

Circuits and Systems 2CJ4

Lab 2

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Set 2 Laboratory Experiment

- I. From the background section, explain why we increase or decrease $v_{in}(t)$ such that $V_{th2} < V_{in}(t) < V_{th1}$ the output remains the same.

The output remains unchanged irrespective of whether V_{in} is increased or decreased, because of the V_{gap} otherwise known as the hysteresis gap. V_{gap} is defined as $V_{th1}-V_{th2}$ when $V_{in}(t) < V_{th2}$ or $V_{in}(t) > V_{th1}$ (not corresponding to the stated case in the question). When the output switches from either the positive or negative saturated state, it reinforces the state which makes it less sensitive to small fluctuations in the V_{in} . When V_{gap} exceeds the peak-to-peak amplitude of the noise, the output remains unaffected, demonstrating effective noise immunity.

- II. Given the circuit from Figure 2 in the example section, fill in the following table using $V_{ref} = 0V, 2V, R_1 = 4.7 \text{ k}\Omega, 22 \text{ k}\Omega$ and $R_2 = 4.7 \text{ k}\Omega$ (assuming $V_{sat+} = 5V$ and $V_{sat-} = -5V$). Include one sample calculation for any row.

| V_{ref}, R_1, R_2 | V_{th1} (theoretical) | V_{th2} (theoretical) | V_{gap} (theoretical) |
|----------------------|-------------------------|-------------------------|-------------------------|
| (0V, 4.7 kΩ, 4.7 kΩ) | 2.5 | -2.5 | 5 |
| (0V, 22 kΩ, 4.7 kΩ) | 0.88 | -0.88 | 1.76 |
| (2V, 4.7 kΩ, 4.7 kΩ) | 3.5 | -1.5 | 5 |
| (2V, 22 kΩ, 4.7 kΩ) | 2.528 | 0.7677 | 1.76 |

Table 1: Theoretical Values for V_{th1} , V_{th2} , V_{gap}

Sample Calculations:

For 0V, 4.7kΩ, 4.7kΩ

Calculation for V_{th1}

$$V_{th1} = V_{sat+} \left(R_2 / (R_1 + R_2) \right) + \left(V_{ref} R_2 / (R_1 + R_2) \right)$$

$$V_{th1} = 5 \left(4.7 / (4.7 + 4.7) \right) + (0V \times 4.7 / (4.7 + 4.7))$$

$$V_{th1} = 2.5 + 0$$

$$V_{th1} = 2.5V$$

Calculation for V_{th2}

$$V_{th2} = V_{sat-} \left(R_2 / (R_1 + R_2) \right) + \left(V_{ref} R_2 / (R_1 + R_2) \right)$$

$$V_{th2} = -5 \left(4.7 / (4.7 + 4.7) \right) + (0V \times 4.7 / (4.7 + 4.7))$$

$$V_{th2} = -2.5 + 0$$

$$V_{th2} = -2.5V$$

Calculation for V_{gap}

$$V_{gap} = V_{th1} - V_{th2}$$

$$V_{gap} = 2.5 - (-2.5)$$

$$V_{gap} = 5V$$

Figure 1: Sample Calculations for 0V, 4.7kΩ, 4.7kΩ

- III. Measure the actual V_{th1}, V_{th2}, and V_{gap} by building the circuits with v_i(t) being a sine wave, square wave, or a triangular wave of amplitude 5V with a 0V offset and filling in the values in the following table. Include the resulting waveforms as well as circuits.
(Hint: you will need to analyze the circuit if V_{ref} is a value that is not zero)

| Vref, R1,R2 | Vth1 (measured) | Vth2 (measured) | Vgap (measured) |
|---------------------|-----------------|-----------------|-----------------|
| (0V,4.7 kΩ, 4.7 kΩ) | 2.0676 | -2.50328 | 4.57 |
| (0V, 22 kΩ, 4.7 kΩ) | 0.969305 | -1.24733 | 2.216 |
| (2V,4.7 kΩ, 4.7 kΩ) | 3.52911 | -2.076696 | 5.605 |
| (2V, 22 kΩ, 4.7 kΩ) | 2.2857 | -0.5886 | 2.8743 |

Table 2: Measured Values for Vth1, Vth2, Vgap

Vref = 0V, R1 = 4.7KΩ and R2 4.7KΩ.

