

# HW2 Report

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## Theory Problems (1-3)

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## Problem 4

In this problem, we implement the numerical method for Runge-Kutta (RK4) to solve the IVP

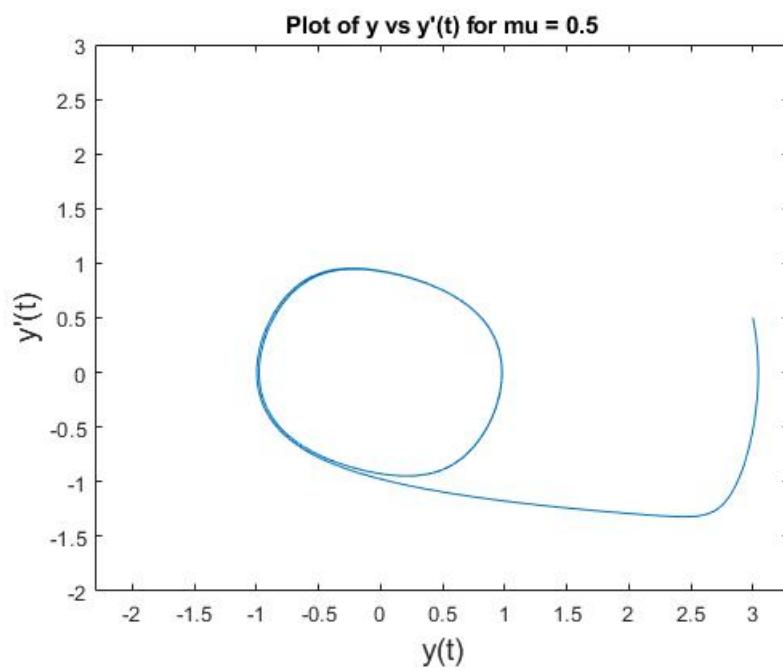
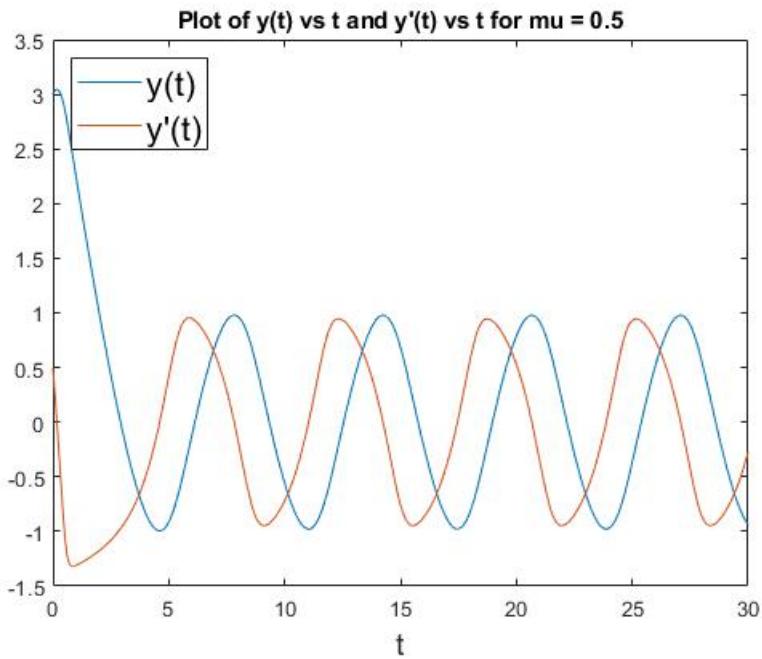
$$\begin{cases} y'' - \mu(2 - \exp(y'^2))y' + y = 0 \\ y(0) = y_0, \quad y'(0) = v_0 \end{cases}$$

