec{y}_1 &= \begin{bmatrix} \frac{1}{2} \\ \frac{3}{2} \\ 1 \\ 0 \end{bmatrix}, \\ \vec{y}_2 &= \begin{bmatrix} 1 \\ -2 \\ 0 \\ 1 \end{bmatrix} - \frac{\begin{bmatrix} 1 \\ -2 \\ 0 \\ 1 \end{bmatrix}^T \cdot \begin{bmatrix} \frac{1}{2} \\ \frac{3}{2} \\ 1 \\ 0 \end{bmatrix}}{\begin{bmatrix} \frac{1}{2} \\ \frac{3}{2} \\ 1 \\ 0 \end{bmatrix}^T \cdot \begin{bmatrix} \frac{1}{2} \\ \frac{3}{2} \\ 1 \\ 0 \end{bmatrix}} \cdot \begin{bmatrix} \frac{1}{2} \\ \frac{3}{2} \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 0 \\ 1 \end{bmatrix} - \frac{\frac{7}{2}}{\frac{7}{2}} \cdot \begin{bmatrix} \frac{1}{2} \\ \frac{3}{2} \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ -1 \\ 1 \end{bmatrix} \end{aligned}$$

Ortonormiranjem vektora \vec{y}_1 i \vec{y}_2 dobijamo ortonormiranu bazu prostora V^\perp :

$$\begin{aligned} \vec{q}_1 &= \frac{1}{\sqrt{(\frac{1}{2})^2 + (\frac{3}{2})^2 + 1^2 + 0^2}} \cdot \begin{bmatrix} \frac{1}{2} \\ \frac{3}{2} \\ 1 \\ 0 \end{bmatrix} = \frac{2}{\sqrt{14}} \cdot \begin{bmatrix} \frac{1}{2} \\ \frac{3}{2} \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{14}} \\ \frac{3}{\sqrt{14}} \\ \frac{2}{\sqrt{14}} \\ 0 \end{bmatrix}, \\ \vec{q}_2 &= \frac{1}{\sqrt{(\frac{1}{2})^2 + (-\frac{1}{2})^2 + (-1)^2 + 1^2}} \cdot \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ -1 \\ 1 \end{bmatrix} = \frac{2}{\sqrt{10}} \cdot \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{10}} \\ -\frac{1}{\sqrt{10}} \\ -\frac{2}{\sqrt{10}} \\ \frac{2}{\sqrt{10}} \end{bmatrix}. \end{aligned}$$

Dakle, ortonormirana baza prostora V^\perp je

$$B_{V^\perp} = \left\{ \begin{bmatrix} \frac{1}{\sqrt{14}} \\ \frac{3}{\sqrt{14}} \\ \frac{2}{\sqrt{14}} \\ 0 \end{bmatrix}, \begin{bmatrix} \frac{1}{\sqrt{10}} \\ -\frac{1}{\sqrt{10}} \\ -\frac{2}{\sqrt{10}} \\ \frac{2}{\sqrt{10}} \end{bmatrix} \right\}.$$

Zadatak 7.

Odrediti ortogonalnu projekciju i ortogonalnu komponentu vektora $\vec{x} = (4, -1, -3, 4)$ na potprostor generisan vektorima $\vec{a} = (1, 1, 1, 1)$, $\vec{b} = (1, 2, 2, -1)$ i $\vec{c} = (1, 0, 0, 3)$.

