

Measurement Incompatibility, Quantum Steering, and High-dimensional Generalisations

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Overview

- 1 Measurement Incompatibility
- 2 Quantum Steering
- 3 Channel-state duality and the Heisenberg picture
- 4 Our Contribution
- 5 Conclusions and Future work

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Two observables A and B are simultaneously measurable if they have a common eigenbasis.

This occurs if and only if they commute:

$$[A, B] = AB - BA = 0. \quad (2)$$

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Definition

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- $M_a \geq 0 \quad \forall a$
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- Doesn't say anything about post-measured state.

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Sets of POVMs

We denote a collection of POVMs as

$$\{M_{a|x}\}_{a,x} \equiv M_{a|x} \quad : \quad M_{a|x} \geq 0 \quad \forall a, x, \quad \sum_a M_{a|x} = \mathbb{1} \quad \forall x$$

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Example

Z	X	
$M_{+1 0} = 0\rangle\langle 0 $	$M_{+1 1} = +\rangle\langle + $	(3)
$M_{-1 0} = 1\rangle\langle 1 $	$M_{-1 1} = -\rangle\langle - $	(4)

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A set of n POVMs $M_{a|x}$ is *jointly-measurable* or *compatible* if there exists a POVM $G_{\mathbf{a}} = G_{a_1 \dots a_n}$ such that

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This is also equivalent to there existing Naimark dilations in which the projective measurements commute.

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$M_{a|x}$ is *compatible* if \exists POVM G_{λ} and probabilities $p(a|x, \lambda)$ s.t.

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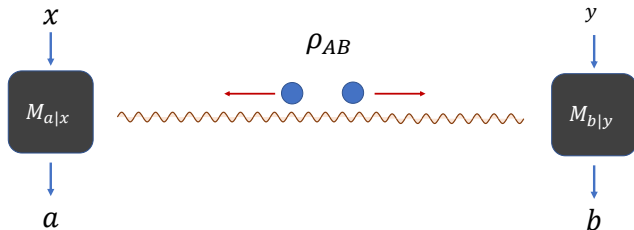
$$M_{a|x} = \sum_{\lambda} p(a|x, \lambda) G_{\lambda}$$

\Rightarrow : Take $\lambda = \mathbf{a}$, $p(a|x, \mathbf{a}) = \delta_{a, a_x}$

\Leftarrow : Define $G_{a_1, \dots, a_n} = \sum_{\lambda} \prod_x p(a_x|x, \lambda) G_{\lambda}$

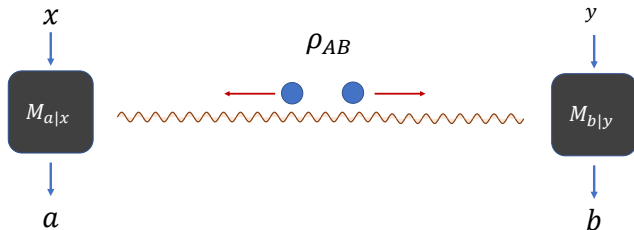
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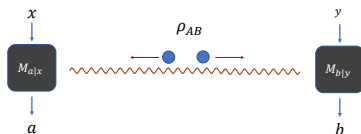


The resulting data is

$$p(a, b|x, y) = \text{Tr}\left(M_{a|x} \otimes M_{b|y} \rho_{AB}\right)$$

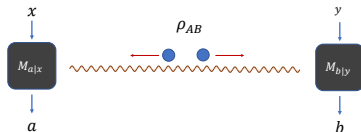
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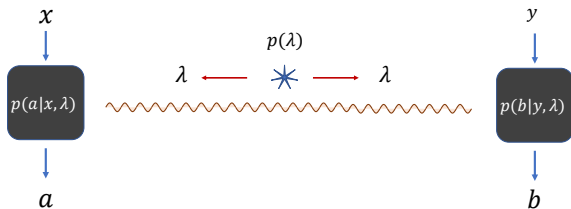
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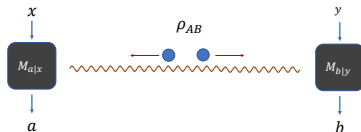
This data has a *local hidden variable* (LHV) model if it can be written as

