

Energy Reconstruction with CALIFA

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CALIFA Calorimeter



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Bundesministerium
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CALorimeter for the **In Flight** detection of γ -rays and light charged **p**Articles

Endcap:

iPhos:

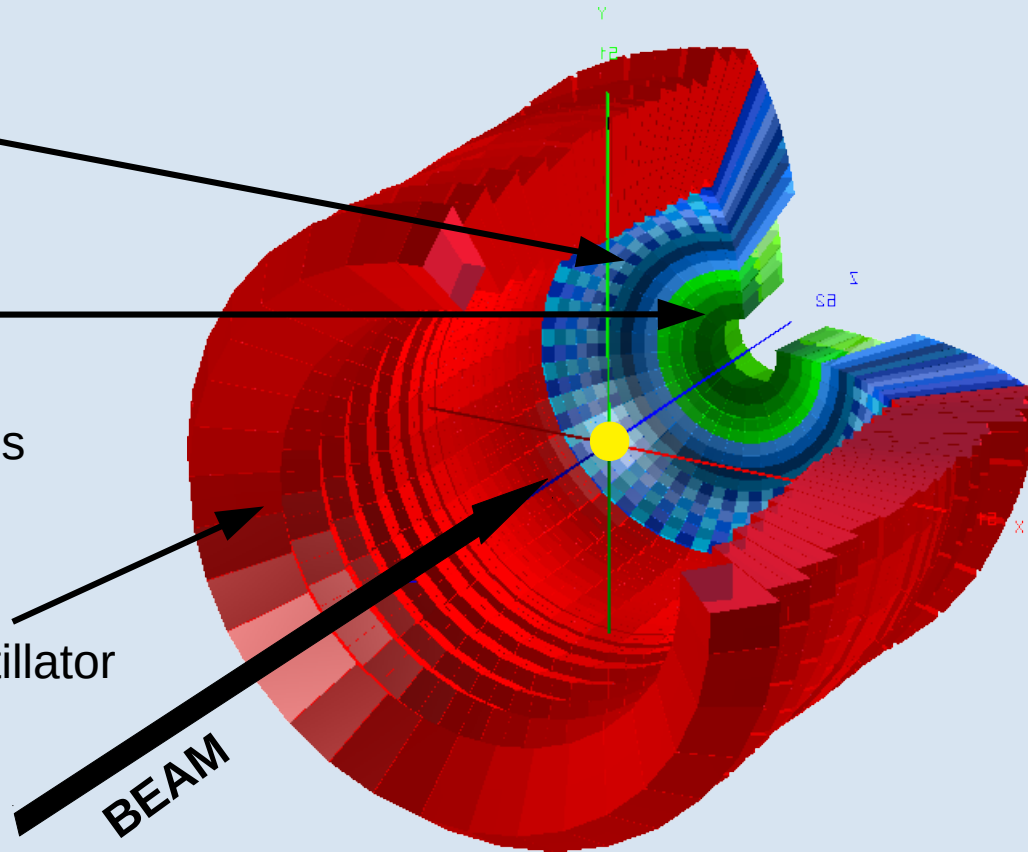
512 CsI(Tl)
crystals

CEPA:

96 LaBr₃ &
LaCl₃ crystals

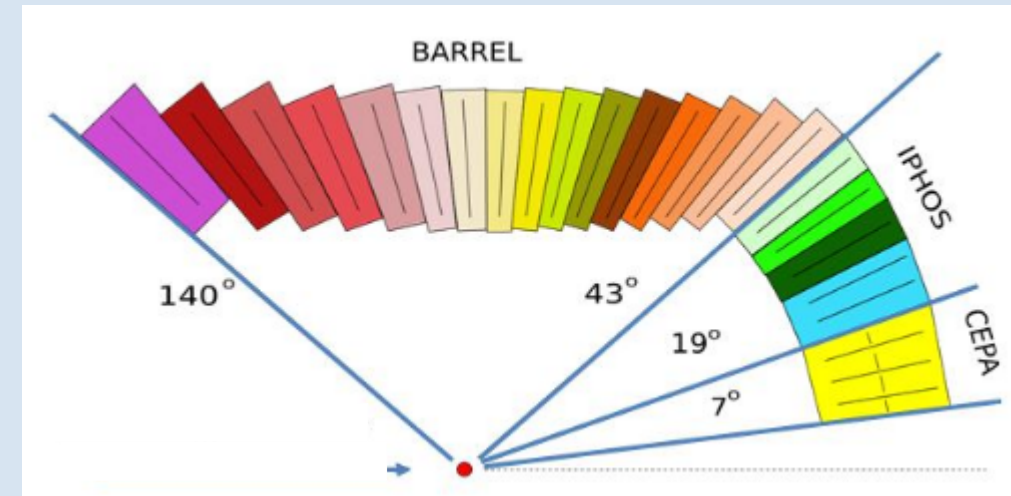
Barrel:

1952 CsI(Tl) scintillator
crystals



Requirements:

- high dynamic range:
100 keV γ -rays – 700 AMeV charged particles
- high efficiency
- high granularity \rightarrow Doppler correction
- particle identification



Over 2500 crystal channels!

Energy

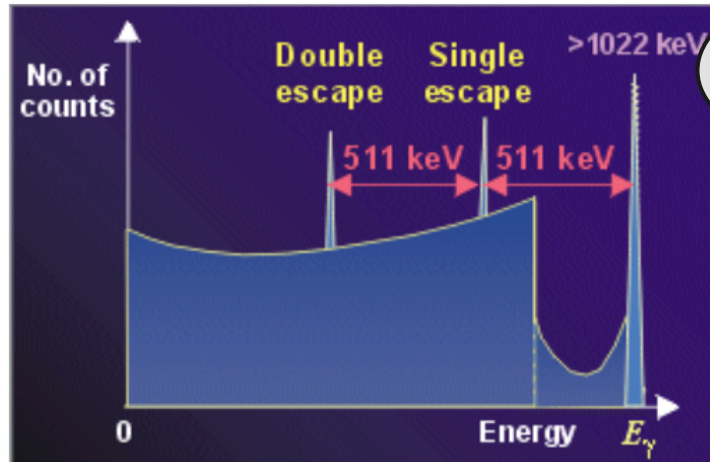
Hit Time

Spatial Position

Correlation with neighboring crystals

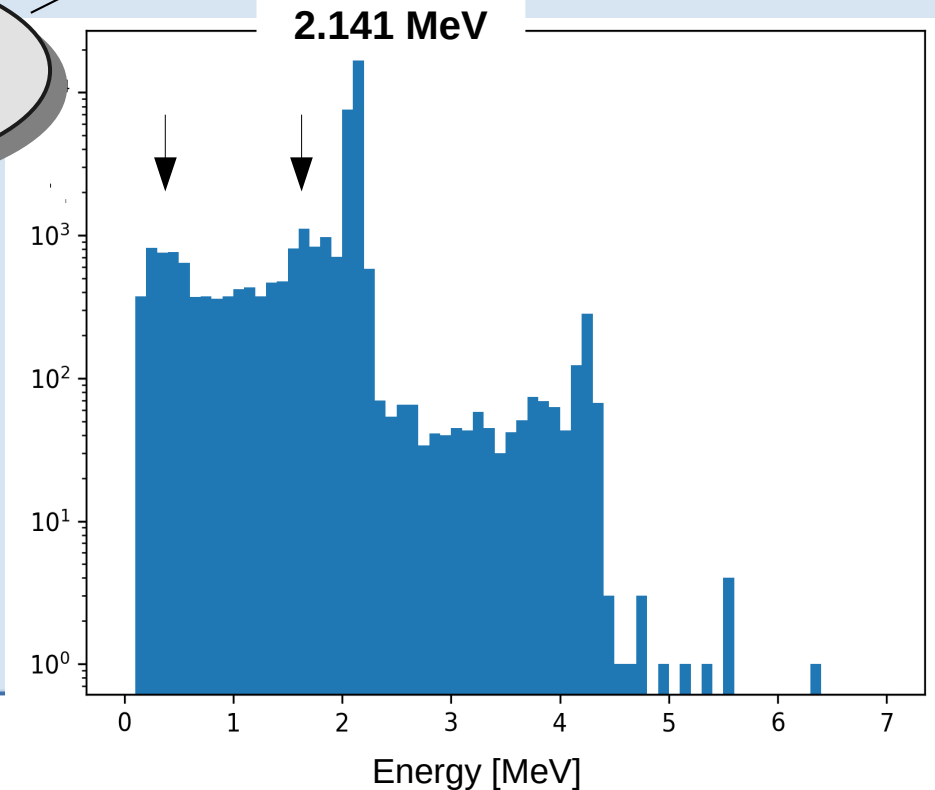
Customized Cluster

In a real detector, if the incident gamma energy is above **1022 keV**, pair production events result in the production of two 511 keV annihilation gamma-rays.

