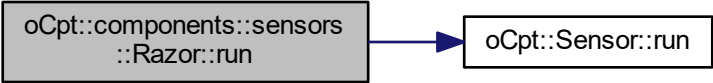


oCpt::components::sensors
::Razor::run



```
graph LR; A[oCpt::components::sensors::Razor::run] --> B[oCpt::Sensor::run];
```

A diagram showing a call from a function to another function. On the left, a gray rectangular box contains the text "oCpt::components::sensors" on the first line and "::Razor::run" on the second line. A dark blue arrow points from the right side of this box to the left side of a white rectangular box on the right. The white box contains the text "oCpt::Sensor::run".

oCpt::Sensor::run