Rješenje

Na početku, odredimo potprostor V^\perp ortogonalan na potprostor V generisan vektorima \vec{a} , \vec{b} i \vec{c} . Iz stepenaste forme proširene matrice

$$\left[\begin{array}{ccc|cccc} \boxed{1} & 1 & 1 & 1 & 0 & 0 & 0 \\ 1 & 2 & 0 & 0 & 1 & 0 & 0 \\ 1 & 2 & 0 & 0 & 0 & 1 & 0 \\ 1 & -1 & 3 & 0 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\substack{R_1 \cdot (-1) + R_2 \\ R_1 \cdot (-1) + R_3 \\ R_1 \cdot (-1) + R_4}} \left[\begin{array}{ccc|cccc} \boxed{1} & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & \boxed{1} & -1 & -1 & 1 & 0 & 0 \\ 0 & 1 & -1 & -1 & 0 & 1 & 0 \\ 0 & -2 & 2 & -1 & 0 & 0 & 1 \end{array} \right] \xrightarrow{\substack{R_2 \cdot (-1) + R_3 \\ R_2 \cdot 2 + R_4}} \left[\begin{array}{ccc|cccc} \boxed{1} & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & \boxed{1} & -1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & -3 & 2 & 0 & 1 \end{array} \right]$$

vidimo da je vektor \vec{c} linearno zavisin sa vektorima \vec{a} i \vec{b} pa je

$$B_V = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 2 \\ -1 \end{bmatrix} \right\}$$

dok je

$$B_{V^\perp} = \left\{ \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -3 \\ 2 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

Vektor \vec{x} moguće je razložiti kao zbir vektora $\vec{y} \in V$ i $\vec{z} \in V^\perp$.

Tada je \vec{y} ortogonalna projekcija vektora \vec{x} na potprostor V dok je \vec{z} ortogonalna komponenta vektora \vec{x} . Iz jednačine

$$\vec{x} = \begin{bmatrix} 4 \\ -1 \\ -3 \\ 4 \end{bmatrix} = \alpha \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \beta \cdot \begin{bmatrix} 1 \\ 2 \\ 2 \\ -1 \end{bmatrix} + \gamma \cdot \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \end{bmatrix} + \delta \cdot \begin{bmatrix} -3 \\ 2 \\ 0 \\ 1 \end{bmatrix}$$

dobijamo sistem

$$\begin{cases} \alpha + \beta - 3\delta = 4 \\ \alpha + 2\beta - \gamma + 2\delta = -1 \\ \alpha + 2\beta + \gamma = -3 \\ \alpha - \beta + \delta = 4 \end{cases}$$

čije je rješenje $\alpha = 3$, $\beta = -2$, $\gamma = -2$, $\delta = -1$. Odavde je

$$\begin{aligned} \vec{y} &= \alpha \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \beta \cdot \begin{bmatrix} 1 \\ 2 \\ 2 \\ -1 \end{bmatrix} = 3 \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} - 2 \cdot \begin{bmatrix} 1 \\ 2 \\ 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ -1 \\ 5 \end{bmatrix} \\ \vec{z} &= \gamma \cdot \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \end{bmatrix} + \delta \cdot \begin{bmatrix} -3 \\ 2 \\ 0 \\ 1 \end{bmatrix} = -2 \cdot \begin{bmatrix} 0 \\ -1 \\ 1 \\ 0 \end{bmatrix} - \begin{bmatrix} -3 \\ 2 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \\ -2 \\ -1 \end{bmatrix} \end{aligned}$$

pa je dakle vektor $\vec{y} = (1, -1, -1, 5)$ ortogonalna projekcija vektora \vec{x} na potprostor generisan vektorima \vec{a} , \vec{b} i \vec{c} .

Vektor $\vec{z} = (3, 0, -2, -1)$ je ortogonalna komponenta vektora \vec{x} .

Zadatak 8.

Odrediti matricu ortogonalnog projektovanja na prostor $Lin \left\{ \begin{bmatrix} 1 \\ 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} \right\}$.

Rješenje

Neka je vektorski prostor $V = Lin \left\{ \begin{bmatrix} 1 \\ 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix} \right\}$.