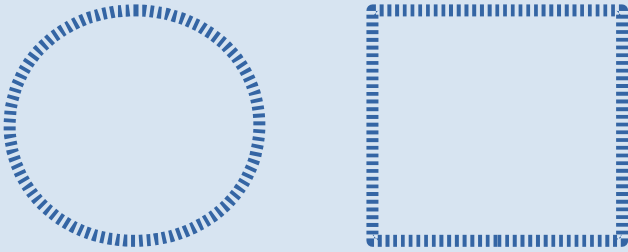


If only one of these gamma-rays escapes while the other is completely absorbed in the detector, 511 keV will be lost from the detector. This results in a separate peak in the spectrum representing $E_\gamma - 511$ keV, called the **single** escape peak.

If both annihilation gamma-rays escape this gives rise to the **double** escape peak at $E_\gamma - 1022$ keV.



User defines shape and size of cluster:

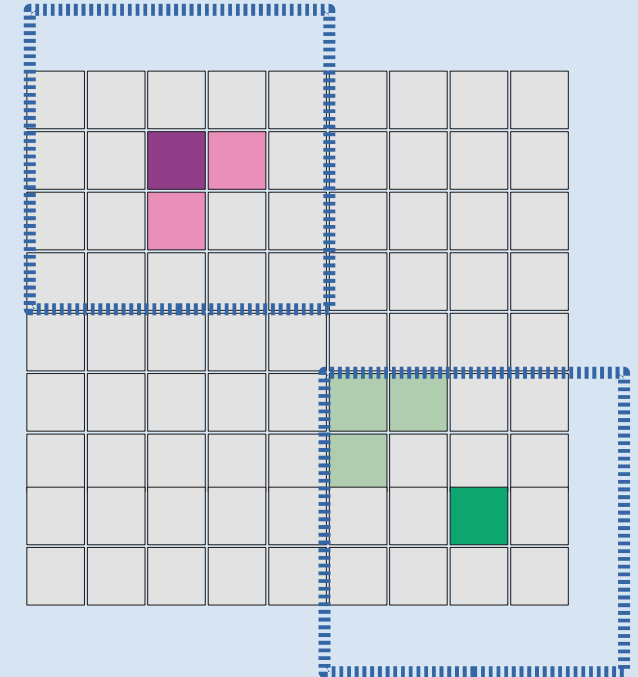


(and set energy threshold for single crystals)

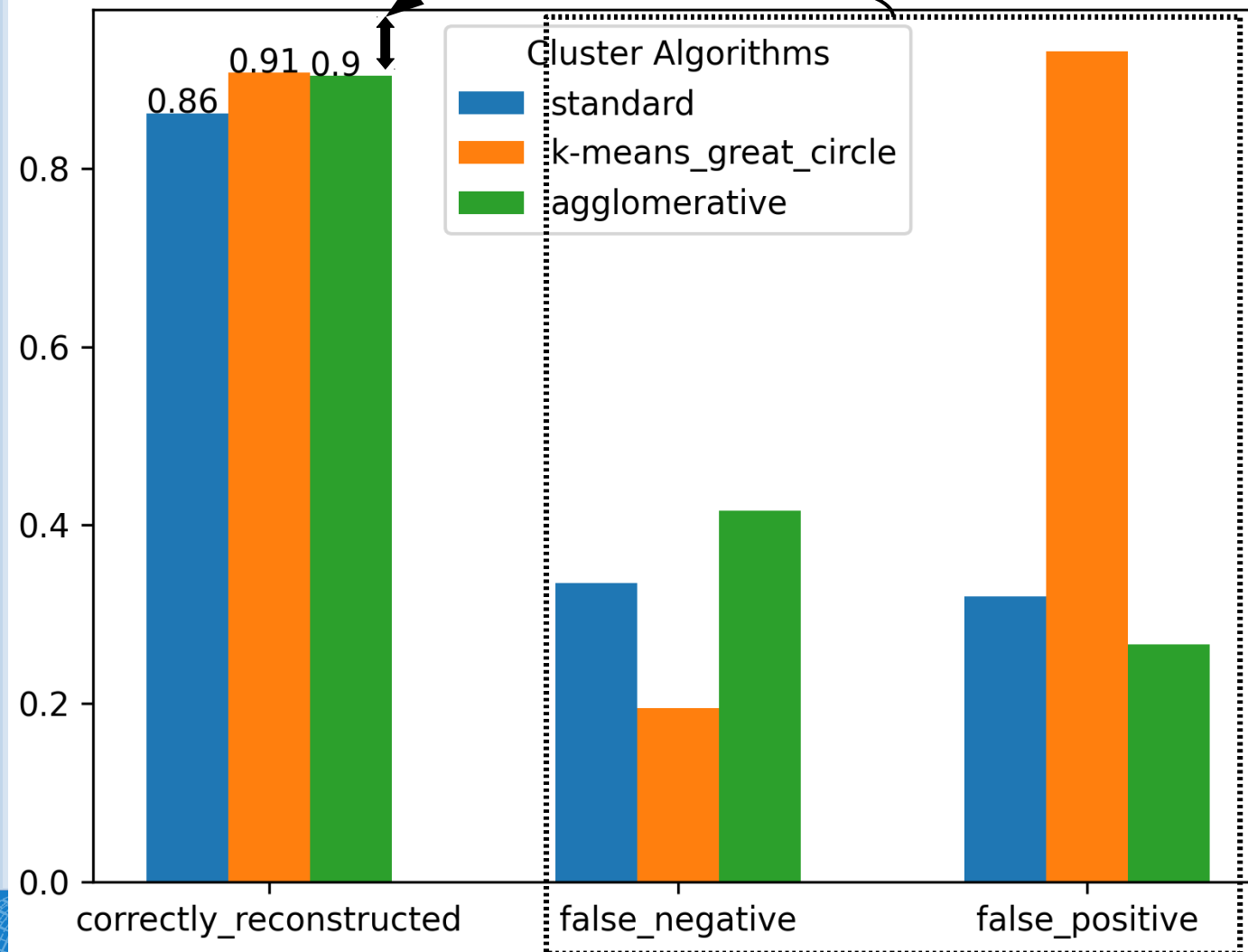
Sort the hit list according to their energy

30. MeV
22. MeV
10. MeV
5. MeV
3. MeV
2.5 MeV
0.7 MeV

1. create cluster centered around first hit
2. loop over all hits in list
→ if hit inside cluster add it and remove it from the list
3. Do this procedure until list is empty



Comparison Clustering Algorithms, E= 2.124 MeV, Mult = 3



false_negative:

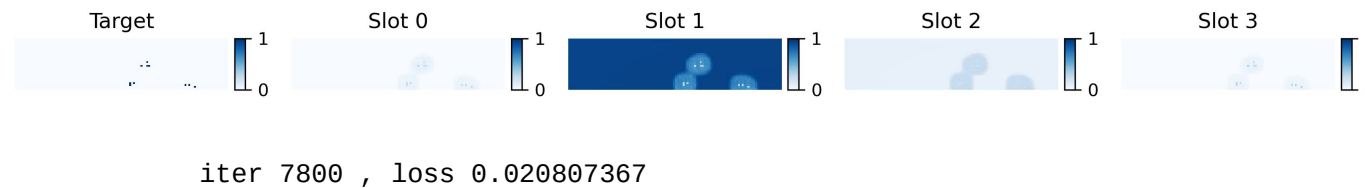
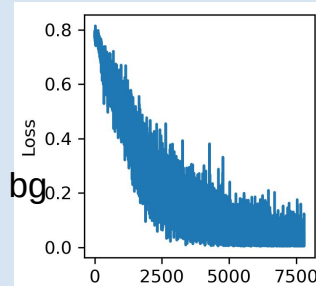
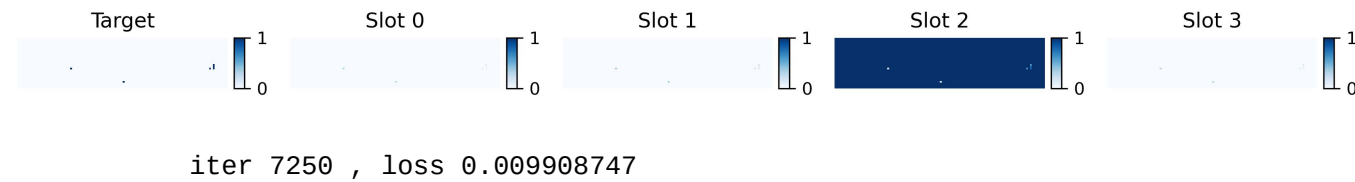
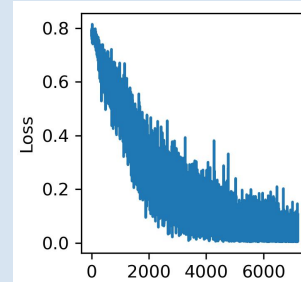
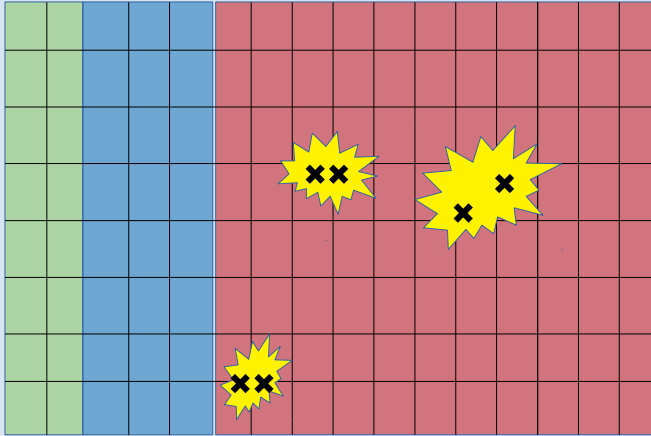
true cluster	reconstructed cluster	
$\begin{pmatrix} 1.2 \\ 0.8 \\ \mathbf{0.124} \end{pmatrix}$	$\begin{pmatrix} 1.2 \\ 0.8 \\ 0.511 \end{pmatrix}$	$\rightarrow \text{false negative} = \frac{0.124}{2.124}$

false_positive:

true cluster	reconstructed cluster	
$\begin{pmatrix} 1.2 \\ 0.8 \\ 0.124 \end{pmatrix}$	$\begin{pmatrix} 1.2 \\ 0.8 \\ \mathbf{0.511} \end{pmatrix}$	$\rightarrow \text{false positive} = \frac{0.511}{2.124}$

Invariant Slot Attention Model

Starting with energy and position information (no time):



```
class InvariantSlotAttention(torch.nn.Module):
    def __init__(self,
        resolution=(27,112),
        xlow=-0.5,
        xhigh=0.5,
        k_slots=4,
        num_conv_layers=3,
        hidden_dim=16,
        final_cnn_relu=False,
        query_dim=32,
        n_iter=2,
        pixel_mult=1,
        device='cpu'
    ):
        ...
```

→ 3 clusters + bg

Parameters I tuned:
Learning rate: 1e-4 to 1e-5
hidden dim: 16 – 32
query_dim: 10 – 16 – 32 - 64

Invariant Slot Attention Model – also with time info

- Dimension of mask: → same as before! $10 \times 3 \times 27 \times 112$
- Dimension of evt_histogram_array : $10 \times \mathbf{2} \times 27 \times 112$

Lr = 5e-5

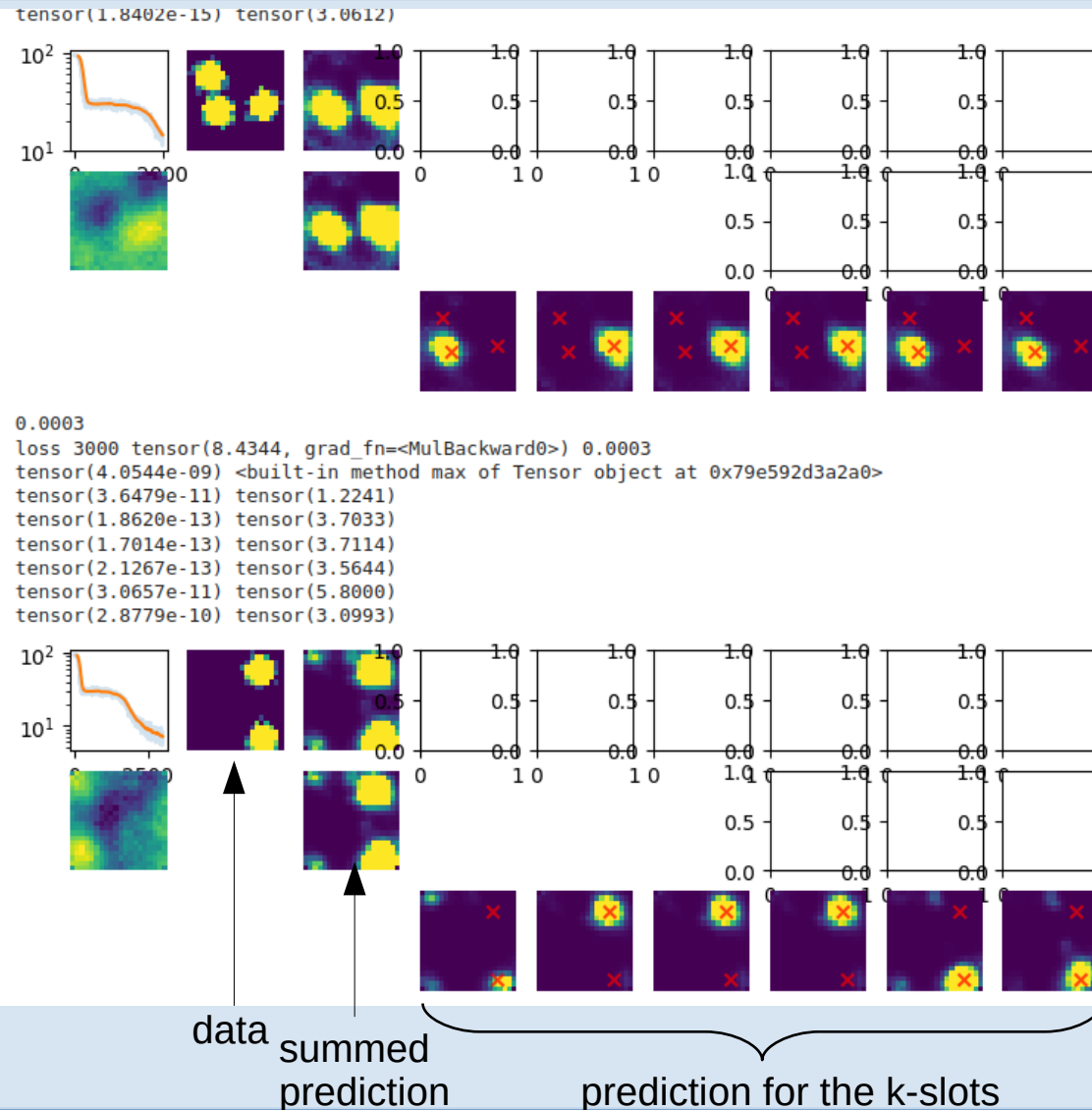
#observables:
time & energy

```
self.gru = torch.nn.GRUCell(self.query_dim, self.query_dim)

kwargs = {'out_channels': hidden_dim, 'kernel_size': 5, 'padding': 2 }
#cnn_layers = [torch.nn.Conv2d(1,**kwargs)] old cnn, with one input channel, energy
cnn_layers = [torch.nn.Conv2d(2,**kwargs)] #now also with time info

for i in range(num_conv_layers-1):
```

