

Optimization

Quadratic forms II



Learning goals

- Properties of Quadratic functions
-

PROPERTIES OF QUADRATIC FUNCTIONS

Univariate case

In 1-variable calculus, the second derivative is just a single value $q''(x) = 2 \cdot a$. Basic properties of q can easily be read off:

- $q''(x) > 0$ implies convex, $q''(x) < 0$ implies concave.
- High absolute values mean high curvature, low absolute values mean a low curvature.

Now: Multivariate case

For a multivariate quadratic function, the second derivative is a symmetric matrix of values **H** (called the Hessian).

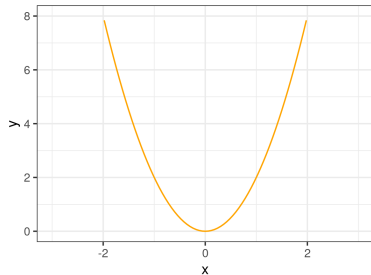
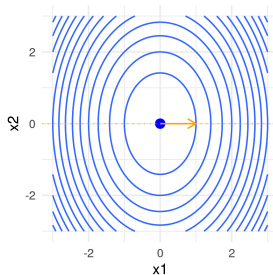
We will see how **H** encodes the basic properties of the function q .

PROPERTIES OF QUADRATIC FUNCTIONS (DIAG)

Example 1: A function composed of two univariate quadratic terms

$$q(\mathbf{x}) = \mathbf{x}^\top \mathbf{A} \mathbf{x} = \mathbf{x}^\top \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \mathbf{x} = 2 \cdot x_1^2 + x_2^2$$

$$\text{with } \nabla q(\mathbf{x}) = 2 \cdot \mathbf{A} \cdot \mathbf{x} = 4 \cdot x_1 + 2 \cdot x_2, \quad \mathbf{H} = 2 \cdot \mathbf{A} = \begin{pmatrix} 4 & 0 \\ 0 & 2 \end{pmatrix}$$



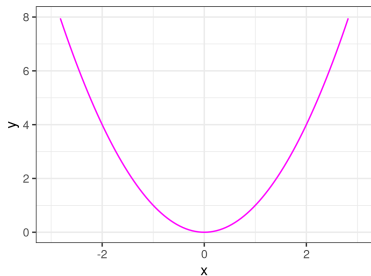
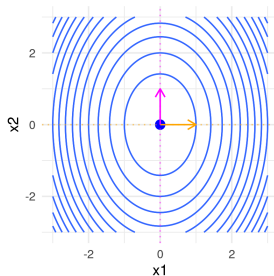
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q has a high positive curvature of 4 in the direction of x_1 , and a lower (positive) curvature of 2 in direction of x_2 .

PROPERTIES OF QUADRATIC FUNCTIONS (DIAG)

Takeaway I:

- The Hessian encodes the curvature of the function
- If the Hessian \mathbf{H} is diagonal, the diagonal elements encode the curvature of the function:
 - The i -th diagonal element gives us the curvature in the direction of $\mathbf{v} = \mathbf{e}_i$ because

$$\mathbf{v}^\top \mathbf{H} \mathbf{v} = \mathbf{e}_i^\top \mathbf{H} \mathbf{e}_i = h_{ii}.$$

- The curvature in an arbitrary direction $\mathbf{v} \in \mathbb{R}^d$, $\|\mathbf{v}\| = 1$, is

$$\mathbf{v}^\top \mathbf{H} \mathbf{v} = h_{11}v_1^2 + h_{22}v_2^2 + \dots + h_{dd}v_d^2.$$

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- In the general case we look at the **eigenspectrum** of \mathbf{H}

Note: For diagonal matrices it is very easy to determine the eigenspectrum: The diagonal elements are the **eigenvalues**, and unit vectors are the **eigenvectors**.

