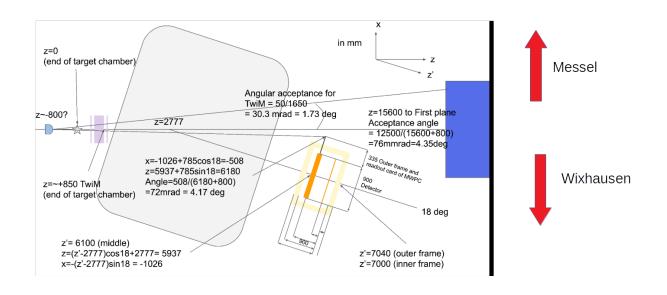
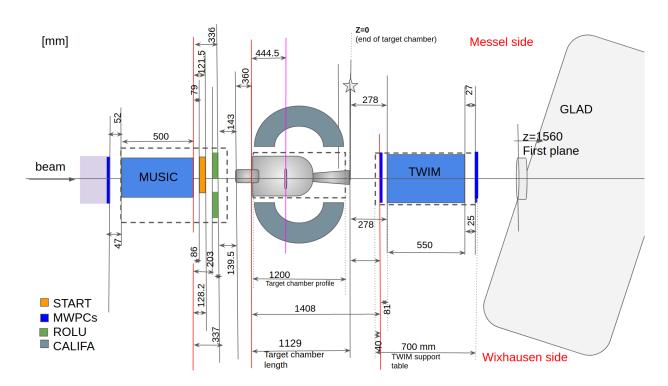
Radius/Momentum Calculation for S444 Experiment February 2020 - Overview

Tobias Jenegger August 10, 2020

0.1 The Setup





1 Geometry and relative position of the detectors in the beam direction

Here, the positions are given for the s444 and s467 experiments

```
zMW0 = -2520 \text{ mm}
z position of the MWPC0:
z position of the target:
                                zT = -684.5 \text{ mm}
z position of the MWPC1 in front of the Twin-MUSIC:
                                                                    zM1 = 279
mm
z position of the middle of the Twin-MUSIC:
                                                       zTwin = 553 \text{ mm}
z position of the MWPC2 after the Twin-MUSIC:
                                                            zM2 = 854 \text{ mm}
\alpha tilted angle of GLAD (14 degrees):
                                               = 0.244 \text{ rad}
effective length of GLAD:
                                  L_{\text{eff}} = 2067 \text{ mm}
z middle of GLAD
                          zGm = 2577mm
horizontal of the central path (18 degree)
                                                   \theta_out0 = pi/10 rad
z position of the MWPC3 after GLAD
                                                zM3 = 5937 \text{ mm}
                                 zToFW = 6660.2 \text{ mm}
z position of the ToFwall
```

Correspondence between the GLAD current and the magnetic field: I=3584~A,~B=2.2~T

Positions of the TOFWPads:

 $1 \Rightarrow \text{Messel}$

27⇒ Wixhausen

$\begin{array}{ll} \mathbf{2} & \mathbf{RUNS} \ \mathbf{used} \ \mathbf{for} \ \mathbf{calibration} = \mathbf{SWEEP} \ \mathbf{RUNS} \\ \mathbf{without} \ \mathbf{target} \end{array}$