Korištenjem stepenaste forme proširene matrice A u kojoj se po kolonama nalaze bazni vektori vektorskog prostora V :

$$\left[\begin{array}{c|cccc} \boxed{1} & 1 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 1 & 0 & 0 \\ -1 & 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right] \xrightarrow[R_1+R_3]{R_1 \cdot (-1)+R_2} \left[\begin{array}{c|cccc} \boxed{1} & 1 & 1 & 0 & 0 & 0 \\ 0 & \boxed{-1} & -1 & 1 & 0 & 0 \\ 0 & 2 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right] \xrightarrow[R_2+R_4]{R_2 \cdot 2+R_3} \left[\begin{array}{c|cccc} \boxed{1} & 1 & 1 & 0 & 0 & 0 \\ 0 & \boxed{-1} & -1 & 1 & 0 & 0 \\ 0 & 0 & -1 & 2 & 1 & 0 \\ 0 & 1 & -1 & 1 & 0 & 1 \end{array} \right]$$

dobijamo da je $V^\perp = Lin \left\{ \begin{bmatrix} -1 \\ 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 0 \\ 1 \end{bmatrix} \right\}$. Kako je $V + V^\perp = \mathbb{R}^4$, skup

$$\mathcal{B}_N = \left\{ \begin{bmatrix} 1 \\ 1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ 0 \\ 1 \end{bmatrix} \right\}$$

je baza prostora \mathbb{R}^4 . Po bazi \mathcal{B}_N , matrica ortogonalnog projektovanja na prostor V je

$$P_{\mathcal{B}_N} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

Kako je potrebno odrediti matricu ortogonalnog projektovanja na prostor V po standardnoj bazi \mathcal{B}_S prostora \mathbb{R}^4 i kako je matrica prelaska

$$S_{\mathcal{B}_N \rightarrow \mathcal{B}_S} = \begin{bmatrix} 1 & 1 & -1 & -1 \\ 1 & 0 & 2 & 1 \\ -1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix},$$

matricu projektovanja po standardnoj bazi \mathcal{B}_S dobijamo kao:

$$\begin{aligned} P_{\mathcal{B}_S} &= S_{\mathcal{B}_N \rightarrow \mathcal{B}_S} \cdot P_{\mathcal{B}_N} \cdot S_{\mathcal{B}_S \rightarrow \mathcal{B}_N} \\ &= \begin{bmatrix} 1 & 1 & -1 & -1 \\ 1 & 0 & 2 & 1 \\ -1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \cdot \begin{bmatrix} 1 & 1 & -1 & -1 \\ 1 & 0 & 2 & 1 \\ -1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 \end{bmatrix}^{-1} \\ &= \begin{bmatrix} \frac{2}{3} & \frac{1}{3} & 0 & \frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} & -\frac{1}{3} & 0 \\ 0 & -\frac{1}{3} & \frac{2}{3} & \frac{1}{3} \\ \frac{1}{3} & 0 & \frac{1}{3} & \frac{1}{3} \end{bmatrix}. \end{aligned}$$

Zadatak 9.

Data je matrica

$$A = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \\ -1 & 1 & -1 & 1 \\ -1 & -1 & -1 & -1 \end{bmatrix}.$$

Odrediti projekcije vektora $\begin{bmatrix} 1 \\ 1 \\ 2 \\ 3 \end{bmatrix} \in \mathbb{R}^4$ na potprostore $N(A)$ i $C(A^T)$.

Rješenje

Iz stepenaste forme proširene matrice A^T

$$\left[\begin{array}{cccc|cccc} \boxed{1} & 1 & -1 & -1 & 1 & 0 & 0 & 0 \\ 1 & -1 & 1 & -1 & 0 & 1 & 0 & 0 \\ 1 & 1 & -1 & -1 & 0 & 0 & 1 & 0 \\ 1 & -1 & 1 & -1 & 0 & 0 & 0 & 1 \end{array} \right] \xrightarrow[R_1 \cdot (-1) + R_4]{\begin{matrix} R_1 \cdot (-1) + R_2 \\ R_1 \cdot (-1) + R_3 \end{matrix}} \left[\begin{array}{cccc|cccc} \boxed{1} & 1 & -1 & -1 & 1 & 0 & 0 & 0 \\ 0 & \boxed{-2} & 2 & 0 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 1 & 0 \\ 0 & -2 & 2 & 0 & -1 & 0 & 0 & 1 \end{array} \right] \xrightarrow{R_2 \cdot (-1) + R_4} \left[\begin{array}{cccc|cccc} \boxed{1} & 1 & -1 & -1 & 1 & 0 & 0 & 0 \\ 0 & \boxed{-2} & 2 & 0 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & -1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & -1 & 0 & 1 \end{array} \right]$$

