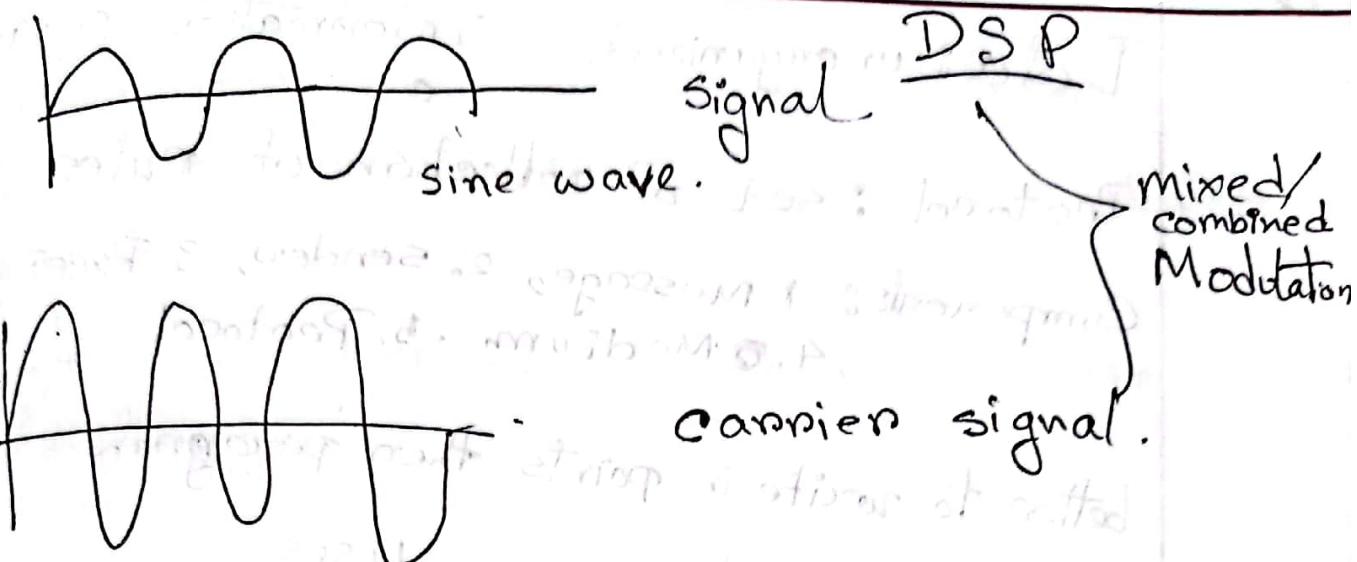


C.V.J

Present
07-06-22
13-Jency
2.24-Janat
3.42-Prompa
4.10-Natasha
5.30-Nishi
6.28-Fahim
7. Niloy



Inosphere Attenuation → the reduction of power of a signal

3 ways of Modulation: the process

1. AM: Amplitude; maximum distance from equilibrium

FM: Frequency; no. of complete wave in 1 second

PM: Phase

Demodulator.

Demodulation: the process of deriving the main signal from noise.

Data Compression: cost effective.

No. of bits per byte = $2^{\log_2 N}$

Interleaving: $N \times M$ → $M \times N$ bytes

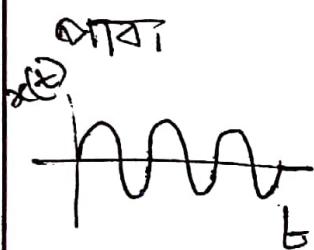
Steganography: hidden message

Digital Signal Processing \rightarrow 7

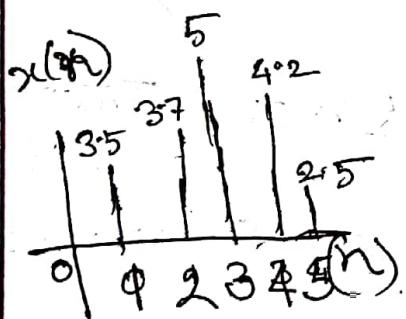
Signal: Physical quantity.

Sampling: Process in which a continuous time signal (continuous with respect to time) is

C.T \rightarrow exists for all instance of time
প্রত্যেকটি time এর জন্য amplitude/value

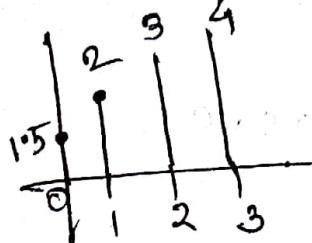


D.T \rightarrow exists only for a certain/specific instance of time.

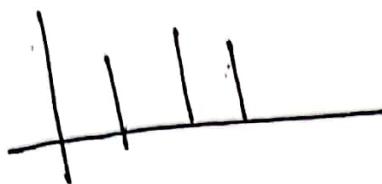


Nyquist theorem.

Continuous ~~valued~~ valued signal:
can take any value



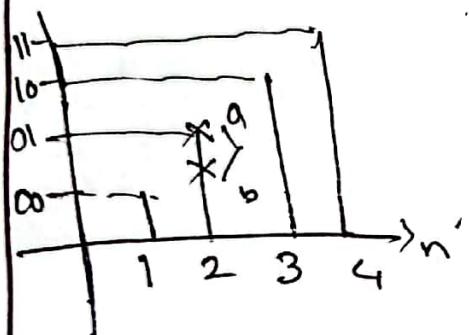
Discrete Valued Signal:



can take ~~only~~ only limited set of value
Quantized Value

2 bit Quantization
 $2^2 \rightarrow 4$ combination.

quantization error.



For 2nd second the value we were supposed to get is at point a, but we got at b. This is caused by noise. This is called quantization error.

1.

→ Continuous and discrete time signal

→ Deterministic and non-deterministic Signal

* * → Even and Odd Signal.

→ Periodic and non-periodic Signal.

* * → Energy and Power Signal

→ Real & Imaginary Signal.

CTS: A signal is said to be continuous if it is defined for an instance of time.

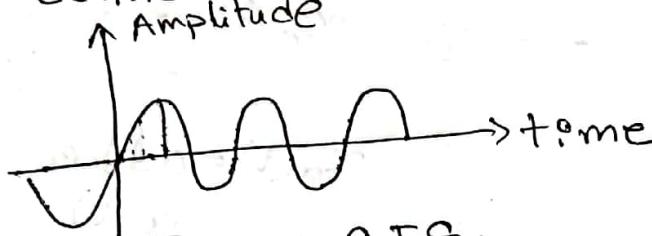
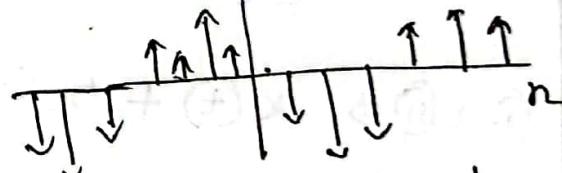


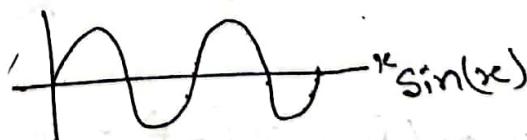
Figure: CTS.

DTS: A signal is said to be discrete when it is defined for at only discrete instance of time $x(n)$

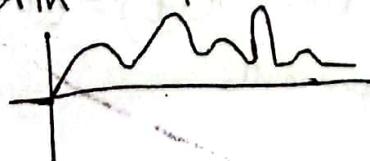
n = sample



Deterministic Signal. Signals which can be defined exactly by a mathematical formula are known as D.S.. Follows a specific/certain pattern after certain time.



NDS: A signal is said to be non-deterministic if there is uncertain with respect to its value at some instance of time.

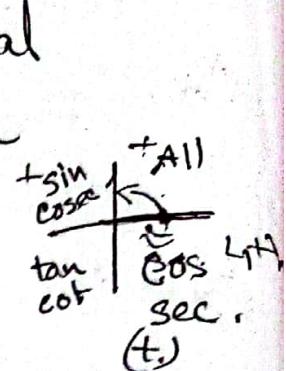


Even Signal: A continuous time signal $x(t)$ is said to be even if $x(-t) = x(t)$ for all t .

$$x(t) = t^2 \quad x(-t) = (-t)^2 = t^2 = x(t) \text{ even signal}$$

$$x(t) = \cos(t) \quad x(-t) = \cos(-t) = \cos t \text{ even}$$

$$x(t) = \sin(t) \quad x(-t) = \sin(-t) = -\sin t \text{ odd}$$



Even & Odd Components

Any continuous time signal $x(t)$ can be written as sum of its even and odd components. i.e. $x(t) = x_e(t) + x_o(t)$. — ①

$x_e(t)$ = even components of $x(t)$

$x_o(t)$ = odd components of $x(t)$

$$\begin{aligned} x(-t) &= x_e(-t) + x_o(-t) \\ &= x_e(t) - x_o(t) \end{aligned} \quad | \quad \because x_e(t) = x_e(-t)$$

$$① + ② \Rightarrow x(t) + x(-t) = 2x_e(t)$$

$$\therefore x_e(t) = \frac{x(t) + x(-t)}{2} \quad [\text{Even Components}]$$

$$① - ② \Rightarrow x(t) - x(-t) = x_o(t) + x_o(-t)$$

$$\Rightarrow x_o(t) = \frac{x(t) - x(-t)}{2} \quad [\text{Odd Components}]$$

Q. Find the even & odd components. $x(t) = e^{j2t}$

→ Describe even & odd components

Given, $x(t) = x^{\text{e}} \text{e}^{j2t}$

$$x_e(t) = \frac{x(t) + x(-t)}{2} = \frac{x^{\text{e}} \text{e}^{j2t} + x^{\text{e}} \text{e}^{-j2t}}{2}$$