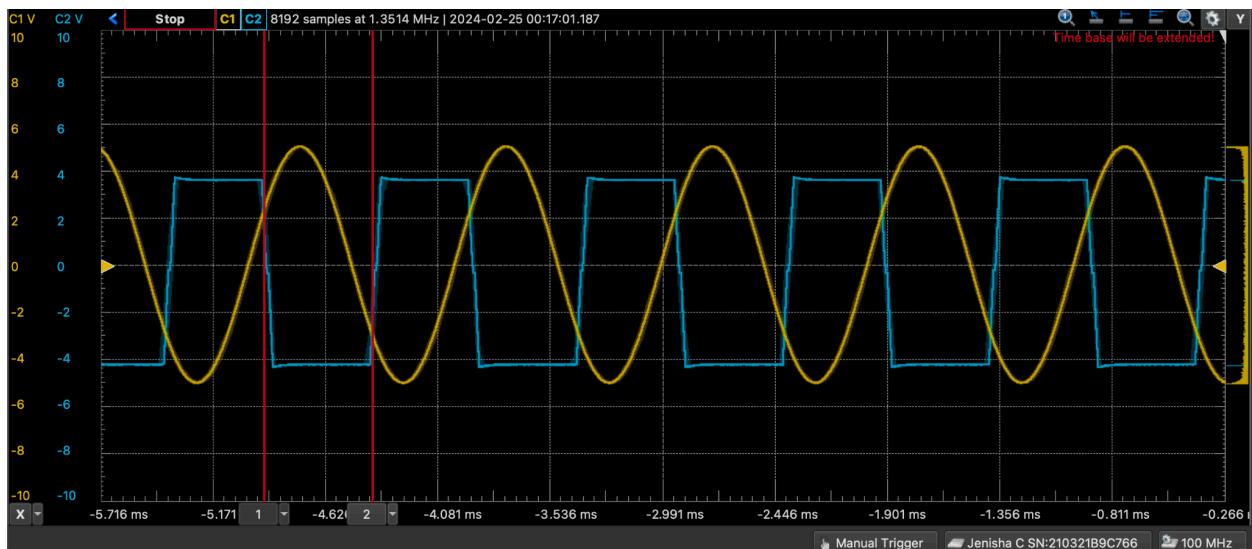


Figure 2: Waveform for Vref = 0V, R1 = 4.7K and R2 4.7K.

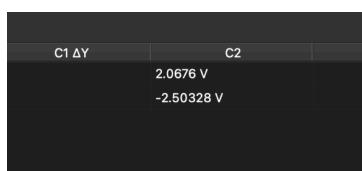


Figure 3: Cursor values for Vref = 0V, R1 = 4.7K and R2 4.7K.