dobijamo da je

$$C(A^T) = \text{Lin} \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} \right\} \text{ i } N(A) = \text{Lin} \left\{ \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

Vektor $\vec{x} = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 3 \end{bmatrix}$ moguće je razložiti kao zbir vektora $\vec{y} \in C(A^T)$ i $\vec{z} \in N(A)$.

Tada je \vec{y} ortogonalna projekcija vektora \vec{x} na potprostor $C(A^T)$ dok je \vec{z} ortogonalna projekcija vektora \vec{x} na potprostor $N(A)$.
Iz jednačine

$$\vec{x} = \begin{bmatrix} 1 \\ 1 \\ 2 \\ 3 \end{bmatrix} = \alpha \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \beta \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} + \gamma \cdot \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + \delta \cdot \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix}$$

dobijamo sistem

$$\begin{cases} \alpha + \beta - \gamma & = 1 \\ \alpha - \beta & - \delta = 1 \\ \alpha + \beta + \gamma & = 2 \\ \alpha - \beta & + \delta = 3 \end{cases}$$

čije je rješenje $\alpha = \frac{7}{4}$, $\beta = -\frac{1}{4}$, $\gamma = \frac{1}{2}$, $\delta = 1$. Odavde je

$$\begin{aligned} \vec{y} &= \alpha \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \beta \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} = \frac{7}{4} \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{4} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} \frac{3}{2} \\ 2 \\ \frac{3}{2} \\ 2 \end{bmatrix} \\ \vec{z} &= \gamma \cdot \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + \delta \cdot \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} = \frac{1}{2} \cdot \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ -1 \\ \frac{1}{2} \\ 1 \end{bmatrix} \end{aligned}$$

pa je dakle vektor $\vec{y} = \begin{bmatrix} \frac{3}{2} \\ 2 \\ \frac{3}{2} \\ 2 \end{bmatrix}$ projekcija vektora \vec{x} na potprostor $C(A^T)$.

Vektor $\vec{z} = \begin{bmatrix} -\frac{1}{2} \\ -1 \\ \frac{1}{2} \\ 1 \end{bmatrix}$ je projekcija vektora \vec{x} na potprostor $N(A)$.

Zadatak 10.

Neka je $\mathbb{R}_2(x)$ vektorski prostor realnih polinoma stepena ne većeg od 2 i neka je u tom vektorskom prostoru skalarni proizvod definisan sa

$$(p(x), q(x)) = \int_0^{+\infty} e^{-x} p(x) q(x) dx.$$

Odrediti ortonormiranu bazu tog prostora pomoću Gram-Šmitovog postupka ortogonalizacije polazeći od standardne baze tog prostora $\{1, x, x^2\}$.

Rješenje

Polazeći od polinoma $p_0(x) = 1$, $p_1(x) = x$ i $p_2(x) = x^2$, odredićemo ortogonalne polinome $q_0(x)$, $q_1(x)$ i $q_2(x)$ koristeći Gram-Šmitov postupak:

$$\begin{aligned} q_0(x) &= p_0(x) = 1, \\ q_1(x) &= p_1(x) - \frac{(p_1(x), q_0(x))}{(q_0(x), q_0(x))} \cdot q_0(x), \\ q_2(x) &= p_2(x) - \frac{(p_2(x), q_0(x))}{(q_0(x), q_0(x))} \cdot q_0(x) - \frac{(p_2(x), q_1(x))}{(q_1(x), q_1(x))} \cdot q_1(x). \end{aligned}$$

