# Prep Course Module 2 Lecture 3

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# Ways to Multiply 2 Matrices

## First way: dot product of row and column

Given matrices A, B, C with AB = C,

$$AB = \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} \begin{bmatrix} b_1 & \cdots & b_n \end{bmatrix} = C$$

where  $a_i$  is the *i*th row of A and  $b_i$  is the *i*th column of B. Then each entry  $C_{ij}$  at row i and column j of C is

$$C_{ij} = \boldsymbol{a_i} \cdot \boldsymbol{b_j}$$

## Second way: linear combinations of columns of A

Given matrices A, B, C with AB = C,

$$AB = \begin{bmatrix} a_1 & \cdots & a_n \end{bmatrix} \begin{bmatrix} b_1 & \cdots & b_n \end{bmatrix} = \begin{bmatrix} c_1 & \cdots & c_n \end{bmatrix} = C$$

where  $a_i$  is the *i*th column of A and  $b_i$  is the *i*th column of B. Let  $b_i := (b_{i,1}, b_{i,2}, \dots, b_{i,n})$ . Then  $c_i$ , the *i*th column of C, is a linear combination of all columns of A with respect to  $b_i$ .

$$\boldsymbol{c_i} = b_{i,1}\boldsymbol{a_1} + b_{i,2}\boldsymbol{a_2} + \dots + b_{i,n}\boldsymbol{a_n}$$

## Third way: linear combinations of rows of B

Given matrices A, B, C with AB = C,

$$AB = \begin{bmatrix} & a_1 \\ & \vdots \\ & a_n \end{bmatrix} \begin{bmatrix} & b_1 \\ & \vdots \\ & b_n \end{bmatrix} = \begin{bmatrix} & c_1 \\ & \vdots \\ & c_n \end{bmatrix} = C$$

where  $a_i$  is the ith row of A and  $b_i$  is the ith row of B. Let  $a_i := (a_{i,1}, a_{i,2}, \ldots, a_{i,n})$ . Then  $c_i$ , the ith row of C, is a linear combination of all rows of B with respect to  $a_i$ .

$$\boldsymbol{c_i} = a_{i,1}\boldsymbol{b_1} + a_{i,2}\boldsymbol{b_2} + \dots + a_{i,n}\boldsymbol{b_n}$$

## Important properties of matrix multiplication

Given matrices A, B, C with compatible dimensions:

Associative Law is valid:

$$(AB)C = A(BC)$$

Commutative Law is NOT true in general:

$$AB \neq BA$$

Distributive Law is valid:

$$A(B+C) = AB + AC,$$
  $(A+B)C = AC + BC$ 

Scalar multiplication: given scalar c

$$c(AB) = (cA)B = (Ac)B = A(cB) = A(Bc) = (AB)c$$

Transpose:

$$(AB)^T = B^T A^T$$

Inverse:

$$(AB)^{-1} = B^{-1}A^{-1}$$

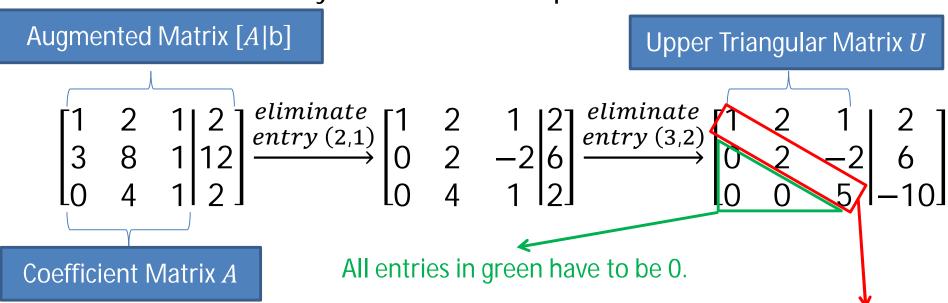
# Elimination with Matrices

## Elimination: to produce an upper triangular matrix

Given the following system of linear equations

$$\begin{array}{cccc}
x + 2y + z &=& 2 \\
3x + 8y + z &=& 12 & \Longleftrightarrow \begin{bmatrix} 1 & 2 & 1 \\ 3 & 8 & 1 \\ 0 & 4 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2 \\ 12 \\ 2 \end{bmatrix} & \Longleftrightarrow Ax = b$$

Elimination is done by a series of row operations



If all diagonal entries are non-zero, the elimination is successful.

#### Backward substitution

Having done a series of row operations, we transform Ax = b into Ux = c, where c = (2,6,-10). With the upper triangular U, we can easily solve the equations in reverse order, meaning, from bottom to top.

$$\begin{bmatrix} 1 & 2 & 1 & 2 \\ 0 & 2 & -2 & 6 \\ 0 & 0 & 5 & -10 \end{bmatrix} \Rightarrow z = -2, y = 1, x = 2$$

#### **Pivots**

A pivot is an entry in a matrix that satisfies the following:

- It's the first non-zero entry at its row;
- All entries below it, if any, are zero.