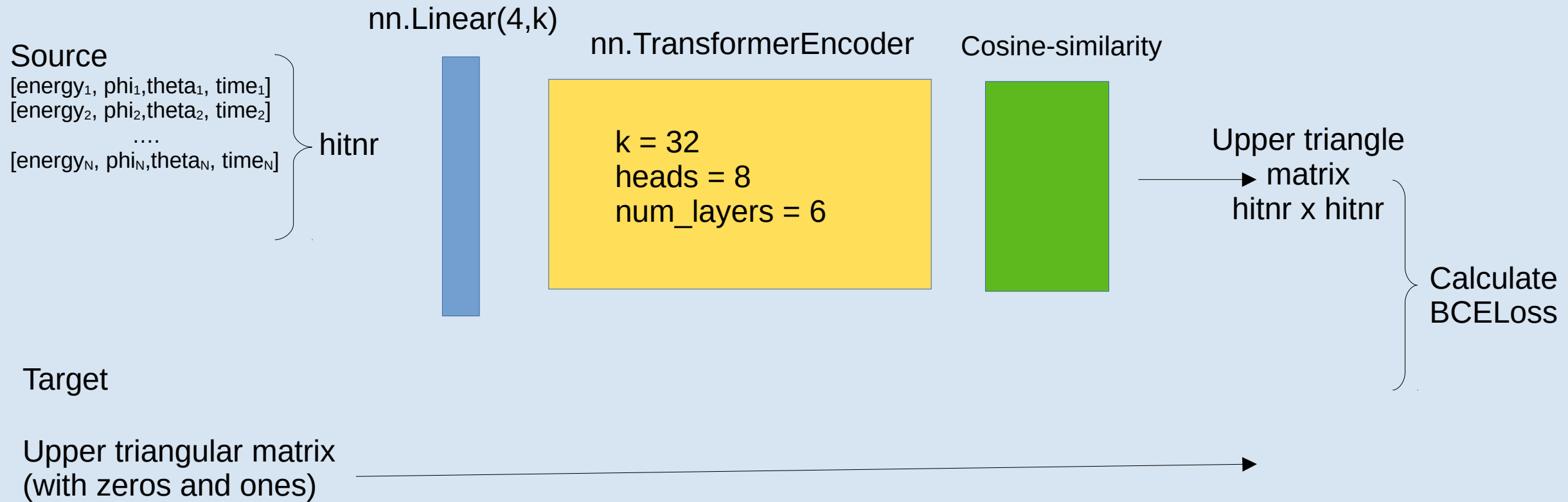
Loss function does not converge!



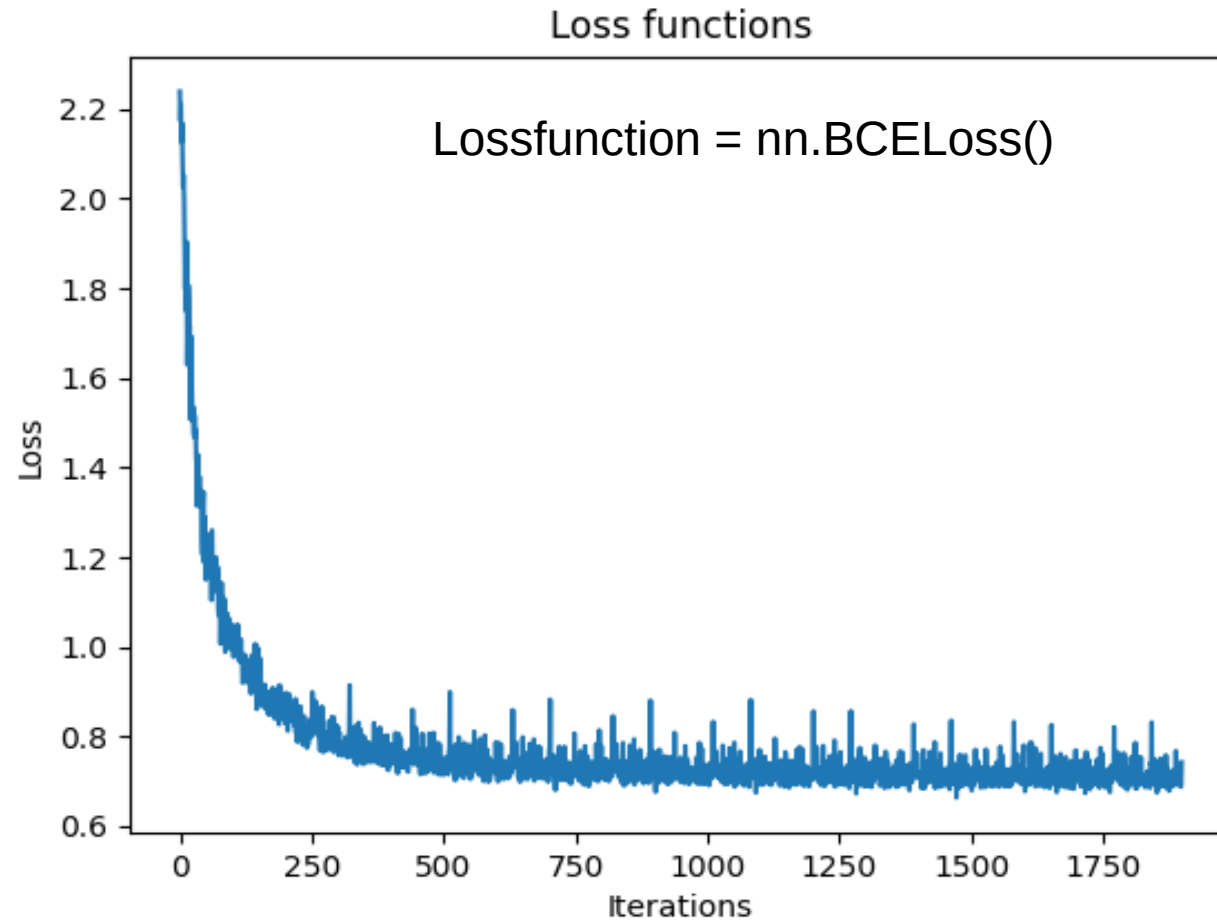
```
class AttModel(torch.nn.Module):
    def __init__(self):
        super().__init__()
        self.latent_dim = 32

        # self.encoder = TSPNEncoder(n_slots = 6)
        # self.encoder = SlotAttentionEncoder(n_slots = 6)
        self.encoder = AddNoiseEncoder(n_slots = 6)
        self.decoder = torch.nn.Sequential(
            torch.nn.Linear(self.latent_dim, 128),
            torch.nn.ReLU(),
            torch.nn.Linear(128, 256),
            torch.nn.ReLU(),
            torch.nn.Linear(256, NBINS*NBINS),
            torch.nn.Unflatten(-1, (NBINS, NBINS))
        )

    def forward(self, data):
        Nbatch, *_ = data.shape
        positions, queries = self.encoder(data)
        decoded = self.decoder(positions).exp()/2.
        reco = decoded.sum(dim = 1)
        return reco, queries, decoded
```

Batchsize = 64
Feature number = 32
n_epochs = 10
Loss_rate = $2e-4$
Loss function = nn.BCELoss()