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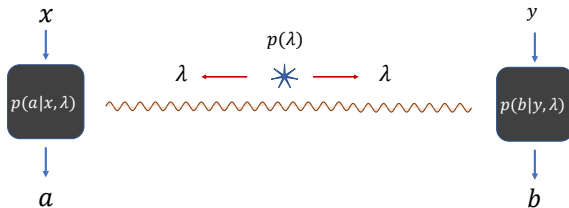
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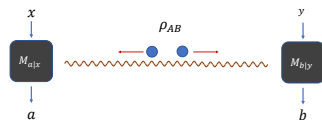


If there is no LHV model, the correlations are *nonlocal*.

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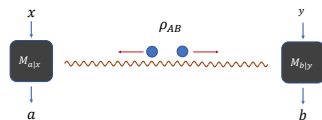
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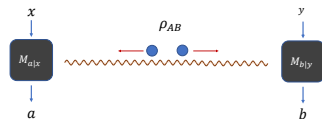


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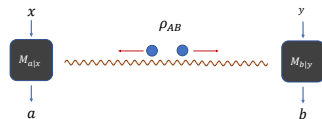
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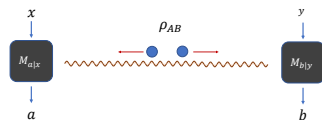
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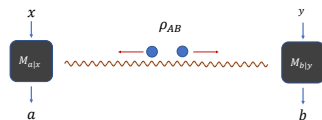
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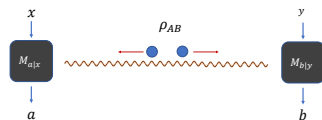
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Hence entanglement is necessary for nonlocal correlations!

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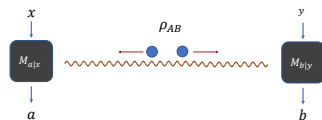


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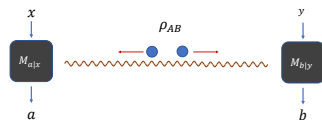
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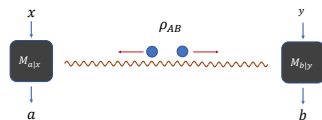
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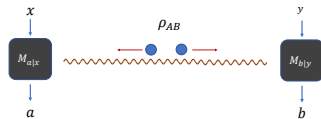
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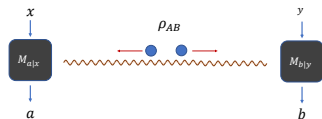
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$$\Rightarrow p(a, b|x, y) = \sum_{\lambda} p(a|x, \lambda) \text{Tr} \left(G_{\lambda} \otimes N_{b|y} \rho_{AB} \right) \quad (8)$$

$$= \sum_{\lambda} p(a|x, \lambda) \text{Tr} \left(N_{b|y} \text{Tr}_A \left[G_{\lambda} \otimes \mathbb{1} \rho_{AB} \right] \right) \quad (9)$$

$$= \sum_{\lambda} p(\lambda) p(a|x, \lambda) \text{Tr} \left(N_{b|y} \sigma_{\lambda} \right) \quad (10)$$

$$= \sum_{\lambda} p(\lambda) p(a|x, \lambda) p(b|y, \lambda) \quad (11)$$

So incompatibility in both measurements is also necessary for nonlocality!

Summary of Measurement Incompatibility

- Incompatibility is an interesting, subtle concept for POVMs.

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- Measurements are compatible if $M_{a|x} = \sum_{\lambda} p(a|x, \lambda) G_{\lambda}$.
- Incompatibility is needed for nonlocality: can be viewed as a resource.
- One can think of incompatibility (of a set of measurements) as the ‘dual’ of entanglement (of a state).

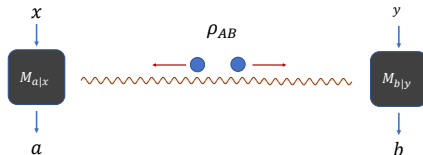
– This can be made precise, more on this later!

