

# Exercise Sheet 3

1

$$a) z_t = \phi_0 + \phi_1 z_{t-1} + a_t$$

$E(\cdot)$

$$E(z_t) = E(\underbrace{\phi_0}_{\mu} + \underbrace{\phi_1}_{\phi_1} \underbrace{z_{t-1}}_{\mu} + \underbrace{a_t}_0)$$

$$[\text{Key assumption? } E(z_t) = E(z_{t-1})]$$

$$\Leftrightarrow (I - \phi_1) \cdot \mu = \phi_0$$

$$\Leftrightarrow \mu = (I - \phi_1)^{-1} \cdot \phi_0$$

Plugging in:

$$\mu = \begin{pmatrix} 0.25 & 0 \\ 0.25 & 0.5 \end{pmatrix}^{-1} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} -4 \\ 2 \end{pmatrix}$$

b) Eigenvalues of  $\phi_1$ :

$$|\phi_1 - I| \stackrel{!}{=} 0$$

$$= \begin{vmatrix} 0.75 & 0 \\ -0.25 & 0.5 \end{vmatrix}$$

$$= (0.75 - \lambda) \quad (0.5 - \lambda) \stackrel{!}{=} 0$$

$$\Rightarrow \left. \begin{array}{l} \lambda_1 = 0.75 \\ \lambda_2 = 0.5 \end{array} \right\} \text{stationary}$$

c) Yule-Walker:

$$\tilde{z}_t = z_t - \mu$$

$$\Rightarrow \tilde{z}_t = \phi_1 \tilde{z}_{t-1} + a_t \quad | \cdot \tilde{z}_{t-1}'$$

$$\Leftrightarrow \tilde{z}_t \tilde{z}_{t-1}' = \phi_1 \tilde{z}_{t-1} \tilde{z}_{t-1}' + a_t \tilde{z}_{t-1}'$$

$$\underline{\mathbb{F}(\cdot)} \quad \Gamma_l = \phi_1 \cdot \Gamma_{l-1} + \begin{cases} l=0: \Sigma_a \\ l \neq 0: Q_k \end{cases}$$

$$l=0: \underline{\Gamma_0} = \phi_1 \cdot \Gamma_{-1} + \Sigma_a$$

$$l=1: \Gamma_1 = \phi_1 \cdot \underline{\Gamma_0} + Q_k$$

$$l=2: \Gamma_2 = \phi_1 \cdot \Gamma_1 + Q_k$$

using  $\Gamma_{-1} = \Gamma_1'$ :

$$\Gamma_0 = \phi_1 \cdot (\phi_1 \Gamma_0') + \Sigma_a$$

$$\Leftrightarrow \Gamma_0 = \phi_1 \Gamma_0' \phi_1' + \Sigma_a$$

and  $P_0' = P_0$  since  $P_0$  is symmetric!

$$d) \begin{pmatrix} \delta_{11} & \delta_{12} \\ \delta_{21} & \delta_{22} \end{pmatrix} = \begin{pmatrix} \delta_{11} & \delta_{12} \\ \delta_{12} & \delta_{22} \end{pmatrix}$$

$$= \begin{pmatrix} 0.75 & 0 \\ -0.25 & 0.5 \end{pmatrix} \begin{pmatrix} \delta_{11} & \delta_{12} \\ \delta_{12} & \delta_{22} \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 0.75 & -0.25 \\ 0 & 0.5 \end{pmatrix}$$

$$= \begin{pmatrix} (0.75)^2 \delta_{11} & (-0.75 \cdot 0.25 \delta_{11}) + 0.5 \cdot 0.75 \delta_{12} \\ (-0.25)^2 \delta_{11} - 0.25 \cdot 0.5 \delta_{12} & (-0.75 \cdot 0.25 \delta_{11}) + 0.5 \cdot 0.75 \delta_{12} \\ (-0.25 \delta_{11} - 0.25 \cdot 0.5 \delta_{12}) & (-0.5 \cdot 0.25 \delta_{12} + (0.5)^2 \delta_{22}) \end{pmatrix}$$

