

oCpt::components::sensors  
::Gps::updateSensor



```
graph LR; A["oCpt::components::sensors  
::Gps::updateSensor"] --> B["oCpt::Sensor::updateSensor"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is light gray with a black border and contains the text 'oCpt::components::sensors' on the first line and '::Gps::updateSensor' on the second line. The right box is white with a black border and contains the text 'oCpt::Sensor::updateSensor'. A dark blue arrow points from the right side of the left box to the left side of the right box.

oCpt::Sensor::updateSensor