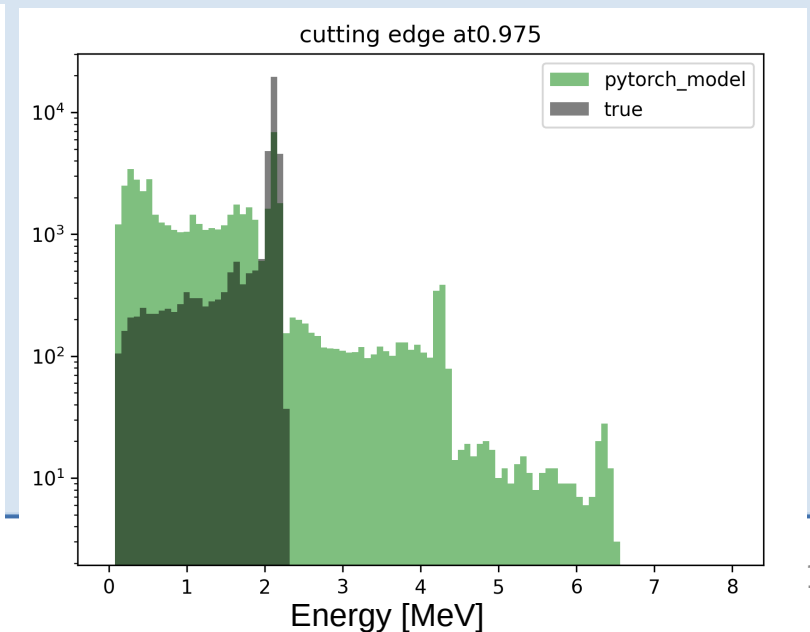
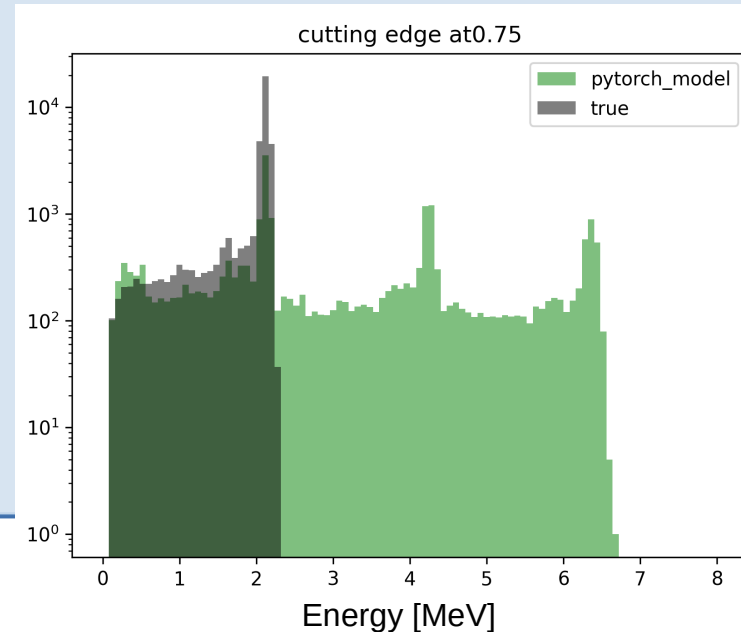
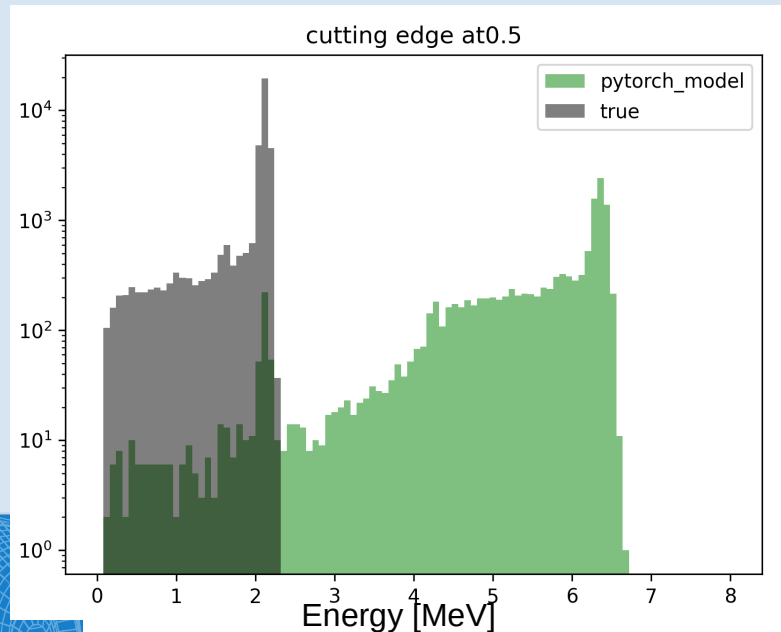
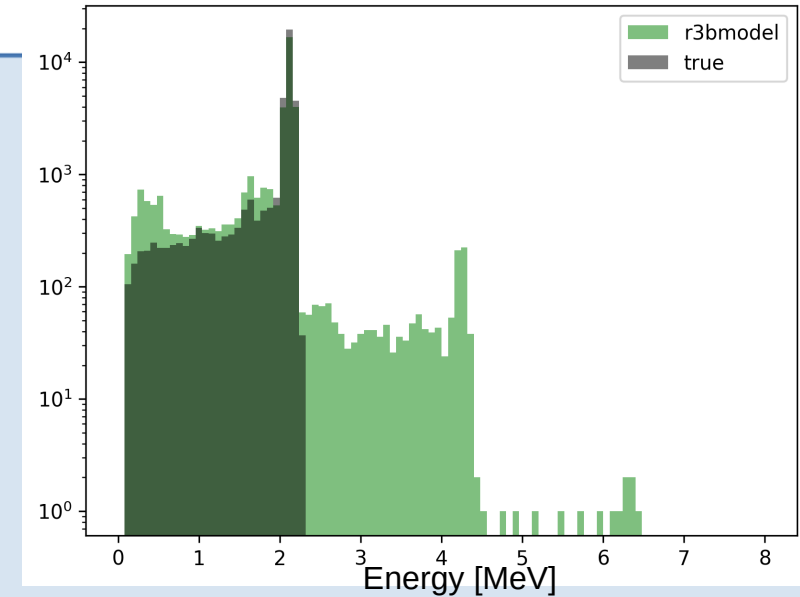


How do the energy spectra look like?

How to clusterize hits from output of transformer model:

- 1) Take the upper triangular matrix $\text{tri}[\text{hitnr} \times \text{hitnr}]$
- 2) set “merge cut”. If $\text{tri}[i,j] > \text{“merge_cut”}$ → hits belong to same cluster
- 3) do this for all combinations and merge them appropriately

Standard Cluster vs True Clusters



Why energy spectra so bad while loss function seems to decrease ?

Most entries in model output tensor ~ 0.5 . This diminishes the loss BCELoss function!

How to improve?

- Include some cut condition in the forward part of the transformer model

```
#out_ret_val = torch.where(ret_val > 0.7, torch.FloatTensor(1,requires_grad=True), torch.FloatTensor(0,requires_grad=True))
```

→ discontinuity of loss function → no learning!

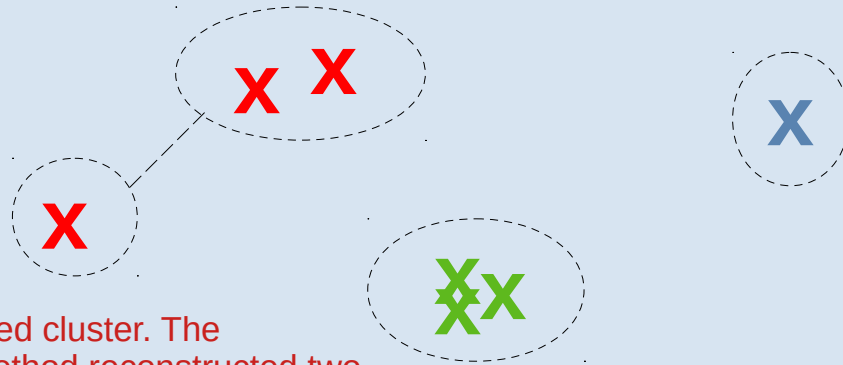
- Use linear net instead of cosine similarity

```
output_tensor = torch.cat([tensor_i.expand(-1, -1, expansion_factor, -1), tensor_j.expand(-1, expansion_factor, -1, -1)], dim=-1)
#small net:
net = nn.Sequential(
    nn.Linear(64,8),
    nn.ReLU(),
    nn.Linear(8,1),
    nn.Sigmoid()
)
res = net(output_tensor)
temp_res = torch.squeeze(res)
upper_tri_mask = torch.triu(torch.ones((temp_res.shape[1],temp_res.shape[1])),diagonal=1).bool() #out[1] is max hit number in batch
result = temp_res[:,upper_tri_mask]
```

No improvements!