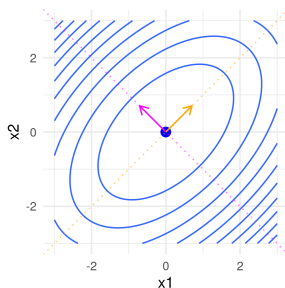
$$\mathbf{H} \mathbf{e}_1 = \begin{pmatrix} 4 & 0 \\ 0 & 2 \end{pmatrix} = 4 \cdot \mathbf{e}_1; \quad \mathbf{H} \mathbf{e}_2 = \begin{pmatrix} 4 & 0 \\ 0 & 2 \end{pmatrix} = 2 \cdot \mathbf{e}_2$$

PROPERTIES OF QUADRATIC FUNCTIONS

Example 2:

$$q(\mathbf{x}) = \mathbf{x}^\top \mathbf{A} \mathbf{x} = \mathbf{x}^\top \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix} \mathbf{x},$$

$$\text{with } \nabla q(\mathbf{x}) = 2 \cdot \mathbf{A} \cdot \mathbf{x}, \quad \nabla^2 q(\mathbf{x}) = \mathbf{H} = 2 \cdot \mathbf{A} = \begin{pmatrix} 4 & -2 \\ -2 & 4 \end{pmatrix}$$

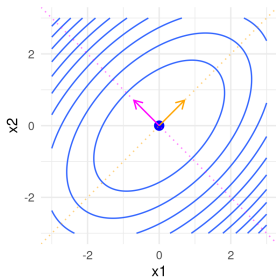


In the general case, the curvature is determined by the Eigenspectrum of \mathbf{H} .

PROPERTIES OF QUADRATIC FUNCTIONS

Takeaway II:

- Geometrically, directions of highest / lowest curvature are along the main axes of the ellipses representing the contour lines of q .
- Mathematically, the direction with the highest (lowest) curvature is the direction of the eigenvector \mathbf{v}_{\max} (\mathbf{v}_{\min}) that belongs to the largest (smallest) eigenvalue λ_{\max} (λ_{\min}) of \mathbf{H} .



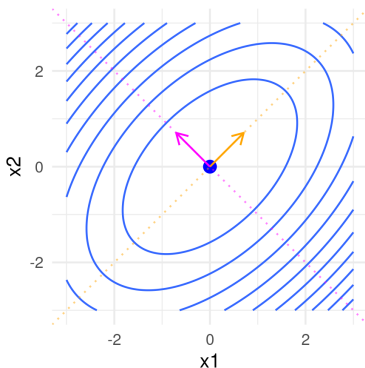
The eigenvectors and eigenvalues of $\mathbf{H} = \begin{pmatrix} 4 & -2 \\ -2 & 4 \end{pmatrix}$ are:

$$\mathbf{v}_{\min} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad \lambda_{\min} = 2$$

$$\mathbf{v}_{\max} = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \end{pmatrix}, \quad \lambda_{\max} = 3$$

PROPERTIES OF QUADRATIC FUNCTIONS

The direction \mathbf{v}_{\max} is also the direction in which the function increases fastest.

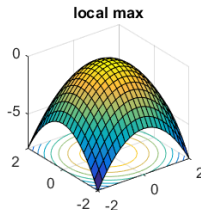
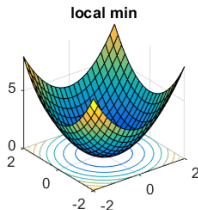


“Walking” the same distance along \mathbf{v}_{\max} (magenta) makes us pass more level curves than walking along any other direction.

PROPERTIES OF QUADRATIC FUNCTIONS

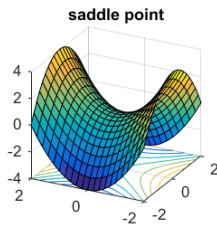
If we know the eigenspectrum of \mathbf{A} , i.e. the set of its eigenvalues $\{\lambda_1, \lambda_2, \dots, \lambda_d\}$, we also know the eigenspectrum of $\mathbf{H} = 2 \cdot \mathbf{A}$. The following basic properties of q can be read off from this eigenspectrum:

- If **all** eigenvalues of the \mathbf{H} are > 0 (we call \mathbf{H} positive definite):
 - the function q is convex,
 - there is a unique global minimum.
- If **all** eigenvalues of the \mathbf{H} are < 0 (we call \mathbf{H} negative definite):
 - the function q is concave,
 - there is a unique global maximum.



PROPERTIES OF QUADRATIC FUNCTIONS

- If there are both positive and negative eigenvalues (we call H indefinite):
 - the function q is neither concave nor convex,
 - there is a saddle point.



