

Formulation

$$\frac{dx}{dt} = a\left(1 - \frac{x}{K}\right)x - bxy \rightarrow \text{prey}$$

$$\frac{dy}{dt} = cxy - dy \rightarrow \text{predator}$$

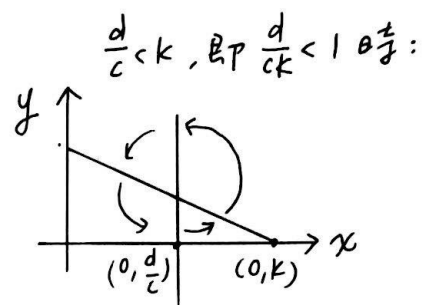
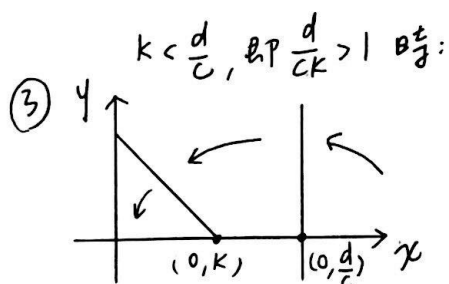
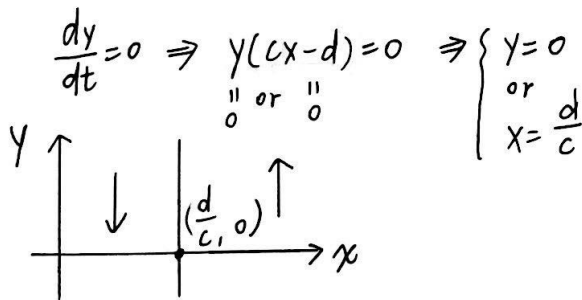
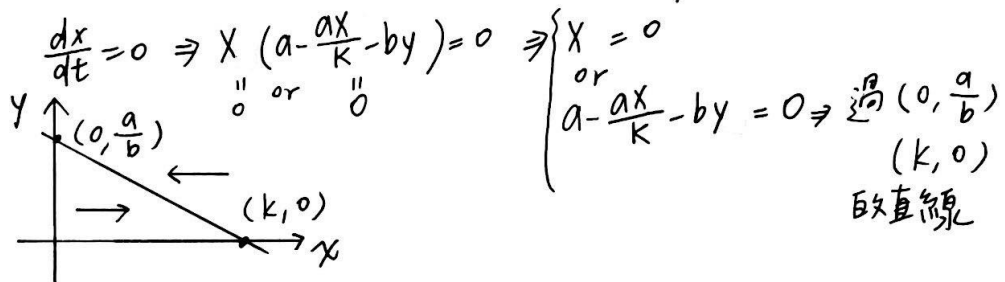
① Find equilibrium condition.  $\rightarrow \frac{dx}{dt} = 0, \frac{dy}{dt} = 0$

$$x_e \left( a - \frac{ax_e}{K} - by_e \right) = 0$$

$$(cx_e - d)y_e = 0$$

$$(x_e, y_e) = (0, 0) \text{ or } (K, 0) \text{ or } \left( \frac{d}{c}, \frac{a}{b} - \frac{ad}{bck} \right)$$

② Plot Isodine to determine the stability.



$$\textcircled{4} \begin{bmatrix} \frac{d\Delta x}{dt} \\ \frac{d\Delta y}{dt} \end{bmatrix} = \begin{bmatrix} \left. \frac{\partial f}{\partial x} \right|_{x_e, y_e} & \left. \frac{\partial f}{\partial y} \right|_{x_e, y_e} \\ \left. \frac{\partial g}{\partial x} \right|_{x_e, y_e} & \left. \frac{\partial g}{\partial y} \right|_{x_e, y_e} \end{bmatrix} = \lambda_{\max} \begin{bmatrix} \Delta x \\ \Delta y \end{bmatrix}$$

$$\lambda_{\max} = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} = \begin{bmatrix} a - \frac{2ax}{k} - by & -bx \\ cy & cx - d \end{bmatrix}$$

$$\textcircled{4-1} (x_e, y_e) = \left( \frac{d}{c}, \frac{a}{b} - \frac{ad}{bck} \right)$$

$$\lambda_{\max} = \begin{bmatrix} a - \frac{2ax}{k} - by & -bx \\ cy & cx - d \end{bmatrix} \xrightarrow{\substack{x=x_e \\ y=y_e}} \begin{bmatrix} -\frac{ad}{ck} & -\frac{bd}{c} \\ \frac{a(c - \frac{d}{k})}{b} & 0 \end{bmatrix}$$

$$\begin{aligned} a - \frac{2ad}{kc} - a - \frac{ad}{ck} \\ = \frac{ad - 2ad}{ck} \end{aligned}$$

