

oCpt::components::sensors
::Gps::run



```
graph LR; A["oCpt::components::sensors  
::Gps::run"] --> B["oCpt::Sensor::run"]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'oCpt::components::sensors' on the top line and '::Gps::run' on the bottom line. The right box is white with a black border and contains the text 'oCpt::Sensor::run'. A dark blue arrow points from the right side of the gray box to the left side of the white box.

oCpt::Sensor::run