Introduction to Machine Learning

NYU K12 STEM Education: Machine Learning

Department of Electrical and Computer Engineering,
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Course Details

- Course Website
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NYU

Outline

1. Review
2. Working with Images
3. Convolution Neural Networks
4. Data Augmentation
5. Normalization
6. Dropout
7. Transfer Learning

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- 2D matrices with each entry specifying the intensity (brightness) of a pixel
- Pixel values range from 0 to 255, 0 being the darkest, 255 being the brightest

```
[[255 255 255]
 [255   0 255]
 [255 255 255]]
```

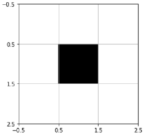

Figure 1: A 3x3 Grayscale Image

Color Images

- Color (RGB) images have an extra dimension for color (3D array)
- Imagine three 2D matrices stacked together
- Each 2D matrix specifies the amount of color for Red, Green, and Blue at each pixel

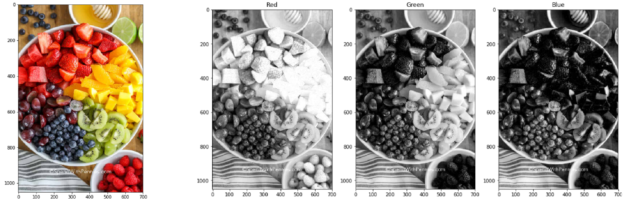

Figure 2: RGB Images

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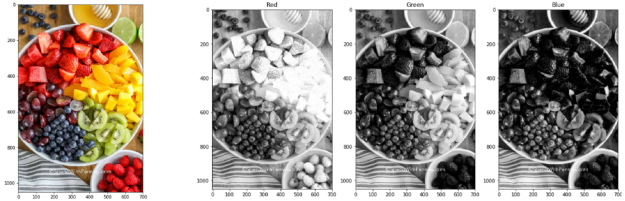

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- Shape - (1050, 700, 3)

Images and Neural Networks

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- Flatten the image!

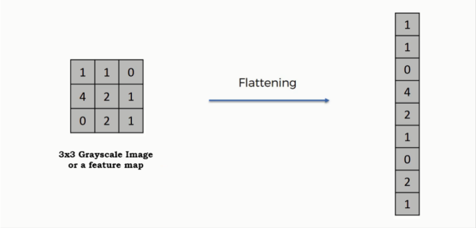

Figure 3: Flattening an Image

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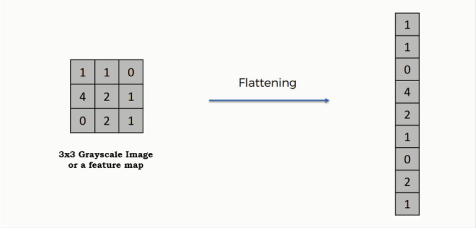

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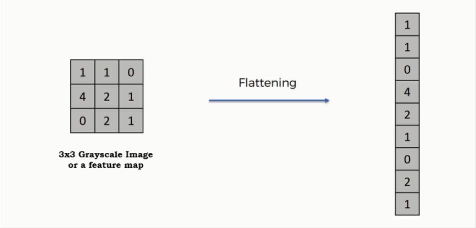

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- Does this make sense? Is this how we see images?
  - No consideration for spatial positions!!
  - How many input neurons for 1024x1024 image?
  - What about slightly rotated photographs?

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The Convolution Operation

- All these problems are solved by Convolutions!
- Convolution operation is applied on an image matrix X with a kernel W

$$Z = X \circledast W$$

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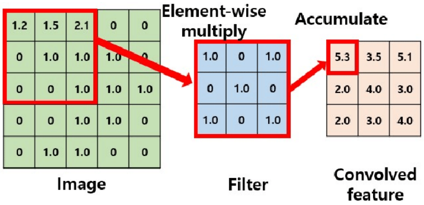

Figure 4: Convolution Operation

The Convolution Operation

- Let's see some visualizations!

Why Convolution?

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- Different kernels capture different features from the image

Convolution for Multiple Channels

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- Each kernel performs a 2D convolution a its respective channel
- The results are then summed

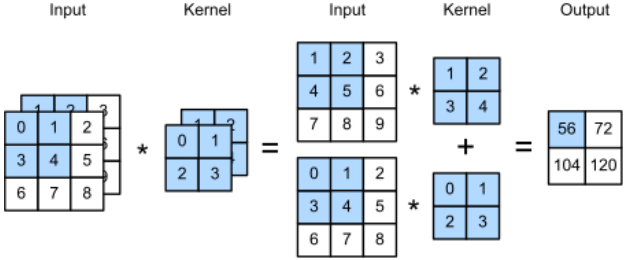

Figure 5: Convolution Across Channels
Source dl2.ai

Max Pooling

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- Reduces the dimensions of intermediate network results

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- Reduces the dimensions of intermediate network results
- It provides "translational invariance". Why?
  - Most prominent feature in every local region is preserved
  - Focuses on the presence of features rather than their precise location

Max Pooling

- Let's see an example!

