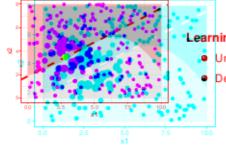
Interpretable Machine Learning

LIME



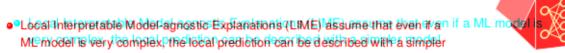


- Learning goals
 - Understand motivation for LIME
 - Develop a mathematical intuition for LIME
 - Develop a mathematical intuition



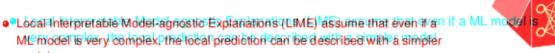
Local Interpretable Model agnostic Explanations (LIME) assume that even from if a ML model is very complex, the local prediction can be described with a simpler model.





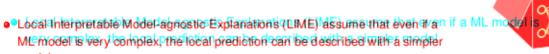
- model explains individual predictions of any black-box model by approximating the model
- LIME explains individual predictions of any black-box model by approximating the model locally with an interpretable model





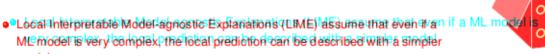
- model explains individual predictions of any black-box model by approximating the model
- LIME explains individual predictions of any black-box model by approximating
 the model locally with an interpretable model erently interpretable models such as linear models
- Called local surrogate models to often inherently interpretable models such as linear models or classification/regression trees are chosen





- model explains individual predictions of any black-box model by approximating the model
- LIME explains individual predictions of any black-box model by approximating
 the model locally with an interpretable model erently interpretable models such as linear models
- Called local surrogate models we often inherently interpretable models such as linear models or classification/regression trees are chosen out x
- LIME should answer why a ML model predicted ŷ for input x





- model explains individual predictions of any black-box model by approximating the model
- LIME explains individual predictions of any black-box model by approximating
 the model locally with an interpretable model erently interpretable models such as linear models
- Called local surrogate models to often inherently interpretable models such as linear models or classification/regression trees are chosen but x
- LIME should answer why a ML model predicted \hat{y} for input \hat{x} and text data
- LIME is model-agnostic and can handle tabular, image and text data

LIME: CHARACTERISTICS

Definition:

Lime provides a local explanation for a black-box model \hat{f} in form of a model $\hat{g} \in \mathcal{G}$. Lime provides a local explanation for a black-box model \hat{f} in form of a model \hat{g} with G as the class of potential (interpretable) models class of potential (interpretable) models

Model g should have two characteristics:

- Interpretable: relation between the input variables and the response are easy understand to understand
- Lbcarry valith tufy Fide lity! similar behavior as 7 in the vicinity of the folds, being being predicted predicted
- Formally, we want to receive a model \hat{q} with minimal complexity and maximal local-fidelity
- Formally, we want to receive a model \hat{q} with minimal complexity and maximal
- local-fidelity

MODEL COMPLEXITY

We can measure the complexity of a model \hat{g} -using a complexity-measure $J(\hat{g}) J(\hat{g})$

Example: Linear modellel

- $\bullet \mathsf{Let} \mathcal{G} = \{ g \mid g\mathcal{X} \not\rightarrow \mathbb{R} \mid \mathbb{R} g(\mathbf{x}) (\mathbf{x}) s (\theta^{\mathsf{T}} \mathbf{x}) \} \text{ be the class of sine at imodels odels}$
- s(-i): identity function for linear regression or logistic sigmoid function for logistic gistic regression
- \sim regression $\sum_{i=1}^{p} \mathcal{I}_{\{\theta_i \neq 0\}}$ could be the L₀ loss, i.e., the number of non-zero coefficients
- $J(g) = \sum_{j=1}^{p} \mathcal{I}_{\{\theta_j \neq 0\}}$ could be the L₀ loss, i.e., the number of non-zero coefficients

MODEL COMPLEXITY

We can measure the complexity of a model \hat{q} using a complexity measure $J(\hat{q}) J(\hat{q})$