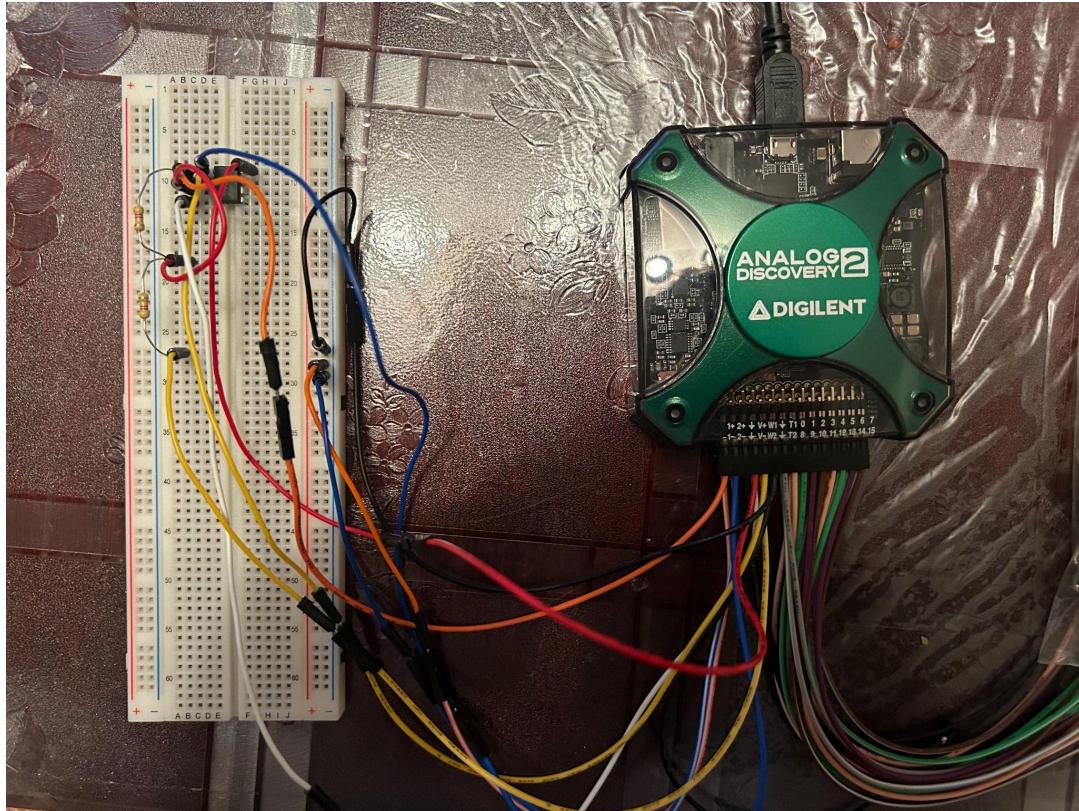


Figure 4: Circuit Configuration for $V_{ref} = 0V$, $R1 = 4.7K$ and $R2 4.7K$.

$V_{ref} = 0V$, $R1 = 22K\Omega$ and $R2 4.7K\Omega$.

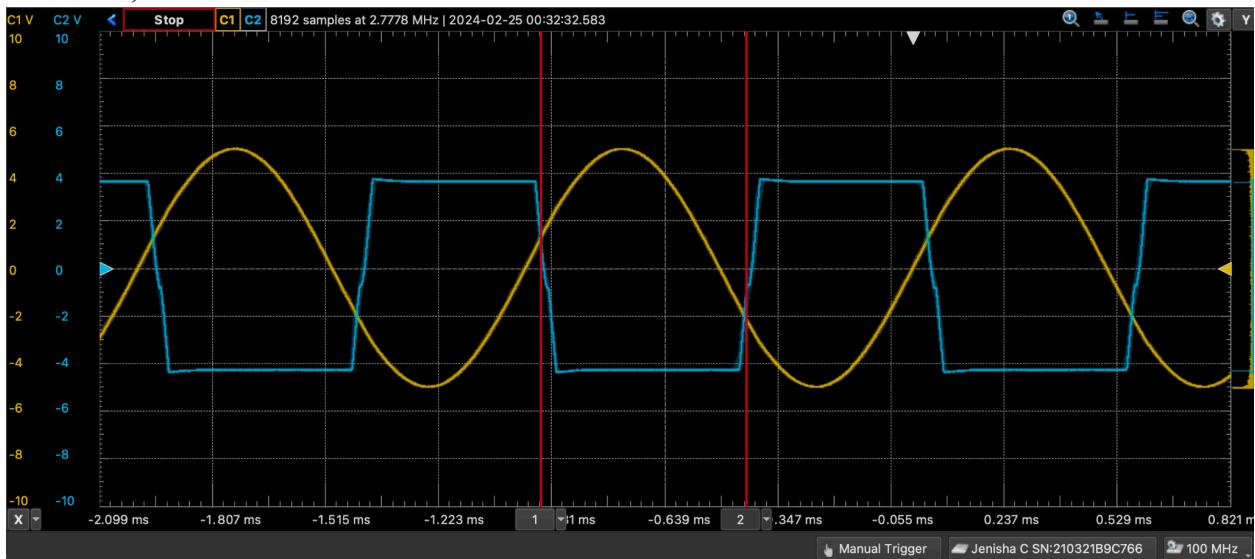


Figure 5: Waveform for $V_{ref} = 0V$, $R1 = 22K$ and $R2 4.7K$.



Figure 6: Cursor values for $V_{ref} = 0V$, $R1 = 22K$ and $R2 = 4.7K$.