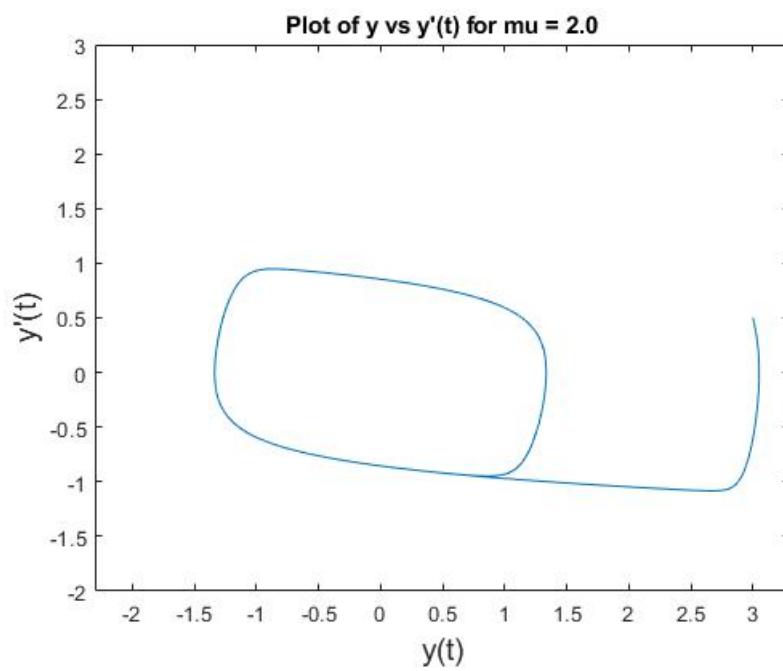
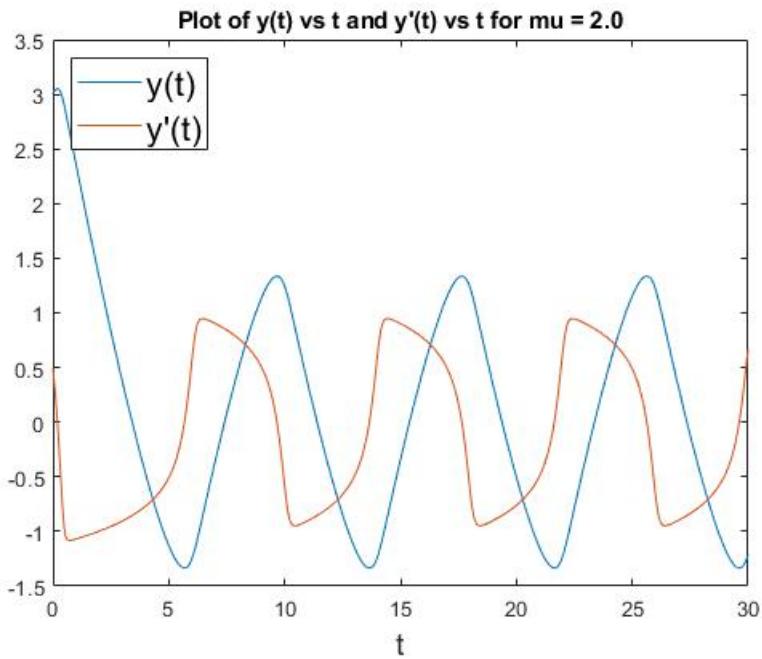
up to  $T = 30$ , where  $y_0 = 3$ ,  $v_0 = 0.5$ ,  $h = 0.025$ , and  $\mu \in \{0.5, 2, 4\}$ . We numerically solve this IVP for each value of  $\mu$  and create six figures below, where the first three are plots of  $y(t)$  and  $y'(t)$  both versus  $t$ , and the remaining three are simply  $y'(t)$  vs  $y(t)$ . In the following problems we're using methods for first order ODEs, hence we must convert the given second order ODE into a system of first order ODEs by letting

