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# Finding optimal goals in card games with uncertainty

## 1 Introduction

Our central question is the following: given the history of the game, what is the optimal goal to pursue? There are 52 possible goals (i.e. straight flushes of 6 cards). We give them each different weights in the weight vector  $\vec{\mathbf{w}} \in \mathbb{R}^{52}$ , which is updated every time we learn new information about the game. At the beginning before any cards are dealt, every goal is equally (un)optimal, and  $\vec{\mathbf{w}} := \vec{\mathbf{0}}$ .

### 2 The Metrics

I propose to evaluate goals with three metrics: Overlap, Distance, and Likelihood.

### 2.1 Overlap

Overlap measures how many cards in common a certain goal G has with a set of cards C, typically the ones visible (in hands and on the table). Formally, Overlap is defined as the following:

$$Overlap(C, G) = |C \cap G| \tag{1}$$

Overlap takes on values in the interval [0,6]. It is independent of game history.

#### 2.2 Distance

DISTANCE measures how close a certain goal G is from a set of cards C. It is independent of game history. IS DISTANCE JUST 6 - OVERLAP?!?!?!

#### 2.3 Likelihood

Likelihood measures how likely a certain goal G can be obtained given all previous history H. Likelihood is defined as the following:

$$\mathcal{L}(G, H) = \sum_{g \in G} (1 - P(g \text{ has been discarded}|H))$$
 (2)

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Given a card g and history H, we can find P(g) has been discarded |H| in the following way. First, we assume that the history H contains information about  $r_i$ , the number of cards reshuffled at round i for all i, as well as which cards we have seen and not seen. Let s be the index of the round that g was last seen, let n be the number of rounds that have occurred between s and now, and let  $D_i$  be the size of the deck at round i. Then we have:

$$P(g \text{ has been discarded}|H) = \begin{cases} 0 & g \in \text{ hands or table, or unseen} \\ \frac{4-r_s}{4-r_s+r_s\prod_{j=1}^n(1-4/D_{s+j})} & \text{o.w.} \end{cases}$$
 (3)

*Proof.* It is easy to see that a card g cannot have been discarded if it is currently in the hands, on the table, or unseen (in the deck). Now, consider the case where g has not been seen for n rounds (since round s). Let F be the event that g was discarded at around s, and let g be the event that we haven't seen g for g rounds. By Bayes' Rule, we have:

$$P(F|U) = \frac{P(U|F)P(F)}{P(U)} \tag{4}$$

$$= \frac{(1)\left(\frac{4-r_s}{4}\right)}{P(U|F)P(F) + P(U|F^c)P(F^c)}$$
 (5)

$$= \frac{(4-r_s)/4}{(4-r_s)/4 + (r_s/4)P(U|F^c)}$$
 (6)

Let's look at  $P(U|F^c)$ . Since we are conditioning on  $F^c$ , we know that g was reshuffled in the previous round, and the size of the deck has been updated to D. The probability of not drawing g in this round is

$$\frac{\binom{D-1}{4}}{\binom{D}{4}} = \frac{D-4}{D},\tag{7}$$

and this pattern continues for every subsequent round. This gives us

$$P(U|F^c) = \prod_{j=1}^{n} \frac{D_{s+j} - 4}{D_{s+j}}.$$
 (8)

Using this result and simplifying, we finally obtain

$$P(F|U) = \frac{4 - r_s}{4 - r_s + r_s \prod_{j=1}^{n} (1 - \frac{4}{D_{s+j}})}.$$
(9)

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Note that we can also write the size of the deck at round k as

$$D_k = 46 + \sum_{i=1}^{k-1} r_i - 4k. \tag{10}$$

*Proof.* In the base case, k = 1 yields 46 - 4(1) = 42, which is correct since we deal 10 cards from the original 52 in the first round. Suppose now that (10) is true for k = n. Then we have:

$$D_{n+1} = D_n + r_n - 4 (11)$$

$$= (46 + \sum_{i=1}^{n-1} r_i - 4n) + r_n - 4 \tag{12}$$

$$=46 + \sum_{i=1}^{n} r_i - 4(n+1) \tag{13}$$

By induction, (10) holds for all values of k.

## 3 Evaluating Goals

Every time the history H is updated and we observe a new set of cards C, the weights  $w_i$  for each goal  $G_i$  are updated with a linear combination of the three metrics:

$$w_i := \alpha_0 \cdot \text{Overlap}(G_i, C) + \alpha_1 \cdot \text{Distance}(G_i, C) + \alpha_2 \cdot \text{Likelihood}(G_i, H)$$
(14)

The values of  $\{\alpha\}$  depend on how we want to weight the different metrics. A less rational player might weight Overlap more than Likelihood, for example.