Table of Contents

- 1 Measurement Incompatibility
- 2 Quantum Steering**
- 3 Channel-state duality and the Heisenberg picture
- 4 Our Contribution
- 5 Conclusions and Future work

Nonlocality vs Entanglement

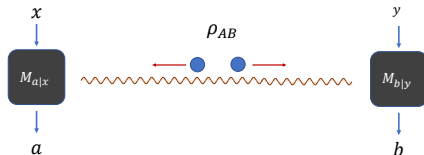
Again recall the Bell scenario



Here the data associated is a probability distribution $p(a, b|x, y)$ – neither party is *trusted*.

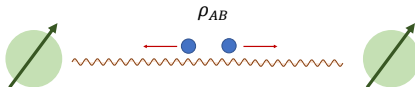
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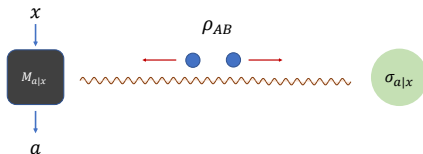
Here the data associated is a probability distribution $p(a, b|x, y)$ – neither party is *trusted*.

If both parties are trusted, the associated data is the full density matrix ρ_{AB} .



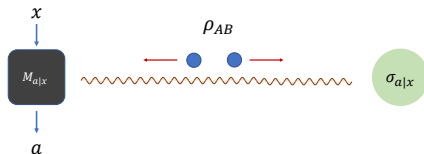
Quantum Steering

Quantum Steering is an intermediate case in which one part is trusted, and the other is untrusted.



Quantum Steering

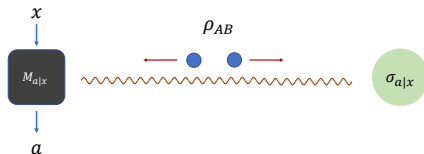
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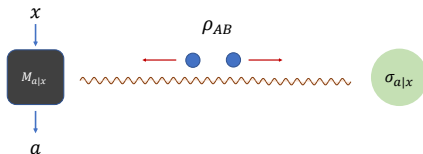
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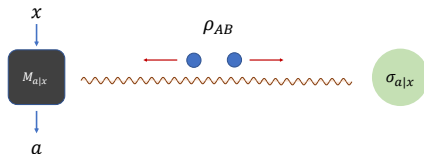
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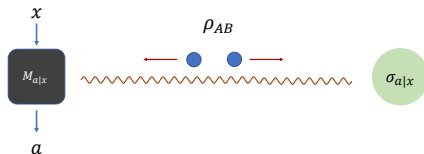
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- Enables one-sided entanglement detection.

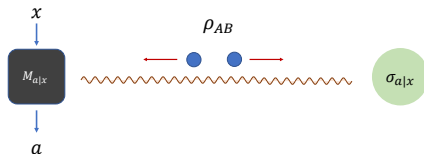
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We can write the data from this scenario as:

$$\sigma_{a|x} := \text{Tr}_A \left(M_{a|x} \otimes \mathbb{1} \rho_{AB} \right)$$

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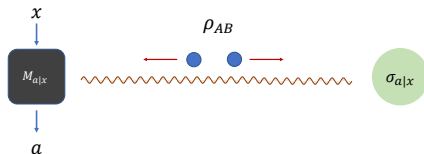


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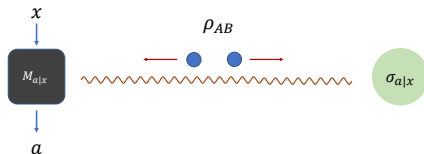


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- We have that $\sum_a \sigma_{a|x} = \text{Tr}_A(\rho_{AB}) = \rho_B$ for all x .
- The data $\sigma_{a|x}$ is referred to as a (steering) **assemblage**.