For example, the upper triangular *U* has three pivots on the diagonal:

$$\begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 0 & 5 \end{bmatrix}$$

If we can successfully transform a matrix K to an upper triangular matrix where every entry on the diagonal is a pivot, then we say the upper triangular matrix has a full set of pivots and the original matrix K is invertible.

#### Elimination matrices

Previously in matrix A, we subtracted 3 times row 1 from row 2 to eliminate entry (2,1):

$$\begin{bmatrix} 1 & 2 & 1 \\ 3 & 8 & 1 \\ 0 & 4 & 1 \end{bmatrix} \xrightarrow{eliminate} \begin{bmatrix} 1 & 2 & 1 \\ entry & (2,1) \\ 0 & 2 & -2 \\ 0 & 4 & 1 \end{bmatrix}$$

The same operation can be done by multiplication by an elimination matrix  $E_{2,1}$  as follows:

$$E_{2,1} = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

where the subscript 2,1 means we are eliminating entry (2,1)

$$E_{2,1}A = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \\ 3 & 8 & 1 \\ 0 & 4 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 4 & 1 \end{bmatrix}$$

## Elimination by matrix multiplication

Now we want to express the following row operations using matrix multiplication:

$$\begin{bmatrix} 1 & 2 & 1 \\ 3 & 8 & 1 \\ 0 & 4 & 1 \end{bmatrix} \xrightarrow{eliminate} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 4 & 1 \end{bmatrix} \xrightarrow{eliminate} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 4 & 1 \end{bmatrix}$$

In addition to  $E_{2,1}$ , let's define  $E_{3,2}$  as follows:

$$E_{2,1} = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
 and  $E_{3,2} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix}$ 

where the subscript 2,1 means we are eliminating entry (2,1)

$$E_{3,2}E_{2,1}A = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & -2 \\ 0 & 0 & 5 \end{bmatrix}$$

## Observations about $E_{3,2}E_{2,1}$

Basically the matrix  $E_{3,2}E_{2,1}$  does all the row operations in one go.

$$E_{3,2}E_{2,1} = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 6 & -2 & 1 \end{bmatrix}$$

#### Note that

- Entry (2,1) is -3
- Entry (3,2) is -2
- Entry (3,1) is 6
- the product of :  $E_{3,2}$  and  $E_{2,1}$  is still lower triangular
- Don't be confused. An elimination matrix does not have to be lower triangular.

## Properties of triangular matrices

- The sum of two lower triangular matrices is lower triangular.
- The product of two lower triangular matrices is lower triangular.
- The inverse of an invertible lower triangular matrix is lower triangular.
- The product of an lower triangular matrix by a scalar is an lower triangular matrix.

The above properties also hold for upper triangular matrices.

# **Inverse Matrices**

#### Invertible matrices

A n by n matrix A is invertible if there exists a matrix  $A^{-1}$  such that

$$A^{-1}A = I$$
 or  $AA^{-1} = I$ 

- $A^{-1}A = I$  if and only  $AA^{-1} = I$
- The inverse exists if and only if elimination produces n pivots.
- The inverse is unique.
- If *A* is invertible, then the only solution to Ax = b is  $x = A^{-1}b$ .
- If there exists a non-zero vector x such that Ax = 0, then A is not invertible, because no matrix  $A^{-1}$  can bring 0 back to x.

## Inverse of a diagonal matrix

A *n by n* diagonal matrix *A* is invertible if no diagonal entries are zero.

If 
$$A = \begin{bmatrix} d_1 \\ & \ddots \\ & & d_n \end{bmatrix}$$
, then  $A^{-1} = \begin{bmatrix} 1/d_1 \\ & \ddots \\ & & 1/d_n \end{bmatrix}$ 

## Inverse of product AB

(Theorem) If A and B are invertible then so is AB. Moreover, the inverse of product AB is

$$(AB)^{-1} = B^{-1}A^{-1}$$

Proof:

$$(AB)(B^{-1}A^{-1}) = A(BB^{-1})A^{-1} = AIA^{-1} = AA^{-1} = I$$

(Corollary) If A, B, C are all invertible, then

$$(ABC)^{-1} = C^{-1}B^{-1}A^{-1}$$

#### Inverse of elimination matrices

Basically the inverse of an elimination matrix is to recover what has been eliminated. Take  $E_{2,1}$  and  $E_{3,2}$  as example:

$$E_{2,1} = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \text{ and } E_{3,2} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -2 & 1 \end{bmatrix}$$