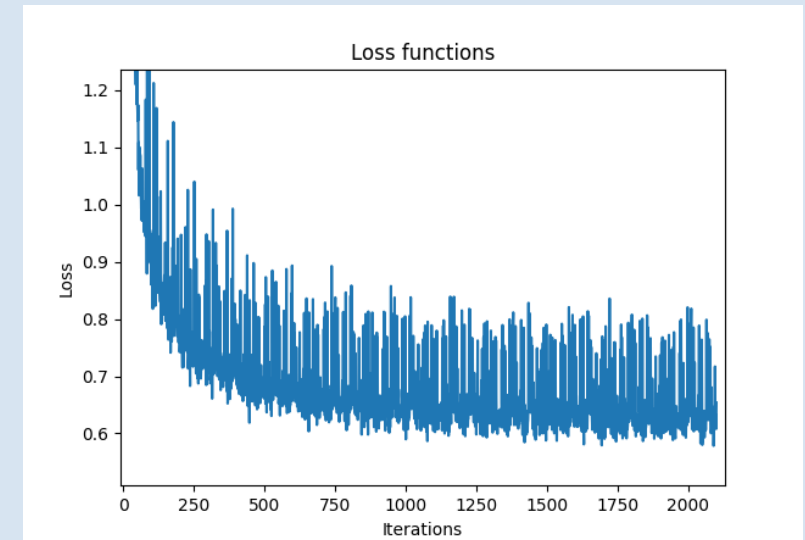
Idea:

1. Use first agglomerative method to cluster
2. Select events where we have too many clusters (false negative)



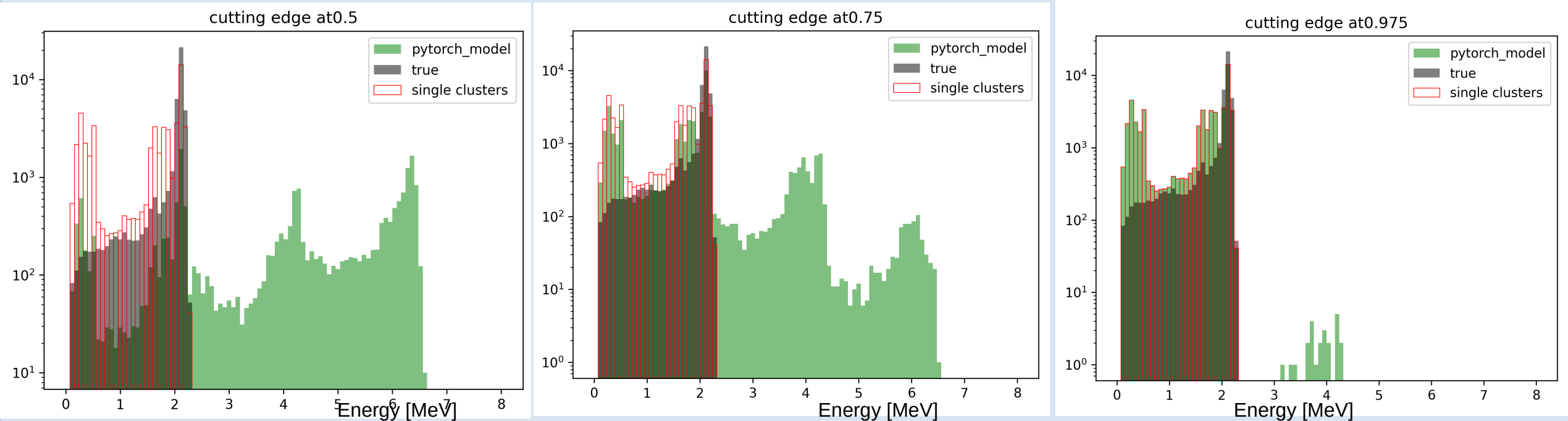
This is one true red cluster. The agglomerative method reconstructed two

3. Feed the clusters to the transformer model (calculating cm of clusters)



Transformer Model

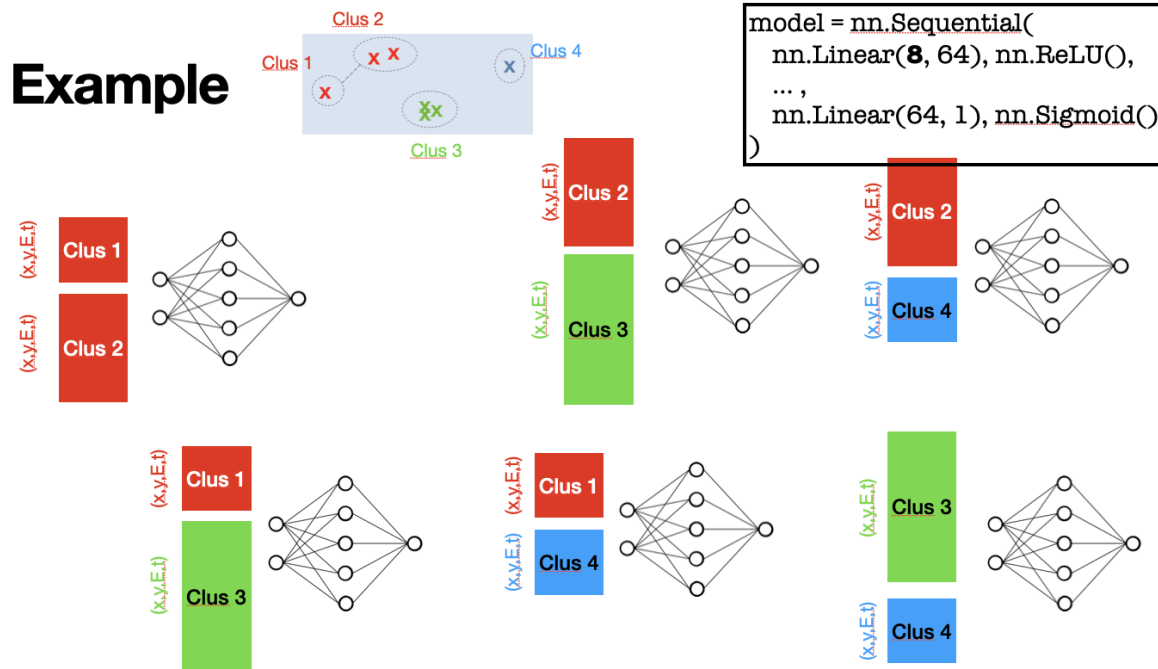
Reconstruction with transformer model (after application of agglomerative model)



Cutting edge: model give output in range $[0,1]$. Cutting edge is threshold:
 If cutting edge $>$ pairwise cluster output \rightarrow clusters do not belong together
 If cutting edge $<$ pairwise cluster output \rightarrow clusters belong together

No improvement in reconstruction,
 High cutting edge \rightarrow = single clusters
 Low cutting edge \rightarrow too many clusters are merged

Example



Since transformer method not successful, start with basic model:

Def init :

