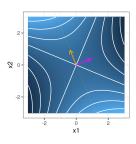
Optimization

Quadratic forms II



Learning goals

- Geometry of quadratic forms
- Eigenspectrum

Univariate function

2nd derivative is a $q''(x) = 2 \cdot a$. Basic properties of q can be read-off:

- q''(x) > 0: q convex; q''(x) < 0: q concave
- High (lows) absolute values of q''(x): high (low) curvature

Multivariate function

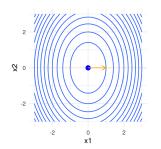
2nd derivative is a symmetric matrix of values **H** (called Hessian).

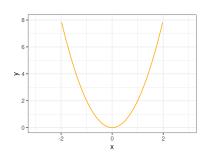
Now: See how Eigenspectrum of \mathbf{H} encodes the basic properties of q.

Example 1: Function composed of two univariate quadratic terms

$$q(\mathbf{x}) = \mathbf{x}^{\top} \mathbf{A} \mathbf{x} = \mathbf{x}^{\top} \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \mathbf{x} = 2 \cdot x_1^2 + x_2^2$$

with
$$\nabla q(\mathbf{x}) = 2 \cdot \mathbf{A} \cdot \mathbf{x} = 4 \cdot x_1 + 2 \cdot x_2$$
, $\mathbf{H} = 2 \cdot \mathbf{A} = \begin{pmatrix} 4 & 0 \\ 0 & 2 \end{pmatrix}$



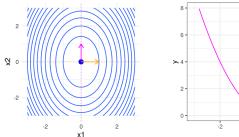


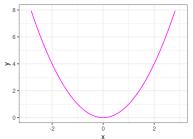
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q has a high positive curvature of 4 in the direction of $v = (1,0)^{\top}$, and a lower (positive) curvature of 2 in direction of $v = (0,1)^{\top}$.

Takeaway I:

- Hessian encodes curvature
- If the Hessian H is diagonal, the diagonal elements encode the curvature of the function:
 - *i*-th diagonal element gives us the curvature in the direction of $\mathbf{v} = \mathbf{e}_i$ because

$$\mathbf{v}^{\top}\mathbf{H}\mathbf{v} = \mathbf{e}_{i}^{\top}\mathbf{H}\mathbf{e}_{i} = h_{ii}.$$

ullet The curvature in an arbitrary direction $oldsymbol{v} \in \mathbb{R}^d, \|oldsymbol{v}\| = 1$, is

$$\mathbf{v}^{\top} \mathbf{H} \mathbf{v} = h_{11} v_1^2 + h_{22} v_2^2 + ... + h_{dd} v_d^2.$$

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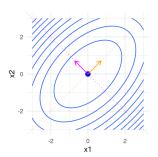
 For general (non-diagonal) matrices we analyze the eigenspectrum of H

Note: For diagonal matrices the eigenspectrum is is to read-off: Diagonal elements of **H eigenvalues**, unit vectors **eigenvectors**

$$\mathbf{He_1} = \begin{pmatrix} \mathbf{4} & \mathbf{0} \\ \mathbf{0} & \mathbf{2} \end{pmatrix} = \mathbf{4} \cdot \mathbf{e_1}; \qquad \mathbf{He_2} = \begin{pmatrix} \mathbf{4} & \mathbf{0} \\ \mathbf{0} & \mathbf{2} \end{pmatrix} = \mathbf{2} \cdot \mathbf{e_2}$$

Example 2:

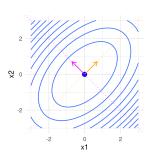
$$q(\mathbf{x}) = \mathbf{x}^{\top} \mathbf{A} \mathbf{x} = \mathbf{x}^{\top} \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \mathbf{x},$$
 with $\nabla q(\mathbf{x}) = 2 \cdot \mathbf{A} \cdot \mathbf{x}$, $\nabla^2 q(\mathbf{x}) = \mathbf{H} = 2 \cdot \mathbf{A} = \begin{pmatrix} 4 & -2 \\ -2 & 4 \end{pmatrix}$



In the general case, the curvature is determined by the Eigenspectrum of H.

Takeaway II:

- Geometrically, directions of highest / lowest curvature along main axes of ellipses representing the contour lines of q.
- Mathematically, the direction with the highest (lowest) curvature is the direction of the eigenvector \mathbf{v}_{max} (\mathbf{v}_{min}) belonging to largest (smallest) eigenvalue λ_{max} (λ_{min}) of **H**.