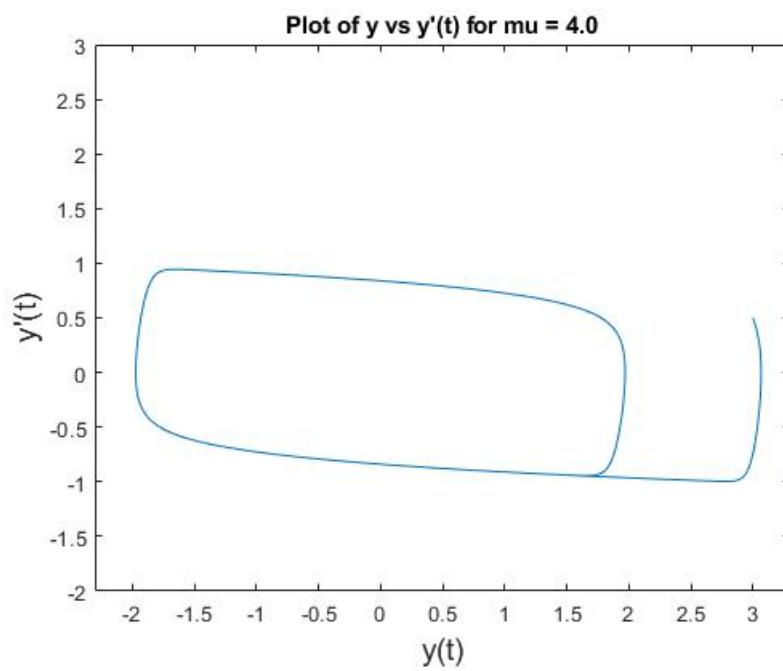
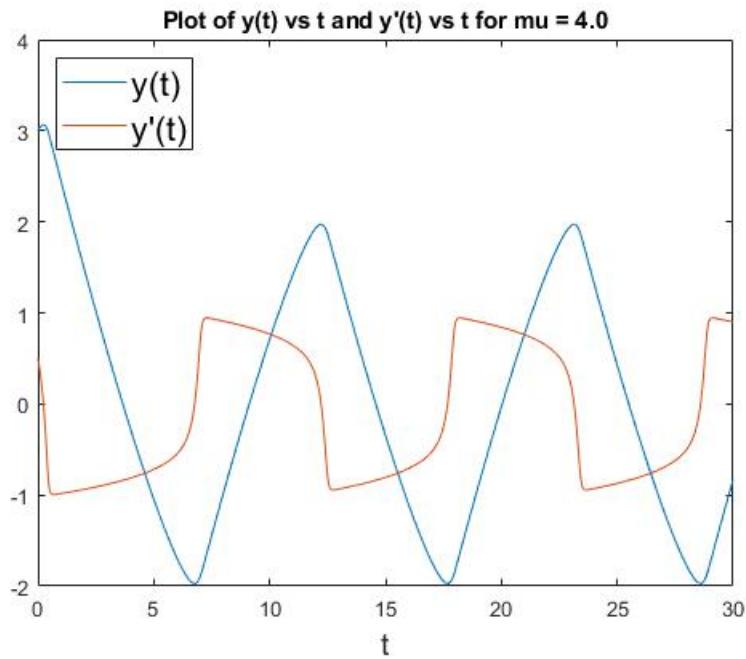
$$w(t) = \begin{bmatrix} w_1(t) \\ w_2(t) \end{bmatrix} = \begin{bmatrix} y(t) \\ y'(t) \end{bmatrix}.$$

This implies that

$$\frac{dw(t)}{dt} = \begin{bmatrix} w'_1(t) \\ w'_2(t) \end{bmatrix} = \begin{bmatrix} w_2(t) \\ \mu(2 - e^{w_2^2})w_2 - w_1 \end{bmatrix}.$$







## Problem 5

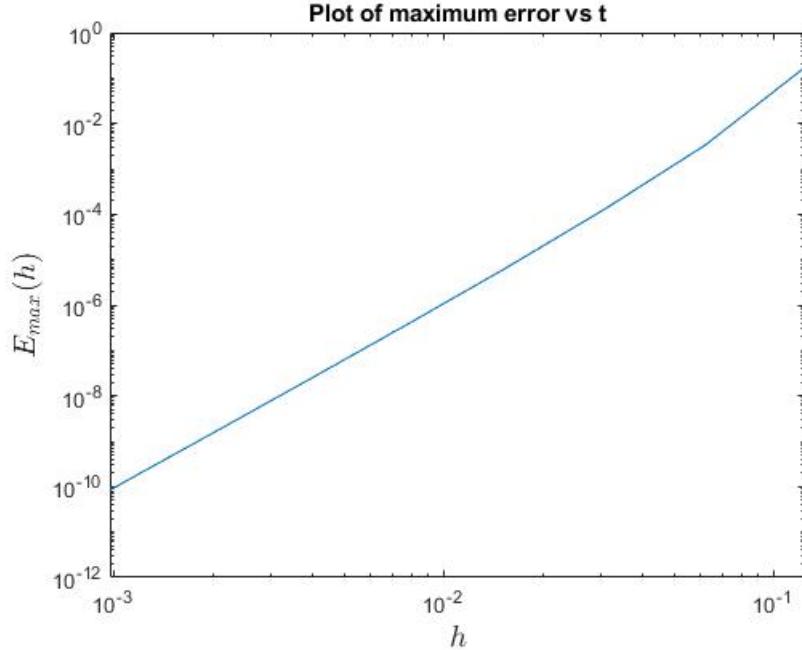
In this problem, we perform numerical error analysis for the same IVP in problem 4. Using  $y_0 = 3$ ,  $v_0 = 0.5$ ,  $\mu = 4$ , we again solve the IVP to  $T = 30$ . However, we now vary our step sizes so that  $h = \frac{1}{2^3}, \frac{1}{2^4}, \frac{1}{2^5}, \frac{1}{2^6}, \dots$ . We estimate errors in the numerical solution using