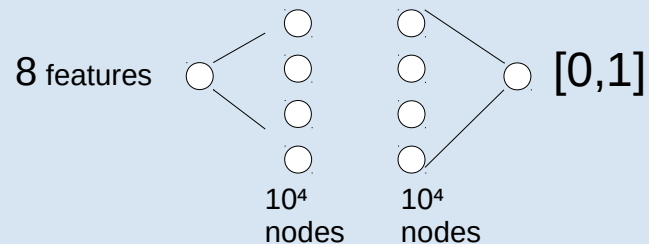
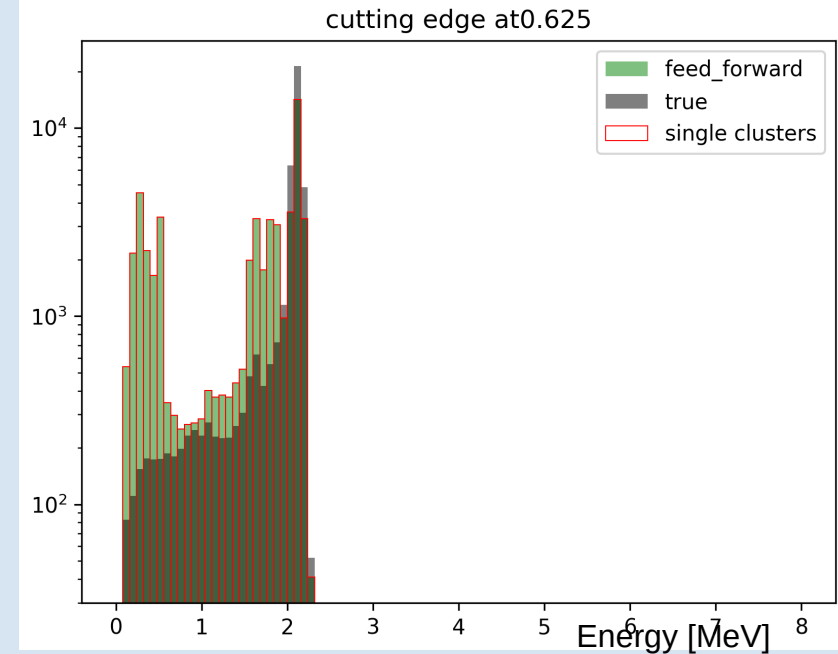
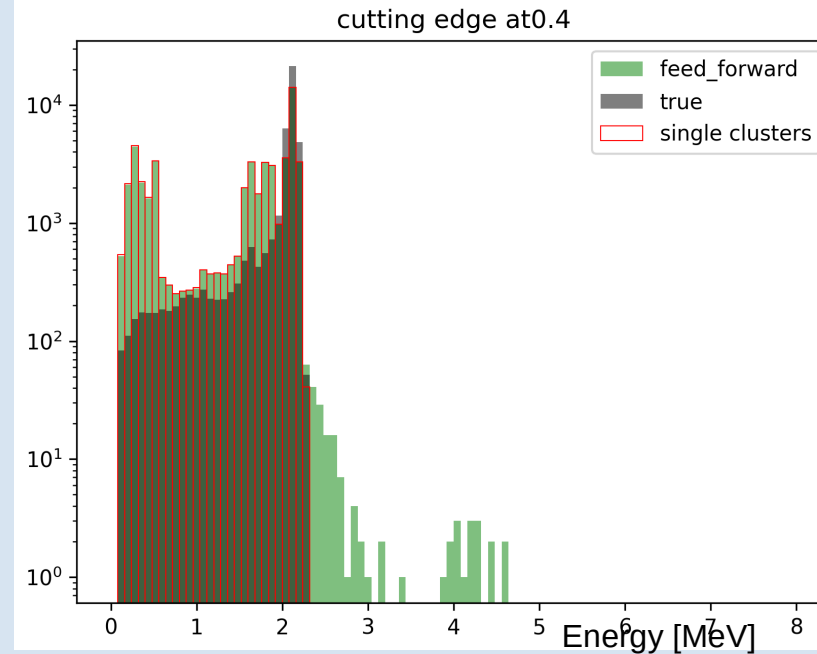
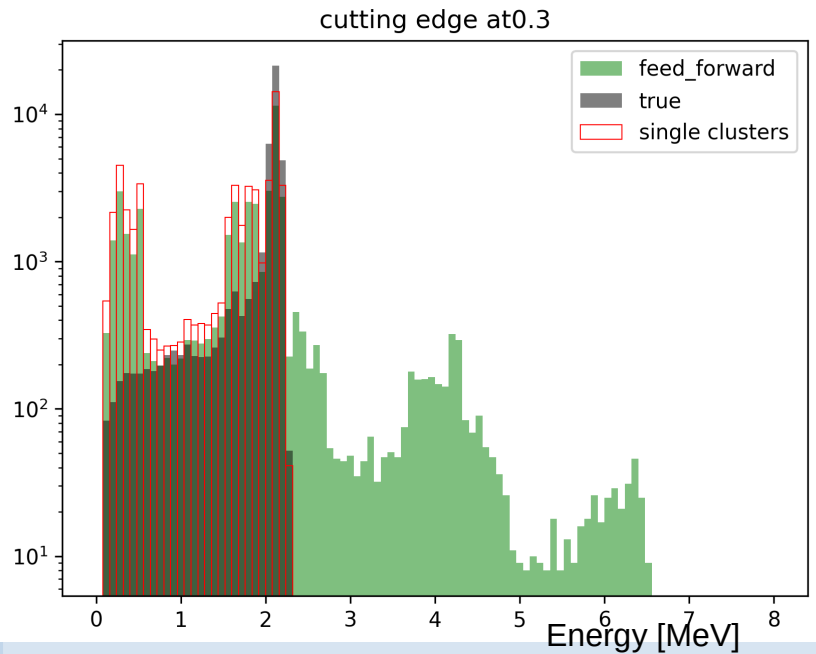
```
self.linear = torch.nn.Linear(8,64)
self.activation = torch.nn.ReLU()
self.linear_back = torch.nn.Linear(64,1)
```

....

Def forward:

```
output_tensor = self.linear(output_tensor)
output_tensor = self.activation(output_tensor)
output_tensor = self.linear_back(output_tensor)
output_tensor = torch.sigmoid(output_tensor)
output_tensor = torch.squeeze(output_tensor)
```

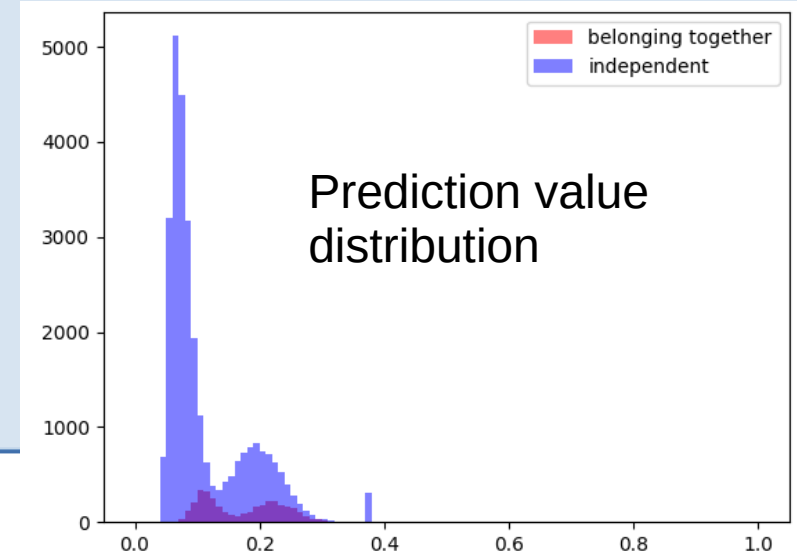
Reconstruction with feed forward (after application of agglomerative model)



0: indep. hits
1: belonging together

Same as in transformer model. However cutting edge has to be set really low...

No improvement in reconstruction!





Thank you!

CALIFA @ Technical University of Munich (TUM)

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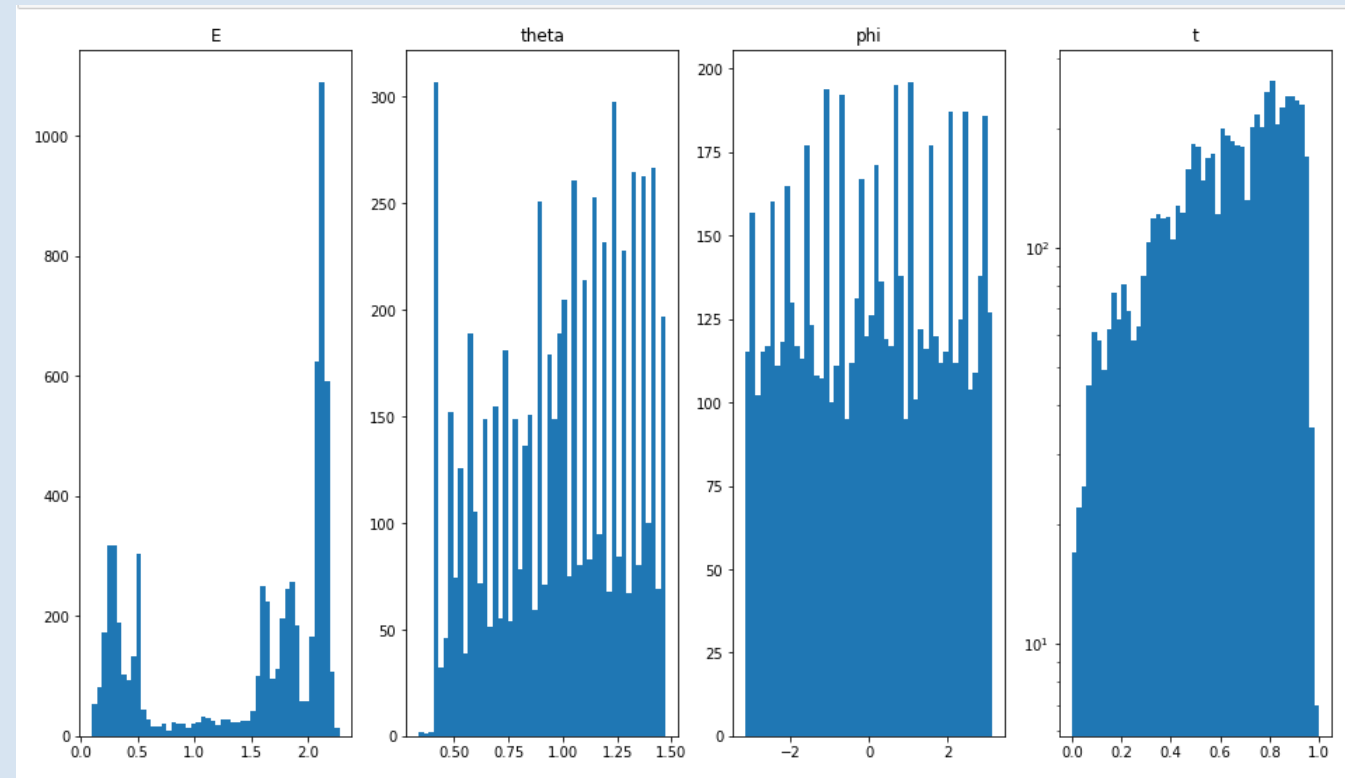
Backup