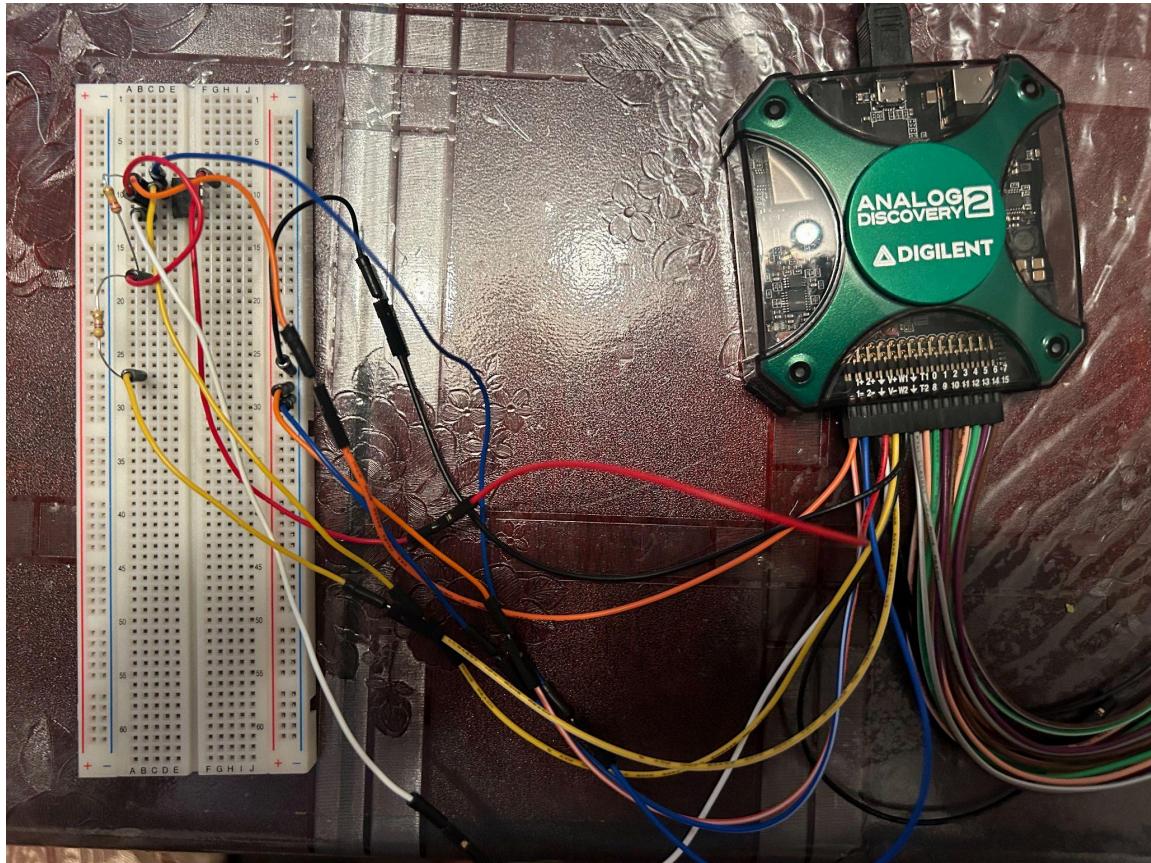


Figure 7: Circuit Configuration for $V_{ref} = 0V$, $R1 = 22K$ and $R2 = 4.7K$.

$V_{ref} = 2V$, $R1 = 4.7K\Omega$ and $R2 4.7K\Omega$.