$\lambda_{\max}$  is a maximum solution of:

$$\begin{aligned} \lambda^2 - (a_{11} + a_{22})\lambda + a_{11} \cdot a_{22} - a_{12} \cdot a_{21} &= 0 \\ \rightarrow \lambda^2 - \left( -\frac{ad}{kc} \right)\lambda + 0 - \left( -\frac{bd}{c} \cdot \frac{a(c - \frac{d}{k})}{b} \right) &= 0 \\ \rightarrow \lambda^2 + \frac{ad}{kc}\lambda + 0 + \frac{ad(c - \frac{d}{k})}{c} &= 0 \end{aligned}$$

$$\begin{aligned} \lambda = \lambda_1 &= \frac{1}{2} \left( -\frac{ad}{kc} + \sqrt{\left( \frac{ad}{kc} \right)^2 - \frac{4ad(c - \frac{d}{k})}{c}} \right) \\ &= \frac{1}{2} \left( -\frac{ad}{kc} + \sqrt{\frac{ad}{ck} \cdot \left( \frac{ad}{ck} - 4(c - d) \right)} \right) \\ \lambda_2 &= \frac{1}{2} \left( -\frac{ad}{kc} - \sqrt{\frac{ad}{ck} \cdot \left( \frac{ad}{ck} - 4(c - d) \right)} \right) \end{aligned}$$

當  $ck - d < 0$ , 即  $\frac{d}{ck} > 1 \rightarrow \lambda_1 > 0, \lambda_2 < 0 \rightarrow$  <sup>-正-負</sup> unstable

當  $ck - d > 0$ , 即  $\frac{d}{ck} < 1 \rightarrow \lambda_1 < 0, \lambda_2 > 0 \rightarrow$  <sup>-正-負</sup> unstable

$$\boxed{4-2} \quad (x_e, y_e) = (0, 0)$$

$$\lambda_{\max} = \begin{bmatrix} a - \frac{2ax}{k} - by & -bx \\ cy & cx - d \end{bmatrix} \xrightarrow{\substack{x=x_e \\ y=y_e}} \begin{bmatrix} a & 0 \\ 0 & -d \end{bmatrix}$$

$\lambda_{\max}$  is a maximum solution of:

$$\lambda^2 - (a_{11} + a_{22})\lambda + a_{11} \cdot a_{22} - a_{12} \cdot a_{21} = 0$$

$$\rightarrow \lambda - (a - d)\lambda + (ad) - 0 = 0$$

$$\rightarrow \lambda = \begin{cases} \lambda_1 = \frac{1}{2} (a - d + \sqrt{(a-d)^2 + 4ad}) = \frac{1}{2}(a - d + a + d) = a \\ \lambda_2 = \frac{1}{2} (a - d - \sqrt{(a-d)^2 + 4ad}) = \frac{1}{2}(a - d - a - d) = -d \end{cases} \rightarrow \begin{matrix} -\text{正-負} \\ \text{unstable} \end{matrix}$$

$$\boxed{4-3} \quad (x_e, y_e) = (k, 0)$$

$$\lambda_{\max} = \begin{bmatrix} a - \frac{2ax}{k} - by & -bx \\ cy & cx - d \end{bmatrix} \xrightarrow{\substack{x=x_e \\ y=y_e}} \begin{bmatrix} -a & -bk \\ 0 & ck - d \end{bmatrix}$$

$\lambda_{\max}$  is a maximum solution of:

$$\lambda^2 - (a_{11} + a_{22})\lambda + a_{11} \cdot a_{22} - a_{12} \cdot a_{21} = 0$$

$$\rightarrow \lambda - (-a + ck - d)\lambda + (-a)(ck - d) - 0 = 0$$

$$\rightarrow \lambda = \begin{cases} \lambda_1 = \frac{1}{2} (-a + ck - d + (-a - (ck - d))) = \frac{1}{2}(-2a) = -a \\ \lambda_2 = \frac{1}{2} (-a + ck - d - (-a - (ck - d))) = \frac{1}{2}(-2d) = ck - d \end{cases}$$

$$ck - d < 0 \rightarrow \lambda_1 < 0, \lambda_2 < 0 \rightarrow \text{stable}$$

$$ck - d > 0 \rightarrow \lambda_1 < 0, \lambda_2 > 0 \rightarrow \text{unstable}$$