$e^{j\theta}$
 $= \cos\theta + j\sin\theta$

$$= \cos 2t + j \sin 2t$$

$$+ \cos 2t - j \sin 2t$$

$$= \frac{2 \cos 2t}{2}$$

$$= \cos 2t \quad \text{Ans}$$

$$x_o(t) = \frac{x(t) - x(-t)}{2}$$

$$= \frac{e^{j2t} - e^{-j2t}}{2}$$

$$= \frac{\cos 2t + j \sin 2t - \cos 2t + j \sin 2t}{2} = \frac{2j \sin 2t}{2}$$

$$= j \sin 2t \quad \text{Ans}$$

$$x(t) = \cos(\omega_0 t + \frac{\pi}{3})$$

$$x_e(t) = \frac{x(t) + x(-t)}{2}$$

$$= \frac{\cos(\omega_0 t + \frac{\pi}{3}) + \cos(\omega_0(-t) + \frac{\pi}{3})}{2}$$

$$= \frac{\cos(\omega_0 t + \frac{\pi}{3}) + \cos(-\omega_0 t + \frac{\pi}{3})}{2}$$

$$= \frac{\cos(\omega_0 t + \frac{\pi}{3})^2 + \cos(-(\omega_0 t - \frac{\pi}{3}))}{2}$$

$$= \frac{\cos(\omega_0 t + \frac{\pi}{3}) + \cos(\omega_0 t - \frac{\pi}{3})}{2}$$

$$= \frac{j \cos \omega_0 t \cdot \cos \frac{\pi}{3}}{2} = \frac{1}{2} \cos \omega_0 t$$

$$x_o(t) = \frac{x(t) - x(-t)}{2}$$

$$= \frac{\cos(\omega_0 t + \frac{\pi}{3}) - \cos(\omega_0 t - \frac{\pi}{3})}{2}$$

$$= \frac{(\cos(\omega_0 t - \frac{\pi}{3}) - \cos(\omega_0 t + \frac{\pi}{3}))}{2}$$

$$= \frac{-j \sin \omega_0 t \sin \frac{\pi}{3}}{2}$$

$$= -\frac{\sqrt{3}}{2} \sin \omega_0 t$$

Ans

$$2 \sin A \sin B = \cos(A-B) - \cos(A+B)$$

$$2 \cos A \cos B = \cos(A+B) + \cos(A-B)$$

Cisco Packet Tracer

24 Tannat

Energy & Power Signal

13 Jency

7 Bithi

33 Nishi.

15 Mashrafi

16 Mithun

14 Sadia

19 Niloy

34 Shorno

26 Fahim

18 Nahid

08 Nadim

A continuous or discrete signal is said to be energy signal if its energy is finite & power is zero.

$$0 < E < \infty ; P = 0$$

2020 \rightarrow 1 no question upload
For Continuous Signals,

$$\textcircled{1} \quad E = \int_{-\infty}^{\infty} |x(t)|^2 dt \rightarrow \text{Real valued signal}$$

$$e^{-t} / e^t \rightarrow$$

$$\textcircled{2} \quad E = \int_{-\infty}^{\infty} |x(t)|^2 dt \rightarrow \text{Complex values signal } e^{j(2t + \frac{\pi}{4})}$$

For discrete Signal,

$$\textcircled{1} \quad E = \sum_{n=-\infty}^{\infty} |x(n)|^2$$

Power: A continuous or discrete time signal is said to be power signal. If its power is finite. Energy is infinite. $0 < P < \infty ; E = \infty$

Fourier transform, Z-transform

Continuous

$$P = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt \rightarrow \text{Real}$$

\Rightarrow sample
 \Rightarrow discrete
 $t \rightarrow$ continuous

$$P = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt \rightarrow \text{complex.}$$

$$\text{Discrete. } P = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^N |x(n)|^2$$

* $x(n) = \left(\frac{1}{4}\right)^n u(n)$ is it energy or power signal

We know

$$E = \sum_{n=-\infty}^{\infty} |x(n)|^2$$

$$= \sum_{n=-\infty}^{\infty} \left| \left(\frac{1}{4}\right)^n \cdot \underbrace{u(n)}_{} \right|^2$$

unit step signal,
For 0 to ∞ = value = 1

$$= \sum_{n=0}^{\infty} \left| \left(\frac{1}{4}\right)^n \right|^2$$

$$= \sum_{n=0}^{\infty} \left| \frac{1}{16} \right|^n$$

$$\sum_{n=0}^{\infty} a^n = \frac{1}{1-a}$$

$$= \sum_{n=0}^{\infty} \left| \frac{1}{16} \right|^n$$

$$= \sum_{n=0}^{\infty} [0.0625]^n$$

$$= \frac{1}{1-0.0625}$$

$$\approx \frac{1}{0.9375} = 10.67^\circ$$

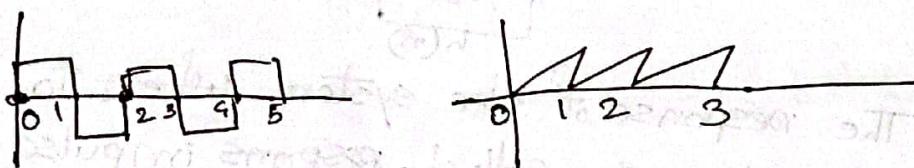
$$\begin{aligned}
 P &= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^{N+1} |x(n)|^2 \quad \text{For discrete power} \\
 &= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^{N+1} \left| \left(\frac{1}{4}\right)^n u(n) \right|^2 \quad \sum_0^n a^n = \frac{a^{n+1}-1}{a-1} \\
 &= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=0}^{N+1} \left| \left(\frac{1}{4}\right)^n \right|^2 \\
 &= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=0}^{N+1} \left(\frac{1}{16} \right)^n \\
 &= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=0}^{N+1} (0.0625)^n \\
 &= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \cdot \frac{0.0625^{N+1} - 1}{0.0625 - 1} \\
 &= \lim_{N \rightarrow \infty} \frac{1}{2N+1} \cdot \frac{\frac{1}{16}^{N+1} - 1}{\frac{1}{16} - 1} \\
 &= \frac{1}{\alpha} \cdot \frac{\frac{1}{16}^{\alpha+1} - 1}{\frac{1}{16} - 1} \\
 &= 0
 \end{aligned}$$

$\therefore E = 10.67$ & $P = 0$ i.e. the given signal is energy signal.

Periodic & Aperiodic Signal.

PS: A continuous time signal $x(t)$ is said to be periodic if it satisfies $x(t+T) = x(t)$ for all 't'. ~~at~~ ~~start~~: value at ~~start~~.

The smallest value of T which satisfies the above equation is fundamental period.



* Find the fundamental period of $x(t) = A \sin(\omega_0 t + \theta)$ (is it periodic / aperiodic).

$$x(t+T) = A \sin(\omega_0(t+T) + \theta)$$
$$= A \sin(\omega_0 t + \omega_0 T + \theta)$$

Let, $\omega_0 T = 2\pi$ then,

$$x(t+T) = A \sin(2\pi + \omega_0 t + \theta)$$
$$= A \sin(\omega_0 t + \theta)$$
$$= x(t) \text{, i.e periodic}$$

$$T = \frac{2\pi}{\omega_0}$$

Periodic : $x(t) = x(t+T)$, $T > 0$. where $T = \text{period of a cycle}$, which is an integer value.

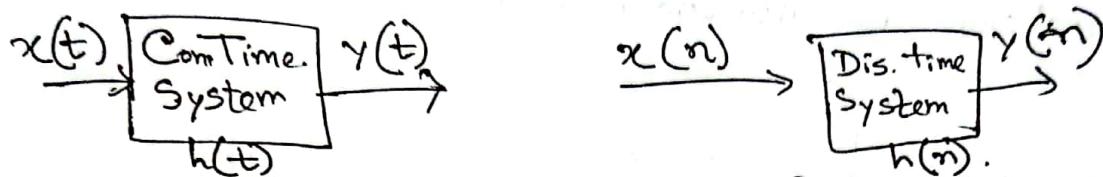
System

07-Bithi Signal: Any physical device which performs
13-Inc

16-Mithun certain operation on the input signal and

24-Jant produces an output. Ex:- Amplifier, Filter.

26-Fahim

Weak signal \rightarrow Strong Signal.

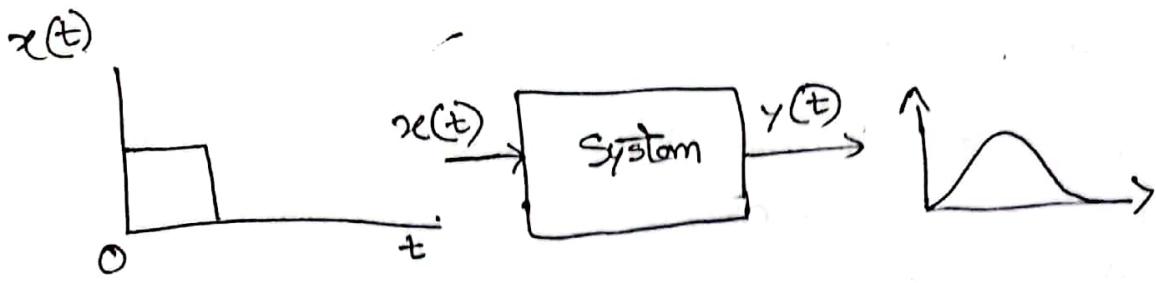
Impulse Response: The response of the system ~~when to~~ to an applied ~~an~~ impulse is called ~~responses~~ impulse response of the system. It is represented as $h(t)$ or $h(n)$.

