Nonlinear Programming 1

## Exercise 1: Nonlinear SVM

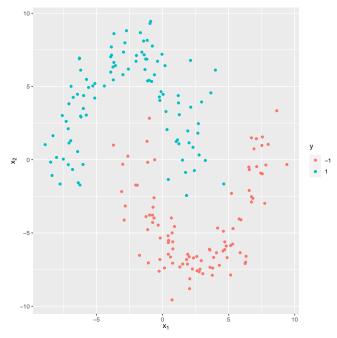
You are given the following data situation:

```
library(ggplot2)
library(mlr3)

# generate 200 nonlinear separable binary observations
set.seed(123)
moon_data = tgen("moons")$generate(200)$data()

moon_data$y = ifelse(moon_data$y == "A", 1, -1)
moon_data$y_dec = as.factor(moon_data$y)

ggplot(moon_data, aes(x=x1, y=x2)) +
    geom_point(aes(color=y_dec)) +
    xlab(expression(x[1])) +
    ylab(expression(x[2])) +
    labs(color=expression(y))
```



We can extend the linear SVM to a nonlinear SVM by transforming the features via a nonlinear transformation  $\phi: \mathbb{R}^d \to \mathbb{R}^l$ . With this, the primal form with soft constraints becomes

$$\min_{\boldsymbol{\theta}, \theta_0, \boldsymbol{\zeta}} 0.5 \|\boldsymbol{\theta}\|^2 + C \sum_{i=1}^n \zeta^{(i)}$$

$$y^{(i)}(\langle \boldsymbol{\theta}, \phi(\mathbf{x}^{(i)}) \rangle + \theta_0) \ge 1 - \zeta^{(i)} \quad \forall i \in \{1, \dots, n\}$$

$$\zeta^{(i)} \ge 0 \quad \forall i \in \{1, \dots, n\}.$$

- (a) Write down the general Lagrangian function of the nonlinear SVM
- (b) Solve the primal nonlinear SVM for C=1 and third order polynomial transformation (without intercept)  $\phi(\mathbf{x})=(x_1,x_2,x_1^2,x_2^2,x_1^3,x_2^3,x_1x_2,x_1^2x_2,x_1x_2^2)^{\mathsf{T}}$  with cvxr in R. Hint: Examples how quadratic problems can be solved with cvxr can be found here.
- (c) State the KKT conditions of the general nonlinear SVM
- (d) Derive the dual form of the nonlinear SVM. State an advantage of the dual form over the primal form. *Hint:* Use the KKT conditions to transform the primal form
- (e) Solve the dual form of b) with cvxr in R. Hint 1: For a polynomial transformation  $\phi$  of order l (without intercept) it holds that there exists a invertible diagonal matrix  $\mathbf{D} \in \mathbb{R}^9$  such that  $\langle \mathbf{D}\phi(\mathbf{x}), \mathbf{D}\phi(\mathbf{z}) \rangle = (\mathbf{x}^\top \mathbf{z} + 1)^l - 1$ Hint 2: Add  $10^{-7} \cdot \mathbf{I}$  to the kernel matrix to ensure that the resulting matrix is invertible.