

## Problem Set 2

1. ARMA( $p, q$ ) Model:

$$y_t = \sum_{i=1}^p \phi_i y_{t-i} + \sum_{i=0}^q \theta_i \varepsilon_{t-i}, \theta_0 = 1$$

Stationary if roots of

$$1 - \phi_1 z - \dots - \phi_p z^p = 0$$

lie outside the unit circle.

Invertible if roots of

$$1 + \theta_1 z + \dots + \theta_q z^q = 0$$

lie outside the unit circle

$$(a) y_t = y_{t-1} + \varepsilon_t + \frac{1}{2} \varepsilon_{t-1} + \frac{1}{2} \varepsilon_{t-2}$$

$\Rightarrow$  ARMA(1, 2)

$$1 - \phi_1 z = 1 - 1 = 0$$

$\Rightarrow$  not stationary

$$1 + \theta_1 z + \theta_2 z^2 = 1 + \frac{1}{2} z + \frac{1}{2} z^2 = 0$$

$$z^2 + z + 2 = 0$$

$$z = \frac{-1 \pm \sqrt{1 - 4(1)(2)}}{2}$$

$$= \frac{-1 \pm i\sqrt{7}}{2}$$

$$R = \sqrt{\left(\frac{-1}{2}\right)^2 + \left(\frac{\sqrt{7}}{2}\right)^2} = \sqrt{\frac{1}{4} + \frac{7}{4}} = \sqrt{2} > 1$$

$\Rightarrow$  invertible

$$(b) y_t = 2y_{t-1} - 2y_{t-2} + \varepsilon_t - \frac{3}{4}\varepsilon_{t-1}$$

$\Rightarrow$  ARMA(2,1)

$$1 - \Phi_1 z - \Phi_2 z^2 = 1 - 2z + 2z^2 = 0$$

$$2z^2 - 2z + 1 = 0$$

$$z = \frac{2 \pm \sqrt{4 - 4(2)(1)}}{4}$$

$$= \frac{2 \pm 2i}{4}$$

$$R = \sqrt{\left(\frac{-1}{2}\right)^2 + \left(\frac{1}{2}\right)^2} = \sqrt{\frac{1}{2}} < 1$$

$\Rightarrow$  not stationary

$$1 + \Theta_1 z = 1 - \frac{3}{4}z = 0$$

$$z = \frac{4}{3} > 1$$

$\Rightarrow$  invertible

$$(c) y_t = \frac{5}{4}y_{t-1} + \frac{3}{2}y_{t-2} + \varepsilon_t - 2\varepsilon_{t-1}$$

$\Rightarrow$  ARMA(2,1)

$$1 - \Phi_1 z - \Phi_2 z^2 = 1 - \frac{5}{4}z - \frac{3}{2}z^2 = 0$$

$$6z^2 + 5z - 4 = 0$$

$$z = \frac{-5 \pm \sqrt{25 - 4(6)(-4)}}{12}$$

$$= \frac{-5 \pm 4\sqrt{6}}{12}$$

$$z_1 = -1.233 < 1$$

$$z_2 = 0.3998 < 1$$

$\Rightarrow$  not stationary

$$1 + \Phi_1 z = 1 - 2z = 0$$

$$z = \frac{1}{2} < 1$$

$\Rightarrow$  not invertible

$$2. y_t = \phi_1 y_{t-1} + \phi_2 y_{t-2} + \varepsilon_t + \theta, \varepsilon_t \sim WN(0, \sigma^2)$$

