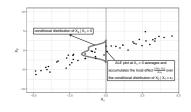
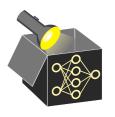
Interpretable Machine Learning

Accumulated Local Effect (ALE): Introduction

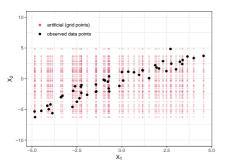


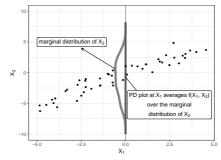


- PD plots and its extrapolation issue
- M plots and its omitted-variable bias
- Understand ALE plots



MOTIVATION - CORRELATED FEATURES





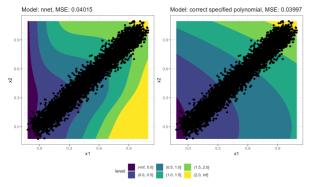


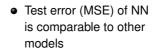
- PD plots average over predictions of artificial points that are out of distribution/ unlikely (red)
 - \Rightarrow Can lead to misleading / biased interpretations, especially if model also contains interactions
- Not wanted if interest is to interpret effects within data distribution

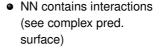
MOTIVATION - CORRELATED FEATURES

Example: Fit a NN to 5000 simulated data points with $x \sim \textit{Unif}(0,1), \epsilon \sim \textit{N}(0,0.2)$ and

$$y = x_1 + x_2^2 + \epsilon$$
, where $x_1 = x + \epsilon_1$, $x_2 = x + \epsilon_2$ and $\epsilon_1, \epsilon_2 \sim N(0, 0.05)$.





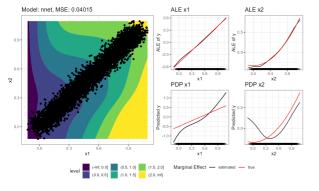




MOTIVATION - CORRELATED FEATURES

Example: Fit a NN to 5000 simulated data points with $x \sim \textit{Unif}(0,1), \epsilon \sim \textit{N}(0,0.2)$ and

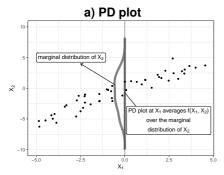
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- Test error (MSE) of NN is comparable to other models
- NN contains interactions (see complex pred. surface)
- ALE in line with ground truth
- PDP does not reflect ground truth effects of DGP well
 - ⇒ Due to interactions and averaging of points outside data distribution

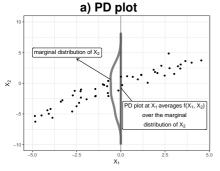
M PLOT VS. PD PLOT

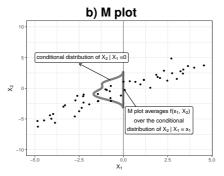


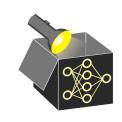


a) PD plot
$$\mathbb{E}_{\mathbf{x}_2}\left(\hat{f}(x_1,\mathbf{x}_2)\right)$$
 is estimated by $\hat{f}_{1,PD}(x_1)=\frac{1}{n}\sum_{i=1}^n\hat{f}(x_1,\mathbf{x}_2^{(i)})$

M PLOT VS. PD PLOT



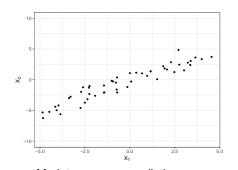


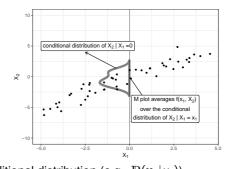


- a) PD plot $\mathbb{E}_{\mathbf{x}_2}\left(\hat{f}(x_1,\mathbf{x}_2)\right)$ is estimated by $\hat{f}_{1,PD}(x_1)=\frac{1}{n}\sum_{i=1}^n\hat{f}(x_1,\mathbf{x}_2^{(i)})$
- **b)** M plot $\mathbb{E}_{\mathbf{x}_2|\mathbf{x}_1}\left(\hat{f}(x_1,\mathbf{x}_2)\middle|\mathbf{x}_1\right)$ is estimated by $\hat{f}_{1,M}(x_1)=\frac{1}{|N(x_1)|}\sum_{i\in N(x_1)}\hat{f}(x_1,\mathbf{x}_2^{(i)}),$ where index set $N(x_1)=\{i:x_1^{(i)}\in[x_1-\epsilon,x_1+\epsilon]\}$ refers to observations with feature value close to x_1 .