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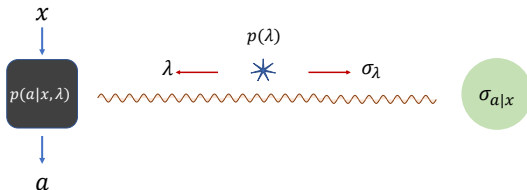
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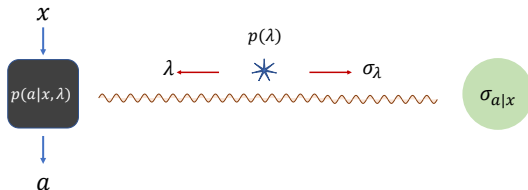


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If there is no LHS model, we say the data demonstrates *steering*.

Entanglement and Incompatibility in Steering

The same arguments go through as before, we have for an assemblage

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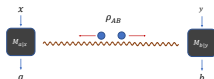
there exist entangled-yet-unsteerable states and steerable-yet-local states!

It is also true that any LHS assemblage can be prepared with a separable state and compatible measurements.

Nonlocality vs Steering vs Entanglement

Scenario:

Nonlocality



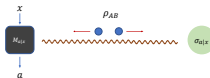
Data:

$$p(a, b|x, y)$$

Local
model:

$$p(a, b|x, y) = \sum_{\lambda} p(\lambda) p(a|x, \lambda) p(b|y, \lambda)$$

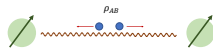
Steering



$$\sigma_{a|x}$$

$$\sigma_{a|x} = \sum_{\lambda} p(\lambda) p(a|x, \lambda) \sigma_B^{\lambda}$$

Entanglement



$$\rho_{AB} = \begin{pmatrix} & \\ & \\ & \\ & \end{pmatrix}$$

$$\rho_{AB} = \sum_{\lambda} p(\lambda) \rho_A^{\lambda} \otimes \rho_B^{\lambda}$$

Connections between Steering and Incompatibility

We already saw one connection between incompatibility and steering.

¹Roope Uola et al. "One-to-one mapping between steering and joint measurability problems". In: *Physical review letters* 115.23 (2015), p. 230402.

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We already saw one connection between incompatibility and steering. Observe that a collection of measurements $M_{a|x}$ and steering assemblage $\sigma_{a|x}$ are very similar types of data:

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$$\text{Measurements } M_{a|x} \qquad \text{Assemblage } \sigma_{a|x} \qquad (12)$$

$$M_{a|x} \geq 0 \quad \forall a, x \qquad \sigma_{a|x} \geq 0 \quad \forall a, x \qquad (13)$$

$$\sum_a M_{a|x} = \mathbb{1} \quad \forall x \qquad \sum_a \sigma_{a|x} = \rho_B \quad \forall x \qquad (14)$$

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There is the following connection¹:

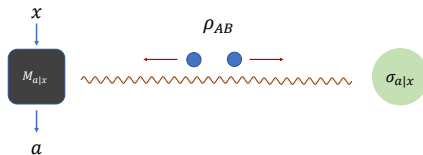
Theorem

An assemblage $\sigma_{a|x}$ admits an LHS model if and only if the measurements $M_{a|x} := \rho_B^{-\frac{1}{2}} \sigma_{a|x} \rho_B^{-\frac{1}{2}}$ are compatible.

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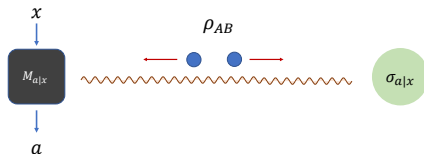
High-dimensional Quantum Steering

Recall the steering scenario



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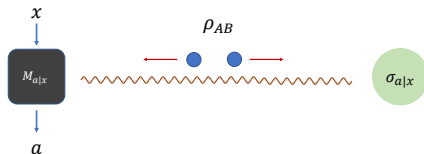


We can certify that the shared state is entangled.

We may want to certify more: that the state involves high-dimensional entanglement.

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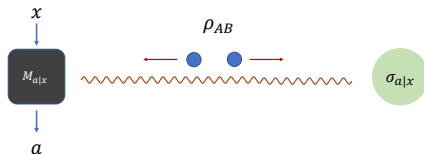
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High-dimensional Quantum Steering

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How can we quantify this?

– The **Schmidt number** is one way ...