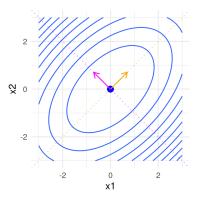
The eigenvectors and eigenvalues of $\mathbf{H} = \begin{pmatrix} 4 & -2 \\ -2 & 4 \end{pmatrix}$ are:

$$v_{min} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad \lambda_{min} = 2$$

$$\mathbf{v}_{\text{min}} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad \lambda_{\text{min}} = 2$$

$$\mathbf{v}_{\text{max}} = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \quad \lambda_{\text{max}} = 3$$

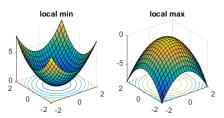
Direction v_{max} is also direction in which the function increases fastest.



"Walking" the same distance along \mathbf{v}_{max} (magenta) makes us pass more level curves than walking along any other direction.

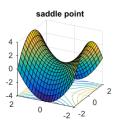
If eigenspectrum of $\bf A$ is known, i.e. the set of its eigenvalues $\{\lambda_1,\lambda_2,...,\lambda_d\}$, also eigenspectrum of $\bf H=2\cdot \bf A$ is known and we can read off:

- If **all** eigenvalues of the \boldsymbol{H} are > 0 (we call \boldsymbol{H} positive definite):
 - the function q is convex,
 - there is a unique global minimum.
- If **all** eigenvalues of the **H** are < 0 (we call **H** negative definite):
 - the function q is concave,
 - there is a unique global maximum.



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- If there are both positive and negative eigenvalues (we call H indefinite):
 - the function *q* is neither concave nor convex,
 - there is a saddle point.



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Example: Sketch the following function

$$q(\mathbf{x}) = \mathbf{x}^{\top} \begin{pmatrix} -1 & -1 \\ -1 & 1 \end{pmatrix} \mathbf{x}$$

Step 1: Compute the Hessian

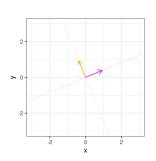
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Step 2: Compute eigenvectors / -values:

$$\begin{array}{rcl} \textbf{\textit{v}}_1 & = & \begin{pmatrix} 1-\sqrt{2} \\ 1 \end{pmatrix}, & \quad \lambda_1 = 2\sqrt{2} \\ \\ \textbf{\textit{v}}_2 & = & \begin{pmatrix} 1+\sqrt{2} \\ 1 \end{pmatrix}, & \quad \lambda_2 = -2\sqrt{2}. \end{array}$$

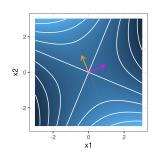


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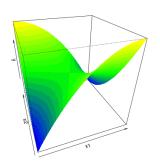
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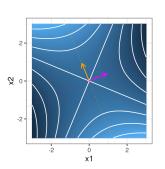
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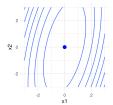


EIGENSPECTRUM AND CONDITION

Also the condition can be read off from Eigenspectrum: $\kappa(\mathbf{A}) = \frac{|\lambda_{\max}|}{|\lambda_{\min}|}$. A high condition means:

- The absolute value of the biggest eigenvalue λ_{max} is much larger than the absolute value of the lowest eigenvalue λ_{min} .
- The curvature in the direction of minimum curvature (v_{max}) is much lower than the one in the direction of maximum curvature (v_{min}).
- We will see later: optimization algorithms like gradient descent will have difficulties optimizing such functions.



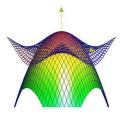


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INTERPRETATION OF GENERAL FUNCTIONS

Every function can be locally approximated by a quadratic function via 2nd order Taylor approximation:

$$f(x) \approx f(\tilde{\mathbf{x}}) + \nabla f(\tilde{\mathbf{x}})^{\top} (\mathbf{x} - \tilde{\mathbf{x}}) + \frac{1}{2} (\mathbf{x} - \tilde{\mathbf{x}})^{\top} \nabla^{2} f(\tilde{\mathbf{x}}) (\mathbf{x} - \tilde{\mathbf{x}})$$



f is shown as the hollow grid and its second-order approximation at (0,0) as a continuous surface. Source: daniloroccatano.blog.

By analyzing $\nabla^2 f(\tilde{\mathbf{x}})$ we can gain a local understanding of a function's geometry.