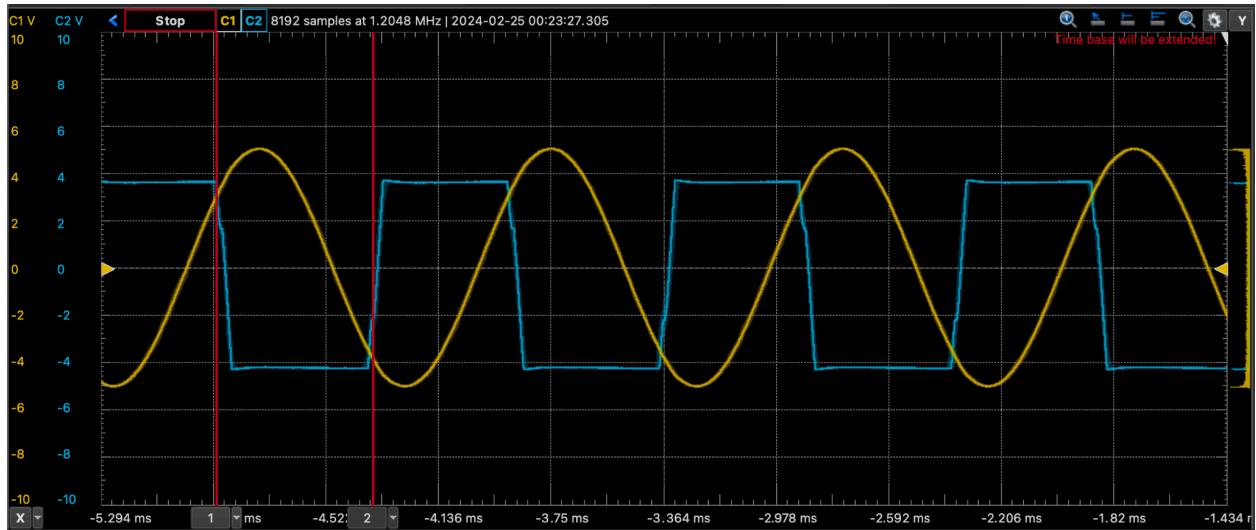


Figure 8: Waveform for $V_{ref} = 2V$, $R1 = 4.7K$ and $R2 4.7K$.

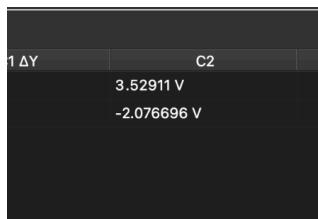


Figure 9: Cursor values for $V_{ref} = 2V$, $R1 = 4.7K$ and $R2 4.7K$.

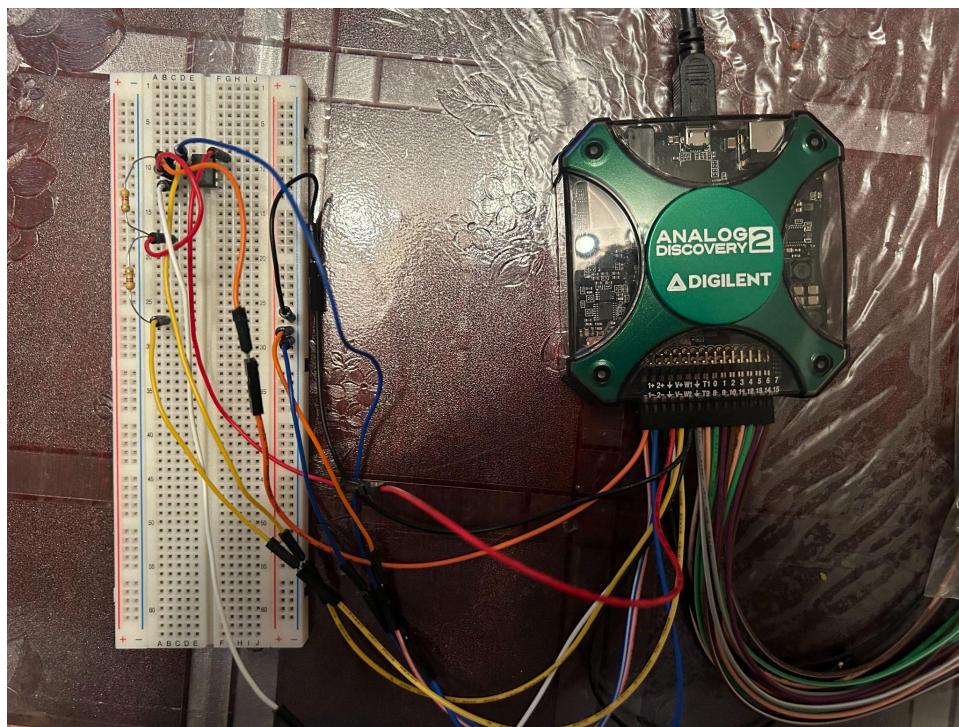


Figure 10: Circuit Configuration for $V_{ref} = 2V$, $R1 = 4.7K$ and $R2 4.7K$.

Vref = 2V, R1 = 22KΩ and R2 4.7KΩ.

