

Random Planted Forest A Directly Interpretable Tree Ensemble

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1

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- → Need to manually specify interactions in model fit

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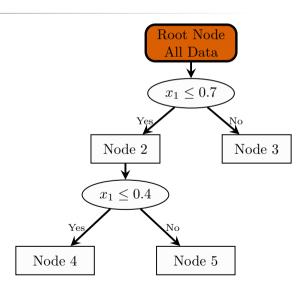
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$$\begin{split} \hat{m}(\mathbf{x}) &= \hat{m}_0 \\ &+ \underbrace{\hat{m}_1(x_1) + \hat{m}_2(x_2) + \hat{m}_3(x_3)}_{\text{Main effects}} \\ &+ \underbrace{\hat{m}_{1,2}(x_1, x_2) + \hat{m}_{1,3}(x_1, x_3) + \hat{m}_{2,3}(x_2, x_3)}_{\text{2nd order interactions}} \\ &+ \underbrace{\hat{m}_{1,2,3}(x_1, x_2, x_3)}_{\text{3rd order interaction}} \end{split}$$



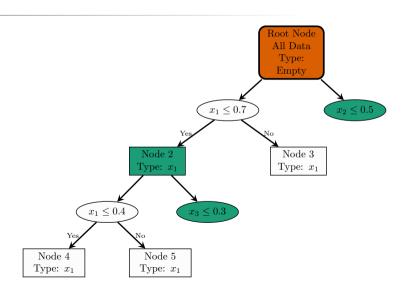
Trees in Random Forest



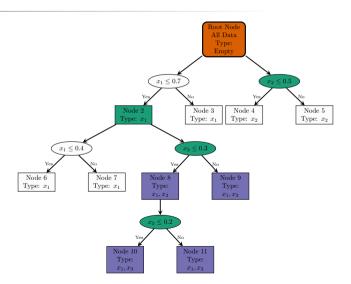


Planted Trees





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6

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- ullet Prediction is average of additive \hat{m}_S estimates



7

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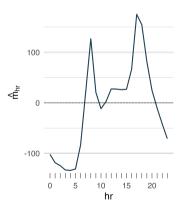
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Lnibniz

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- Target bikers: Number of bikers on a given day in 2011/2012
- Focus on 3 features for example
 - hour of day $\in \{0, 1, \dots, 23\}$
 - temp normalized temperature $\in [0, 1]$
 - workingday binary → {workingday, no workingday}
- ullet Average prediction: $\hat{m}_0 pprox$ 143.7

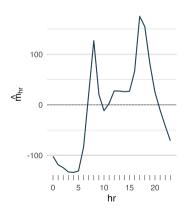
Main Effects

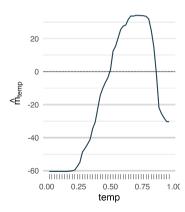




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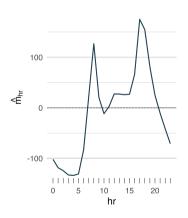


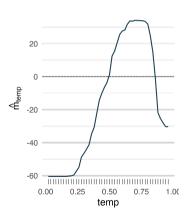


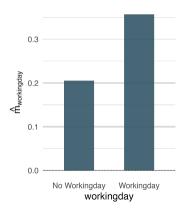


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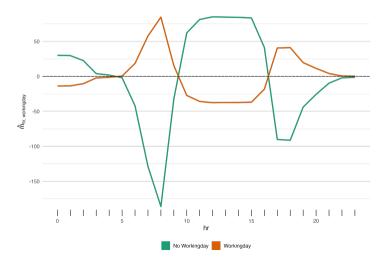






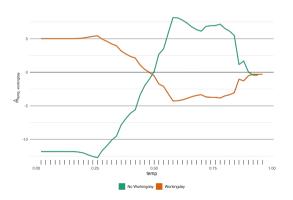
Hour × Working Day: "Rush Hour Effect"





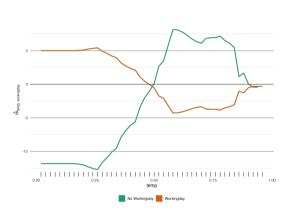
More 2nd Order Interactions

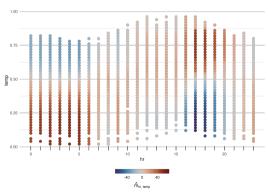




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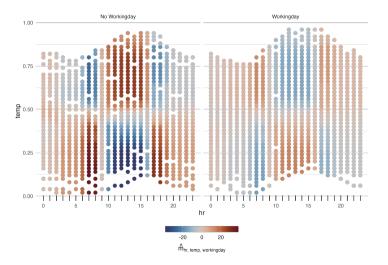