Recall  $E(\varepsilon_t^2) = \sigma^2$  and  $\gamma_h = E[y_t y_{t-h}]$   
 $E(\varepsilon_t \varepsilon_{t-1}) = 0$   $\gamma_0 = E[y_t^2]$   
 $E(\varepsilon_t y_t) = 0$

$$\gamma_0 = E(y_t^2)$$

$$\begin{aligned} &= \phi_1 E(y_t y_{t-1}) + \phi_2 E(y_t y_{t-2}) + E(y_t \varepsilon_t) \\ &\quad + \theta, \underline{E(y_t \varepsilon_{t-1})} \\ &= \phi_1 E(y_{t-1} \varepsilon_{t-1}) + \theta, E(\varepsilon_{t-1}^2) \\ &= \phi_1 \sigma^2 + \theta, \sigma^2 \end{aligned}$$

$$\begin{aligned} &= \phi_1 \gamma_1 + \phi_2 \gamma_2 + \sigma^2 + \theta, (\phi_1 \sigma^2 + \theta, \sigma^2) \\ &= \phi_1 \gamma_1 + \phi_2 \gamma_2 + (\theta, \phi_1 + \theta^2 + 1) \sigma^2 \end{aligned}$$

$$\gamma_1 = E(y_t y_{t-1})$$

$$\begin{aligned} &= \phi_1 E(y_{t-1}^2) + \phi_2 E(y_{t-1} y_{t-2}) + E(\varepsilon_t y_{t-1}) \\ &\quad + \theta, E(\varepsilon_{t-1} y_{t-1}) \\ &= \phi_1 \gamma_0 + \phi_2 \gamma_1 + \theta, \sigma^2 \end{aligned}$$

$$\gamma_2 = E(y_t y_{t-2})$$

$$\begin{aligned} &= \phi_1 E(y_{t-1} y_{t-2}) + \phi_2 E(y_{t-2}^2) + E(\varepsilon_t y_{t-2}) \\ &\quad + \theta, E(\varepsilon_{t-1} y_{t-2}) \\ &= \phi_1 \gamma_1 + \phi_2 \gamma_0 \end{aligned}$$

$$E(\varepsilon_t y_{t-h}) = 0 \text{ for } h \geq 1$$

$$E(\varepsilon_{t-1} y_{t-h}) = 0 \text{ for } h \geq 2$$

$$\Rightarrow \gamma_h = \phi_1 \gamma_{h-1} + \phi_2 \gamma_{h-2} \text{ for } h \geq 2$$

### 3. AR(2)

$$y_t = 3 + 0.3y_{t-1} + 0.04y_{t-2} + \varepsilon_t, \quad \varepsilon_t \sim WN(0, .25)$$

$$y_{99} = 4$$

$$y_{100} = 3.5$$

(a) One-step forecast:

$$\begin{aligned}\hat{y}_{101|100} &= 3 + 0.3 E[y_{100} | \mathcal{S}_{100}] + 0.04 E[y_{99} | \mathcal{S}_{100}] \\ &\quad + E[\varepsilon_{101} | \mathcal{S}_{100}] \\ &= 3 + 0.3 y_{100} + 0.04 y_{99} \\ &= 3 + 0.3(3.5) + 0.04(4) \\ &= 4.21\end{aligned}$$

$$\text{var}(e_{101}) = \sigma^2 = 0.25$$

$$\sigma = \sqrt{0.25} = 0.5$$

$$\begin{aligned}CI &= \hat{y}_{101|100} \pm 1.96 \sigma \left( \sum_{i=0}^{\infty} \phi_1^{2i} \right)^{1/2} \\ &= 4.21 \pm 1.96(0.5)(1) \\ &= 4.21 \pm 0.98\end{aligned}$$

Two-Step Forecast:

$$\begin{aligned}\hat{y}_{102|100} &= 3 + 0.3 E[y_{101} | \mathcal{S}_{100}] + 0.04 E[y_{100} | \mathcal{S}_{100}] \\ &= 3 + 0.3 \hat{y}_{101|100} + 0.04 y_{100} \\ &= 3 + 0.3(4.21) + 0.04(3.5) \\ &= 4.403\end{aligned}$$

$$\text{var}(e_{102}) = \sigma^2 (1 + \phi_1^2) = 0.25(1 + 0.3^2) = 0.2725$$

$$\tilde{\sigma} = \sqrt{0.2725} = 0.522$$

$$\begin{aligned}CI &= \hat{y}_{102|100} \pm 1.96 \tilde{\sigma} \left( \sum_{i=0}^{\infty} \phi_1^{2i} \right)^{1/2} \\ &= 4.403 \pm 1.96(0.522)(1 + 0.3^2) \\ &= 4.403 \pm 1.115\end{aligned}$$

(b) 100-step forecast:

Since  $|\phi_1|, |\phi_2| < 1$ , we know

$$\hat{y}_{200|100} \rightarrow \mu = \frac{\phi_0}{1-\phi_1-\phi_2} = \frac{3}{1-0.3-0.04} = 4.545,$$

the unconditional mean.