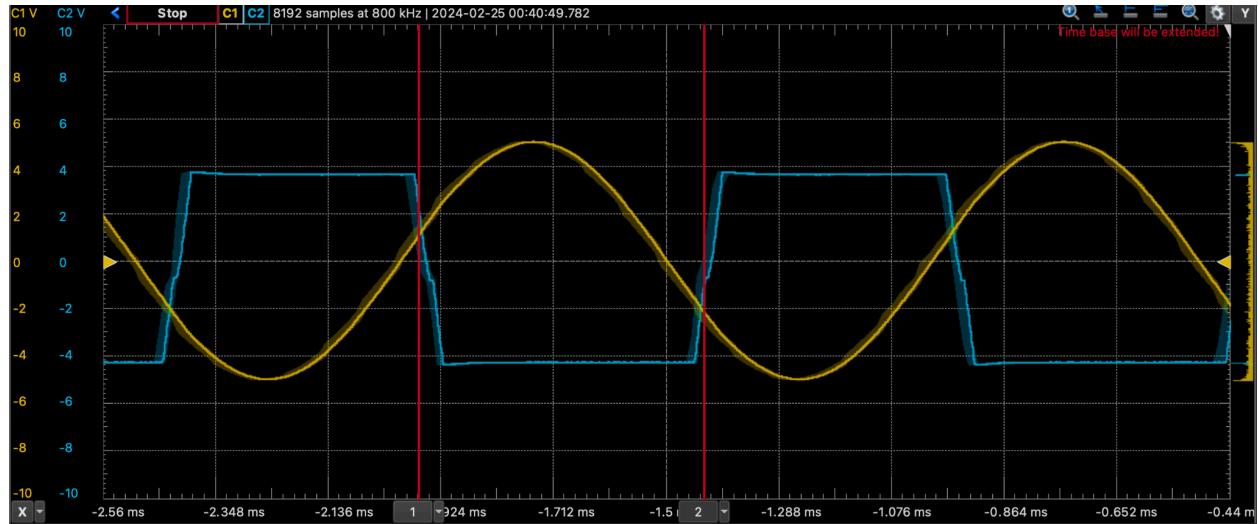


Figure 11: Waveform for $V_{ref} = 2V$, $R1 = 22K$ and $R2 4.7K$.

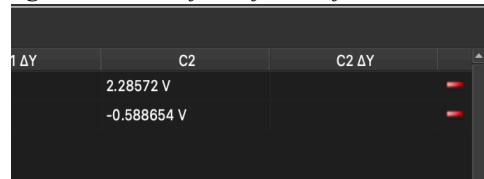


Figure 12: Cursor values for $V_{ref} = 2V$, $R1 = 22K$ and $R2 4.7K$.

