

Overfitting and Generalization

NYU K12 STEM Education: Machine Learning

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Course Details

- ▶ Course Website
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Outline

Review 000

- 1. Review

- 4. Optimization

Review

- ► For the Boston housing dataset we have the following information in the data:
- 'CRIM'.'ZN'.'INDUS'.'CHAS'.'NOX'.'RM'.'AGE'.'DIS'. 'RAD'.'TAX','PTRATIO','B','LSTAT','PRICE'

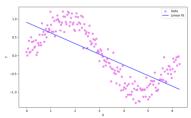
Review

- You have a large inventory of identical items, you want to predict how many you can sell in the next 3 months.
- You want a software to examine individual costumer's account and for each account decide if it has been hacked.
- ► (Credit to Andrew Na)

Outline

- 1. Review
- 2. Polynomial Fitting
- 4. Optimization

- We have been using straight lines to fit our data. But it doesn't work well every time
- Some data have more complex relation that cannot be fitted well using a straight line

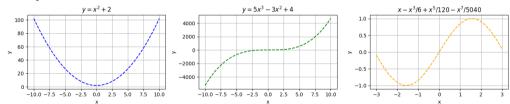


Can we use some other model to fit this data?

Can we use a polynomial to fit our data?

Polynomial: A sum of different powers of a variable

Example:



Polynomials of x: $\hat{y} = w_0 + w_1 x + w_2 x^2 + \cdots + w_m x^m$

m is called the order of the polynomial.

The process of fitting a polynomial is similar to linearly fitting multivariable data.

In matrix-vector form:

$$\begin{bmatrix} \hat{y_1} \\ \hat{y_2} \\ \vdots \\ \hat{y_N} \end{bmatrix} = \begin{bmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^m \\ 1 & x_2 & x_2^2 & \cdots & x_2^m \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_N & x_N^2 & \cdots & x_N^m \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \\ \vdots \\ w_m \end{bmatrix}$$

This can still be written as: $\hat{V} = XW$

Loss:

$$J(W) = \frac{1}{N}||Y - XW||^{2}$$

The i^{th} row of the design matrix X is simply a transformed feature:

$$\phi(x_i) = (1, x_i, x_i^2, \cdots, x_i^m)$$

Original Design Matrix:

$$\begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_N \end{bmatrix}$$

Design matrix after feature transformation:

$$\begin{bmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^m \\ 1 & x_2 & x_2^2 & \cdots & x_2^m \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_N & x_N^2 & \cdots & x_N^m \end{bmatrix}$$

For the polynomial fitting, we just added columns of features that are powers of the original feature.

Model:

$$\hat{y} = W^T \phi(x)$$

Loss:

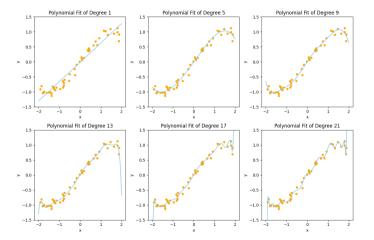
$$J(W) = \frac{1}{N}||Y - XW||^2$$

Find W that minimizes J(W)

Overfitting

- We learned how to fit our data using polynomials of different order
- With a higher model order, we can fit the data with increasing accuracy
- As you increase the model order, at certain point it is possible find a model that fits your data perfectly (ie. zero error)
- What could be the problem?

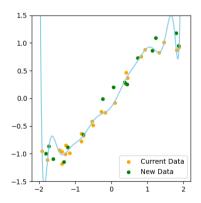
Overfitting



Which of these model do you think is the best? Why?

► Open Fit a Polynomial Demo

- ► We are only fitting our model using data that is given
- Data usually contains noise
- When a model becomes too complex, it will start to fit the noise in the data
- What happens if we apply our model to predict some data that the model has never seen before? It will not work well.
- ► This is called overfitting

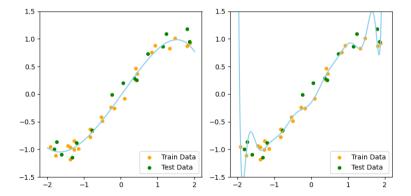


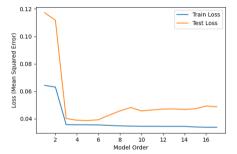
Solution to Overfitting

- Split the data set into a train set and a test set
- Train set will be used to train the model
- The test set will not be seen by the model during the training process
- Use test set to evaluate the model when a model is trained

Solution to Overfitting

With the training and test sets shown, which one do you think is the better model now?