Example: Linear model el

- Let $\mathcal{G} = \{g(\mathbf{x}) \not\to \mathbb{R} \mid \mathbb{R}(\mathbf{x}) \neq \mathbf{x}\}$ be the class of sine arimodels odels
- s(s): identity function for linear regression or logistic sigmoid function for logistic gistic regression
- \sim regression $\sum_{i=1}^{p} \mathcal{I}_{\{\theta_i \neq 0\}}$ could be the L₀ loss, i.e., the number of non-zero coefficients
- \rightarrow $J(g) = \sum_{i=1}^{p} \mathcal{I}_{\{\theta_i \neq 0\}}$ could be the L₀ loss, i.e., the number of non-zero

Exacoefficients

Let $\mathcal{G} = \left\{ g : \mathcal{X} \to \mathbb{R} \mid g(\mathbf{x}) = \sum_{m=1}^{M} c_m \mathcal{I}_{\{\mathbf{x} \in Q_m\}} \right\}$ be the class of trees i.e., the class of additive models (e.g., constant c_m) over the leaf-rectangles Q_m • Let $\mathcal{G} = \left\{ g : \mathcal{X} \to \mathbb{R} \mid g(\mathbf{x}) = \sum_{m=1}^{M} c_m \mathcal{I}_{\{\mathbf{x} \in Q_m\}} \right\}$ be the class of trees $\mathcal{G} = \left\{ g : \mathcal{X} \to \mathbb{R} \mid g(\mathbf{x}) = \sum_{m=1}^{M} c_m \mathcal{I}_{\{\mathbf{x} \in Q_m\}} \right\}$ be the class of trees

- i.e., the class of additive models (e.g., constant c_m) over the leaf-rectangles Q_m
- → J(g) could measure the number of terminal/leaf nodes

- g is locally faithfull to \hat{f} \hat{w} . n, n, if for $z \in \mathbb{Z} \subseteq \mathbb{R}^p$ close to n, the predictions of $\hat{g}(z)$ are close to f(z)• are close to $\hat{f}(\mathbf{z})$ tion task: the closer \mathbf{z} is to \mathbf{x} , the closer $\hat{g}(\mathbf{z})$ should be to $\hat{f}(\mathbf{z})$ • In an optimization task: the closer \mathbf{z} is to \mathbf{x} , the closer $\hat{g}(\mathbf{z})$ should be to $\hat{f}(\mathbf{z})$

- g is locally faithful to \hat{f} \hat{w} . r.t., \mathbf{x} if for $\mathbf{z} \in \mathcal{Z} \subseteq \mathbb{R}^p$ close to \mathbf{x} , the predictions of $\hat{g}(\mathbf{z})$ and $\hat{g}(\mathbf{z})$ are close to $f(\mathbf{z})$ • are close to $\hat{f}(z)$ tion task: the closer z is to x, the closer $\hat{g}(z)$ should be to $\hat{f}(z)$ • In an optimization task: the closer z is to x, the closer $\hat{g}(z)$ should be to $\hat{f}(z)$
- Two required measures $\phi_{\mathbf{x}}(\mathbf{z})$ between \mathbf{z} and \mathbf{x} , e.g. the exponential kerne
 - A proximity (similarity) measure $\phi_{\mathbf{x}}(\mathbf{z})$ between \mathbf{z} and \mathbf{x} , e.g. the $\phi_{\mathbf{x}}(\mathbf{z}) = \exp(-d(\mathbf{x},\mathbf{z})^2/\sigma^2)$ exponential kernel:

with σ as the kernel $\psi_{\sigma}(z) = exp(s) d(x, z)^2 / (s^2)$ and distance (numeric features) or the Gower distance (mixed features) with σ as the kernel width and d as the Euclidean distance (numeric

features) or the Gower distance (mixed features)