$$E_n(h) = \frac{1}{1 - (0.5)^4} \left( w_n(h) - w_{2n}(\frac{h}{2}) \right),$$

where  $E_n(h)$  is the error associated with the numerical solution  $w_n(h)$ . Then, for each time step size, we calculate

$$E_{\max}(h) = \max_{nh \in [0, 30]} \|E_n(h)\|$$

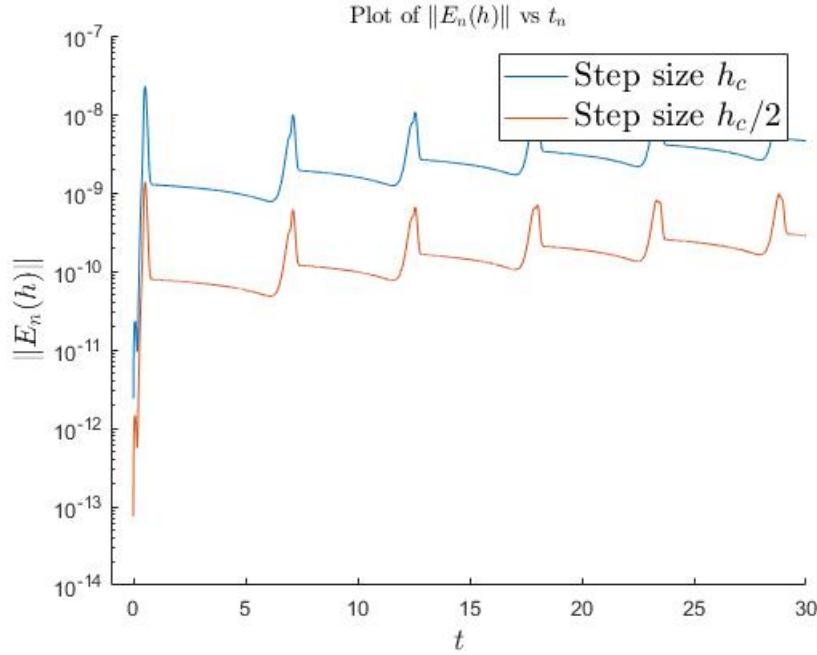
and plot the values for  $E_{\max}(h)$  versus  $h$  in a log-log scale plot, pictured below.



We can see that as the length of the step size increases, the maximum error increases. When  $h = \frac{1}{2^8} := h_c$ , we have that

$$E_{\max}(h) < 5 \times 10^{-8}.$$

Pictured below is one figure containing a plot of  $\|E_n(h)\|$  versus  $t_n$  respectively, for time step lengths  $h_c$  and  $h_c/2$ .