*Difference between digital signal & analog signal

Both Dis. & Con. time system are classified ~~invariant~~ ~~or variant~~ system in

- i. Time invariant and variant system.
 - ii. Static or dynamic system.
 - iii. Causal or Non-causal
 - iv. Linear or Non-linear
 - v. Stable or unstable
- not done

1. If a time shift in the input results the same corresponding time shift in the output. Then it is called time invariant system.



check whether the following system is time invariant or
variant system (i) $y(t) = t \cdot x(t)$

- 1. Shift
- 2. Replace

$$y(t, t_1) = t \cdot x(t - t_1) \quad \text{--- (1)}$$

$$y(t - t_1) = (t - t_1) x(t - t - t_1) \quad \text{--- (2)} \\ \text{(time variant)}$$

$$y(t) = x(t)$$

$$y(t, t_1) = x(t - t_1)$$

$$y(t - t_1) = x(t - t_1)^2$$

time variant

$$y(t) = t^2 x(t).$$

$$y(t, t_1) = t^2 x(t - t_1)$$

$$y(t - t_1) = (t - t_1)^2 x(t - t_1) .$$

time variant

$$y(t) = e^{2x(t)}.$$

Time variant system: results
different

$$y(t, t_1) = e^{2x(t - t_1)}$$

$$y(t - t_1) = e^{2x(t - t_1)}$$

invariant.

main $\frac{\partial}{\partial t} \frac{\partial}{\partial x}$
w.r.t $\frac{\partial}{\partial t} \frac{\partial}{\partial x}$
the 2nd w.r.t $\frac{\partial}{\partial t} \frac{\partial}{\partial x}$
 $t - t_1$ replace $\frac{\partial}{\partial t} \frac{\partial}{\partial x}$

Static or dynamic.

A continuous or discrete time system is said to be static or memory less system. If the output at any instance of time depends on input at that instant time only. Otherwise it is dynamic system.

$$\textcircled{1} \quad y(t) = x(t-3)$$

$y(0) = x(-3)$, past \cancel{x} value
 $y(1) = x(-2)$, \cancel{x} value
∴ dynamic

$$\textcircled{11} \quad x(n) = x^2(n)$$

$$x(0) = x^2(0)$$

$$x(1) = x^2(1)$$

$$x(2) = x^2(2)$$

↳ static

$$\textcircled{10} \quad y(t) = x(2t)$$

$y(0) = x(0)$
 $y(1) = x(2)$ future value
depends upon
∴ dynamic

Present value \cancel{x} only

static = memory less

dynamic = requires memory

C.W

Absent

DSP

me
Shivno
nisha
nishi

18-06-22

Saturday

7.Bithi
8 Nadim
16 Mithun
24 Jannat
26 Fahim
27 Mou
42 Prema
19 Niloy vai

*** Causal and non-causal (anti-causal) system

A continuous or discrete time system is said to be causal if the output at any instant of time depends on present and past values of input. But not on future values of input.

If the output depends on future values of input also then the system is called non-causal or anti-causal.

$$\textcircled{1} \quad y(t) = x(t) + x(-4)$$

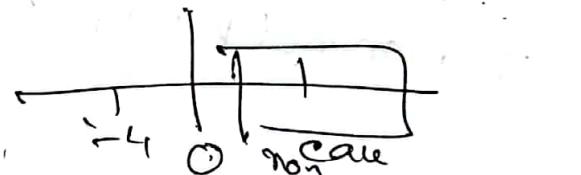
$$y(0) = x(0) + x(-4)$$

\uparrow Present value \uparrow Past value

$$\textcircled{2} \quad y(t) = x(2-t) + x(t-4)$$

$$y(0) = x(2) + x(-4)$$

\uparrow Future \uparrow Past



DSP block diagrams

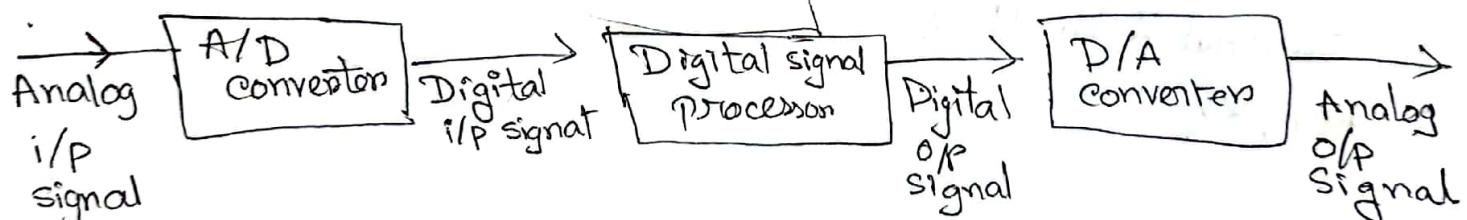


Figure: Block diagram of DSP system.

Elementary signals

The standard elementary discrete time signals are as follows:

- 1. Unit step sequence
- 2. Unit ramp sequence.
- 3. Unit impulse sequence
- 4. Sinusoidal

5. Unit parabolic sequence

6. Real exponential

7. Complex "

1. Unit step function: The discrete time unit step sequence

$u(n)$ is defⁿ defined as $u(n) = \begin{cases} 1 & \text{for } n \geq 0 \\ 0 & \text{for } n < 0. \end{cases}$

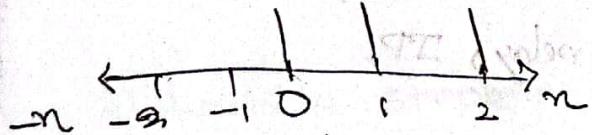
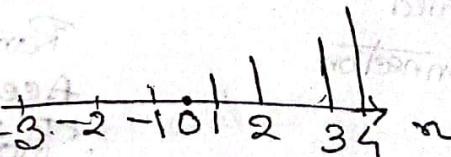


Figure: Discrete time unit step seq.

2. Unit ramp sequence: The discrete time unit ramp sequence $r(n)$ is that sequence which starts at $n=0$ and increases linearly with time and is defined as

$$r(n) = \begin{cases} n & \text{for } n \geq 0 \\ 0 & \text{for } n < 0 \end{cases}$$



Cu. U.

DSP

17-07-22

Z-transform

Discrete time signal

analysis of \uparrow

Laplace

Continuous time signal

analysis of \uparrow

two sided Z-transform (bilateral)

The two sided Z-transform of discrete time signal

$x(n)$ is defined as $Z\{x(n)\} = \sum_{n=-\infty}^{+\infty} x(n) z^{-n}$ where z is complex variable

$$X(\omega) \xrightarrow{ZT} X(z)$$

One sided: $x(n)$ defined as $Z\{x(n)\} = \sum_{n=0}^{\infty} x(n) z^{-n}$

(unilateral) Inverse Z-transform: The inverse Z-transform

Inverse Z-transform: The inverse Z-transform of $X(z) = \frac{1}{2\pi j} \oint_C z^{n-1} x(z) dz$ is defined as $x(n) = \frac{1}{2\pi j} \oint_C z^{n-1} X(z) dz$

Properties of Z.T

Scalability, Convolution, Linearity

ROC: Region of Convergence.

the range of values of z for which the summation of Z-transform i.e. $X(z) = \sum_{n=-\infty}^{\infty} x(n) z^{-n}$ converges. (for getting finite value)

is called ROC.

Find the Z-transform of $x(n) = \{1, 2, 3, 2\}$

$$Z\{x(n)\} = \sum_0^3 x(n) z^{-n} = x(0)z^0 + x(1)z^1 + x(2)z^2 + x(3)z^3$$

$$= 1z^0 + 2z^1 + 3z^2 + 2z^3$$

$$= 1 + \frac{2}{z} + \frac{3}{z^2} + \frac{2}{z^3}$$

For $z = \infty$ value of

$$Z(x(n)) = \infty$$

\therefore ROC for all values of z except $z=0$. Ans.

ROC for entire z -plane except $z=0$.

* $x(n) = \{ 3, 2, -1, -4, 1 \}$

-4 -3 -2 -1 0 ↑

$$\begin{aligned} z\{x(n)\} &= \sum_{n=-4}^{\infty} x(n) z^{-n} \\ &= x(-4)z^{-(-4)} + x(-3)z^{-(-3)} + x(-2)z^{-(-2)} + \\ &\quad x(-1)z^{-(-1)} + x(0)z^0 \\ &= 3z^4 + 2z^3 + (-1)z^2 + (-4)z + 1 \\ &= 3z^4 + 2z^3 - z^2 - z + 1. \end{aligned}$$

For $z=\alpha$ the value of $z\{x(n)\} = \infty$.

\therefore ROC for entire z -plane except $z=\alpha$. Ans.

* $x(n) = \{ 0, 1, 2, 3, 4, 5 \}$

$$\begin{aligned} z\{x(n)\} &= \sum_{n=0}^{5} x(n) z^{-n} = 2z^0 + (-1)z^1 + 3z^2 + 2z^3 + 0z^4 + 1z^5 \\ &= 2 - z + \frac{3}{z^2} + \frac{2}{z^3} + \frac{1}{z^5} \\ &= 2 - \frac{1}{z} + \frac{3}{z^2} + \frac{2}{z^3} + \frac{1}{z^5} \end{aligned}$$

ROC for entire z -plane except $z=0$ Ans.

CNL

1. Switch and End Device Connection

192.168.10.2

2. Router and End-device.

3. Static Routing with connecting 4 routers.

4. Dynamic " " " "

- 7 -
- 8 .
- 10
- 13
- 16
- ~~20~~ 20 .
- 27 -
- 34
- 19

24

Z-transform

18-07-22

DSP

Find the z-transform of the following signal

$$x(n) = u(n) = 1; n \geq 0$$

$$\begin{aligned} z\{x(n)\} &= \sum_{n=-\infty}^{+\infty} x(n) z^{-n} \\ &= \sum_{n=0}^{\infty} u(n) z^{-n} \end{aligned}$$

$$\sum_{n=0}^{\infty} c^n = \frac{1}{1-c}; 0 < |c| < 1$$

$$= \sum_{n=0}^{\infty} z^{-n}$$

$$= \sum_{n=0}^{\infty} (z^{-1})^n$$

What is condition to converge? (ROC)

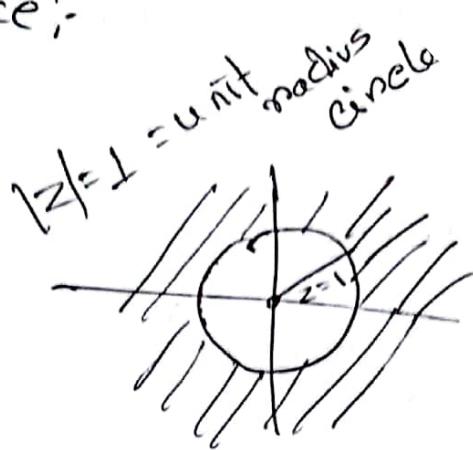
$$\begin{aligned} 0 &= -\log|z| \Rightarrow \frac{1}{1-z} \\ &= \frac{z}{z-1} \end{aligned}$$