3rd Order Interaction







12

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- Unlike RF Feature importance:
 - Scores per interaction term



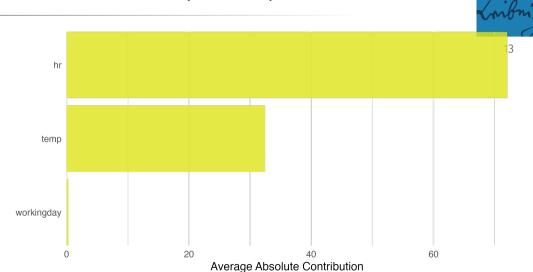
12

Average of absolute values of term of interest

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- Unlike RF Feature importance:
 - Scores per interaction term
 - Importance scores on same scale as prediction

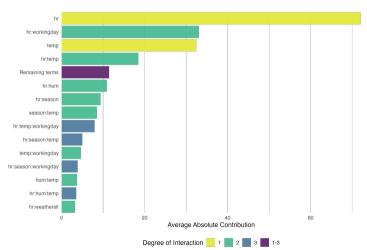
Feature Importance per Main Term



Feature Importance per All Terms

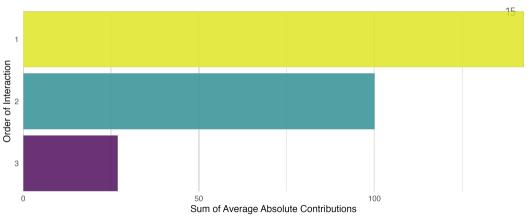


14



Feature Importance by Order of Interaction





Related work



16

Glex²: Same ANOVA decomposition but generally for tree-based methods (e.g. XGBoost)

• Idea:

²Hiabu, Meyer, and Wright (2023)

Related work



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 - Fit XGBoost with more shallow trees (e.g. max_depth = 4 ↔ max_interaction = 4)

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- Drawback: Computationally intensive post-hoc computation

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17



17

Better interpretibility → worse predictive performance?

• Benchmark comparing RPF with XGBoost, RF incl. tuning



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- 28 datasets from OpenML-CTR23 regression benchmark suite ³
- Also comparing XGBoost / RPF with interactions restrained to 2
- Generally XGBoost best, RPF and RF closely behind

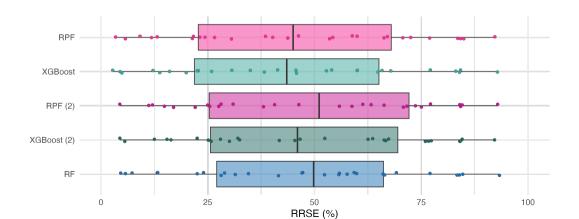
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Benchmark Results (Aggregated)



• Root-Relative Squared Error (RRSE) $\sqrt{\frac{SSE(Y,\hat{Y})}{SSE(Y,\bar{Y})}}$

18



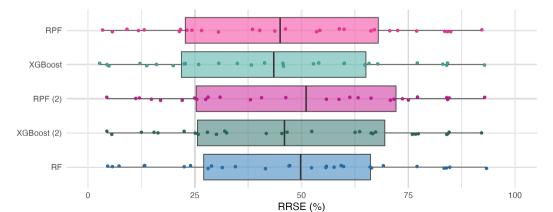
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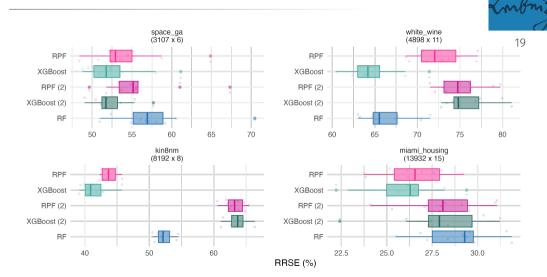
• Root-Relative Squared Error (RRSE) $\sqrt{\frac{SSE(Y,\hat{Y})}{SSE(Y,Y)}}$

• Featureless model scores 1, perfect score 0

18



Results for Selected Tasks





20

Random Planted Forests = Additive Random Forests

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- (+) Interpretability on global and local perspective
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- (~) Predictive performance worse but similar to comparable algorithms
- (-) Computationally heavy for large data
- (+) R package available ⁴

⁴github.com/PlantedML/randomPlantedForest

Thank you for your attention!



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References I



22



Hiabu, Munir, Joseph T. Meyer, and Marvin N. Wright (Apr. 11, 2023). "International Conference on Artificial Intelligence and Statistics". In: ISSN: 2640-3498 Citation Key: hiabu2023unifyinglocala. PMLR, pp. 7040–7060.