- g is locally faithful to \hat{f} \hat{w} . \mathbf{x} , \mathbf{x} , if for $\mathbf{z} \in \mathcal{Z} \subseteq \mathbb{R}^p$ close to \mathbf{x} , the predictions of $\hat{g}(\mathbf{z})$ are close to $f(\mathbf{z})$. • are close to $\hat{f}(z)$ tion task: the closer z is to x, the closer $\hat{g}(z)$ should be to $\hat{f}(z)$ • In an optimization task: the closer z is to x, the closer $\hat{g}(z)$ should be to $\hat{f}(z)$
- Two required measures $\phi_{\mathbf{x}}(\mathbf{z})$ between \mathbf{z} and \mathbf{x} , e.g. the exponential kernel
 - A proximity (similarity) measure $\phi_{\mathbf{x}}(\mathbf{z})$ between \mathbf{z} and \mathbf{x} , e.g. the $\phi_{\mathbf{x}}(\mathbf{z}) = \exp(-d(\mathbf{x},\mathbf{z})^2/\sigma^2)$ exponential kernel:

with σ as the kernel $\psi_{\sigma}(\mathbf{z}) = e^{i\mathbf{x}\mathbf{b}}(\mathbf{z}) + e^{i\mathbf{x}\mathbf{b}}(\mathbf{z})$ and distance (numeric features) or the

- Gower distance (mixed features)

 with a san the kernel width and d as the Euclidean distance (numerics) features) or the Gower distance (mixed features)
- A distance measure or loss function $\hat{t}(\hat{f}(z), \hat{g}(z))$, e.g. the \hat{L}_2 loss/squared error

$$L(\hat{f}(\mathbf{z}), \hat{g}(\mathbf{z})) = (\hat{g}(\mathbf{z}) - \hat{f}(\mathbf{z}))^2$$

- g is locally faithfull to \hat{f} \hat{w} . n, n, if for $z \in \mathbb{Z} \subseteq \mathbb{R}^p$ close to n, the predictions of $\hat{g}(z)$ are close to f(z)• are close to $\hat{f}(\mathbf{z})$ tion task: the closer \mathbf{z} is to \mathbf{x} , the closer $\hat{g}(\mathbf{z})$ should be to $\hat{f}(\mathbf{z})$ • In an optimization task; the closer \mathbf{z} is to \mathbf{x} , the closer $\hat{g}(\mathbf{z})$ should be to $\hat{f}(\mathbf{z})$
- Two required measures $\phi_{\mathbf{x}}(\mathbf{z})$ between \mathbf{z} and \mathbf{x} , e.g. the exponential kernel
 - A proximity (similarity) measure $\phi_{\mathbf{x}}(\mathbf{z})$ between \mathbf{z} and \mathbf{x} , e.g. the $\phi_{\mathbf{x}}(\mathbf{z}) = \exp(-d(\mathbf{x},\mathbf{z})^2/\sigma^2)$ exponential kernel:

with σ as the kernel $\psi_{\mathbf{x}}(\mathbf{z}) = exb(\mathbf{x}, \mathbf{z})^2 \sqrt{|\sigma|^2}$ and distance (numeric features) or the

- Gower distance (mixed features)

 with a san the kernel width and d as the Euclidean distance (numerics) features) or the Gower distance (mixed features)
- A distance measure or loss function $\hat{t}(\hat{f}(z), \hat{g}(z))$, e.g. the \hat{L}_2 loss/squared error
- Given points z, we can $mE(\hat{f}(z))e\hat{g}(z)$ $|f(z)|e\hat{g}(z)| = |f(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat{g}(z)|e\hat$
- Given points **z**, we can measure local fide lity of g with respect to \hat{f} in terms of a weighted loss

$$L(\hat{t}, g, \phi_{x}) = \sum_{\mathbf{z} \in \mathcal{Z}} \phi_{x}(\mathbf{z}) L(\hat{t}(\mathbf{z}), \hat{g}(\mathbf{z}))$$

MINIMIZATION TASK



Optimization objective of LIME!

$$\mathop{\arg\min}_{g\in\mathcal{G}} \mathcal{L}(F,\hat{g},\phi_{\mathbf{x}}) + \mathcal{G}(g)\hat{g},\phi_{\mathbf{x}}) + J(g)$$

- In practice:
- In practice only optimizes $L(\hat{t}, \hat{g}, \phi_x)$ (model-fidelity)
 - LIME only optimizes of $(f | \hat{g}_0 \phi_x)$ (model-fidelity) J(g) beforehand
 - Goal: model-agnostic explainer
- ullet Goal: model-agnostic explainer making any assumptions about \hat{t}
 - \sim optimize $L(\hat{t},\hat{g},\phi_{\mathbf{x}})$ without making any assumptions about \hat{t}
 - → learn ĝ only approximately

