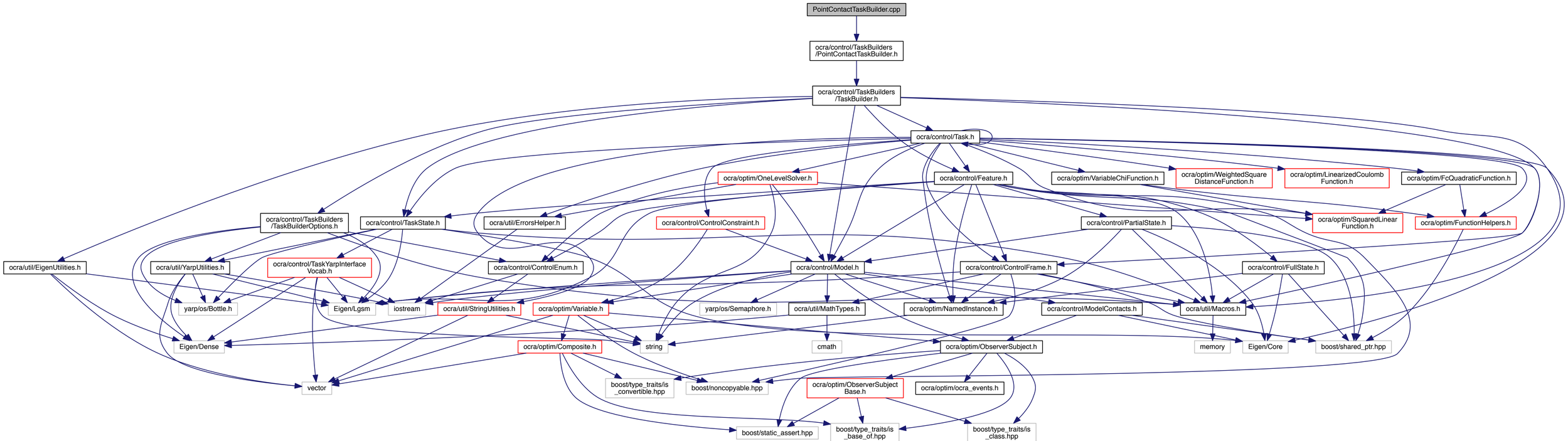
PointContactTaskBuilder.cpp
ocra/control/TaskBuilders/PointContactTaskBuilder.h
ocra/control/TaskBuilders/TaskBuilder.h
ocra/control/Task.h
ocra/optim/OneLevelSolver.h
ocra/control/Feature.h
ocra/optim/VariableChiFunction.h
ocra/optim/WeightedSquareDistanceFunction.h
ocra/optim/LinearizedCoulombFunction.h
ocra/optim/FcQuadraticFunction.h
ocra/control/TaskBuilders/TaskBuilderOptions.h
ocra/control/TaskState.h
ocra/util/ErrorsHelper.h
ocra/control/ControlConstraint.h
ocra/control/PartialState.h
ocra/optim/SquaredLinearFunction.h
ocra/optim/FunctionHelpers.h
ocra/util/EigenUtilities.h
ocra/util/YarpUtilities.h
ocra/control/TaskYarpInterfaceVocab.h
ocra/control/ControlEnum.h
ocra/control/Model.h
ocra/control/ControlFrame.h
ocra/control/FullState.h
yarp/os/Bottle.h
Eigen/Lgsm
iostream
ocra/util/StringUtilities.h
ocra/optim/Variable.h
yarp/os/Semaphore.h
ocra/util/MathTypes.h
ocra/optim/NamedInstance.h
ocra/control/ModelContacts.h
ocra/util/Macros.h
Eigen/Dense
ocra/optim/Composite.h
string
cmath
ocra/optim/ObserverSubject.h
memory
Eigen/Core
boost/shared_ptr.hpp
vector
boost/type_traits/is_convertible.hpp
boost/noncopyable.hpp
ocra/optim/ObserverSubjectBase.h
ocra/optim/ocra_events.h
boost/static_assert.hpp
boost/type_traits/is_base_of.hpp
boost/type_traits/is_class.hpp