And the inverses of them are as follows:

$$E_{2,1}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
 and  $E_{3,2}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix}$ 

However, let's compare  $E_{3,2}E_{2,1}$  and its inverse  $E_{2,1}^{-1}E_{3,2}^{-1}$ 

$$E_{3,2}E_{2,1} = \begin{bmatrix} 1 & 0 & 0 \\ -3 & 1 & 0 \\ 6 & -2 & 1 \end{bmatrix} \text{ and } E_{2,1}^{-1}E_{3,2}^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 0 & 2 & 1 \end{bmatrix}$$

# Gauss-Jordan Elimination

## Finding an inverse is like solving linear equations

In  $\mathbb{R}^n$ , let  $e_i$  denote a vector which has 1 at the *i*th component and 0 at the rest. For example, in  $\mathbb{R}^3$ ,  $e_1 = (1,0,0)$ ,  $e_2 = (0,1,0)$ ,  $e_3 = (0,0,1)$ . Given a n by n matrix A, finding its inverse is equivalent to solving the following equations:

$$AA^{-1} = A\begin{bmatrix} x_1 & \dots & x_n \end{bmatrix} = \begin{bmatrix} e_1 & \dots & e_n \end{bmatrix} = I$$

where  $x_i$ 's represents the columns of  $A^{-1}$  and  $e_i$ 's are the columns of identity matrix I. Previously we have only one system of equations Ax = b. Now we have n systems of equations. Gauss-Jordan elimination helps us solve the n systems together.

## Example of Gauss-Jordan elimination (1/3)

Given matrix A as follows:

$$A = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$$

Initially the augmented matrix = [A|I].

$$\begin{bmatrix} 2 & -1 & 0 & | 1 & 0 & 0 \\ -1 & 2 & -1 & | 0 & 1 & 0 \\ 0 & -1 & 2 & | 0 & 0 & 1 \end{bmatrix} \xrightarrow{eliminate} \begin{bmatrix} 2 & -1 & 0 & | 1 & 0 & 0 \\ entry & (2,1) & | & 0 & 3/2 & -1 & | 1/2 & 1 & 0 \\ 0 & -1 & 2 & | & 0 & 0 & 1 \end{bmatrix}$$

$$\frac{eliminate}{entry (3,2)} \begin{bmatrix} 2 & -1 & 0 & 1 & 0 & 0 \\ 0 & 3/2 & -1 & 1/2 & 1 & 0 \\ 0 & 0 & 4/3 & 1/3 & 2/3 & 1 \end{bmatrix}$$

## Example of Gauss-Jordan elimination (2/3)

$$\begin{bmatrix} 2 & -1 & 0 & 1 & 0 & 0 \\ 0 & 3/2 & -1 & 1/2 & 1 & 0 \\ 0 & 0 & 4/3 & 1/3 & 2/3 & 1 \end{bmatrix} \xrightarrow{eliminate} \begin{bmatrix} 2 & -1 & 0 & 1 & 0 & 0 \\ 0 & 3/2 & 0 & 3/4 & 3/2 & 3/4 \\ 0 & 0 & 4/3 & 1/3 & 2/3 & 1 \end{bmatrix}$$

$$\frac{\text{divide row}}{\text{by pivot}} \begin{bmatrix} 1 & 0 & 0 & 3/4 & 1/2 & 1/4 \\ 0 & 1 & 0 & 1/2 & 1 & 1/2 \\ 0 & 0 & 1 & 1/4 & 1/2 & 3/4 \end{bmatrix}$$

$$\Rightarrow A^{-1} = \begin{bmatrix} 3/4 & 1/2 & 1/4 \\ 1/2 & 1 & 1/2 \\ 1/4 & 1/2 & 3/4 \end{bmatrix}$$

## Example of Gauss-Jordan elimination (3/3)

Here are the matrices corresponding the elimination steps

$$E_{2,1} = \begin{bmatrix} 1 & 0 & 0 \\ 1/2 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} E_{3,2} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 2/3 & 1 \end{bmatrix} E_{2,3} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 3/4 \\ 0 & 0 & 1 \end{bmatrix}$$
$$E_{1,2} = \begin{bmatrix} 1 & 2/3 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} D = \begin{bmatrix} 1/2 & 0 & 0 \\ 0 & 2/3 & 0 \\ 0 & 0 & 3/4 \end{bmatrix}$$

Initially we have

$$AA^{-1} = I$$

Then we multiply both sides by the matrices above:

$$DE_{1,2}E_{2,3}E_{3,2}E_{2,1}AA^{-1} = DE_{1,2}E_{2,3}E_{3,2}E_{2,1}I$$
  
$$\Rightarrow A^{-1} = DE_{1,2}E_{2,3}E_{3,2}E_{2,1}$$