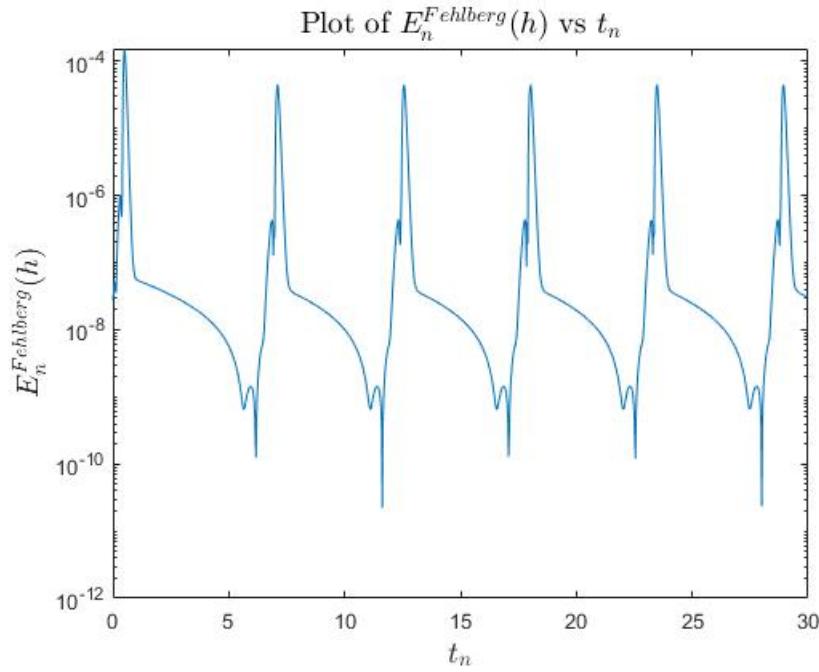


## Problem 6

In this problem, we implement the embedded Runge-Kutta method with orders 5 and 4 (Fehlberg 45) and solve the IVP in problem 4 to  $T = 30$ , using  $y_0 = 3$ ,  $v_0 = 0.5$ ,  $\mu = 4$ ,  $h = 0.025$ . For each time step, we compute

$$E_n^{(\text{Fehlberg})}(h) \approx \frac{e_n(h)}{h} = \frac{\|w_{n+1} - \tilde{w}_{n+1}\|}{h},$$

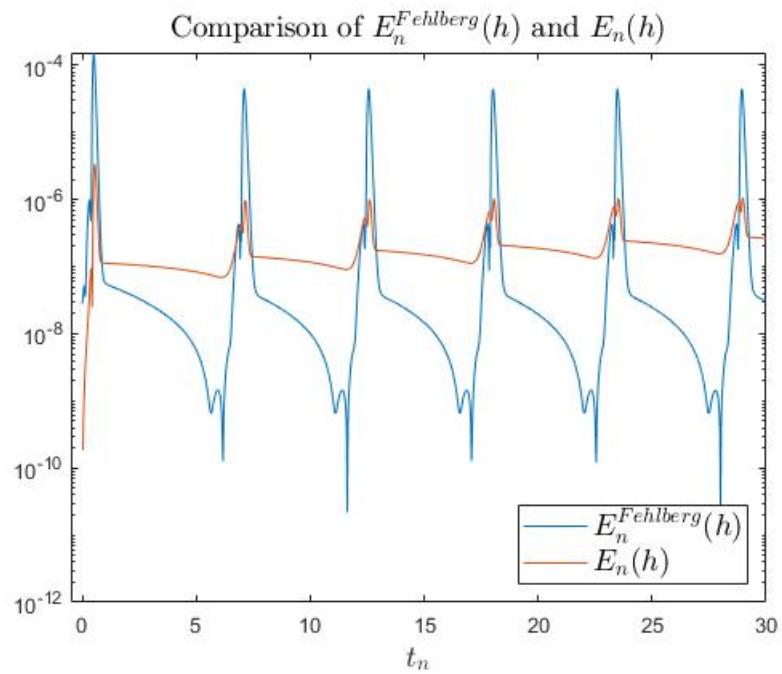
where, respectively,  $w_{n+1}$  and  $\tilde{w}_{n+1}$  are the vector results of the 5th order and 4th order RK methods in the Fehlberg method. Below is a logarithmic plot of  $E_n^{(\text{Fehlberg})}(h)$  versus  $t_n$ .



We also estimate the error  $E_n(h)$  by

$$E_n(h) = \frac{1}{1 - (0.5)^4} \left( w_n(h) - w_{2n}(\frac{h}{2}) \right),$$

and then (in the figure below) plot  $E_n^{(\text{Fehlberg})}(h)$  versus  $t_n$  as well as  $E_n(h)$  versus  $t_n$ ,



**Problem 1 (Theoretical)**

Suppose  $k$  satisfies the equation

$$k = h \exp(1+k) \quad \text{where } h \text{ is a small quantity}$$

P1

Recall the approach of iterative expansion we used in lecture.

Start with  $k = O(h)$ . Expand  $k$  iteratively into

$$k = a_1 h + a_2 h^2 + \dots$$

Find the coefficients  $a_1$  and  $a_2$ .

We have  $k = h \cdot \exp(1+k)$ .

Assuming  $k$  is bounded, we start with  $k = O(h)$ .

$$\Rightarrow k = h \cdot \exp(1+O(h)) = h \cdot e \cdot \exp(O(h))$$

Applying a Taylor expansion to  $\exp(O(h))$ ,

$$k = h e (1+O(h)) = e h + O(h^2).$$

Assuming that  $k$  can be written as

$$k = a_1 h + O(h^2), \quad \text{we have}$$

$$k = e h + O(h^2) = a_1 h + O(h^2) \Rightarrow e h = a_1 h,$$

hence  $\boxed{a_1 = e.}$

To find  $a_2$ , we write

$$k = h \cdot \exp(1 + e h + O(h^2)) = h e \cdot \exp(e h) \cdot \exp(O(h^2)).$$

Expanding  $\exp(O(h^2))$  as

$$\exp(O(h^2)) = 1 + O(h^2), \quad \text{then}$$

$$\dots \dots (1 + O(h^2)) = h e \cdot \exp(e h) (1 + O(h^2))$$

$$he \cdot \exp(ah) \cdot \exp(O(h^2)) = he \cdot \exp(ah)(1 + O(h^2)) \\ = he \cdot \exp(ah) + O(h^3).$$

