- * APSTA.GE 2004
- * Homework 5
- * Jennifer Jackson

use "/Users/jenniferjackson/Desktop/Assignment 5.dta"

tabstat stature hip_ht leg_length arm_length sitting_ht knee_girth elbow_girth /// wrist girth, stats(n, mean, sd, skewness) format(%6.0g)

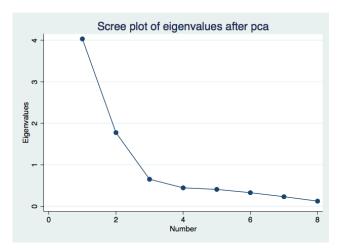
correl stature hip_ht leg_length arm_length sitting_ht knee_girth elbow_girth wrist_girth

pca stature hip_ht leg_length arm_length sitting_ht knee_girth elbow_girth wrist_girth

- * Because the unexplained values are zero, the total amount of variance per
- * variable equals one.
- * The eigenvalues sum to the number of diagonal elements in the input matrix.
- * Because the input matrix here is the correlation matrix, the sum is the same
- * as the number of components: seven.
- * If all the loadings of Composite 1 are positive, that means that's the best
- * way to explain the variance among the variables. As for the other composites,
- * the signs will have to be adjusted because the sum of the cross-products of
- * the factor loadings for each pair of components is zero.

screeplot

* m = 2 factors



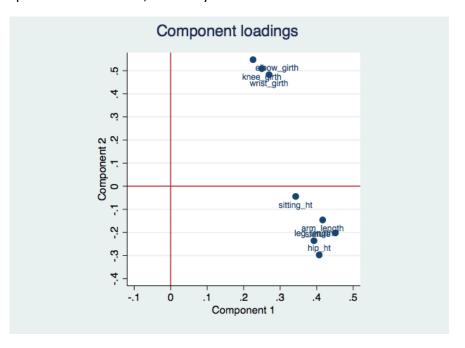
pca stature hip_ht leg_length arm_length sitting_ht knee_girth elbow_girth wrist_girth, comp(2)

- * Because the unexplained variance values are so small, that means that the
- * first two components can account for the majority of the variance.
- * Only considering the first two components, the sitting height variable still
- * has about 52% of its variance unexplained. I.e., sitting height is the least
- * well accounted for.
- * Problem 10

loadingplot, xlab(-.1(.1).5) ylab(-.4(.1).5) aspect(1) yline(0) xline(0)

* The x axis kind of lines up with the variables, but the y axis does not line

* up at all.

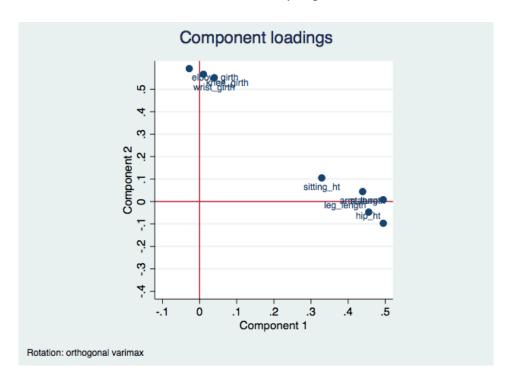


* Problem 11

rotate, orthogonal varimax normalize comp(2)

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* The unexplained amounts of variance remain the same.
* Problem 12
* Comp1 Rotated
display 0.4944^2 + 0.4947^2 + 0.4555^2 + 0.4390^2 + 0.3289^2 + 0.0104^2 + (-0.0279)^2 +
0.0396^2
* = 1
* Comp2 Rotated
display 0.0081^2 + (-0.0968)^2 + (-0.0471)^2 + 0.0444^2 + 0.1052^2 + 0.5668^2 + 0.5917^2 + 0.0444^2 + 0.1052^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.0444^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.044^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.04^2 + 0.0
0.5513^2
* = 1
* Comp1 Unrotated
display 0.4512^2 + 0.4070^2 + 0.3926^2 + 0.4164^2 + 0.3425^2 + 0.2497^2 + 0.2257^2 + 0.2497^2 + 0.2257^2 + 0.2497^2 + 0.2257^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0.2497^2 + 0
0.2696^2
* = 1
* Comp2 Unrotated
display (-0.2023)^2 + (-0.2974)^2 + (-0.2358)^2 + (-0.1460)^2 + (-0.0442)^2 + 0.5089^2 +
0.5477^2 + 0.4825^2
* = 1
* Problem 13
* Given e(r T) is the Varimax transformation matrix
matrix B = e(r_T)'
matrix C = e(r T) * B
matrix list C
* shows the identity matrix (give or take some rounding)
* Problem 14
* Rotation redistributes the variance, so the first loading is no longer much
* larger than the rest.
  * Problem 15
loadingplot, xlab(-.1(.1).5) ylab(-.4(.1).5) aspect(1) yline(0) xline(0)
```

* Yes, the variables are much more closely aligned with the axes after rotation.



* Problem 16

- * I would say Component 1: Joint Girth and Component 2: Length of Limbs and Torso
- * To summarise, the majority of variation among physical attributes can be
- * accounted for by joint girth and limb/torso length.