

04_tasks

October 28, 2025

```
[64]: import numpy as np
import matplotlib.pyplot as plt
import pandas as pd
```

1 Numerical Methods for Ordinary Differential Equations

1.1 Assignment: Solving an Initial Value Problem

Objective: Write a program to numerically solve a given Initial Value Problem (IVP) using various one-step methods, and perform a convergence analysis by comparing the numerical results to the exact solution.

1.1.1 Exercise

Consider the initial value problem (IVP)

$$u' = \frac{u^2 + u}{t}, \quad 1 \leq t \leq 5, \quad u(1) = -2,$$

whose exact solution is $u(t) = \frac{2t}{1-2t}$.

Part A: Implementation

Write a program (using a language like Python, MATLAB, or C++) to solve this IVP using the numerical methods listed below. Note that for the **Backward Euler method**, you will need to solve a quadratic equation for U^{n+1} at each time step.

1. Forward Euler method (FE):

$$U^{n+1} = U^n + kf(U^n, t_n).$$

2. Backward Euler method (BE):

$$U^{n+1} = U^n + kf(U^{n+1}, t_{n+1}).$$

(Hint: This is an implicit method; rearrange it into a quadratic equation $AU^2 + BU + C = 0$ for U^{n+1} and use the quadratic formula.)

3. Explicit midpoint RK2:

$$\begin{aligned}k_1 &= f(U^n, t_n) \\k_2 &= f\left(U^n + \frac{k}{2}k_1, t_n + \frac{k}{2}\right) \\U^{n+1} &= U^n + kk_2\end{aligned}$$

4. Explicit trapezoidal RK2 (Improved Euler):

$$\begin{aligned}k_1 &= f(U^n, t_n) \\k_2 &= f(U^n + kk_1, t_n + k) \\U^{n+1} &= U^n + \frac{k}{2}(k_1 + k_2)\end{aligned}$$

5. Heun's method (RK3):

$$\begin{aligned}k_1 &= f(U^n, t_n) \\k_2 &= f\left(U^n + \frac{k}{3}k_1, t_n + \frac{k}{3}\right) \\k_3 &= f\left(U^n + \frac{2k}{3}k_2, t_n + \frac{2k}{3}\right) \\U^{n+1} &= U^n + \frac{k}{4}(k_1 + 3k_3)\end{aligned}$$

6. Standard RK4:

$$\begin{aligned}k_1 &= f(U^n, t_n) \\k_2 &= f\left(U^n + \frac{k}{2}k_1, t_n + \frac{k}{2}\right) \\k_3 &= f\left(U^n + \frac{k}{2}k_2, t_n + \frac{k}{2}\right) \\k_4 &= f(U^n + kk_3, t_n + k) \\U^{n+1} &= U^n + \frac{k}{6}(k_1 + 2k_2 + 2k_3 + k_4)\end{aligned}$$

```
[ ]: def one_step_method_solver(f, k, u0, t0, tf, method):  
    """  
    Function to implement differents one-step methods and solve the ODE  $u' = f(u, t)$ .  
  
    Parameters  
    f: callable  
        Function that defines the ODE.  
    k: float  
        Time step.  
    u0: float  
        Initial condition.  
    t0: float  
        Initial time.
```

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tf: float
    Final time.
method: str

"""
N = int((tf-t0)/k)
U = np.zeros(N+1)
U[0]=u0
T = np.linspace(t0, tf, N+1)

def FE_method(f, k):
    for n in range(0, N):
        U[n+1] = U[n] + k*f(U[n], T[n])
    return U, T

def BE_method(k):
    for n in range(N):
        a = k / T[n+1]
        U[n+1] = (1 - a - np.sqrt((1 - a)**2 - 4*a*U[n])) / (2*a)  # ␣
    ↪negative root for continuity
    return U, T

def RK2_midpoint(f, k):
    for n in range(0, N):
        k1 = f(U[n], T[n])
        k2 = f(U[n] + k*k1/2, T[n] + k/2)
        U[n+1] = U[n] + k*k2
    return U, T

def RK2_trapezoidal(f, k):
    for n in range(0, N):
        k1 = f(U[n], T[n])
        k2 = f(U[n]+k*k1, T[n] + k)
        U[n+1] = U[n] + k/2 * (k1+k2)
    return U, T

def RK3(f, k):
    for n in range(0, N):
        k1 = f(U[n], T[n])
        k2 = f(U[n] + k*k1/3, T[n] + k/3)
        k3 = f(U[n] + 2*k*k2/3, T[n] + 2*k/3)
        U[n+1] = U[n] + k/4 * (k1 + 3*k3)
    return U, T