We applied agglomerative cluster
What you see here is already clustered data
BUT all events where you have too many clusters

Agglomerative clustering has also
drawbacks:

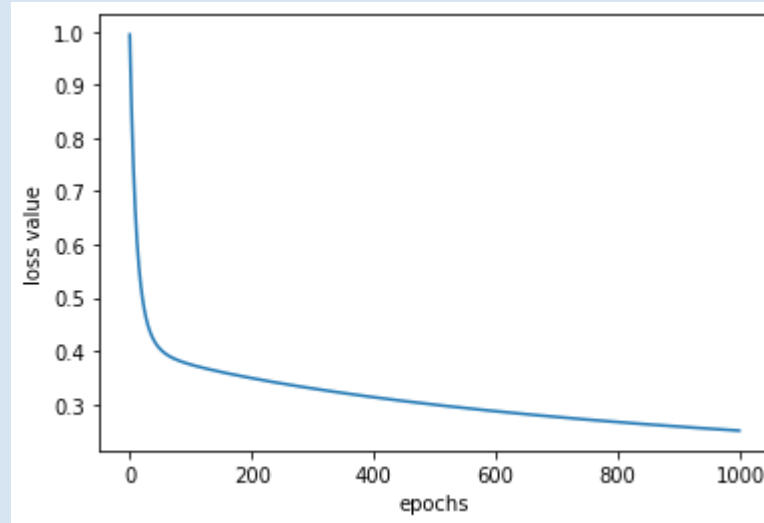
Clustering is done using E,theta,phi,time
where the time is taken as radius

- time starts from 0 up to...
- for time ~ 0 everything is clustered together!

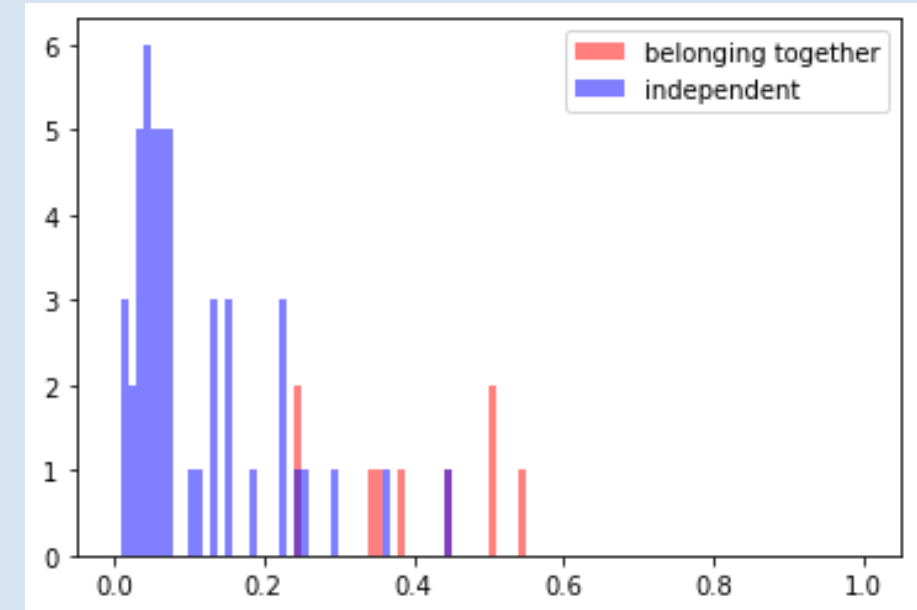


[0.	1.128016	0.913283	-2.69977	0.27121927]
[1.	0.952915	0.519144	0.878809	0.95261156]
[1.	0.434082	0.56767	-2.311936	0.93668561]
[2.	2.209619	1.105468	2.333682	0.52416023]
[3.	1.71197	1.189179	1.119164	0.78435412]
[3.	0.461599	0.777167	-0.144536	0.75403444]
[4.	2.029792	1.287946	1.30295	0.]
[5.	0.756178	1.33176	-2.309371	0.68407621]
[6.	2.1872	0.476108	2.85122	0.8842718]
[7.	1.921325	1.287711	-2.407052	1.]
[7.	0.24677	0.972258	1.512456	0.95922116]
[8.	2.12424	1.190137	0.532672	0.63181968]
[9.	2.165567	0.780356	1.333373	0.52338727]
[10.	1.927867	0.979187	-1.390222	0.83159162]
[10.	0.155214	1.058012	-2.217043	0.81032574]
[11.	2.17151	0.581699	-0.050691	0.75626808]
[12.	2.145626	0.444849	1.000789	0.69102447]
[13.	2.124236	0.907799	1.22338	0.93919196]
[14.	1.594131	0.931724	-0.470997	0.35572331]
[14.	0.518059	0.958237	1.420141	0.31123073]
[15.	1.55693	0.851083	-1.916148	0.3734817]
[15.	0.206072	1.377727	0.637334	0.43616126]
[16.	1.702479	1.014433	2.493843	0.51384286]
[17.	1.654359	1.057384	1.224166	0.95706616]
[18.	1.647063	1.212656	-0.142311	0.9388571]
[18.	0.479129	1.147077	2.998456	0.88034231]
[19.	0.887473	0.777098	-2.89615	0.68520254]
[20.	2.10968	0.773892	1.628614	0.85522686]
[21.	1.16823	1.331397	-1.120366	0.96468413]
[21.	0.287956	1.237488	-2.217654	0.97093477]
[22.	2.154496	0.828804	-0.161298	0.79557305]
[23.	1.302665	0.712428	-0.693234	0.61380342]
[24.	1.599256	0.952238	-2.448033	0.93131397]
[24.	0.505705	1.100893	-2.893951	0.92312015]
[25.	2.141112	0.839635	0.501495	0.51226942]
[26.	2.075262	1.398027	1.62944	0.71680964]
[27.	2.107771	1.101413	-2.803576	0.52078744]
[28.	2.133439	1.160672	0.212617	0.49220052]
[29.	0.432454	1.237877	-2.503905	0.94673509]

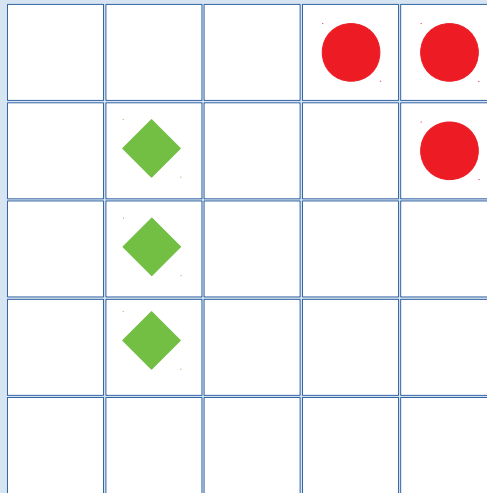
Lr = 9e-4
torch.nn.Linear(8,1000)



Prediction value distribution



→ i,i+1,i+2 belong together, in sets of 3



Small grid (10x10)
Two (true clusters), with sparse data
Gaussian energy distribution of cluster hits

With machine learning tools we should get at least as good as with the standard clustering (even without considering time information)!