LIME ALGORITHM: OUTLINE

- Pre-trained model f
 Pre-trained model f

- Observation x whose prediction f(x) we want to explain
 Observation x whose prediction f(x) we want to explain
 Model class G for local surrogate (to limit the complexity of the explanation)
 Model class G for local surrogate (to limit the complexity of the explanation)



LIME ALGORITHM: OUTLINE

- Pre-trained model f

- Observation x whose prediction f(x) we want to explain
 Observation x whose prediction f(x) we want to explain
 Model class G for local surrogate (to limit the complexity of the explanation)
 Model class G for local surrogate (to limit the complexity of the explanation)

- Independently sample new points $\mathbf{z} \in \mathcal{Z}$ Independently sample new points $\mathbf{z} \in \mathcal{Z}$
- Retrieve predictions f(z) for obtained points zRetrieve predictions f(z) for obtained points z
- Weight $\mathbf{z} \in \mathcal{Z}$ by their proximity $\phi_{\mathbf{x}}(\mathbf{z})$ Weight $\mathbf{z} \in \mathcal{Z}$ by their proximity $\phi_{\mathbf{x}}(\mathbf{z})$
- Train an interpretable surrogate model g on weighted data points $\mathbf{z} \in \mathcal{Z}$. Train an interpretable surrogate model g on weighted data points $\mathbf{z} \in \mathcal{Z}$
- - → predictions f(z) are the target of this model
- Return the interpretable model \hat{g} as the explainer Return the interpretable model \hat{g} as the explainer



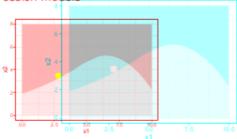
LIME ALGORITHM: EXAMPLE

Illustration of LIME based on a classification task:

Illustration of LIME based on a classification task face of a classifier

- Light/dark:gray background:prediction surface of a classifier
- Yellow pointf x to be explained n models

G: class of logistic regression models





LIME ALGORITHM: EXAMPLE (STEP 1+2: SAMPLING))

Ribeiro. 2016 Strategies for sampling:

Strategies for sampling:

- Use the training data set with or without perturbations
 Uniformly sample new points from the feasible feature range
 Draw samples from the estimated univariate distribution of each feature
- Use the training data set with or without perturbations ure range
- Draw samples from the estimated univariate distribution of each feature

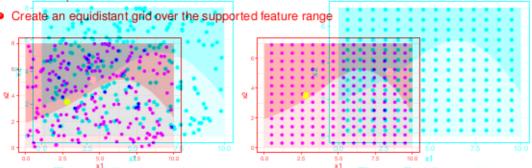


Figure: Equidistant grid

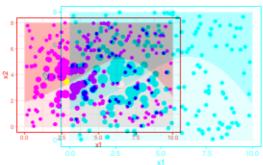
Interpretable Machine Learning - 8 / 10

LIME ALGORITHM: EXAMPLE (STEP 3: PROXIMITY)) • Riberto. 2016

▶ Ribeiro, 2016

In this example, we use the exponential kernel defined on the Euclidean distance d In this example, we use the exponential kernel defined on the Euclidean distance d

$$\begin{array}{l} \phi_{\mathbf{x}}(\mathbf{z}) = \exp(-d(\mathbf{x},\mathbf{z})^2/\sigma^2).\\ \phi_{\mathbf{x}}(\mathbf{z}) = \exp(-d(\mathbf{x},\mathbf{z})^2/\sigma^2). \end{array}$$





LIME ALGORITHM: EXAMPLE (STEP 4: SURROGATE)) * Riberto 2015

→ Ribeiro. 2016

In our example, we fit a **logistic regression** model (consequently, $L(\hat{f}(\mathbf{z}), \hat{g}(\mathbf{z}))$ is the Bernoull Levi

In our example, we fit a **logistic regression** model (consequently, $L(\hat{f}(\mathbf{z}), \hat{g}(\mathbf{z}))$ is the

Bernoulli loss)