Expanding  $\exp(ah)$  as  $\exp(ah) = 1 + ah + O(h^2)$ ,

We have

$$k = he \cdot (1 + ah + O(h^2)) + O(h^3) \\ \Rightarrow k = ah + e^2 h^2 + O(h^3) = ah + a_2 h^2 + O(h^3)$$

Hence,

$$ah + e^2 h^2 = ah + a_2 h^2$$

$$\Rightarrow e^2 h^2 = a_2 h^2$$

So,

$$\boxed{a_2 = e^2}$$

### Problem 2 (Theoretical)

Consider the Runge-Kutta (RK) method specified by the Butcher tableau below

$c^T$	$A$	$b$
	$\begin{matrix} 0 & 0 \\ \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{matrix}$	

P2

Write out the method in the form of  $k_1 = \dots, k_2 = \dots, \dots, u_{n+1} = u_n + \dots$

Support  $f(u, t)$  satisfies  $|f(u, t) - f(v, t)| \leq C|u - v|$  for all  $u, v$ , and  $t$ .

Part 1: Show that the method is stable.

Part 2: Use Taylor expansion to show  $e_n(h) = O(h^2)$ .

Part 3: What is the order of its global error  $E_N(h)$ ?

We're given the Butcher tableau

$$\left[ \begin{array}{c|cc} C^T & A \\ \hline b & \end{array} \right] = \left[ \begin{array}{c|ccc} & 0 & 0 & 0 \\ & 1/2 & 1/2 & 0 \\ \hline & 1/2 & 1/2 & \end{array} \right]$$

$$\Rightarrow P=2, \quad A = \begin{bmatrix} 0 & 0 \\ 1/2 & 0 \end{bmatrix}, \quad b = (1/2, 1/2), \quad C = (0, 1/2)$$

$$\Rightarrow \begin{cases} k_1 = h \cdot f(u_n, t_n) \\ k_2 = h \cdot f(u_n + \frac{1}{2}k_1, t_n + \frac{1}{2}h) \\ u_{n+1} = u_n + \frac{1}{2}k_1 + \frac{1}{2}k_2 \end{cases}$$

Part 1: Show the method is stable.

Proof:

We're given  $f$  is LC.

$$u_{n+1} = u_n + \frac{1}{2}h \cdot f(u_n, t_n) + \frac{1}{2}h f(u_n + \frac{1}{2}h f(u_n, t_n), t_n + \frac{1}{2}h)$$

$$v_{n+1} = v_n + \frac{1}{2}h \cdot f(v_n, t_n) + \frac{1}{2}h f(v_n + \frac{1}{2}h f(v_n, t_n), t_n + \frac{1}{2}h)$$

$\Rightarrow$

$$|u_{n+1} - v_{n+1}| = |(u_n - v_n) + \frac{1}{2}h [f(u_n, t_n) + f(u_n + \frac{1}{2}h f(u_n, t_n), t_n + \frac{1}{2}h) - f(v_n, t_n) - f(v_n + \frac{1}{2}h f(v_n, t_n), t_n + \frac{1}{2}h)]|$$

$$= |(u_n - v_n) + \frac{1}{2}h \underbrace{[f(u_n, t_n) - f(v_n, t_n)]}_{\dots}|$$

$$= |(u_n - v_n) + \frac{1}{2}h \underbrace{[f(u_n, t_n) - f(v_n, t_n)]}_{a} + f\left(u_n + \frac{1}{2}hf(u_n, t_n), t_n + \frac{1}{2}h\right) - f\left(v_n + \frac{1}{2}hf(v_n, t_n), t_n + \frac{1}{2}h\right)|$$

$$\Rightarrow |u_{n+1} - v_{n+1}| \leq |(u_n - v_n)| + \frac{1}{2}h|a+b|$$

Since  $f$  is LC,

$$a \leq C|u_n - v_n|$$

and

$$b \leq C \left| u_n + \frac{1}{2}hf(u_n, t_n) - \left(v_n + \frac{1}{2}hf(v_n, t_n)\right) \right|.$$