def RK4(f, k):
    for n in range(0, N):
        k1 = f(U[n], T[n])

```

```

        k2 = f(U[n] + k*k1/2, T[n] + k/2)
        k3 = f(U[n] + k*k2/2, T[n] + k/2)
        k4 = f(U[n] + k*k3, T[n] + k)
        U[n+1] = U[n] + k/6 * (k1 + 2*k2 + 2*k3 + k4)
    return U, T

if method=="FE":
    U_sol, T_sol = FE_method(f, k)

if method=="BE":
    U_sol, T_sol = BE_method(k)

if method=="Midpoint":
    U_sol, T_sol = RK2_midpoint(f, k)

if method=="Trapezoidal":
    U_sol, T_sol = RK2_trapezoidal(f, k)

if method=="RK3":
    U_sol, T_sol = RK3(f, k)

if method=="RK4":
    U_sol, T_sol = RK4(f, k)

return U_sol, T_sol

```

```

[90]: F = lambda x, t: (x**2 + x)/t
      u,t = one_step_method_solver(F, 0.1, -2, 1, 5, method="BE")

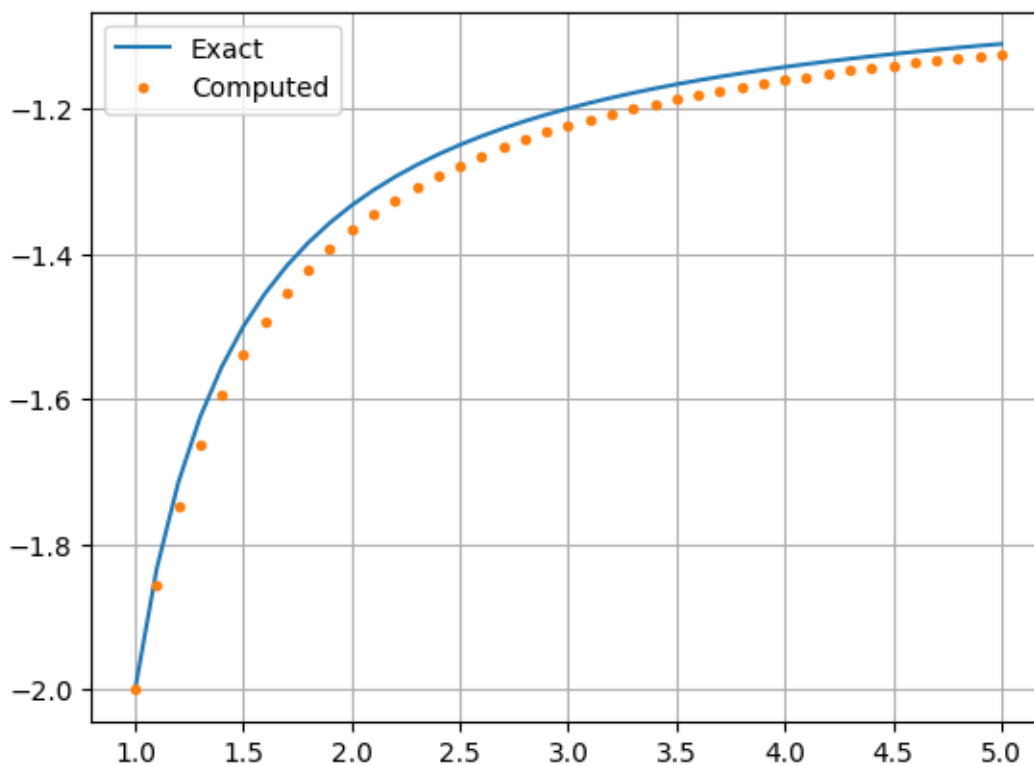
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```

[91]: t_points= np.linspace(1, 5, len(y))
      f_sol = lambda t: 2*t/(1-2*t)