PROPERTIES OF QUADRATIC FUNCTIONS

Example: Sketch the following function

$$q(\mathbf{x}) = \mathbf{x}^\top \begin{pmatrix} -1 & -1 \\ -1 & 1 \end{pmatrix} \mathbf{x}$$

Step 1: Compute the Hessian

$$\mathbf{H} = 2 \cdot \mathbf{A} = \begin{pmatrix} -2 & -2 \\ -2 & 2 \end{pmatrix}$$

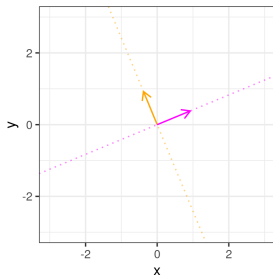
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Step 2: Compute eigenvectors / -values:

$$\begin{aligned} \mathbf{v}_1 &= \begin{pmatrix} 1 - \sqrt{2} \\ 1 \end{pmatrix}, & \lambda_1 &= 2\sqrt{2} \\ \mathbf{v}_2 &= \begin{pmatrix} 1 + \sqrt{2} \\ 1 \end{pmatrix}, & \lambda_2 &= -2\sqrt{2}. \end{aligned}$$



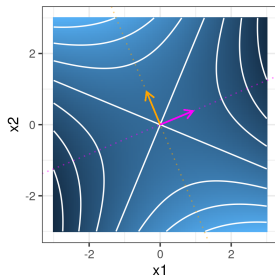
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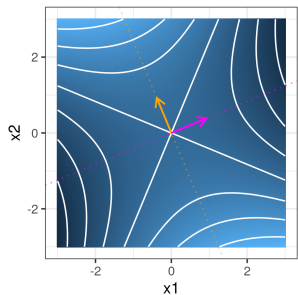
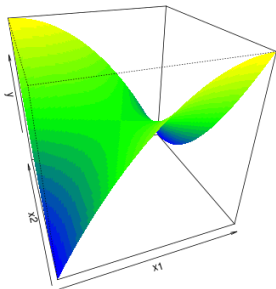
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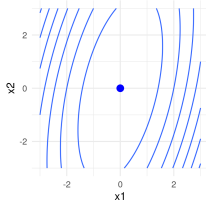
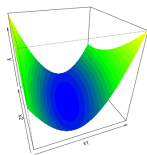
$$q(\mathbf{x}) = \mathbf{x}^\top \begin{pmatrix} -1 & -1 \\ -1 & 1 \end{pmatrix} \mathbf{x}$$



EIGENSPECTRUM AND CONDITION

The condition of squared full-rank matrix can be read off from its eigenspectrum: it is $\kappa(\mathbf{A}) = \frac{|\lambda_{\max}|}{|\lambda_{\min}|}$, with λ_{\max} being the largest eigenvalue and λ_{\min} being the lowest eigenvalue (in absolute terms). A high condition means:

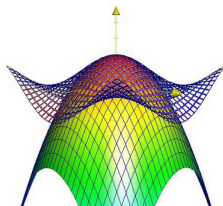
- The absolute value of the biggest eigenvalue λ_{\max} is much larger than the absolute value of the lowest eigenvalue λ_{\min} .
- The curvature in the direction of minimum curvature (\mathbf{v}_{\max}) is much lower than the one in the direction of maximum curvature (\mathbf{v}_{\min}).
- We will see later, that optimization algorithms like gradient descent will have difficulties optimizing such functions.



INTERPRETATION OF GENERAL FUNCTIONS

Every function can be locally approximated by a quadratic function via Taylor approximation:

$$f(\mathbf{x}) \approx f(\tilde{\mathbf{x}}) + \nabla f(\tilde{\mathbf{x}})^\top (\mathbf{x} - \tilde{\mathbf{x}}) + \frac{1}{2}(\mathbf{x} - \tilde{\mathbf{x}})^\top \nabla^2 f(\tilde{\mathbf{x}})(\mathbf{x} - \tilde{\mathbf{x}})$$



f is shown as the hollow grid and its second-order approximation at $(0,0)$ as a continuous surface. Source: daniloroccatano.blog.

By a basic geometric understanding of quadratic functions, we are able to understand a function's local geometry by looking at the Hessian $\nabla^2 f(\tilde{\mathbf{x}})$.