Koristeći definiciju skalarnog proizvoda dobijamo:

$$\begin{aligned} (q_0(x), q_0(x)) &= \int_0^{+\infty} e^{-x} \cdot 1 \cdot 1 dx = -e^{-x} \Big|_0^{+\infty} = -\lim_{x \rightarrow +\infty} e^{-x} - (-e^0) = 1 \\ (p_1(x), q_0(x)) &= \int_0^{+\infty} e^{-x} \cdot x \cdot 1 dx \quad \begin{cases} u = x \\ du = dx \\ v = -e^{-x} \\ dv = e^{-x} dx \end{cases} \\ &= -xe^{-x} \Big|_0^{+\infty} - \int_0^{+\infty} -e^{-x} dx = -\left(\lim_{x \rightarrow +\infty} xe^{-x} - 0 \cdot e^0\right) - e^{-x} \Big|_0^{+\infty} = -\lim_{x \rightarrow +\infty} \frac{x}{e^x} - \left(\lim_{x \rightarrow +\infty} e^{-x} - e^0\right) = 1 \end{aligned}$$

pa je

$$q_1(x) = x - \frac{1}{1} \cdot 1 = x - 1.$$

Dalje je

$$\begin{aligned} (p_2(x), q_0(x)) &= \int_0^{+\infty} e^{-x} \cdot x^2 \cdot 1 dx \quad \begin{cases} u = x^2 \\ du = 2x dx \\ v = -e^{-x} \\ dv = e^{-x} dx \end{cases} \\ &= -x^2 e^{-x} \Big|_0^{+\infty} + \int_0^{+\infty} e^{-x} \cdot 2x dx = -\left(\lim_{x \rightarrow +\infty} x^2 e^{-x} - 0^2 \cdot e^0\right) + 2 \cdot (p_1(x), q_0(x)) = -\lim_{x \rightarrow +\infty} \frac{x^2}{e^x} + 2 = 2 \\ (q_1(x), q_1(x)) &= \int_0^{+\infty} e^{-x} \cdot (x-1)^2 dx = \int_0^{+\infty} e^{-x} \cdot (x^2 - 2x + 1) dx = \int_0^{+\infty} e^{-x} \cdot x^2 dx - 2 \cdot \int_0^{+\infty} e^{-x} \cdot x dx + \int_0^{+\infty} e^{-x} dx \\ &= (p_2(x), q_0(x)) - 2 \cdot (p_1(x), q_0(x)) + (q_0(x), q_0(x)) \\ &= 2 - 2 \cdot 1 + 1 = 1 \end{aligned}$$

$$\begin{aligned} (p_2(x), q_1(x)) &= \int_0^{+\infty} e^{-x} \cdot x^2 \cdot (x-1) dx = \int_0^{+\infty} e^{-x} \cdot x^3 dx - \int_0^{+\infty} e^{-x} \cdot x^2 dx \quad \begin{cases} u = x^3 \\ du = 3x^2 dx \\ v = -e^{-x} \\ dv = e^{-x} dx \end{cases} \\ &= -x^3 e^{-x} \Big|_0^{+\infty} + \int_0^{+\infty} e^{-x} \cdot 3x^2 dx - \int_0^{+\infty} e^{-x} \cdot x^2 dx = -\left(\lim_{x \rightarrow +\infty} \frac{x^3}{e^x} - 0^3 \cdot e^0\right) + 2 \cdot \int_0^{+\infty} e^{-x} \cdot x^2 dx \\ &= 2 \cdot (p_2(x), q_0(x)) = 4 \end{aligned}$$

pa je

$$q_2(x) = x^2 - \frac{2}{1} \cdot 1 - \frac{4}{1} \cdot (x-1) = x^2 - 2 - 4x + 4 = x^2 - 4x + 2.$$

Dakle, ortogonalna baza prostora $\mathbb{R}_2(x)$ je

$$B_{\mathbb{R}_2(x)} = \{q_0(x), q_1(x), q_2(x)\} = \{1, x-1, x^2-4x+2\}.$$

Prethodnu bazu je potrebno ortonormirati.

