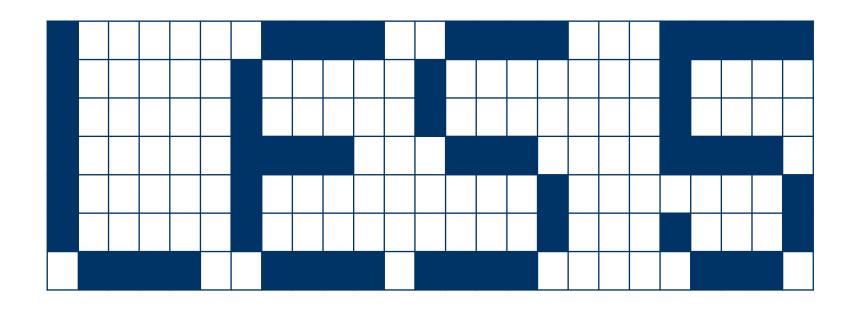


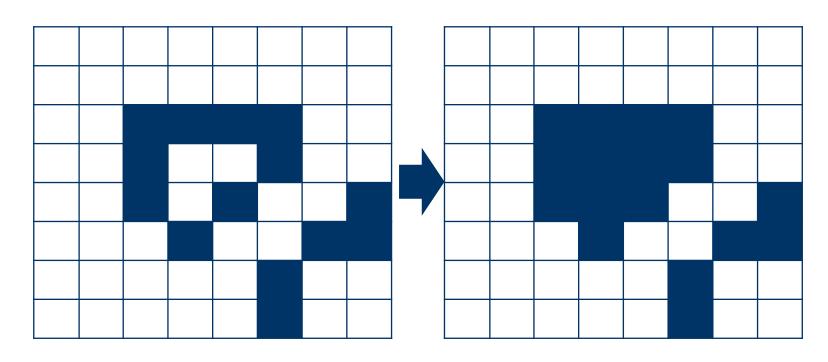


## **EVD1 – Vision operators**









Source

**Destination** 





	1	1	1	1		
	1			1		
	1		1			1
		1			1	1
				1		
				1		

2	2	2	2	2	2	2	2
2							2
2		1	1	1	1		2
2		1			1		2
2		1		1			1
2			1			1	1
2					1		2
2	2	2	2	2	1	2	2

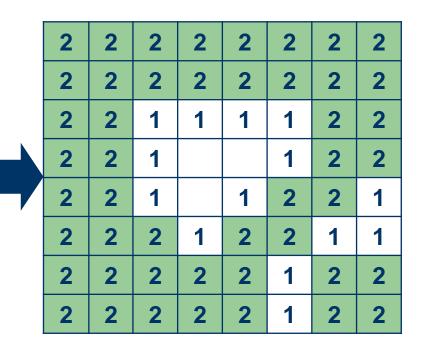
**Source** 

1. Markeer alleen de rand pixels die niet deel uitmaken van een blob





2	2	2	2	2	2	2	2
2							2
2		1	1	1	1		2
2		1			1		2
2		1		1			1
2			1			1	1
2					1		2
2	2	2	2	2	1	2	2

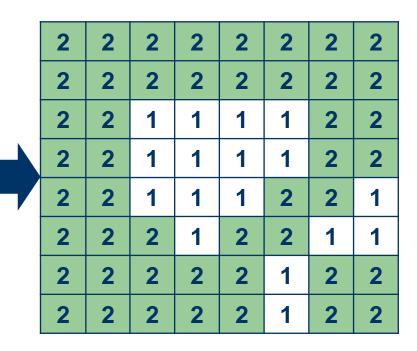


#### 2. Markeer alle background pixels





2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2
2	2	1	1	1	1	2	2
2	2	1			1	2	2
2	2	1		1	2	2	1
2	2	2	1	2	2	1	1
2	2	2	2	2	1	2	2
2	2	2	2	2	1	2	2

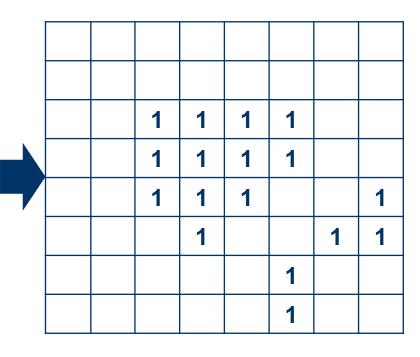


3. Set alle gaten op 1





2	2	2	2	2	2	2	2
2	2	2	2	2	2	2	2
2	2	1	1	1	1	2	2
2	2	1	1	1	1	2	2
2	2	1	1	1	2	2	1
2	2	2	1	2	2	1	1
2	2	2	2	2	1	2	2
2	2	2	2	2	1	2	2



4. Maak alle gemarkeerde pixels 0





### Fill holes

#### **Opdracht**

Implementeer de functie:

vFillHoles()

Gebruik iNeighbourCount()