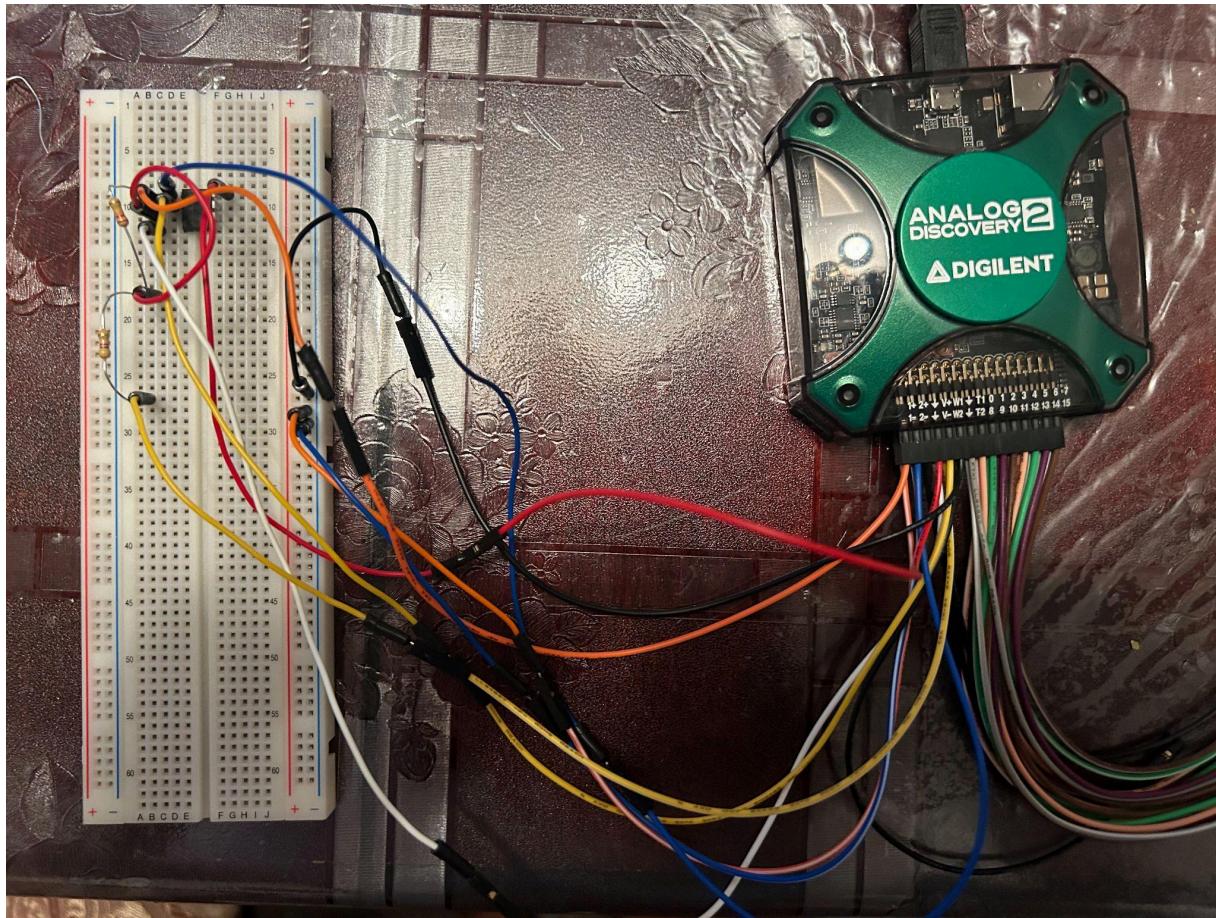


Figure 13: Circuit Configuration for $V_{ref} = 2V$, $R_1 = 22K$ and $R_2 4.7K$.

IV. What is the percentage difference between the calculated and measured voltages?

| V_{ref} , R_1, R_2 | Percent Difference (Theoretical vs Measured V_{th1}) | Percent Difference (Theoretical vs Measured V_{th2}) | Percent Difference (Theoretical vs Measured V_{gap}) |
|------------------------|---|---|---|
| (0V, 4.7 kΩ, 4.7 kΩ) | 18.9334% | 0.128637% | 8.98642% |
| (0V, 22 kΩ, 4.7 kΩ) | 9.65822% | 34.5344% | 22.9376% |
| (2V, 4.7 kΩ, 4.7 kΩ) | 0.82827% | 32.2474% | 11.4097% |
| (2V, 22 kΩ, 4.7 kΩ) | 10.0671% | 26.41% | 47.9482% |

Table 3: Percent Difference Values for V_{th1} , V_{th2} , V_{gap}

As seen in Table 3, there is a discrepancy between the calculated and measured values. Multiple factors can lead to significant percentage errors between AD2 waveform simulations, theoretical calculations, and physical experiments. These discrepancies can stem from the internal resistance of the breadboard, loose wiring to the breadboard, and constraints of our measuring equipment. Factors such as background interference, complex behaviors, unintended electrical connections, and errors in the sampling process may contribute to additional inaccuracies. It is crucial to comprehend and tackle these elements to make sense of and reduce errors observed in experimental data. Another major contributor to the discrepancy of values is the internal tolerance of circuit components, where variations in their values can affect overall precision, such as the resistors. Inaccuracies in op-amp properties, such as input offset voltage and gain, also play a role in impacting precision.

V . What do you notice about the hysteresis gap V_{gap} if we change V_{ref} from zero to some non-zero value?

By adjusting V_{ref} from zero to a non-zero value, the measurements indicated that the V_{gap} values remained consistent from both the measured values for the AD2 and the theoretical values. The hysteresis gap (V_{gap}) remains unchanged during the transition of V_{ref} from zero to a non-zero value. As illustrated in Table 1, where identical calculations were conducted with the same resistance and V_{sat} values but a non-zero V_{ref} , the V_{gap} value exhibited no variation. The hysteresis gap is primarily determined by the differential between the upper and lower threshold voltages which are independent of the reference voltage. As a result, regardless of the value of V_{ref} , as long as it lies between the positive and negative saturation voltages, the hysteresis gap is constant.