Additionally,

$$\text{var}(e_{200}) \rightarrow \frac{\sigma^2}{1-\phi_1^2-\phi_2^2} = \frac{0.25}{1-0.09-0.0016} = 0.275$$

#### 4. ARMA(1,1)

$$y_t = \phi_0 + \phi_1 y_{t-1} + \varepsilon_t + \theta_1 \varepsilon_{t-1}, \quad \varepsilon_t \sim WN(0, \sigma^2)$$

(a) One-Step Forecast:

$$\begin{aligned}\hat{y}_{T+1|T} &= E[y_{T+1} | \mathcal{I}_T] \\ &= \phi_0 + \phi_1 E[y_T | \mathcal{I}_T] \\ &\quad + E[\varepsilon_{T+1} | \mathcal{I}_T] + \theta_1 E[\varepsilon_T | \mathcal{I}_T] \\ &= \phi_0 + \phi_1 y_T + \theta_1 \varepsilon_T\end{aligned}$$

$$\begin{aligned}e_{T+1} &= y_{T+1} - \hat{y}_{T+1|T} \\ &= (\cancel{\phi_0} + \cancel{\phi_1} y_T + \varepsilon_{T+1} + \cancel{\theta_1} \varepsilon_T) \\ &\quad - (\cancel{\phi_0} + \cancel{\phi_1} y_T + \cancel{\theta_1} \varepsilon_T) \\ &= \varepsilon_{T+1}\end{aligned}$$

$$\begin{aligned}
 (b) \hat{y}_{T+2|T} &= E[y_{T+2} | \mathcal{I}_T] \\
 &= \phi_0 + \phi_1 E[y_{T+1} | \mathcal{I}_T] \\
 &\quad + E[\varepsilon_{T+2} | \mathcal{I}_T] + \theta_1 E[\varepsilon_{T+1} | \mathcal{I}_T] \\
 &= \phi_0 + \phi_1 \hat{y}_{T+1} \\
 &= \phi_0 + \phi_1 \phi_0 + \phi_1^2 y_T + \phi_1 \theta_1 \varepsilon_T
 \end{aligned}$$

$$\begin{aligned}
 \hat{y}_{T+3|T} &= E[y_{T+3} | \mathcal{I}_T] \\
 &= \phi_0 + \phi_1 \hat{y}_{T+2} \\
 &= \phi_0 + \phi_1 \phi_0 + \phi_1^2 \phi_0 + \phi_1^3 y_T + \phi_1^2 \theta_1 \varepsilon_T
 \end{aligned}$$

$\stackrel{=h}{\boxed{\phantom{0}}}$        $\stackrel{=h-1}{\boxed{\phantom{0}}}$

geometric series

At  $h \geq 2$ , the expected error terms are 0.

By forward iteration,

$$\begin{aligned}
 \hat{y}_{T+h|T} &= E[y_{T+h} | \mathcal{I}_T] = \mu \\
 &= \phi_0 \left( \frac{1 - \phi_1^h}{1 - \phi_1} \right) + \phi_1^h y_T + \phi_1^{h-1} \theta_1 \varepsilon_T
 \end{aligned}$$

If  $|\phi_1| < 1$ , then  $\phi_1^h \rightarrow 0$  as  $h \rightarrow \infty$ .