$$+ \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\Rightarrow \delta_{11} = (0.75)^2 \delta_{11} + 1$$

$$\Leftrightarrow \delta_{11} = \frac{16}{7}$$

$$\Rightarrow \delta_{12} = \frac{1}{4} \cdot \left(-\frac{3}{4}\right) \cdot \frac{16}{7} + \frac{2}{4} \cdot \frac{3}{4} \cdot \delta_{12}$$

$$\Leftrightarrow \delta_{12} = -\frac{24}{35}$$

$$\Rightarrow \delta_{22} = \frac{1}{16} \delta_{11} - 2 \cdot \frac{1}{2} \cdot \frac{1}{4} \delta_{12} + \frac{1}{4} \delta_{22} + 1$$

$$= \frac{1}{\cancel{76}} \cdot \frac{\cancel{16}}{7} - \frac{1}{4} \cdot \left(-\frac{24}{35}\right) + \frac{1}{4} x_{22} + 1$$

$$\Leftrightarrow x_{22} = \frac{184}{105}$$


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$$P_1 = q_1 \cdot P_0$$

$$= \begin{pmatrix} 0.75 & 0 \\ -0.25 & 0.5 \end{pmatrix} \cdot \begin{pmatrix} \frac{16}{7} & -\frac{24}{35} \\ -\frac{24}{35} & \frac{184}{105} \end{pmatrix}$$



[2]

$$Z_t = \phi_0 + \phi_1 \cdot Z_{t-1} + \dots + \phi_p \cdot Z_{t-p} + a_t$$

$$\text{as VAR}(1): Z_t = \begin{pmatrix} \phi_0 \\ 0 \\ \vdots \end{pmatrix} + I_1 Z_{t-1} + \begin{pmatrix} a_t \\ 0 \\ \vdots \end{pmatrix}$$

with

$$Z_t = \begin{pmatrix} Z_t \\ Z_{t-1} \\ \vdots \\ Z_{t-p+1} \end{pmatrix}$$

and

$$Z_{t-1} = \begin{pmatrix} Z_{t-1} \\ Z_{t-2} \\ \vdots \\ Z_{t-p} \end{pmatrix}$$



$$\overline{\phi} = \overline{1}$$

$$\left( \begin{array}{cccc} \phi_1 & \phi_2 & \dots & \phi_p \\ \overline{1}_k & O_k & \dots & O_k \\ \vdots & \vdots & \ddots & \vdots \\ O_k & \overline{1}_k & \dots & O_k \end{array} \right)$$

$\Rightarrow$  can apply the formulas for a VAR(1) to check stationarity!

$$| \Phi - I | \stackrel{!}{=} 0$$

$$\Leftrightarrow (-1) \stackrel{!}{=} 0$$

$$\Rightarrow |\lambda| \left( I - \Phi_1 \frac{1}{\lambda} \right) \stackrel{!}{=} 0$$

since  $\lambda$   
is scalar  
 $I = I_{kp}$

$$\Leftrightarrow \lambda^{kp} \left| I - \Phi_1 \frac{1}{\lambda} \right| \stackrel{!}{=} 0 \text{ and let } \frac{1}{\lambda} =: z$$

$$\Rightarrow \left| I - \Phi_1 z \right| \stackrel{!}{=} 0$$

stationarity iff:  
all  $|z_i| > 1$   
 $(|\lambda| < 1)$

$$I_{kp} - \Phi_1 Z$$

=

$$\left( \begin{array}{cccc} \underline{I_k - \phi_1 Z} & -\phi_2 Z & -\phi_3 Z & \dots \\ \underline{I_k} & \underline{I_k} & \dots & \dots \\ \dots & \dots & \dots & \dots \\ \underline{I_k} & -\underline{I_k} & -\underline{I_k} & \dots \end{array} \right) \begin{array}{c} O_k \\ O_k \\ \dots \\ O_k \end{array}$$

$$\left( \begin{array}{cc} -\phi_{p-1} Z & -\phi_p Z \\ O_k & O_k \\ \dots & \dots \\ O_k & \dots \\ \dots & \dots \end{array} \right) \begin{array}{c} O_k \\ O_k \\ \dots \\ O_k \end{array}$$


$$\Rightarrow -I_k \cdot Z + I_k \cdot Z = O_k$$

Since adding multiples of columns to other columns does not affect the determinant:

$\Rightarrow$  column  $i' \cdot Z + \text{column } i-1$   $\forall i \in \{0, \dots, r\}$   
yields a triangular matrix

$$\Rightarrow \left( \begin{array}{ccc} I_k & -\phi_1 z - \phi_2 z^2 - \dots - \phi_p z^p & \vdots \\ & \ddots & \\ & & I_k \end{array} \right) \vdots \left( \begin{array}{ccc} -\phi_1 - \phi_2 z - \dots - \phi_{p-1} z^{p-1} & \vdots & \\ & \ddots & \\ & & I_k \end{array} \right)$$

$$\Rightarrow \left| I_k - \phi_1 z^{-1} \dots \phi_p z^{-p} \right| = \left( I_k - \phi_1 z^{-1} \dots \phi_p z^{-p} \right) \prod_{i=1}^{p-1} I_k$$

$$\stackrel{.}{=} \left| I_k - \phi_1 z^{-1} \dots \phi_p z^{-p} \right|$$

Since it  
is a  
triangular  
matrix



3 a) check if

$$|\underline{I}_2 - \phi_1 z - \phi_2 z^2| \stackrel{!}{=} 0$$

$$\Rightarrow \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} - \begin{pmatrix} 0.52 & 0.12 \\ 0.42 & 0.52 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0.25 & 0 \end{pmatrix} \stackrel{!}{=} 0$$

$$\Leftrightarrow \begin{vmatrix} 1-0.52 & -0.12 \\ -0.42-0.25z^2 & 1-0.52 \end{vmatrix}$$

$$= (1-0.52)^2 - (0.42+0.25z^2) \cdot 0.12$$

$$= 1 - z + 0.21z^2 - 0.025z^3 \stackrel{!}{=} 0$$

$\rightarrow R$

$\Rightarrow$  stationary

$$b) z_t = \phi_0 + \phi_1 z_{t-1} + \phi_2 z_{t-2} + a_t$$
$$\stackrel{\mathbb{E}(\cdot)}{=} \dots \Rightarrow \mu = \left( \begin{matrix} 1 & -\phi_1 & -\phi_2 \end{matrix} \right)^{-1} \phi_0$$

$$= \begin{pmatrix} 1-0.5 & -0.1 \\ -0.4-0.25 & 1-0.5 \end{pmatrix}^{-1} \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{228}{37} \\ \frac{360}{37} \end{pmatrix}$$

$$E(\tilde{z}_t \tilde{z}_{t-c}' ) = \phi_1 E(\tilde{z}_{t-1} \tilde{z}_{t-c}') \\ + \phi_2 E(\tilde{z}_{t-2} \tilde{z}_{t-c}') + \dots + E(a_t \tilde{z}_{t-c}')$$

$$\Rightarrow \ell=0: P_0 = \phi_1 P_{-1} + \phi_2 P_{-2} + \dots + a$$

$$\ell=1: P_1 = \phi_1 P_0 + \phi_2 P_{-1} + a_{ex1}$$

$$\ell=2: P_2 = \phi_1 P_1 + \phi_2 P_0 + a_{2x2}$$

$$A) \overbrace{\begin{pmatrix} r_1 & r_2 \end{pmatrix}}^{\text{row vector}} = (\phi_1, \phi_2) \begin{pmatrix} r_0 & r_1 \\ r_1 & r_0 \end{pmatrix}$$

$$\Leftrightarrow (\phi_1, \phi_2) = \begin{pmatrix} r_0 & r_1 \\ r_1 & r_0 \end{pmatrix}^{-1} (r_1, r_0)$$