UN	Beam ion	Beam Energy [AmeV]	GLAD current [A]	Comments
		W 10000W		before broken motor, here we see that tof is about 5ns faster. So they
	36 12C primary	400	1444	probably changed the position of the TOFW afterwards
	37 12C primary	400		it has be seen that motor drive not working
	38 12C primary	400	1444	tof is back with new gates *magnet sweep 1444A
	39 12C primary	400	1498	
	40 12C primary	400	1501	
	41 12C primary	400	1501	stopped with 1558 A
	42 12C primary	400		
	43 12C primary	400		stopped with 1653 A
	44 12C primary	400		
	45 12C primary	400		stopped with 1748 A
	46 12C primary	400	1748	
	47 12C primary	400		stopped with 1843 A
	48 12C primary	400	1843	
	49 12C primary	400		stopped with 1938 A
	51 12C primary	400		
	52 12C primary	400		stopped with 1444 A
	53 12C primary	400		
	54 12C primary	400		stopped with 1349 A
	55 12C primary	400		
	56 12C primary	400		stopped with 1254 A
	57 12C primary	400	1254	
	58 12C primary	400		stopped with 1159
	59 12C primary	400	1159	
	60 12C primary	400		stopped with 1064
	61 12C primary	400		
	62 12C primary	400		stopped with 1444 A
	23 12C primary	650		stopped with 1957
1	24 12C primary	650	1957	
	=	sweeping		
	=	stable GLAD current		

2.0.1 Other RUNS used for various checks:

RUN 70: 2 cm C target

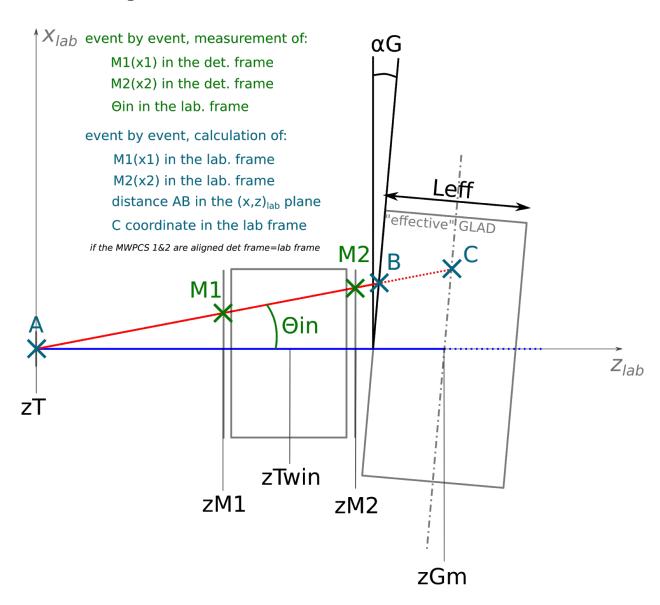
RUN 80: 10.86 mm C target RUN 81: 24.53 mm CH2 target RUN 67: 24 mm CH2 target

RUN 68: 1 cm C target

RUN 79: 12.29 mm CH2 target RUN 75: 21.98mm C target

3 Methods for flightpath reconstruction in the (x,z) plane

- 3.1 The "Kickplane" method
- 3.1.1 From MW0 to the entrance of GLAD, the ion is following a straight line



The straight line trajectory from MW0 to entrance before glad is defined by:

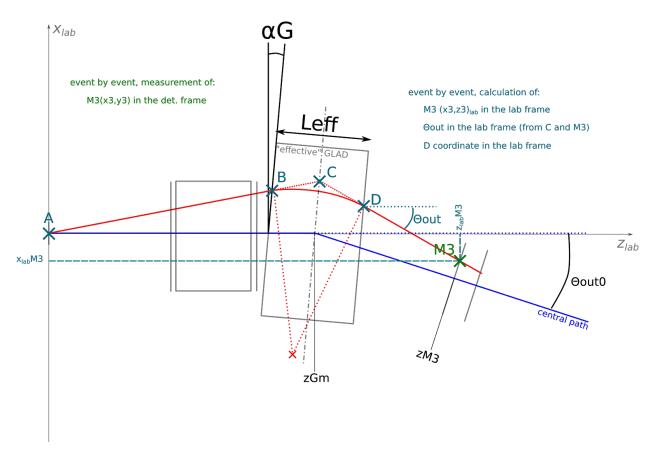
\Rightarrow one absolute value before GLAD

absolute = calibrated position in mm in the laboratory frame To get the position, use the position given by one MWPCs (1 or 2)