      plt.figure()
      plt.plot(t_points, f_sol(t_points), label='Exact')
      plt.plot(t, u, '.', label='Computed')
      plt.plot()
      plt.legend()
      plt.grid()
      plt.show()

```



1.1.2 Part B: Convergence Analysis

Analyze the **convergence** of each method. Compare the numerical solution against the exact solution $u(t)$ at the final time $t = 5$ for a sequence of step sizes:

$$k_m = \frac{0.2}{2^m}, \quad \text{for } m = 0, 1, \dots, 6.$$

The exact value at $t = 5$ is $u(5) = \frac{2(5)}{1-2(5)} = -\frac{10}{9}$.

Required Deliverables:

1. **Tabular Results:** For each method, present the results in a clear table format, showing k_m , the absolute error $\mathcal{E}(k_m) = |U^N(k_m) - u(5)|$, and the **estimated order of convergence** p for consecutive steps.

m	k_m	N	FE	BE	Midpoint	Trapezoidal	Heun	RK4
			Error \mathcal{E}	Error \mathcal{E}	RK2	RK2	RK3	
			Error \mathcal{E}	Error \mathcal{E}	Error \mathcal{E}	Error \mathcal{E}	Error \mathcal{E}	Error \mathcal{E}
0	0.2000	20						
1	0.1000	40						
2	0.0500	80						

m	k_m	N	FE Error \mathcal{E}	BE Error \mathcal{E}	Midpoint RK2 Error \mathcal{E}	Trapezoidal RK2 Error \mathcal{E}	Heun RK3 Error \mathcal{E}	RK4 Error \mathcal{E}
3	0.0250	160						
4	0.0125	320						
5	0.0063	640						
6	0.0031	1280						
Observed								
p								

```
[100]: f = lambda u,t: (u*u + u)/t
t0, tf, u0 = 1.0, 5.0, -2.0
u_exact_5 = -10.0/9.0

methods = ["FE", "BE", "Midpoint", "Trapezoidal", "RK3", "RK4"]
kms = [0.2/(2**m) for m in range(7)]

rows = []
for m, k in enumerate(kms):
    N = int((tf - t0)/k)
    row = {"m": m, "k_m": k, "N": N}
    for meth in methods:
        U, T = one_step_method_solver(f, k, u0, t0, tf, meth)
        err = abs(U[-1] - u_exact_5)
        row[f"{meth} Error "] = err
    rows.append(row)

table = pd.DataFrame(rows)

def observed_p(errs):
    p = [np.nan]
    for i in range(1, len(errs)):
        e_old, e_new = errs[i-1], errs[i]
        p.append(np.log(e_old/e_new)/np.log(2) if e_old>0 and e_new>0 else np.
        ↪nan)
    return p

for meth in methods:
    table[f"{meth} p"] = observed_p(table[f"{meth} Error "].to_numpy())

table
```

```
[100]:   m      k_m      N  FE Error  BE Error  Midpoint Error  \
0  0  0.200000    20   0.031373   0.027677   4.957013e-03
1  1  0.100000    40   0.014992   0.014144   1.048329e-03
2  2  0.050000    80   0.007367   0.007159   2.404533e-04
```

3	3	0.025000	160	0.003655	0.003603	5.759537e-05
4	4	0.012500	320	0.001821	0.001808	1.409647e-05
5	5	0.006250	640	0.000909	0.000905	3.487104e-06
6	6	0.003125	1280	0.000454	0.000453	8.671988e-07

	Trapezoidal Error	RK3 Error	RK4 Error	FE p	BE p \
0	1.105883e-03	6.404530e-04	4.867114e-06	NaN	NaN
1	2.891698e-04	6.879651e-05	6.692678e-08	1.065306	0.968436
2	7.164031e-05	7.872264e-06	1.616277e-09	1.025018	0.982313
3	1.772532e-05	9.388160e-07	2.538914e-10	1.011243	0.990525
4	4.403035e-06	1.145520e-07	2.019673e-11	1.005360	0.995078
5	1.096935e-06	1.414510e-08	1.389999e-12	1.002620	0.997489
6	2.737392e-07	1.757309e-09	9.126033e-14	1.001296	0.998731

	Midpoint p	Trapezoidal p	RK3 p	RK4 p
0	NaN	NaN	NaN	NaN
1	2.241379	1.935209	3.218686	6.184339
2	2.124263	2.013074	3.127485	5.371837
3	2.061732	2.014960	3.067864	2.670391
4	2.030619	2.009241	3.034840	3.652017
5	2.015232	2.005020	3.017628	3.860966
6	2.007595	2.002605	3.008863	3.928952

2. **Log-Log Plot:** Generate a single log-log plot showing the absolute error \mathcal{E} versus the step size k for **all six methods**.

```
[98]: plt.figure(figsize=(7,5))

# Cada método en la misma gráfica
for meth in methods:
    plt.loglog(
        table["k_m"],
        table[f"{meth} Error "],
        marker="o",
        label=meth
    )

plt.xlabel("Step size k", fontsize=11)
plt.ylabel("Absolute error ", fontsize=11)
plt.title("Convergence comparison of one-step methods", fontsize=12)
plt.grid(True, which="both", ls="--", alpha=0.6)
plt.legend()
plt.tight_layout()
plt.show()
```