Condition for Convergence:-

$$0 < |c| < 1$$

$$0 < |\bar{z}^1| < 1$$

$$0 < \frac{1}{n} < 1.$$



$$\frac{1}{\sum} < 1$$

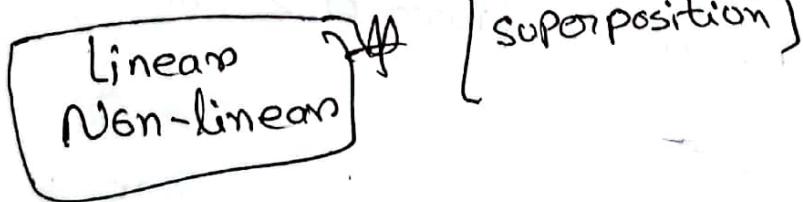
$|z| > 1$. for infinite

entire z-plane
 \therefore ROC for all ratios
except $|z|=1$.

$$\frac{1}{1-1} = \frac{1}{1-\frac{1}{1}} = \frac{1}{1-1} = \frac{1}{0} = \infty$$

H.N Properties of ROC

Z-trans /
Roc
Diff la



DSP (In DSP Lab)

Find the z-transform

$$u(n) = 1; n \geq 0 \\ 0; n < 0$$

$$x(n) = 0.3^n u(n)$$

$$x(n) = 0.3^n; n \geq 0 \\ 0; n < 0$$

$$X(z) = z \{x(n)\} = \sum_{-\infty}^{\infty} x(n) z^{-n}$$

$$= \sum_{-\infty}^{\infty} 0.3^n u(n) z^{-n}$$

$$= \sum_{0}^{\infty} 0.3^n z^{-n}$$

$$= \sum_{0}^{\infty} (0.3z^{-1})^n$$

$$= \sum_{0}^{\infty} \left(\frac{0.3}{z}\right)^n$$

$$= \frac{1}{1 - \frac{0.3}{z}} \quad [\text{value of z-transform}]$$

$$= \frac{z}{z - 0.3}$$

ROC for entire
z-plane

for $z > 0.3$

or

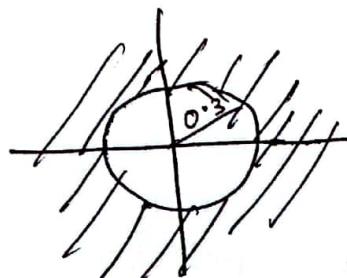
Extension of circle
with radius 0.3 in z-plane

$$0 \leq \left| \frac{0.3}{z} \right| \leq 1$$

$$\frac{0.3}{|z|} \leq 1$$

$$0.3 \leq |z|$$

$$|z| > 0.3$$



$$x(n) = 0.8^n u(-n-1)$$

$$\sum \{x(n)\} = \sum_{-\infty}^{\infty} 0.8^n u(-n-1) z^{-n}$$

$$\sum_{-\infty}^{-1} 0.8^n z^{-n}$$

$$u(-n-1) = 1 ; n \leq -1$$

$$= 0 ; n \geq 0$$

$$x(n) = 0.8^n ; n \leq -1$$

$$0 ; n \geq 0$$

$$= \sum_{-1}^{\infty} 0.8^{-n} z^{-n} \quad \frac{1}{1-0.8z}$$

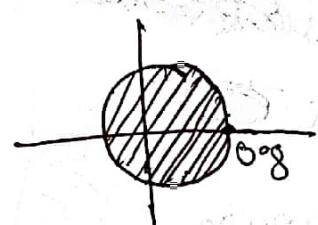
$$= \sum_{-1}^{\infty} (0.8z)^{-n}$$

$$= \sum_{0}^{\infty} (0.8z)^{-n} - 1$$

$$= \frac{1}{1 - \frac{z}{0.8}} - 1 \quad \left| \begin{array}{l} = \frac{0.8 - 0.8z}{0.8 - z} \\ = \frac{z}{0.8 - z} \end{array} \right.$$

$$= \frac{0.8}{0.8 - z} - 1 \quad \left| \begin{array}{l} = \frac{z}{z - 0.8} \\ = -\frac{z}{z - 0.8} \end{array} \right.$$

$$|0.8z| < 1$$



$$\left| \frac{z}{0.8} \right| < 1$$

$$|z| < 0.8$$

$$\underline{u(-n-1)} = 1 ; n \leq -1$$

$$\underline{-(-1)} = 0$$

$$-(-1) - 1$$

$$+1 - 1$$

0

1

$$x(n) = 0.3u(n) + 0.8u(-n-1)$$

$$= \frac{z}{z-0.3} + \frac{-z}{z-0.8}$$

$$= \frac{z}{z-0.3} - \frac{z}{z-0.8}$$

$$= \frac{z(z-0.8) - z(z+0.3)}{(z-0.3)(z-0.8)}$$

$$= \frac{z^2 - 0.8z - z^2 + 0.3z}{z^2 - 0.8z - 0.3z + 0.24}$$

$$= \frac{-0.5z}{z^2 - 1.1z + 0.24}$$

$$\frac{0.3}{R} < 1$$

$$0.3 < |z|$$

$$\frac{|z|}{0.8} < 1$$

$$|z| < 0.8$$

$$u(n) = \begin{cases} 1 & n \geq 1 \\ 0 & n \leq 0 \end{cases}$$

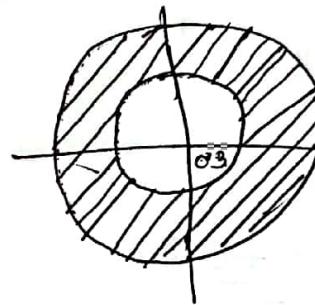
$$\int_{-\infty}^{+\infty} u(n-1) z^{-n} dz$$

$$z^{-n} = \int_1^\infty (\bar{z})^n dz$$

$$\therefore = \int_0^\infty (\bar{z})^n dz - 1$$

$$= \frac{1}{1-\bar{z}} - 1$$

$$\begin{aligned} &= \frac{z}{z-1} - 1 \\ &= \frac{z-z+1}{z-1} \\ &= \frac{1}{z-1} \\ &= -\frac{1}{1-z} \end{aligned}$$



C.W.

DSP

21-07-22

Thursday.

Determine inverse z-transform.

$$x(z) = \frac{3 + 2z^{-1} + z^{-2}}{1 - 3z^{-1} + 2z^{-2}}$$

$$\begin{aligned} & \frac{1 - 3z^{-1} + 2z^{-2}}{(z - 3)(z - 2)} \left| \begin{array}{c} 3 + 11z^{-1} + 28z^{-2} + 62z^{-3} \\ (-) \quad (+) \end{array} \right. \\ & \frac{(-9z^{-1} + 6z^{-2})}{(z - 11z^{-1} - 5z^{-2})} \\ & \frac{(-14z^{-1} + 33z^{-2} + 22z^{-3})}{(28z^{-2} - 22z^{-3})} \\ & \frac{(-28z^{-2} - 84z^{-3} + 56z^{-4})}{(56z^{-4} - 56z^{-4})} \\ & \frac{(-62z^{-3})}{(62z^{-9} + 186z^{-4} + 124z^{-5})} \\ & \frac{(-130z^{-4} - 124z^{-6})}{\dots} \end{aligned}$$

$$x(z) = 3 + 11z^{-1} + 28z^{-2} + 62z^{-3}$$

$$= 3z^0 + 11z^1 + 28z^2 + 62z^3$$

$$x(z) = \sum_{n=-\infty}^{\infty} x(n)z^n = x(0) \sum_{n=0}^{\infty} x(n)z^n$$

$$= x(0) + x(1)z^1 + x(2)z^2 + x(3)z^3 + \dots$$

$$= 3z^0 + 11z^1 + 28z^2 + 62z^3 + \dots$$

$$x(z) = \{3, 11, 28, 62, \dots\}$$



$$\text{Determine inverse z-transform, } x(z) = \frac{z^2 + 2z}{z^3 - 3z^2 + 4z + 1}$$

ROC : $|z| > 1$.

$$|z| > 1.$$

Condition
 $|z| > 1$ means it's causal system or right sided sequences

For such case z^n i.e., the power of z must be negative. \therefore Do in descending order.

$$\frac{z^2 + 2z}{z^3 - 3z^2 + 4z + 1} = \frac{z^2 + 2z}{z^{-1} + 5z^{-2} + 11z^{-3} + 12z^{-4}} =$$

$$\frac{(+) z^2 + (-) 3z + (+) 4 + (-) z^{-1}}{5z - 4 - z^{-1}}$$

$$\frac{5z - 15 + 20z^{-1} + 5z^{-2}}{11 - 21z^{-1} - 5z^{-2}}$$

$$\frac{(-) 11 - 33z^{-1} + 44z^{-2} + 19z^{-3}}{30z^{-1} - 40z^{-2} - 11z^{-3}}$$

$$\frac{(+ 18z^{-1} - 36z^{-2} + 48z^{-3} + 12z^{-4})}{-13z^{-2} - 59z^{-3} - 19z^{-4}}$$

$$x(z) = z^1 + 5z^2 + 11z^3 + 12z^4 + \dots$$

$$x(n) = \sum_{n=-\infty}^{\infty} x(n)z^{-n} = x(0) + x(1)z^1 + x(2)z^2 + x(3)z^3 + x(4)z^4 + \dots$$

$$= 0 + 1z^1 + 5z^2 + 11z^3 + 12z^4 + \dots$$

$$x(0) = 0 \quad x(2) = 5 \quad x(n) = \{0, 1, 5, 11, 12, \dots\}$$

$$x(1) = 1 \quad x(3) = 11$$

$$x(4) = 12$$

non-causal/anti causal for NOT right sided. $|z| > \infty$

\hookrightarrow causal form $>$ sign
 $\therefore z$ at power inverse.

$$x(z) = \frac{z^2 + z + 2}{z^3 - 2z^2 + 3z + 4} \quad \text{ROC } |z| < 1$$

arrange in ascending order.