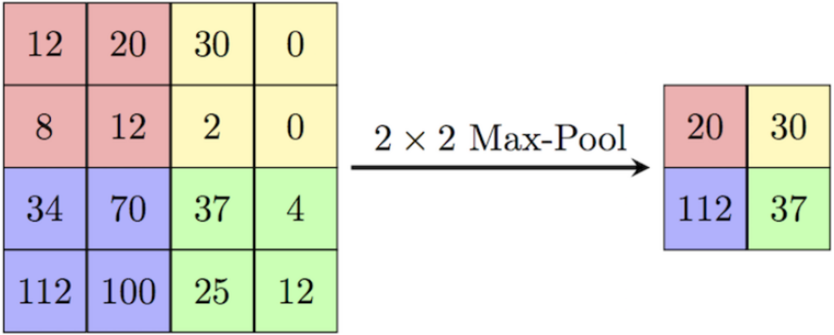

Figure 6: Max Pooling Example

Outline

Scarcity of training data

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- Labelling data is expensive and time-consuming
- What can we do now?
- Create new images!

Data Augmentation

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- Let's look at some techniques for Data Augmentation

Mirroring

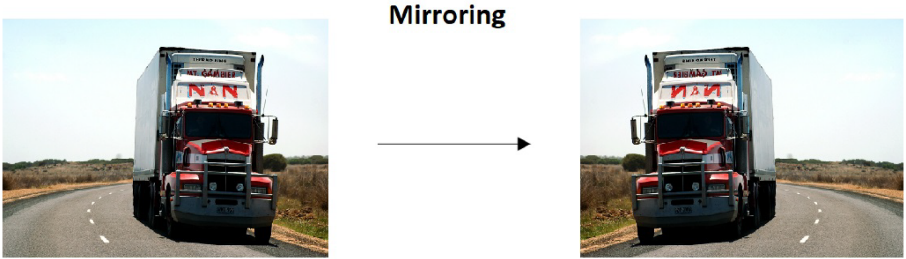

Figure 7: Mirroring

Rotation and Translation

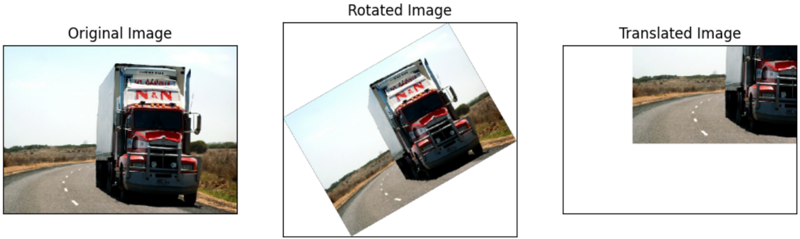

Figure 8: Rotation and Translation

Random Cropping

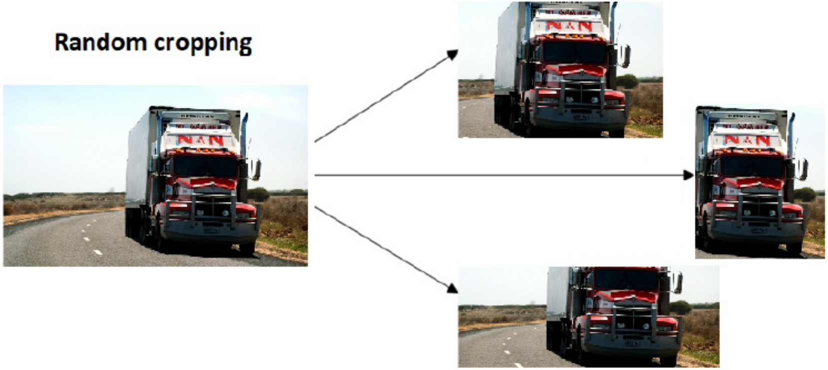

Figure 9: Random Cropping

Color Shifting

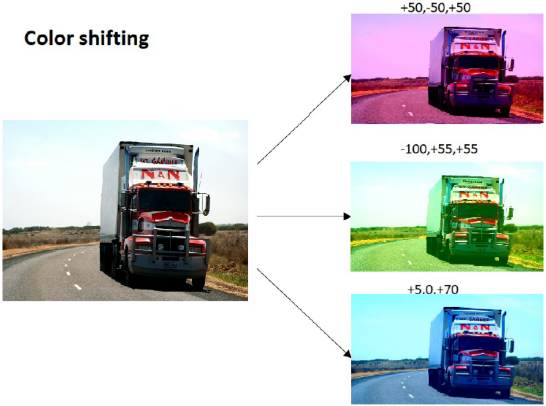

Figure 10: Color Shifting

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- Consider the dataset $(x_i, y_i)\ \forall i \in \{1, 2, 3..., N\}$
- Mean $\bar{x} = \frac{1}{N} \sum x_i$
- Variance $\sigma^2 = \frac{1}{N} \sum (x_i - \bar{x_i})^2$
- Normalization: Replace each x_i with x_i', where:

$$x_i' = \frac{x_i - \bar{x}}{\sigma}$$

- The new dataset will have a mean of 0 and a variance of 1

Data Normalization

- Consider a single weight w and bias b
- The contours in the plot represents the value of the loss function for the given w and b

