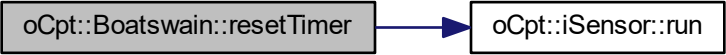


oCpt::Boatswain::resetTimer



```
graph LR; A[oCpt::Boatswain::resetTimer] --> B[oCpt::iSensor::run];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'oCpt::Boatswain::resetTimer'. The right box is white and contains the text 'oCpt::iSensor::run'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

oCpt::iSensor::run