$$\Rightarrow b \leq C \left| (u_n - v_n) + \frac{1}{2}h(f(u_n, t_n) - f(v_n, t_n)) \right|$$

$$\Rightarrow b \leq C|u_n - v_n| + \frac{C}{2}h|f(u_n, t_n) - f(v_n, t_n)|$$

$$\Rightarrow b \leq C|u_n - v_n| + \frac{C^2}{2}h|u_n - v_n|$$

$$b \leq \left(C + \frac{C^2}{2}h\right)|u_n - v_n|$$

$$\begin{aligned} \Rightarrow |a+b| &\leq C|u_n - v_n| + \left(C + \frac{C^2}{2}h\right)|u_n - v_n| \\ &\leq \left(2C + \frac{C^2}{2}h\right)|u_n - v_n| \end{aligned}$$

Hence,

$$|u_{n+1} - v_{n+1}| \leq |u_n - v_n| + \frac{1}{2}h|a+b|$$

$\Rightarrow$

$$\begin{aligned}|U_{n+1} - V_{n+1}| &\leq |U_n - V_n| + \frac{1}{2}h\left(2C + \frac{C^2}{2}h\right)|U_n - V_n| \\&\leq \left(1 + Ch + \frac{C^2h^2}{4}\right)|U_n - V_n|.\end{aligned}$$

For small enough  $h$ ,  $\frac{C^2h^2}{4} \rightarrow 0$ .

Hence

$$|U_{n+1} - V_{n+1}| \leq (1 + Ch)|U_n - V_n|,$$

so the method is stable.

□

Part 2:

We have that

$$U_{n+1} = U_n + \frac{1}{2}hf(U_n, t_n) + \frac{1}{2}hf\left(U_n + \frac{1}{2}hf(U_n, t_n), t_n + \frac{1}{2}h\right)$$

$$\Rightarrow e_n(h) =$$

$$U(t_{n+1}) - U(t_n) - \frac{1}{2}hf(U(t_n), t_n) - \frac{1}{2}hf\left(U(t_n) + \frac{1}{2}f(U(t_n), t_n), t_n + \frac{1}{2}h\right)$$

Write  $U(t_{n+1}) = U(t_n + h)$ , then

$$U(t_n + h) - U(t_n) - \frac{h}{2} \left[ f(U(t_n), t_n) + f\left(U(t_n) + \frac{1}{2}f(U(t_n), t_n), t_n + \frac{1}{2}h\right) \right]$$

Applying a Taylor expansion to  $U(t_n + h)$ , we have

Applying a Taylor expansion to  $U(t_n+h)$ , we have

$$U(t_n+h) = U(t_n) + U'(t_n)h + U''(t_n)\frac{h^2}{2!} + \dots$$

Substituting into  $e_n(h)$ , we get

$$U'(t_n) \cdot h - \frac{1}{2}h \left[ f(U(t_n), t_n) + f\left(U(t_n) + \frac{h}{2}f(U(t_n), t_n), t_n + \frac{1}{2}h\right) \right] + O(h^2)$$

Since  $U(t_n)$  is an exact solution, we know

$$U'(t_n) = f(U(t_n), t_n).$$

Thus,

$$\frac{h}{2}f(U(t_n), t_n) - \underbrace{\frac{h}{2}f\left(U(t_n) + \frac{h}{2}f(U(t_n), t_n), t_n + \frac{h}{2}\right)}_{\text{expand this further}} + O(h^2)$$

$$\Rightarrow e_n(h) = \frac{h}{2}f(U(t_n), t_n) - \frac{h}{2} \left[ f(U(t_n), t_n) + O(h) \right] + O(h^2)$$
$$= \frac{h}{2}f(U(t_n), t_n) - \frac{h}{2}f(U(t_n), t_n) + O(h^2)$$

Hence,  $e_n(h) = O(h^2)$ .