- Plot of train loss and test loss for different model order
- Initially both train and test loss go down as model order increase
- But at a certain point, test loss start to increase because of overfitting

Outline

- 1. Review
- 3. Regularization
- 4. Optimization

How can we prevent overfitting without knowing the model order before-hand?

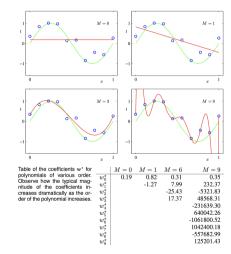
- **Regularization:** methods to prevent overfitting
- One way to regularize is by model order selection.
- Is there another way?

How can we prevent overfitting without knowing the model order before-hand?

- **Regularization:** methods to prevent overfitting
- One way to regularize is by model order selection.
- Is there another way?
- We can change the cost function

Weight Based Regularization

- Looking back at the polynomial overfitting
- Notice that weight value increases with overfitting



Weight Based Regularization

New Cost Function:

$$J(W) = \frac{1}{N}||Y - XW||^2 + \lambda||W||^2$$

- Penalize complexity by simultaneously minimizing weight values.
- \blacktriangleright We call λ a hyper-parameter
 - $-\lambda$ determines relative importance

Table of the coefficients \mathbf{w}^* for M =9 polynomials with various values for the regularization parameter λ . Note that $\ln \lambda = -\infty$ corresponds to a model with no regularization, i.e., to the graph at the bottom right in Figure 1.4. We see that, as the value of λ increases, the typical magnitude of the coefficients gets smaller.

	$\ln \lambda = -\infty$	$\ln \lambda = -18$	$\ln \lambda = 0$
v_0^*	0.35	0.35	0.13
v_1^*	232.37	4.74	-0.05
v_2^*	-5321.83	-0.77	-0.06
v_3^*	48568.31	-31.97	-0.05
v_4^{\star}	-231639.30	-3.89	-0.03
v_5^*	640042.26	55.28	-0.02
v_6^{\star}	-1061800.52	41.32	-0.01
v_7^{\star}	1042400.18	-45.95	-0.00
v_8^{\star}	-557682.99	-91.53	0.00
υč	125201.43	72.68	0.01

Tuning Hyper-parameters

Motivation: never determine a hyper-parameter based on training data

- **Hyper-Parameter:** a parameter of the algorithm that is not a model-parameter solved for in optimization. Example: λ weight regularization value vs. model weights (W)
- Solution: Split dataset into three:
 - Training Set: to compute the model parameters (W)
 - Validation Set: to tune the hyper-parameters (λ)
 - Testing Set: to compute the performance of the ML algorithm (MSE)

Regularization

▶ Open Overfitting, Weight Regularization Demo

- 1. Review

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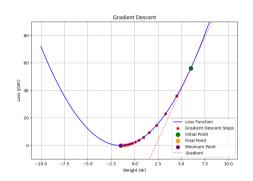
Non-linear Optimization

- Cannot rely on closed form solutions
 - Computation Efficiency: operations like inverting a matrix is not efficient
 - For more complex problems such as neural networks, a closed form solution is not always available
- ▶ Need an optimization technique to find an optimal solution
 - Machine learning practitioners use **gradient** based methods

Update Rule:

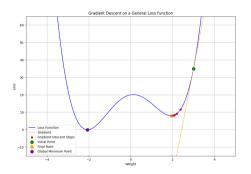
Repeat {
$$W_{\rm new} = W - \alpha \nabla J(W)$$
 }

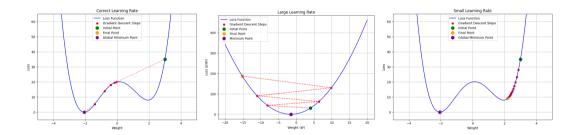
 α is the learning rate



Loss Function Contours

- Most loss function contours are not perfectly parabolic
- ► Our goal is to find a solution that is very close to global minimum by the right choice of hyper-parameters.





Gradient Descent Animations

