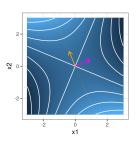
# **Optimization in Machine Learning**

# Mathematical Concepts: Quadratic forms II



## Learning goals

- Geometry of quadratic forms
- Eigenspectrum

# **Univariate function**

2nd derivative is a  $q''(x) = 2 \cdot a$ . Basic properties of q can be read-off:

- q''(x) > 0: q convex; q''(x) < 0: q concave
- High (lows) absolute values of q''(x): high (low) curvature

#### **Multivariate function**

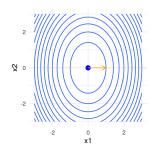
2nd derivative is a symmetric matrix of values **H** (called Hessian).

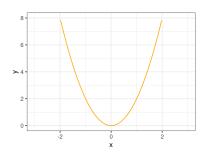
Now: See how Eigenspectrum of  $\mathbf{H}$  encodes the basic properties of q.

**Example 1**: Function composed of two univariate quadratic terms

$$q(\mathbf{x}) = \mathbf{x}^{\top} \mathbf{A} \mathbf{x} = \mathbf{x}^{\top} \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \mathbf{x} = 2 \cdot x_1^2 + x_2^2$$

with 
$$\nabla q(\mathbf{x}) = 2 \cdot \mathbf{A} \cdot \mathbf{x} = 4 \cdot x_1 + 2 \cdot x_2$$
,  $\mathbf{H} = 2 \cdot \mathbf{A} = \begin{pmatrix} 4 & 0 \\ 0 & 2 \end{pmatrix}$ 



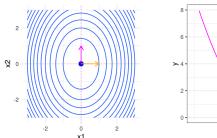


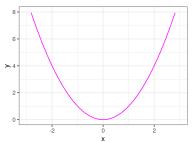
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q has a high positive curvature of 4 in the direction of  $v = (1,0)^{\top}$ , and a lower (positive) curvature of 2 in direction of  $v = (0,1)^{\top}$ .

#### Takeaway I:

- Hessian encodes curvature
- If the Hessian H is diagonal, the diagonal elements encode the curvature of the function:
  - *i*-th diagonal element gives us the curvature in the direction of  $\mathbf{v} = \mathbf{e}_i$  because

$$\mathbf{v}^{\top}\mathbf{H}\mathbf{v} = \mathbf{e}_{i}^{\top}\mathbf{H}\mathbf{e}_{i} = h_{ii}.$$

ullet The curvature in an arbitrary direction  $oldsymbol{v} \in \mathbb{R}^d$ ,  $\|oldsymbol{v}\| = 1$ , is

$$\mathbf{v}^{\top} \mathbf{H} \mathbf{v} = h_{11} v_1^2 + h_{22} v_2^2 + ... + h_{dd} v_d^2.$$

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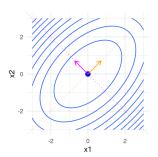
 For general (non-diagonal) matrices we analyze the eigenspectrum of H

**Note:** For diagonal matrices the eigenspectrum is is to read-off: Diagonal elements of **H eigenvalues**, unit vectors **eigenvectors** 

$$\mathbf{He_1} = \begin{pmatrix} 4 & 0 \\ 0 & 2 \end{pmatrix} = \mathbf{4} \cdot \mathbf{e_1}; \qquad \mathbf{He_2} = \begin{pmatrix} 4 & 0 \\ 0 & 2 \end{pmatrix} = \mathbf{2} \cdot \mathbf{e_2}$$

#### Example 2:

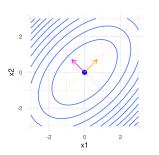
$$q(\mathbf{x}) = \mathbf{x}^{\top} \mathbf{A} \mathbf{x} = \mathbf{x}^{\top} \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \mathbf{x},$$
 with  $\nabla q(\mathbf{x}) = 2 \cdot \mathbf{A} \cdot \mathbf{x}$ ,  $\nabla^2 q(\mathbf{x}) = \mathbf{H} = 2 \cdot \mathbf{A} = \begin{pmatrix} 4 & -2 \\ -2 & 4 \end{pmatrix}$ 



In the general case, the curvature is determined by the Eigenspectrum of H.

#### Takeaway II:

- Geometrically, directions of highest / lowest curvature along main axes of ellipses representing the contour lines of q.
- Mathematically, the direction with the highest (lowest) curvature is the direction of the eigenvector  $\mathbf{v}_{max}$  ( $\mathbf{v}_{min}$ ) belonging to largest (smallest) eigenvalue  $\lambda_{max}$  ( $\lambda_{min}$ ) of **H**.