M PLOT VS. PD PLOT

are present







- M plots average predictions over conditional distribution (e.g., $\mathbb{P}(\mathbf{x}_2|x_1)$) ⇒ Averaging predictions close to data distribution avoid extrapolation issues
- But: M plots suffer from omitted-variable bias (OVB)
 - They contain effects of other dependent features
 - Useless in assessing a feature's marginal effect if feature dependencies

M PLOT VS. PD PLOT - OVB EXAMPLE

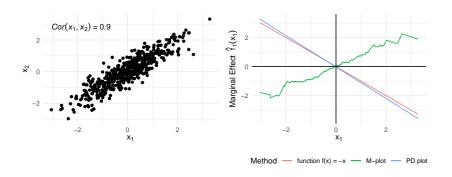




Illustration: Fit LM on 500 i.i.d. observations with features $x_1, x_2 \sim N(0, 1)$, $Cor(x_1, x_2) = 0.9$ and

$$y = -x_1 + 2 \cdot x_2 + \epsilon, \ \epsilon \sim N(0, 1).$$

Results: M plot of x_1 also includes marginal effect of all other dependent features (here: x_2)

Idea: To remove unwanted effects of other features, take partial derivatives (local effects) of prediction function w.r.t. feature of interest and integrate (accumulate) them w.r.t. the same feature

- \Rightarrow Computing the partial derivative of \hat{f} w.r.t. \mathbf{x}_j removes other main effects
- \Rightarrow Integrating again w.r.t. \mathbf{x}_j recovers the original main effect of \mathbf{x}_j



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Example:

Consider an additive prediction function:

$$\hat{f}(x_1,x_2)=2x_1+2x_2-4x_1x_2$$



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Example:

Consider an additive prediction function:

$$\hat{f}(x_1,x_2)=2x_1+2x_2-4x_1x_2$$

• Partial derivative of \hat{t} w.r.t. x_1 : $\frac{\partial \hat{f}(x_1, x_2)}{\partial x_1} = 2 - 4x_2$



Idea: To remove unwanted effects of other features, take partial derivatives (local effects) of prediction function w.r.t. feature of interest and integrate (accumulate) them w.r.t. the same feature

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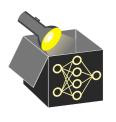


Consider an additive prediction function:

$$\hat{f}(x_1,x_2)=2x_1+2x_2-4x_1x_2$$

- Partial derivative of \hat{t} w.r.t. x_1 : $\frac{\partial \hat{t}(x_1, x_2)}{\partial x_1} = 2 4x_2$
- Integral of partial derivative $(z_0 = \min(x_1))$:

$$\int_{z_0}^{x} \frac{\partial \hat{f}(x_1, x_2)}{\partial x_1} dx_1 = [2x_1 - 4x_1 x_2]_{z_0}^{x}$$



Idea: To remove unwanted effects of other features, take partial derivatives (local effects) of prediction function w.r.t. feature of interest and integrate (accumulate) them w.r.t. the same feature

- \Rightarrow Computing the partial derivative of \hat{f} w.r.t. \mathbf{x}_j removes other main effects
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Consider an additive prediction function:

$$\hat{f}(x_1,x_2)=2x_1+2x_2-4x_1x_2$$

- Partial derivative of \hat{t} w.r.t. x_1 : $\frac{\partial \hat{t}(x_1, x_2)}{\partial x_1} = 2 4x_2$
- Integral of partial derivative $(z_0 = \min(x_1))$:

$$\int_{z_0}^{x} \frac{\partial \hat{f}(x_1, x_2)}{\partial x_1} dx_1 = [2x_1 - 4x_1 x_2]_{z_0}^{x}$$

• We removed the main effect of x_2 , which was our goal