$$\begin{array}{r} z^2 + z + 2 \\ \hline 4 + 3z - 2z^2 + z^3 \end{array}$$

$$4x\alpha = 0.5$$

$$\alpha = \frac{1}{8}$$

$$4x\alpha = 2.375$$

$$4 + 3z - 2z^2 + z^3 \left| \begin{array}{r} z^2 + z + 2 \\ \hline \frac{1}{2} - \end{array} \right. \quad \frac{1}{8}z + \frac{19}{32}z^2$$

$$\begin{array}{r} 2 + \frac{3}{2}z - z^2 + \frac{z^3}{2} \\ (-) (+) (-) \hline -0.5z + 2z^2 - 0.5z^3 \end{array}$$

$$\begin{array}{r} -0.5z - 0.375z^2 + 0.25z^3 - 0.125z^4 \\ (+) (+) (-) (+) \hline 2.375z^2 - 0.75z^3 + 0.125z^4 \end{array}$$

$\sum_{n=0}^{\infty} x(n)$

$$x(z) = \frac{1}{2} - \frac{1}{8}z + \frac{19}{32}z^2$$

$$x(z) = \dots + \frac{19}{32}z^{(-2)} - \frac{1}{8}z^{(-1)} + \frac{1}{2}z^{(0)}$$

$$\left\{ \frac{19}{32}, -\frac{1}{8}, \frac{1}{2} \right\}$$

$$x(n) = \{ \dots \}$$

DSP

24-07-22

DFT

What is DFT

What is DTS

Frequency domain Sampling & reconstruction of

DTS (Discrete time Signal).
sequence.

DTS $\xrightarrow{\text{transform}}$ Equivalent F. D(frequency domain)

to analyze $\xrightarrow{\text{Fourier transform}} X(e^{j\omega})$

But then $\xrightarrow{\text{not convenient}}$

$X(e^{jn\omega})$ not so convenient to analyze DTS.

So, we sample DT

Frequency Domain representation is not convenient representation

for a DTS $x(n)$. Let's do it

Hence, the Fourier transform is sampled to obtain a frequency domain sequence, $X(k)$.

This is called Discrete Fourier Transform

Fourier Transform \rightarrow Sample \rightarrow a Fourier Domain Sequence $x(k)$

DFT is a powerful tool for frequency analysis of DTS.

$$F.T = X(e^{j\omega})$$

$$D.F.T = X(k)$$

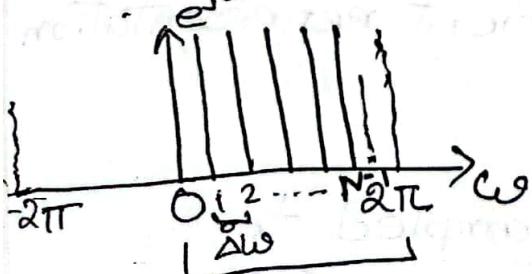
Let's consider a non-periodic discrete time signal $x(n)$. Now, the F.T. of $x(n)$ can be written as - F.T. of $x(n) \rightarrow X(e^{j\omega})$

F.T of $x(n)$

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\omega n}$$

$X(e^{j\omega})$ is periodic with fundamental frequency

ranging from $0 < \omega < 2\pi$



$$\Delta\omega = \frac{2\pi}{N}$$

Let's take N equidistant sample in the interval $0 \leq \omega \leq 2\pi$ to $N-1$ sample

$$\Delta\omega = \frac{2\pi}{N}$$

$$\Delta\omega = \frac{2\pi}{N} \cdot k \quad [k = \# \text{ of sample}]$$

$; 0 \leq k \leq N-1$

$$k=0, \Delta\omega=0$$

$$k=1, \Delta\omega = \frac{2\pi}{N}$$

$$k=2, \Delta\omega = \frac{4\pi}{N} \quad [\text{Dis from } 0 \text{ to } 2]$$

$$x\left(\frac{2\pi}{N} \cdot k\right) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\left(\frac{2\pi}{N}\right) kn}; \quad 0 \leq k \leq n-1$$

Here, $x(n)$ has infinite no. of summation with N

sample ranging from ~~0 to~~ $0 - (N-1)$

$$x\left(\frac{2\pi}{N} \cdot k\right) = \sum_{n=N}^{+\infty} x(n) e^{-j\frac{2\pi}{N} \cdot kn} + \sum_{n=0}^{N-1} x(n) e^{-j\frac{2\pi}{N} \cdot kn} + \dots$$

$\sum_{n=N}^{2N-1} x(n) e^{-j\frac{2\pi}{N} \cdot kn} + \dots$

(11)

$$x\left(\frac{2\pi}{N} \cdot k\right) = \sum_{l=\alpha}^{\infty} \sum_{n=lN}^{(l+1)N-1} x(n) e^{-j\frac{2\pi}{N} \cdot kn} \quad (4)$$

compact version of (11).

$$n = n - lN$$

$$lN = n - n$$

$$lN = 0$$

$$x\left(\frac{2\pi}{N} \cdot k\right) = \sum_{l=-\alpha}^{\alpha} \cdot \sum_{n=0}^{N-1} x(n-lN) e^{-j \frac{2\pi}{N} kn}$$

$$x\left(\frac{2\pi}{N} \cdot k\right) = \sum_{n=0}^{N-1} \sum_{l=-\alpha}^{\alpha} x(n-lN) e^{-j \frac{2\pi}{N} kn}$$

periodic signal of N

$$x(n-lN) = x_p(n)$$

$$X\left(\frac{2\pi}{N} k\right) = \sum_{n=0}^{N-1} x_p(n) e^{-j \frac{2\pi}{N} kn} \quad (5)$$

D.F.T equation -

What is DFT?

*Properties of DFT

Using Fourier Series any periodic Signal can be written as -

$$x_p(n) = \sum_{k=0}^{N-1} a_k \cdot e^{j \frac{2\pi}{N} k n} ; 0 \leq n \leq N-1 \quad (6)$$

Here,

$$a_k = \left(\frac{1}{N} \sum_{n=0}^{N-1} x_p(n) \cdot e^{-j \frac{2\pi}{N} k n} ; 0 \leq k \leq N-1 \right) \quad (7)$$

Fourier coefficient

Compare 5 & 7: ⑤/⑦

$$\frac{x\left(\frac{2\pi}{N} \cdot k\right)}{a_k} = \frac{\cancel{1}}{\cancel{N}} = \frac{1}{N}$$

$$\frac{x\left(\frac{2\pi}{N} \cdot k\right)}{a_k} = N$$

$$a_k = \frac{1}{N} \cdot x\left(\frac{2\pi}{N} \cdot k\right)$$

$$x_p(n) = \sum_{k=0}^{N-1} \frac{1}{N} x\left(\frac{2\pi}{N} \cdot k\right) e^{-j \frac{2\pi}{N} \cdot kn}$$

$$x_p(n) = \frac{1}{N} \sum_{k=0}^{N-1} x\left(\frac{2\pi}{N} \cdot k\right) e^{-j \frac{2\pi}{N} \cdot kn} \quad -⑧$$

Inverse Discrete Fourier Transform
IDFT

* Define IDFT

C.W.

7

10

13

16

26

27

33

34

42

19

16 ema opu
sumon vai

DSP

$0 \leq k \leq N-1$

DFT $\rightarrow x(n)$

$$DFT \rightarrow \{x(n)\} = x(k) = \sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi}{N} k \cdot n}$$

~~DFT~~

↳ main DFT equation

$$\text{DFT} \{x(n)\} = X(k) = \sum_{n=0}^{N-1} x(n) e^{-j\frac{2\pi}{N} kn}$$

$$w_k = e^{-j\frac{2\pi}{N}}$$

w_n = Phase factor / twiddle factor.

Q: What is phase factor?

$$\text{IDFT} \{X(k)\} = x(n) = \frac{1}{N} \sum_{k=0}^{N-1} X(k) e^{j\frac{2\pi}{N} \cdot kn}$$

* Compute the N -point DFT of the signal -

(a) $x(n) = \delta(n)$

We know, from DFT equⁿ

$$X(k) = \sum_{n=0}^{N-1} x(n) e^{-j\frac{2\pi}{N} \cdot kn}$$

$$= \sum_{n=0}^{N-1} \delta(n) e^{-j\frac{2\pi}{N} \cdot kn}$$

$$= \delta(0) \cdot e^{-j\frac{2\pi}{N} \cdot k \cdot 0}$$

$$= \delta(0) \cdot e^0$$

$$= 1$$

(b) $x(n) = \delta(n - n_0)$

$$X(k) = \sum_{n=0}^{N-1} x(n) e^{-j\frac{2\pi}{N} \cdot kn}$$

$$= \sum_{n=0}^{N-1} \delta(n - n_0) e^{-j\frac{2\pi}{N} \cdot kn}$$

$$= \sum_{n=0}^{N-1} \delta(n - n_0) e^{-j\frac{2\pi}{N} \cdot kn_0}$$

$$\left. \begin{aligned} \delta(n) &= 1; n=0 \\ &= 0; n \neq 0 \end{aligned} \right|$$

$$\left. \begin{aligned} n-n_0 &= 0 \\ n &= n_0 \end{aligned} \right|$$

$$= b e^{-\frac{2\pi}{N} k \cdot n}$$

$$= e^{-\frac{2\pi}{N} \cdot kn}$$

$$x(n) = a^n \quad 0 \leq n \leq N-1$$

$$x(k) = \sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi}{N} \cdot kn}$$

$$= \sum_{n=0}^{N-1} a^n e^{-j \frac{2\pi}{N} \cdot n}$$

$$= \sum_{n=0}^{N-1} \left(a e^{-j \frac{2\pi}{N} k} \right)^n$$

$$= \frac{\left(a e^{-j \frac{2\pi}{N} k} \right)^0 - \left(a e^{-j \frac{2\pi}{N} k} \right)^{N-1}}{1 - a e^{-j \frac{2\pi}{N} k}}$$

$$= \frac{1 - \left(a e^{-j \frac{2\pi}{N} k} \right)^N}{1 - a e^{-j \frac{2\pi}{N} k}}$$

$$= \frac{1 - a^N e^{-j 2\pi k}}{1 - a e^{-j \frac{2\pi}{N} k}}$$

$$= \frac{1 - a^N}{1 - a e^{-j \frac{2\pi}{N} k}}$$

Formula

$$\sum_{n=0}^{N-1} a^n = \frac{a^N - a^{N+1}}{1 - a}$$

$$x(n) = a^n = 1 \quad ; n=0$$

$$e^{-j 2\pi k}$$

$$= \cos 2\pi k - j \sin 2\pi k$$

$$k = 0, 1, 2, 3, \dots$$

$$\cos(2\pi \cdot 0) - \sin(2\pi \cdot 0)$$

$$\text{then } 1 - 0 = 1$$

27-07-22

Wednesday.