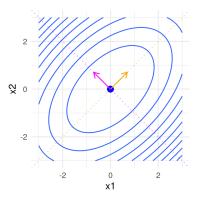
The eigenvectors and eigenvalues of  $\mathbf{H} = \begin{pmatrix} 4 & -2 \\ -2 & 4 \end{pmatrix}$  are:

$$v_{\text{min}} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \qquad \lambda_{\text{min}} = 2$$

$$\mathbf{v}_{\min} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad \lambda_{\min} = 2$$

$$\mathbf{v}_{\max} = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \quad \lambda_{\max} = 3$$

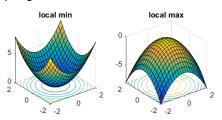
Direction  $v_{\text{max}}$  is also direction in which the function increases fastest.



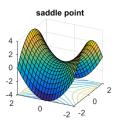
"Walking" the same distance along  $v_{max}$  (magenta) makes us pass more level curves than walking along any other direction.

If eigenspectrum of  $\bf A$  is known, i.e. the set of its eigenvalues  $\{\lambda_1,\lambda_2,...,\lambda_d\}$ , also eigenspectrum of  $\bf H=2\cdot \bf A$  is known and we can read off:

- If **all** eigenvalues of the  $\boldsymbol{H}$  are > 0 (we call  $\boldsymbol{H}$  positive definite):
  - the function q is convex,
  - there is a unique global minimum.
- If **all** eigenvalues of the **H** are < 0 (we call **H** negative definite):
  - the function q is concave,
  - there is a unique global maximum.



- If there are both positive and negative eigenvalues (we call H indefinite):
  - the function *q* is neither concave nor convex,
  - there is a saddle point.



**Example**: Sketch the following function

$$q(\mathbf{x}) = \mathbf{x}^{\top} \begin{pmatrix} -1 & -1 \\ -1 & 1 \end{pmatrix} \mathbf{x}$$

Step 1: Compute the Hessian

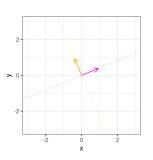
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Step 2: Compute eigenvectors / -values:

$$\begin{array}{rcl} \textbf{v}_1 & = & \begin{pmatrix} 1-\sqrt{2} \\ 1 \end{pmatrix}, & \quad \lambda_1 = 2\sqrt{2} \\ \\ \textbf{v}_2 & = & \begin{pmatrix} 1+\sqrt{2} \\ 1 \end{pmatrix}, & \quad \lambda_2 = -2\sqrt{2}. \end{array}$$

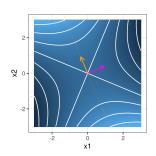


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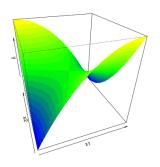
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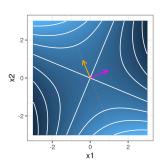
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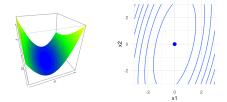




## **EIGENSPECTRUM AND CONDITION**

Also the condition can be read off from Eigenspectrum:  $\kappa(\mathbf{A}) = \frac{|\lambda_{\max}|}{|\lambda_{\min}|}$ . A high condition means:

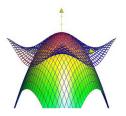
- The absolute value of the biggest eigenvalue  $\lambda_{\text{max}}$  is much larger than the absolute value of the lowest eigenvalue  $\lambda_{\text{min}}$ .
- The curvature in the direction of minimum curvature (v<sub>max</sub>) is much lower than the one in the direction of maximum curvature (v<sub>min</sub>).
- We will see later: optimization algorithms like gradient descent will have difficulties optimizing such functions.



# INTERPRETATION OF GENERAL FUNCTIONS

Every function can be locally approximated by a quadratic function via 2nd order Taylor approximation:

$$f(x) \approx f(\tilde{\boldsymbol{x}}) + \nabla f(\tilde{\boldsymbol{x}})^{\top} (\mathbf{x} - \tilde{\boldsymbol{x}}) + \frac{1}{2} (\mathbf{x} - \tilde{\boldsymbol{x}})^{\top} \nabla^2 f(\tilde{\boldsymbol{x}}) (\mathbf{x} - \tilde{\boldsymbol{x}})$$



f is shown as the hollow grid and its second-order approximation at (0,0) as a continuous surface. Source: daniloroccatano.blog.

By analyzing  $\nabla^2 f(\tilde{\mathbf{x}})$  we can gain a local understanding of a function's geometry.