Schmidt rank

Consider a bipartite pure state vector $|\psi\rangle_{AB} \in \mathbb{C}^d \otimes \mathbb{C}^d$.

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Definition

The Schmidt rank is defined as

$$\text{SR}(|\psi\rangle) := \min k \quad \text{s.t.} \quad |\psi\rangle = \sum_{i=1}^k \lambda_i |a_i\rangle \otimes |b_i\rangle$$

- This is a restatement of the singular value decomposition.

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Note that

$$\text{SR}(|\psi\rangle) = 1 \quad \Longleftrightarrow \quad |\psi\rangle = |\phi\rangle \otimes |\tau\rangle \quad \text{product state}$$

Schmidt number

The Schmidt rank is just for pure states. A general quantum state

$\rho_{AB} = \sum_k p_k |\psi_k\rangle\langle\psi_k|$ will have many decompositions.

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$$\begin{aligned} \text{SN}(\rho) &:= \min_{\{p_k, |\psi_k\rangle\}} \max_k \text{SR}(|\psi_k\rangle) \\ \text{s.t. } &\rho = \sum_k p_k |\psi_k\rangle\langle\psi_k|. \end{aligned} \quad (15)$$

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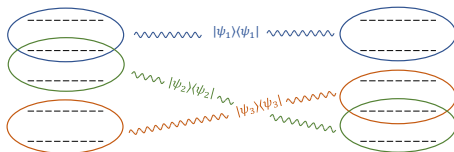
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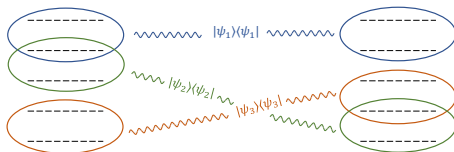
$$\text{s.t. } \rho = \sum_k p_k |\psi_k\rangle\langle\psi_k|.$$

Again we have $\text{SN}(\rho) \in \{1, \dots, d\}$, and

$$\text{SN}(\rho) = 1$$

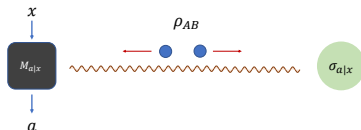
$$\iff \rho = \sum_k p_k |\phi_k\rangle\langle\phi_k| \otimes |\tau_k\rangle\langle\tau_k|$$

separable state.



High-dimensional Quantum Steering

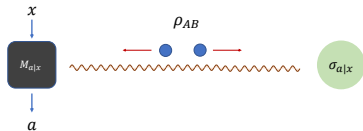
A previous paper² considered how to provide guarantees on the dimension of the underlying state.



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An assemblage $\sigma_{a|x}$ is **n -preparable** if it can be written as

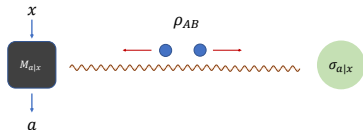
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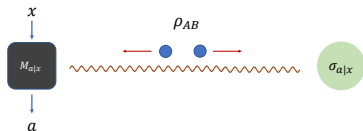
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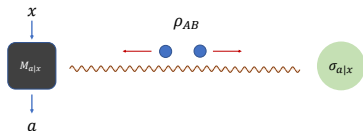
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- Here 1-preparable \iff LHS.
- Not n -preparable \implies Genuine HD steering
- They provided practical bounds for doing this in the lab.

²Sébastien Designolle et al. "Genuine high-dimensional quantum steering". In: *Physical Review Letters* 126.20 (2021), p. 200404.

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- We know compatibility and LHS models are equivalent: does this generalise in terms of dimension?

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- 1 Measurement Incompatibility
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- 3 Channel-state duality and the Heisenberg picture**
- 4 Our Contribution
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The Heisenberg picture

Under the Hilbert-Schmidt inner product $\langle A, B \rangle := \text{Tr}(A^\dagger B)$, recall the definition of the dual map $\mathcal{F} \longleftrightarrow \mathcal{F}^*$:

$$\langle \mathcal{F}(A), B \rangle = \langle A, \mathcal{F}^*(B) \rangle \quad (16)$$

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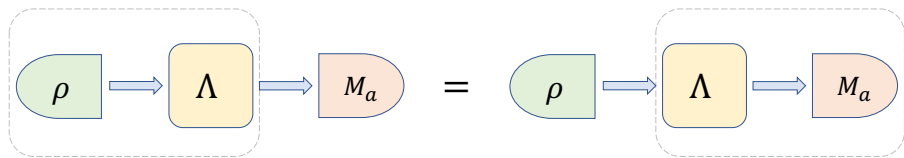
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This is also referred to as the *Choi–Jamiołkowski* isomorphism, and ρ_Λ is often called the *Choi state* of the channel.