Kako je

$$\left(q_0\left(x\right),q_0\left(x\right)\right)=1$$

$$\left(q_1\left(x\right),q_1\left(x\right)\right)=1$$

$$\left(q_2\left(x\right),q_2\left(x\right)\right)=\int_0^{+\infty}e^{-x}\cdot\left(x^2-4x+2\right)^2dx=\int_0^{+\infty}e^{-x}\cdot\left(x^4-8x^3+20x^2-16x+4\right)dx$$

$$=\int_0^{+\infty}e^{-x}\cdot x^4dx-8\cdot\int_0^{+\infty}e^{-x}\cdot x^3dx+20\cdot\int_0^{+\infty}e^{-x}\cdot x^2dx-16\cdot\int_0^{+\infty}e^{-x}\cdot xdx+4\cdot\int_0^{+\infty}e^{-x}dx\qquad\left\{\begin{array}{l}u=x^4\\du=4x^3dx\\v=-e^{-x}\\dv=e^{-x}dx\end{array}\right.$$

$$=-x^4e^{-x}\Big|_0^{+\infty}+\int_0^{+\infty}e^{-x}\cdot 4x^3dx-8\cdot\int_0^{+\infty}e^{-x}\cdot x^3dx+20\cdot\int_0^{+\infty}e^{-x}\cdot x^2dx-16\cdot\int_0^{+\infty}e^{-x}\cdot xdx+4\cdot\int_0^{+\infty}e^{-x}dx$$

$$=-\left(\lim_{x\rightarrow+\infty}\frac{x^4}{e^x}-0^4\cdot e^0\right)-4\cdot\int_0^{+\infty}e^{-x}\cdot x^3dx+20\cdot\left(p_2\left(x\right),q_0\left(x\right)\right)-16\cdot\left(p_1\left(x\right),q_0\left(x\right)\right)+4\cdot\left(q_0\left(x\right),q_0\left(x\right)\right)\qquad\left\{\begin{array}{l}u=x^3\\du=3x^2dx\\v=-e^{-x}\\dv=e^{-x}dx\end{array}\right.$$

$$=-4\cdot\left(-x^3e^{-x}\Big|_0^{+\infty}+\int_0^{+\infty}e^{-x}\cdot 3x^2dx\right)+20\cdot 2-16\cdot 1+4\cdot 1$$

$$=4\cdot\left(\lim_{x\rightarrow+\infty}\frac{x^3}{e^x}-0^3\cdot e^0\right)-12\cdot\int_0^{+\infty}e^{-x}\cdot x^2dx+28$$

$$=-12\cdot\left(p_2\left(x\right),q_0\left(x\right)\right)+28$$

$$=-12\cdot 2+28=4,$$

ortonormirana baza prostora $\mathbb{R}_2(x)$ je

$$\begin{aligned}B_{\mathbb{R}_2(x)}&=\left\{\frac{1}{\|q_0(x)\|}\cdot q_0(x),\frac{1}{\|q_1(x)\|}\cdot q_1(x),\frac{1}{\|q_2(x)\|}\cdot q_2(x)\right\}\\&=\left\{\frac{1}{\sqrt{(q_0(x),q_0(x))}}\cdot q_0(x),\frac{1}{\sqrt{(q_1(x),q_1(x))}}\cdot q_1(x),\frac{1}{\sqrt{(q_2(x),q_2(x))}}\cdot q_2(x)\right\}\\&=\left\{q_0(x),q_1(x),\frac{1}{2}\cdot q_2(x)\right\}\\&=\left\{1,x-1,\frac{x^2-4x+2}{2}\right\}\\&=\left\{1,x-1,\frac{x^2}{2}-2x+1\right\}.\end{aligned}$$