

oCpt::components::sensors
::KalmanIMU::init



```
graph LR; A["oCpt::components::sensors  
::KalmanIMU::init"] --> B["oCpt::Sensor::init"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is light gray with a black border and contains the text 'oCpt::components::sensors' on the first line and '::KalmanIMU::init' on the second line. The right box is white with a black border and contains the text 'oCpt::Sensor::init'. A blue arrow points from the right side of the left box to the left side of the right box.

oCpt::Sensor::init