C.W.

13

16

33

34

18 → 19

- 15

CN & DSP → Assignment Mid Question.

* DSP

* Derivation v.v.I. for exam.

^{4 point}
 Find the DFT of the sequence $x(n) = \begin{cases} 1 & ; 0 \leq n \leq 2 \\ 0 & ; \text{otherwise.} \end{cases}$

Sol:

N=4. Sketch the magnitude and phase spectrum.

$$x(n) = \{ \underset{\substack{\rightarrow \text{position} \\ \text{of DFT points.}}}{\begin{matrix} 0 & 1 & 2 & 3 \end{matrix}} \}$$

$$* X(k) = \sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi}{N} kn} ; 0 \leq k \leq N-1$$

$$= \sum_{n=0}^3 x(n) e^{-j \frac{2\pi}{N} kn} ; 0 \leq k \leq 3$$

$$x(k) = x(0) + x(1) \cdot e^{-j\frac{2\pi}{N} \cdot k \cdot 1} + x(2) \cdot e^{-j\frac{2\pi}{N} \cdot k \cdot 2}$$

$$x(3) = x(3) \cdot e^{-j\frac{2\pi}{N} \cdot k \cdot 3} = e^{-j\theta} = \cos\theta - j\sin\theta$$

If $k=0, 1$

~~$$\begin{aligned} x(0) &= x(0) \cdot 1 + x(1) \cdot 1 \cdot e^{-j\frac{2\pi}{4} \cdot 0 \cdot 1} + \\ &\quad x(1) \cdot e^{-j\frac{2\pi}{4} \cdot 1 \cdot 2} + 0 \\ &= 1 + e^{-j\frac{\pi}{2}} + e^{-j\frac{\pi}{4}} + 0 \end{aligned}$$~~

Calculator
complex
radian

~~$$\begin{aligned} &= 1 + \left(\cos \frac{\pi}{2} - j \sin \frac{\pi}{2} \right) + \cos 2\pi - j \sin 2\pi \\ &= 1 + 0 - j + 1 - 0 \\ &= 2 - j \end{aligned}$$~~

If $k=0$, $x(0) = 1 + 1 \times 1 + 1 \times 1 + 0 = 3$

~~$$k=1, x(1) = 1 + 1 \cdot e^{-j\frac{2\pi}{4} \cdot 1 \cdot 1} + 1 \cdot e^{-j\frac{2\pi}{4} \cdot 1 \cdot 2} + 0$$~~

~~$$= 1 + e^{-j\frac{\pi}{2}} + e^{-j\pi}$$~~

~~$$= 1 + \cos \frac{\pi}{2} - j \sin \frac{\pi}{2} + \cos \pi - j \sin \pi$$~~

~~$$= 1 + 0 - j + (-1) + 0$$~~

~~$$= -j$$~~

$$x(2) = x(6) + x(1) e^{-j \frac{2\pi}{4} \cdot 2 \cdot 1} + x(2) e^{-j \frac{2\pi}{4} \cdot 2 \cdot 2} + 0$$

$$= 1 + 1 \times e^{-j\pi} + 1 \times e^{-j2\pi} + 0$$

$$= 1 + \cos \pi - j \sin \pi + \cos 2\pi - j \sin 2\pi = 1 - 1 + 1 - 0 = 1$$

$$x(3) = x(0) + x(1) e^{-j \frac{2\pi}{4} \cdot 3 \cdot 1} + x(2) e^{-j \frac{2\pi}{4} \cdot 3 \cdot 2} + 0$$

$$= 1 + e^{-j \frac{3\pi}{2}} + e^{-j 3\pi}$$

$$= 1 + \cos \frac{3\pi}{2} - j \sin \frac{3\pi}{2} + \cos 3\pi - j \sin 3\pi = 1 + 0 - j - 1 + 0 = j$$

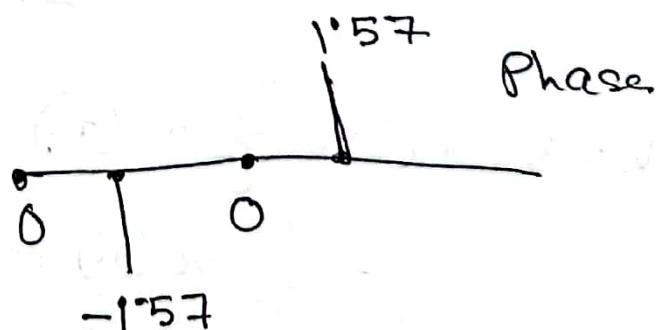
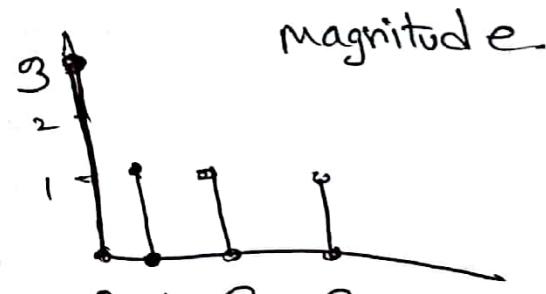
$$x(k) = \{3, -j, 1, j\}$$

Magnitude: $|x(k)| = \{3, 1, 1, 1\}$

Phase: $\angle x(k) = \{0, -1.57, 0, 1.57\}$

$3 \cdot (\text{shift } +)$ + spectrum = 3

shift = 0



C. WE

DSP

28-07-22

Thursday.

8 * Compute the DFT of the following sequence-
 13 For 4 point
 16
 26
 33
 42
 19
 5
 10

$$x(n) = 1 ; 0 \leq n \leq 1
 0 ; \text{ otherwise}$$

$$N=4 \text{ bits}$$

$$N-1=3$$

$$x(n) = \begin{cases} 1 & n=0 \\ 1 & n=1 \\ 0 & n=2 \\ 0 & n=3 \end{cases}$$

According to formula, DFT equation-

$$X(k) = \sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi}{N} k n}$$

$$= \sum_{n=0}^{3} x(n) e^{-j \frac{2\pi}{4} k n}$$

$$= \sum_{n=0}^{3} x(n) e^{-j \frac{2\pi}{4} k n} \quad \text{--- (1)}$$

$$0 \leq k \leq N-1$$

generalized
formula

$$k=0, x(0) = \sum_{n=0}^{3} x(n) e^{-j \frac{2\pi}{4} \cdot 0 \cdot n}$$

$$= \sum_{n=0}^{3} x(n) e^0$$

$$= \sum_{n=0}^{3} x(n)$$

$$= x(0) + x(1) + x(2) + x(3)$$

$$= 1 + 1 + 0 + 0$$

$$= 2$$

$$k=1, x(1) = \sum_{n=0}^{3} x(n) e^{-j \frac{\pi}{2} \cdot 1 \cdot n}$$

$$= \sum_{n=0}^{3} x(n) e^{-j \frac{\pi}{2} n}$$

$$= x(0) e^{-j \frac{\pi}{2} \cdot 0} + x(1) e^{-j \frac{\pi}{2} \cdot 1}$$

$$= 1 \times 1 + 1 \times e^{-j \frac{\pi}{2}}$$

$$= 1 + e^{-j \frac{\pi}{2}}$$

$$= 1 + \cos \frac{\pi}{2} - j \sin \frac{\pi}{2} = 1 + 0 - j = 1 - j$$

$$\begin{aligned}
 k=2 \quad x(2) &= \sum_{n=0}^3 x(n) e^{-j\frac{\pi}{2} \cdot 2 \cdot n} \\
 &= \sum_{n=0}^3 x(n) e^{-j\pi n} \\
 &= x(0) e^{-j\pi \cdot 0} + x(1) e^{-j\pi \cdot 1} + 0 + 0 \\
 &= 1 + e^{-j\pi} \\
 &= 1 + \cos \pi - j \sin \pi \\
 &= 1 - 1 - j \times 0 \\
 &= 0
 \end{aligned}$$

