

Jennifer Yang

(541) 908-8158 | jennifer.yang017@gmail.com | jennifey.github.io/

EDUCATION

Carnegie Mellon University

Master of Science in Robotics

Bachelor of Science in Mechanical Engineering

Pittsburgh, PA

Aug. 2024

May 2023

EXPERIENCE

Research Assistant

May 2023 – Aug. 2024

Carnegie Mellon University Zoom Lab

Pittsburgh, PA

- Built an affordable, easy-to-manufacture, omnidirectional quadruped robot with 3-DOF linear Delta actuators.
- Developed simulations in PyBullet to test potential walking gaits, enabling rapid qualitative gait assessments.
- Applied trajectory optimization to generate 4 different gaits with 4+ variations, and 1 rotation gait.
- Characterized robot performance through experiments, using computer vision to track and analyze position errors.
- Authored a comprehensive master's thesis and defended it in a formal presentation.

Mechanical Engineering Intern

May 2022 – May 2023

Gecko Robotics

Pittsburgh, PA

- Designed, prototyped, and assembled a dedicated testing unit for the TOKA 4 Robot Center Body, streamlining build and verification processes by reducing bottlenecks and saving 200+ hours throughout the build cycle.
- Performed thermal testing to ensure system reliability and prevent overheating during extended operation.

Resident Assistant

Aug. 2021 – May 2023

Carnegie Mellon University

Pittsburgh, PA

- Fostered community engagement among 40+ residents by organizing events, leading House Council initiatives, and mediating conflicts to maintain a positive living environment.

Research Experiences for Undergraduates Student Intern

Jun. 2021 – Aug. 2021

Oregon State University Laboratory for Robotics and Applied Mechanics

Corvallis, OR

- Refined the sidewinding gait of a soft, pneumatic robot snake by assessing 2 control schemes and 8 flow rates.
- Enhanced understanding of its capabilities by evaluating performance across 3 terrains with 3 robot materials.

LEADERSHIP

Society of Women Engineers | Carnegie Mellon University

Aug. 2019 – Sep. 2022

- Coordinated the 2020 – 2022 STEM Career Fairs by managing catering for 200+ people, recruiting companies to attend, and collaborating with CMU to promote the event.

PROJECTS

Haptic Mouse | Carnegie Mellon University

Mar. 2024 – May 2024

- Worked with a team of 5 to implement haptic feedback on a computer mouse augmented with a rotary Delta actuator, improving learning experiences for visually impaired users through user studies.

BeanBag Pick and Place | Carnegie Mellon University

Oct. 2023 – Dec. 2023

- Contributed to a team of 5 in utilizing behavior cloning to develop and test a pick and place network for deformable objects with modified transporter networks.

Posture Enhancing Chair | Carnegie Mellon University

Aug. 2022 – Dec. 2022

- Collaborated within a 5-person team to design and prototype an electro-mechanical device integrated into a chair, featuring a sensor system for posture detection, and haptic and visual feedback for posture correction.
- Evaluated feedback mechanism options through user surveys and testing with stakeholders.

Bellcranks and Dampers System Lead | Carnegie Mellon Racing

Aug. 2021 – May 2022

- Engineered and manufactured the bellcranks and dampers system using kinematic simulations and stress analysis, ensuring it met specified design goals through kinematic simulations and stress analysis.

SKILLS

Programming: Python, C/C++, MATLAB, Julia, Arduino, PyBullet

Software: CAD (SolidWorks), CAM (HSMWorks, MasterCAM), FEA (SolidWorks FEA, ANSYS)

Machines: CNC Mill, Vertical Mill, Lathe, 3D Printer, Laser Cutter

Languages: French (Conversant), Mandarin (Conversant)