⇒ the theta angle (theta_in) before GLAD

Angle obtained from comining MWPC1 and MWPC2 (to get higher precision the drift time in TWIM MUSIC could be used)

3.1.2 From entrance to the exit of GLAD, the effective trajectory is circular



The circular trajectory is defined by:

 \Rightarrow one absolute position before GLAD B and angle theta_in (see: 3.1.1)

 \Rightarrow one absolute position at MWPC3

From this information the angle theta_out is constructed in follwing steps:

- 1. Extend the straight flightline of the ion before the GLAD.
- 2. The point of intersection with the "kickplane" (symmetry axis line of GLAD magnet) is the kickpoint C.
- 3. Draw a straight line between C and the absolute position at MWPC3 = M3.
- 4. theta_out is the positive angle between the z-beam direction and the line between C and M3.

The curvature radius ρ is given by:

$$\rho = \frac{\text{L-eff}}{2 \cdot \sin(\frac{t heta - in}{2} + \frac{t heta - out}{2}) \cdot \cos(\delta)}$$

With δ :

$$\delta = \arctan\left(\left|\frac{\frac{cos(theta_out) - cos(theta_in)}{\sin(theta_out) + \sin(theta_in)} + \tan(\alpha)}{1 - \frac{cos(theta_out) - cos(theta_in)}{\sin(theta_out) + \sin(theta_in)} \cdot \tan(\alpha)}\right|\right)$$

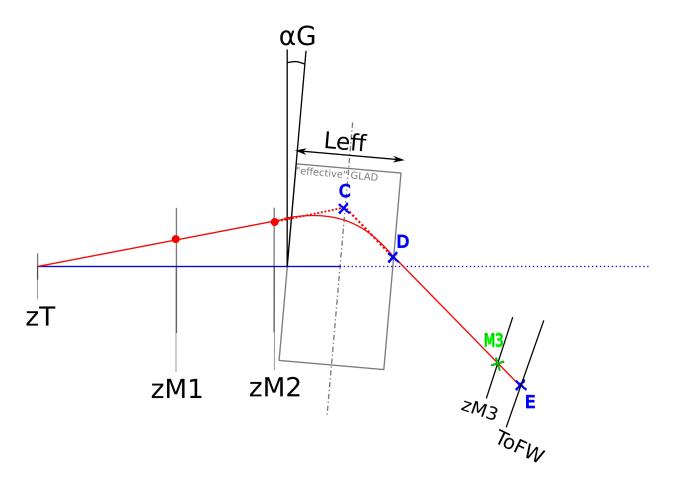
The full derivation can be found in the appendix.

The circular trajectory is given by:

$$\omega = 2 * \left| \arcsin \left[\frac{BD}{2 \cdot \rho} \right] \right|$$

with BD = length of the BD segment

3.1.3 After GLAD up to the TOFW, the trajectory is a straight line



The straight line trajectory from D to E is definded by:

- ⇒ the output angle from GLAD theta_out
- ⇒ one absolute position after GLAD in the laboratory frame M3

With this information the straight line trajectory length after GLAD can be measured. It starts at the exit point of GLAD D and follows the straigh line (characterized by the angle theta_out and the absolute position at MWPC3) until the intersection with the TofW (middle position of the ToFWall zToFW=6660.2mm, tilted angle=18°).

Finally the pathlength in the (x,z) plane from the target position to the ToFW is given by:

$$P = AB + \rho \cdot \omega + DE$$

where:

A = (x,z) position at the target point

B = (x,z) position at the GLAD entry point

D = (x,z) position at the GLAD exit point

E = (x,z) position where the constructed trajectory line hits the ToFW

The assumption in the "Kickplane" method is that the kickpoint for each event lies on the predefinded Kickplane, the symmetry axis line of the GLAD magnet.

3.2 The "Fit-Track" method

3.3 The "Optic correction" method