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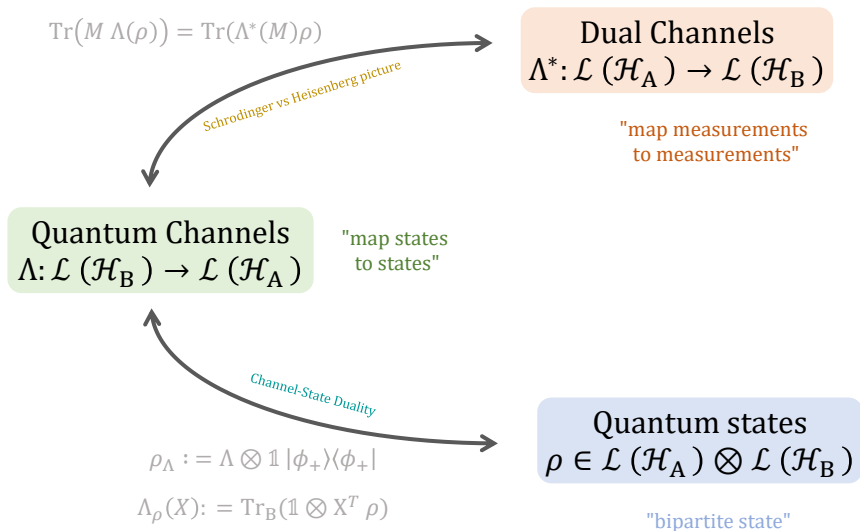
$$\rho_\Lambda := \Lambda \otimes \mathbb{1} |\Omega\rangle\langle\Omega| \quad (22)$$

$$\Lambda_\rho^*(X) := \sigma^{-\frac{1}{2}} \text{Tr}_A(X \otimes \mathbb{1} \rho)^T \sigma^{-\frac{1}{2}} \quad (23)$$

$$\iff \Lambda_\rho(Y) = \text{Tr}_B(\mathbb{1} \otimes (\sigma^{-\frac{1}{2}} Y \sigma^{-\frac{1}{2}})^T \rho) \quad (24)$$

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Recap



Comparing the pictures

It can be often helpful conceptually to use these connections:

Given some property of a channel, can also consider the associated dual and Choi state.

Λ	Λ^*	ρ_Λ
Trace-preserving	Unital	Unit trace
Completely-positive	Completely-positive	Positive semi-definite
Unitary	Unitary	Pure state
??	??	Separable
??	??	Schmidt number n

Entanglement breaking channels

Definition

A channel Λ is entanglement breaking if

$$\Lambda \otimes \mathbb{1} [\rho_{AB}] \quad \text{is separable} \quad \forall \rho_{AB}$$

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One can show that the Choi states of these channels are separable:

$$\Lambda \text{ entanglement breaking} \iff \rho_{\Lambda} \text{ separable}$$

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This is also equivalent to there existing a Kraus decomposition

$$\Lambda(\cdot) = \sum_{\lambda} K_{\lambda}(\cdot) K_{\lambda}^{\dagger} \quad \text{such that: } \text{rank}(K_{\lambda}) \leq n \quad \forall \lambda$$

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So if the measurements can be written as $\Lambda^*(M_{a|x})$ for some n -PEB channel Λ , then the assemblage will also be n -preparable.