Therefore

$$\lim_{h \rightarrow \infty} \hat{y}_{T+h|T} = \phi_0 \left( \frac{1}{1 - \phi_1} \right) = \mu,$$

meaning the  $h$ -step forecast decays exponentially to the unconditional mean,

$$\mu = \frac{\phi_0}{1 - \phi_1}.$$

$$\begin{aligned}
 (c) e_{T+1} &= y_{T+1} - \hat{y}_{T+1|T} \\
 &= (\cancel{\phi}_0 + \phi_1 \cancel{y}_T + \varepsilon_{T+1} + \theta_1 \cancel{\varepsilon}_T) \\
 &\quad - (\cancel{\phi}_0 + \phi_1 \cancel{y}_T + \theta_1 \cancel{\varepsilon}_T) \\
 &= \varepsilon_{T+1}
 \end{aligned}$$

$$\begin{aligned}
 \text{var}(e_{T+1}) &= \text{var}(\varepsilon_{T+1}) \\
 &= \sigma^2
 \end{aligned}$$

$$\begin{aligned}
 e_{T+2} &= y_{T+2} - \hat{y}_{T+2|T} \\
 &= (\cancel{\phi}_0 + \phi_1 y_{T+1} + \varepsilon_{T+2} + \theta_1 \varepsilon_{T+1}) \\
 &\quad - (\cancel{\phi}_0 + \phi_1 \phi_0 + \phi_1^2 y_T + \phi_1 \theta_1 \varepsilon_T) \\
 &= (\phi_1 \phi_0 + \phi_1^2 \cancel{y}_T + \phi_1 \varepsilon_{T+1} + \phi_1 \theta_1 \cancel{\varepsilon}_T \\
 &\quad + \varepsilon_{T+2} + \theta_1 \varepsilon_{T+1}) - (\phi_1 \phi_0 + \phi_1^2 \cancel{y}_T + \phi_1 \theta_1 \cancel{\varepsilon}_T) \\
 &= \varepsilon_{T+2} + (\theta_1 + \phi_1) \varepsilon_{T+1}
 \end{aligned}$$

$$\text{var}(e_{T+2}) = (1 + \theta_1 + \phi_1) \sigma^2$$

$$\begin{aligned}
 e_{T+3} &= y_{T+3} - \hat{y}_{T+3|T} \\
 &= (\cancel{\phi}_0 + \phi_1 y_{T+2} + \varepsilon_{T+3} + \theta_1 \varepsilon_{T+2}) \\
 &\quad - (\cancel{\phi}_0 + \phi_1 \phi_0 + \phi_1^2 \phi_0 + \phi_1^3 y_T + \phi_1^2 \theta_1 \varepsilon_T) \\
 &= (\phi_1 \phi_0 + \phi_1^2 y_{T+1} + \phi_1 \varepsilon_{T+2} + \phi_1 \theta_1 \varepsilon_{T+1} \\
 &\quad + \varepsilon_{T+3} + \theta_1 \varepsilon_{T+2}) \\
 &\quad - (\phi_1 \phi_0 + \phi_1^2 \phi_0 + \phi_1^3 y_T + \phi_1^2 \theta_1 \varepsilon_T) \\
 &= \phi_1^2 \phi_0 + \phi_1^3 \cancel{y}_T + \phi_1^2 \varepsilon_{T+1} + \phi_1^2 \theta_1 \cancel{\varepsilon}_T \\
 &\quad + \phi_1 \varepsilon_{T+2} + \phi_1 \theta_1 \varepsilon_{T+1} + \varepsilon_{T+3} + \theta_1 \varepsilon_{T+2} \\
 &\quad - (\phi_1^2 \phi_0 + \phi_1^3 \cancel{y}_T + \phi_1^2 \theta_1 \cancel{\varepsilon}_T) \\
 &= \varepsilon_{T+3} + (\phi_1 + \theta_1) \varepsilon_{T+2} + \phi_1 (\phi_1 + \theta_1) \varepsilon_{T+1}
 \end{aligned}$$

$$\text{var}(e_{T+3}) = (1 + \phi_1 + \phi_1 + \phi_1 \theta_1 + \phi_1^2) \sigma^2$$

The coefficient of  $\sigma^2$  increases with each forecast. Hence the variance grows as  $h \rightarrow \infty$ .