

oCpt::components::sensors  
::KalmanIMU::run



```
graph LR; A[oCpt::components::sensors::KalmanIMU::run] --> B[oCpt::Sensor::run];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is light gray with a black border and contains the text 'oCpt::components::sensors' on the first line and '::KalmanIMU::run' on the second line. The right box is white with a black border and contains the text 'oCpt::Sensor::run'. A blue arrow points from the right side of the left box to the left side of the right box.

oCpt::Sensor::run