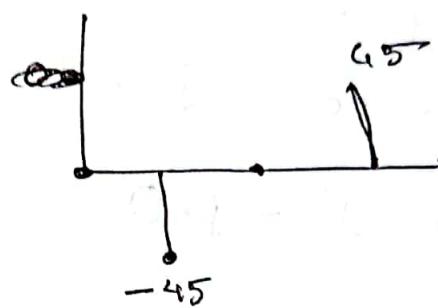
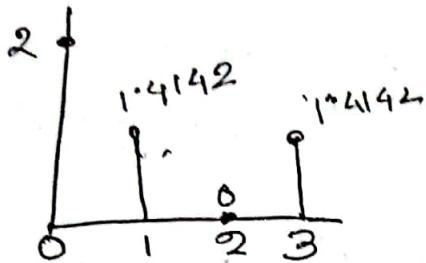
$e^{-j3\pi} = 1$ $e^{j\pi} = -1$
 $e^{-j\frac{3\pi}{2}} = j$ $e^{-j\pi} = -1$
 $e^{-j\frac{9\pi}{2}} = -j$ $e^{j\frac{9\pi}{2}} = j$
 $e^{j2\pi} = 1$ $e^{j\frac{\pi}{2}} = j$
 $e^{j3\pi} = -1$ $e^{-j\frac{7\pi}{2}} = -j$

$$\begin{aligned}
 k=3 \quad x(3) &= \sum_{n=0}^3 x(n) e^{-j\frac{\pi}{2} \cdot 3 \cdot n} \\
 &= \sum_{n=0}^3 x(n) e^{-j\frac{3\pi}{2} n} e^{j\frac{3\pi}{2}} = -j \\
 &= x(0) e^{-j\frac{3\pi}{2} \cdot 0} + x(1) \cdot e^{-j\frac{3\pi}{2} \cdot 1} + 0 + 0 \\
 &= 1 + e^{-j\frac{3\pi}{2}} \\
 &= 1 + \cos \frac{3\pi}{2} - j \sin \frac{3\pi}{2} \\
 &\approx 1 + 0 \angle(-j) \\
 &= 1 + j
 \end{aligned}$$

$$x(k) = \{ 2, 1-j, 0, 1+j \}$$

Magnitude: $|x(k)| = \{ 2, \sqrt{2}, 0, \sqrt{2} \}$

Phase: $\angle x(k) = \{ 0, -0.785, 0, 0.785 \}$
 $-45^\circ \quad 45^\circ$



* Compute 4 point DFT of following sequence
 $x(n) = \{ 1, 0, 0, 1 \}$ sketch magnitude & phase

$$x(n) = \{ 1, 0, 0, 1 \}$$

$$x(k) = \sum_{n=0}^{N-1} x(n) e^{-j \frac{2\pi}{N} \cdot kn}$$

$$= \sum_{n=0}^3 x(n) e^{-j \frac{2\pi}{4} k \cdot n}$$

$$= \sum_{n=0}^3 x(n) e^{-j \frac{\pi}{2} k \cdot n}$$

$$= \sum_{n=0}^3 x(n) e^{-j \frac{\pi}{2} k \cdot n}$$

$$\text{For } k=0, x(0) = \sum_{n=0}^3 x(n) e^{-j \frac{\pi}{2} k \cdot n}$$

$$= \sum_{n=0}^3 x(n) 1$$

$$= x(0) + x(1) + x(2) + x(3)$$

$$= 1 + 0 + 0 + 1 = 2$$

$$\text{For } k=1 \quad x(1) = \sum_{n=0}^3 x(n) e^{-j\frac{\pi}{2} \cdot 1 \cdot n}$$

$$= \sum_{n=0}^3 x(n) e^{-j\frac{\pi}{2} n}.$$

$$= x(0) e^{-j\frac{\pi}{2} \cdot 0} + 0 + x(3) e^{-j\frac{\pi}{2} \cdot 3}$$

$$= 1 + e^{-j\frac{3}{2}\pi}$$

$$= 1 + \cos \frac{3}{2}\pi - j \sin \frac{3}{2}\pi$$

$$= 1 + 0 - j(-1)$$

$$= 1 + j$$

$$k=2 \quad x(2) = \sum_{n=0}^3 x(n) e^{-j\frac{\pi}{2} \cdot 2 \cdot n} = \sum_{n=0}^3 x(n) e^{-j\pi n}$$

$$= x(0) e^{-j\pi \cdot 0} + 0 + 0 + x(3) e^{-j\pi \cdot 3}$$

$$= 1 + \cos 3\pi - j \sin 3\pi = 1 + (-1) - j(0) = 0$$

$$k=3, x(3) = \sum_{n=0}^3 x(n) e^{j\frac{\pi}{2} \cdot 3 \cdot n} = \sum_{n=0}^3 x(n) e^{-j\frac{3}{2}\pi \cdot n}$$

$$= x(0) e^{-j\frac{3}{2}\pi \cdot 0} + 0 + 0 + x(3) e^{-j\frac{3}{2}\pi \cdot 3}$$

$$= 1 + e^{-j\frac{9}{2}\pi}$$

$$= 1 + \cos \frac{9}{2}\pi - j \sin \frac{9}{2}\pi$$

$$= 1 + 0 - j(1)$$

$$= 1 - j$$

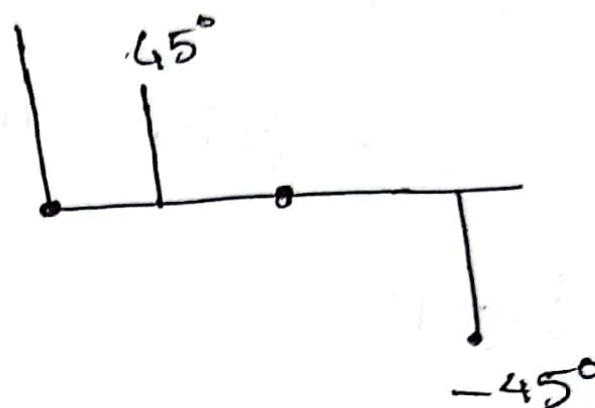
$$\therefore x(k) = \{ 2 \quad 1+j \quad 0 \quad 1-j \}$$

$$|x(k)| = \{ 2 \quad 1.414 \quad 0 \quad 1.414 \}$$

$$\angle x(k) = \{ 0 \quad 45 \quad 0 \quad -45 \}$$



$|x(k)|$



DFT \rightarrow Math

\hookrightarrow Matrix method

\hookrightarrow sequence, point, values etc

DSP
Find the IDFT of $x(k) = \{6, -2+2j, -2, -2-2j\}$

We know,

$$x(n) = \frac{1}{N} \sum_{k=0}^{N-1} x(k) \cdot e^{j \frac{2\pi}{N} kn}$$

$N = 4$

$$= \frac{1}{4} \sum_{k=0}^3 x(k) \cdot e^{j \frac{2\pi}{4} kn}$$
$$= \frac{1}{4} \left[x(0) + x(1) e^{j \frac{2\pi}{4} \cdot 1 \cdot n} + x(2) e^{j \frac{2\pi}{4} \cdot 2 \cdot n} + x(3) e^{j \frac{2\pi}{4} \cdot 3 \cdot n} \right]$$

$$n=0, x(0) = \frac{1}{4} [x(0) + x(1) + x(2) + x(3)]$$
$$= \frac{1}{4} [6 + \cancel{-2+2j} - \cancel{-2} - \cancel{-2-2j}]$$
$$= \frac{1}{4} \times 0 = 0$$

$$n=1, x(1) = \frac{1}{4} \left[x(0) e^{j \frac{2\pi}{4} \cdot 1 \cdot 1} + x(1) e^{j \frac{2\pi}{4} \cdot 2 \cdot 1} + x(2) e^{j \frac{2\pi}{4} \cdot 3 \cdot 1} + x(3) e^{j \frac{2\pi}{4} \cdot 4 \cdot 1} \right]$$
$$= \frac{1}{4} [6 + (-2+2j)j + (-2)(-1) + (-2-2j)(-j)]$$
$$= \frac{1}{4} [6 - 2j - 2 + 2 - 2j + 2]$$
$$= \frac{1}{4} \times 4$$
$$= 1$$

$$n=2, x(2) = \frac{1}{4} [x(0) + x(1) e^{j\frac{2\pi}{4} \cdot 2} + x(2) e^{j\frac{2\pi}{4} \cdot 2 \cdot 2} + x(3) e^{j\frac{2\pi}{4} \cdot 3 \cdot 2}]$$

$$= \frac{1}{4} [6 + (-2+2j) e^{j\pi} + (-2) e^{j2\pi} + (-2-2j) e^{j3\pi}]$$

$$= \frac{1}{4} [6 + (-2+2j)(-1) + (-2) 1 + (-2-2j)(-1)]$$

$$= \frac{1}{4} [6 + 2 - 2j - 2 + 2 + 2j]$$

$$= \frac{1}{4} \times 8$$

$$= 2$$

$$n=3, x(3) = \frac{1}{4} [x(0) + x(1) e^{j\frac{2\pi}{4} \cdot 3} + x(2) e^{j\frac{2\pi}{4} \cdot 3} + x(3) e^{j\frac{2\pi}{4} \cdot 3 \cdot 3}]$$

$$= \frac{1}{4} [6 + (-2+2j) e^{j\frac{3\pi}{2}} + (-2) e^{j3\pi} + (-2-2j) e^{j\frac{9\pi}{2}}]$$

$$= \frac{1}{4} [6 + (-2+2j)(-j) + (-2)(-1) + (-2-2j)(j)]$$

$$= \frac{1}{4} [6 + 2j + 2 + 2 - 2j + 2]$$

$$= \frac{1}{4} \times 12$$

$$= 3$$

$$x(n) = \{0, 1, 2, 3\}$$

H.W.

IDFT

Math

previous classes

DSP - Presentation

Bithi →

anti-aliasing ?

aliasing.

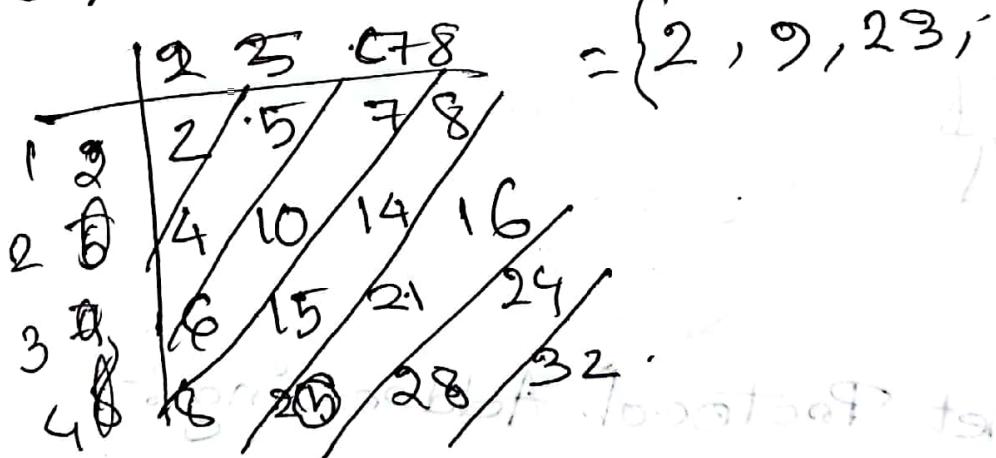
Nadim → convolution signal.