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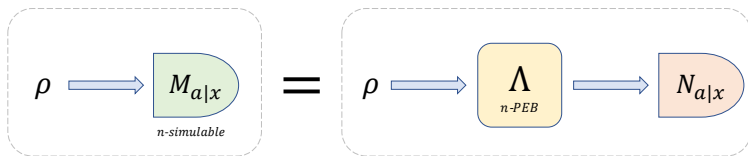
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This can be viewed as a form of compression



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- Analytical and numerical results on when noisy MUBs and the set of all projective measurements become n -simulable not discussed in this talk.

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We also have a quantitative version of this result using the convex weight.

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$$\iff M_{a|x}^T = \rho_B^{-\frac{1}{2}} \text{Tr}_A(N_{a|x} \otimes \mathbb{1} \rho_{AB})^T \rho_B^{-\frac{1}{2}} \quad (30)$$

$$(31)$$

Result 2

Theorem

Consider a steering assemblage $\sigma_{a|x}$ and measurements $M_{a|x}$ such that $M_{a|x} = \rho_B^{-\frac{1}{2}} \sigma_{a|x} \rho_B^{-\frac{1}{2}}$, where $\rho_B := \sum_a \sigma_{a|x}$ is of full rank. Then $M_{a|x}$ is n -simulable if and only if $\sigma_{a|x}$ is n -preparable.

Proof sketch: We have the following equivalences:

$$\sigma_{a|x} = \text{Tr}_A(N_{a|x} \otimes \mathbb{1} \rho_{AB}) \quad (28)$$

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$$\iff M_{a|x}^T = \Lambda_{\rho_{AB}}^* \left(N_{a|x} \right). \quad \text{by CS duality} \quad (31)$$

Incompatibility breaking channels

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Definition

A channel Λ is **n -partially incompatibility breaking** (n -PIB) if for any measurement assemblage $M_{a|x}$ the resulting measurement assemblage $\Lambda^*(M_{a|x})$ is n -simulable.

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i.e. for all $M_{a|x}$ there exists $N_{a|x}$ and a n -PEB channel Ω such that

$$\Lambda^*(M_{a|x}) = \Omega^*(N_{a|x}). \quad (32)$$

Result 3

Definition

Λ n -PIB if $\Lambda^*(M_{a|x})$ is n -simulable $\forall M_{a|x}$.

Theorem

The Choi states of n -PIB channels are exactly those states for whom a Schmidt number of n can be verified in a steering scenario.

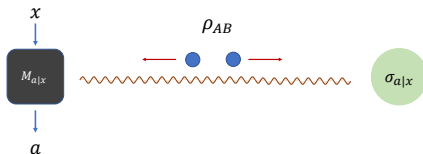
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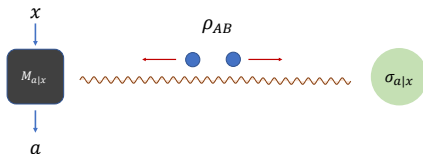
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This is analogous to the existence of entangled yet unsteerable states: There exist states with Schmidt number n , but one can only verify a Schmidt number of $n' < n$.

Table of Contents

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Conclusions

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- We reviewed channel-state duality, the Heisenberg picture, the Schmidt number and partially entanglement breaking channels.
- I discussed recent results on high-dimensional steering and incompatibility.

Future work

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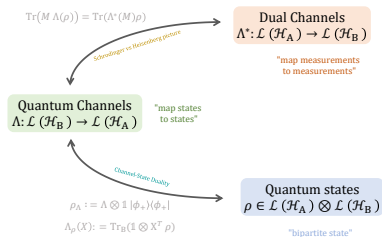
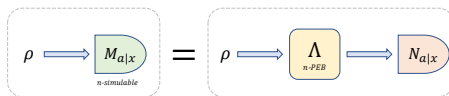
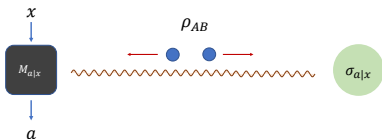
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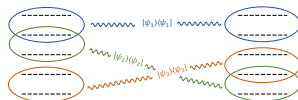
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- Extension to infinite dimensional systems (rank of Kraus operators breaks down).
- Better bounds on how much noise before certain measurements/assemblages become n -simulable/ n -preparable.



Thanks! :)



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