### Part 3

From lecture 2, we can apply the theorem relating global error and the LTE. Since we proved in Part 1 that the method is stable, and in part 2 we showed  $e_n(h) = O(h^2)$ ,

We know

$$E_N(h) = O(h).$$

**Problem 3 (Theoretical)**

Recall that in lecture, we carried out polynomial interpolation based on 3 points and used the polynomial interpolation to derive

- 3-step Adams-Basforth method and
- 2-step Adams-Moulton method

Carry out polynomial interpolation based on 2 points and use it to derive

- 2-step Adams-Basforth method and
- 1-step Adams-Moulton method

P3

To derive Adams-Basforth 2, we let  $s=1 \Rightarrow r=s+1=2$ .

$$\Rightarrow \left\{ t_n, t_{n+1} \right\}, \quad t_n \rightarrow x_1 = -s = -1 \\ t_{n+1} \rightarrow x_2 = -(s-1) = 0.$$

$$\text{Recall } x = \frac{t-t_{n+2}}{h}.$$

Then, the method is given by

$$u_{n+2} = u_{n+1} + \int_{t_{n+1}}^{t_{n+2}} P\left(\frac{t-t_{n+2}}{h}\right) dt \\ = u_{n+1} + \int_0^1 P(x) dx. \quad \text{We must calculate } P(x).$$

$$P(x) = f(u_n, t_n) P_1(x) + f(u_{n+1}, t_{n+1}) P_2(x),$$

where

$$P_j(x) := \prod_{k=1, k \neq j}^m \left( \frac{x - x_k}{x_j - x_k} \right), \quad j = 1, 2. \quad \begin{cases} x_1 = -1 \\ x_2 = 0 \end{cases}$$

$$\Rightarrow P_1(x) = \left( \frac{x - 0}{-1 - 0} \right) = -x$$

$$P_2(x) = \left( \frac{x + 1}{0 + 1} \right) = x + 1.$$

$$\Rightarrow u_{n+2} = u_{n+1} + h f(u_n, t_n) \int_0^1 P_1(x) dx + h f(u_{n+1}, t_{n+1}) \int_0^1 P_2(x) dx$$

We have

$$\int_0^1 P_1(x) dx = \int_0^1 (-x) dx = -\frac{1}{2} x^2 \Big|_0^1 = -\frac{1}{2}$$

$$\int_0^1 P_2(x) dx = \int_0^1 (x+1) dx = \left( \frac{1}{2} x^2 + x \right) \Big|_0^1 = \frac{3}{2}$$

$$\Rightarrow u_{n+2} = u_{n+1} + -\frac{1}{2} h f(u_n, t_n) + \frac{3}{2} h f(u_{n+1}, t_{n+1})$$

Hence, AB-2:

$$u_{n+2} = u_{n+1} + \frac{h}{2} \left[ -f(u_n, t_n) + 3f(u_{n+1}, t_{n+1}) \right]$$

Now, we derive Adams-Moulton 1 method. This is the same as the trapezoidal method.

Here,  $s=1 \Rightarrow r=s=1$

$$\begin{cases} t_n \rightarrow x_1 = -s = -1 \\ t_{n+1} \rightarrow x_2 = -(s-1) = 0 \end{cases}$$

$$\text{Here, } s=1 \Rightarrow r=s = 1$$

$$\begin{cases} t_n \rightarrow x_1 = -s = -1 \\ t_{n+1} \rightarrow x_2 = -(s-1) = 0 \end{cases}$$

So,

$$U_{n+1} = U_n + \int_{t_n}^{t_{n+1}} P\left(\frac{t-t_{n+1}}{h}\right) dt$$

$$= U_n + \int_{-1}^0 P(x) dx.$$

$$P_{Lx1} = h f(U_n, t_n) P_1(x) + h f(U_{n+1}, t_{n+1}) P_2(x)$$

$$P_j(x) = \prod_{k=1, k \neq j}^m \left( \frac{x-x_k}{x_j-x_k} \right), j=1, 2 \quad \begin{matrix} x_1 = -1 \\ x_2 = 0 \end{matrix}$$

$$\Rightarrow P_1(x) = \frac{x}{-1} = -x \Rightarrow \int_{-1}^0 (-x) dx = -\frac{1}{2}x^2 \Big|_{-1}^0 = \frac{1}{2}$$

$$P_2(x) = \frac{x+1}{1} = x+1. \Rightarrow \int_{-1}^0 (x+1) dx = \left( \frac{1}{2}x^2 + x \right) \Big|_{-1}^0 = \frac{1}{2}$$

Thus, AM-1 method is

$$U_{n+1} = U_n + \frac{1}{2} h f(U_n, t_n) + \frac{1}{2} h f(U_{n+1}, t_{n+1})$$

$$\Rightarrow U_{n+1} = U_n + \frac{h}{2} [f(U_n, t_n) + f(U_{n+1}, t_{n+1})]$$

(Also trapezoidal).