Mithun → Window

Fahim → Inverse, deconvolution

$h(n)$ = linear time invariant system $\{1, 2, 3, 4\}$
 $x(n)$ = input $= \{2, 5, 7, 8\}$

Find $y(n) = h(n) * x(n)$



$$y(n) = x(-n)$$

$$xy(n, n_0) = x(-n + n_0)$$

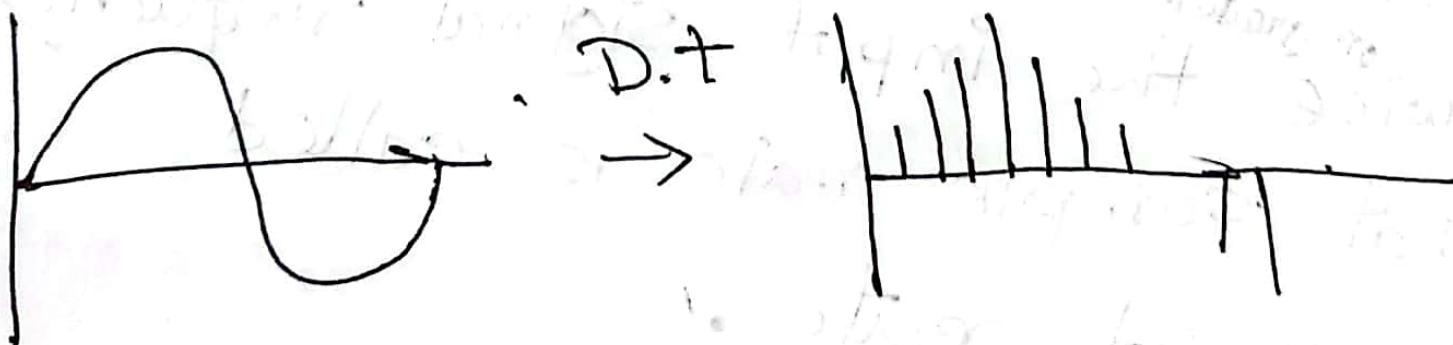
$$\Rightarrow y(n - n_0) = x(-(n - n_0)) \\ = x(-n + n_0)$$

∴ time variant

DSP \rightarrow 31.08.22

Model test \rightarrow 8th September

Sampling theorem



Sampling Theorem:-

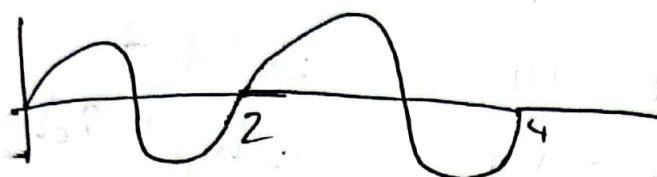
Continuous form of a time variant signal can be represented in the discrete form of a signal with the help of samples and the sampled signal can be recovered to original form when the sampling frequency (f_s) having greater frequency value than or equal to the highest input signal frequency (f_{max}). $f_s \geq 2 f_{max}$.

→ Any sampling frequency f_s less than twice the input signal frequency will cause a effect. This effect is known as aliasing effect.

When sampling frequency equals twice the input signal frequency or greater, that sample rate is called nyquist rate.

aliasing effects.

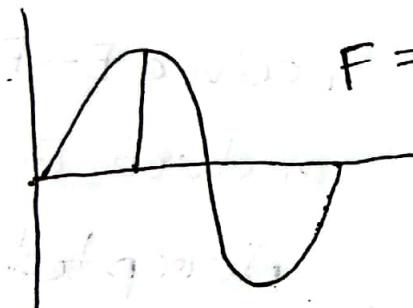
1. Frequency: complete wave in 1 second



$$F = 0.5 \text{ Hz}$$

$$-\infty < F < \infty$$

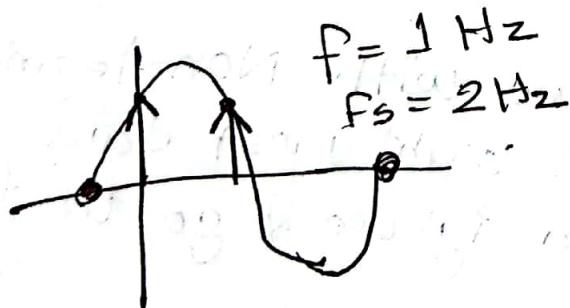
Normalized, $f = \frac{F}{F_s} = \text{frequency cont. time signal}$
 $F_s = \text{Sampling}$



$$F = 1 \text{ Hz}$$

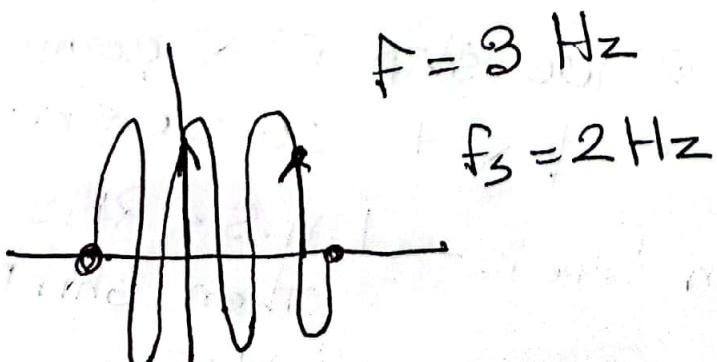
$$F_s = 2 \text{ Hz}$$

unability to detect which frequency is sampled is derived from frequency is aliasing effect.



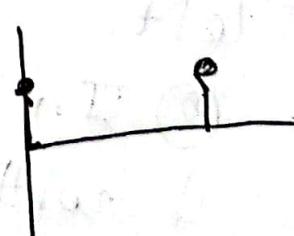
$$f = 1 \text{ Hz}$$

$$f_s = 2 \text{ Hz}$$



$$f = 3 \text{ Hz}$$

$$f_s = 2 \text{ Hz}$$



04-09-22

Consider an Analog Signal

$$x_a = 2 \cos(50\pi t)$$

Q1: Determine the minimum sampling rate required to avoid aliasing?

$$f_s \geq 2F(\text{input frequency})$$

* * * analog signal $x_a(t) = A \cos(2\pi F t)$
 ↓ important ↑
 analog signal input frequency

Here,

$$x_a = 2 \cos(2\pi \cdot 25t)$$

$$\therefore f_s \geq 2F$$

$$\geq 2 \times 25$$

$$\geq 50$$

∴ the minimum sampling rate required

$$\therefore f_s \geq 50$$

~~Important equations~~

$$x_a(t) = A \cos(2\pi F t)$$

$$x(n) = x_a(nt)$$

Q2: Suppose the signal is sampled at the rate $F_s = 200 \text{ Hz}$. What is the discrete time signal obtained after sampling?

$$\begin{aligned}
 x(n) &= x_a(nt) \quad \text{where } T = \frac{1}{F_s} \\
 &= A \cos(2\pi F(nt)) \\
 &= A \cos(2\pi n F T) \\
 &= A \cos(2\pi n F \cdot \frac{1}{F_s}) \\
 &= 2 \cos(2\pi n \cdot \frac{1}{200}) \\
 &= 2 \cos(\pi \cdot n \cdot \frac{1}{4})
 \end{aligned}$$

$x(n) = 2 \cos(\frac{\pi}{4}n)$ i.e. discrete time signal with $F_s = 200 \text{ Hz}$.

Q3: $\rightarrow x_a(t) = 2 \cos(50\pi t)$
 Q3: What is the frequency $0 < F < \frac{F_s}{2}$. If

What is the frequency that generate samples a sinusoid identical to obtained in Q2.

$$x(n) = A \cos(2\pi f_n n) \leftarrow \text{discrete time signal}$$

We know, $x(n) = A \cos(2\pi f_n n)$ - ①

$$x(n) = 2 \cos\left(\frac{\pi}{4} \cdot n\right) \quad \text{from Q2}$$

Comparing ① & ② \Rightarrow

$$x(n) = 2 \cos\left(2\pi \cdot \frac{1}{8} \cdot n\right)$$

$$\therefore f = \frac{1}{8}$$

We know, $f = \frac{F}{F_s}$

$$\begin{aligned} F &= f \times F_s \\ &= \frac{1}{8} \times 200 \\ &= 25 \text{ Hz} \end{aligned}$$

$$\therefore x(t) = 2 \cos(2\pi F t)$$
$$= 2 \cos(2\pi 25 t)$$

Q4: Consider analog signal ;

$$x_a(t) = 3 \cos(100\pi t) + 10 \sin(400\pi t) - \cos(600\pi t)$$

* what is the Nyquist rate of
the signal

$$x_a(t) = 3\cos(2\pi \frac{50t}{f_1}) + 10\sin(2\pi \frac{200t}{f_2}) - \cos(2\pi \frac{300t}{f_3})$$

Here, $f_1 = 50 \text{ Hz}$, $f_2 = 200 \text{ Hz}$, $f_3 = 300 \text{ Hz}$

$\therefore F_{\max} = 300 \text{ Hz}$ input equation at maximum frequency or twice or greater frequency

$$\therefore f_N = 2 \times F_{\max}$$

$$= 2 \times 300$$

$$= 600 \text{ Hz}$$

rate is nyquist rate

Q4: $x(t) = 3\cos(400\pi t) + 5\sin(800\pi t) + 10\cos(1400\pi t)$

Find \rightarrow Nyquist rate?

\rightarrow If we sample this signal using sampling rate $f_s = 600$ sample/s. What is discrete time signal after sampling.

a) Here,
 $x(t) = 3\cos(2\pi 200t) + 5\sin(2\pi 400t) + 10\cos(2\pi 700t)$

$$\therefore f_{\max} = 700 \text{ Hz}$$

$$\therefore f_N = 2 \times 700 \text{ Hz}$$

$$= 1400 \text{ Hz}$$

Nyquist rate

$$f_N \geq 1400 \text{ Hz}$$

(b) We know,

$$x_n = x_a(n+)$$

$$= x_a\left(n \cdot \frac{1}{F_s}\right)$$

$$x_n = x_a\left(\frac{n}{6000}\right)$$