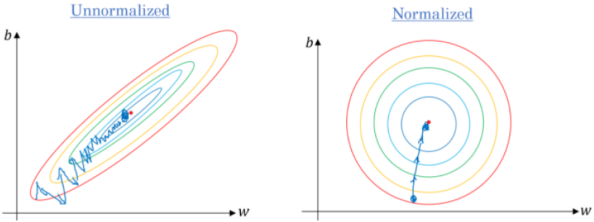

Figure 11: Unnormalized vs Normalized Descent
Source: TowardsDataScience

Batch Normalization

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- Batch Normalization involves normalizing the inputs to each layer within each mini-batch
- Batch normalization is applied before activation

```
model = models.Sequential()

model.add(layers.Conv2D(64,(3,3)))
model.add(layers.BatchNormalization())
model.add(layers.Activation('relu'))


model.add(layers.Flatten())
model.add(layers.Dense(64))
model.add(layers.BatchNormalization())
model.add(layers.Activation('relu'))

model.add(layers.Dense(1, activation =
'sigmoid'))
```

Figure 12: Batch Normalization

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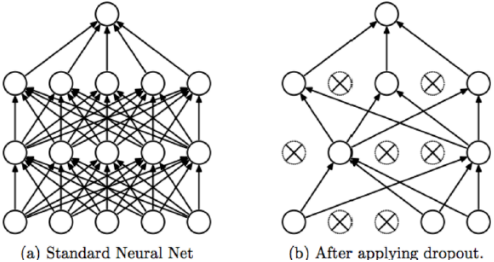

Figure 13: Dropout

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- This techinque is patented by Google
- Randomly disable neurons and their connections between each other
- Without dropout, neurons can become too reliant on the outputs of specific other neurons, leading to overfitting

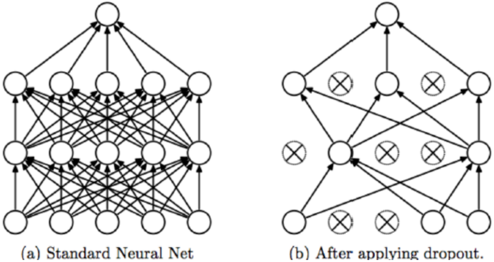
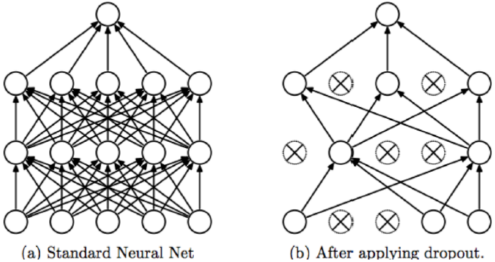


Figure 13: Dropout

Dropout

- This is the same as using a neural network with the same amount of layers but less neurons per layer.



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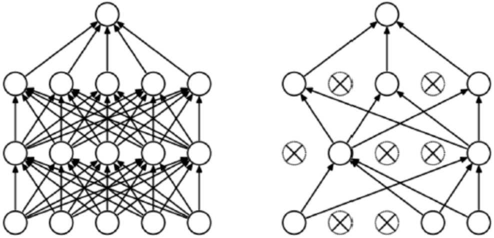
- The more neurons the more powerful the neural network is, and the more likely it is to overfit.



(a) Standard Neural Net (b) After applying dropout.

Figure 14: Dropout

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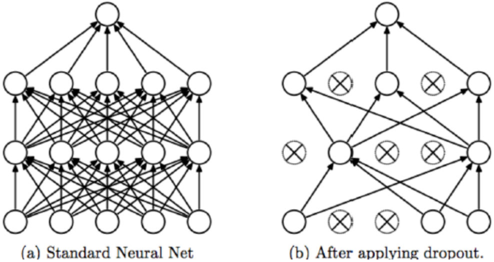
- This is the same as using a neural network with the same amount of layers but less neurons per layer.
- The more neurons the more powerful the neural network is, and the more likely it is to overfit.
- This also means that the model can not rely on any single feature, therefore would need to spread out the weights



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- Training large computer vision models requires extensive hyperparameter search and multiple GPU running for weeks!
- Solution: Transfer Learning

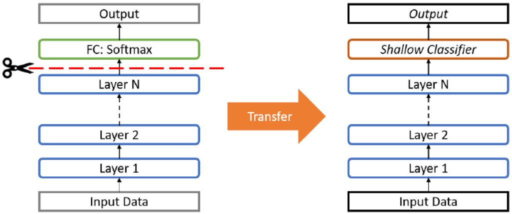

Figure 15: Transfer Learning
Source: Oreilly

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- Often in practice, people preserve the feature extractor and re-train the classification head
- Freeze the early layers and replace the last few to match your needs. Only train the replaced layers
- This is similar to transferring the knowledge from one network to another, thus the name transfer learning.