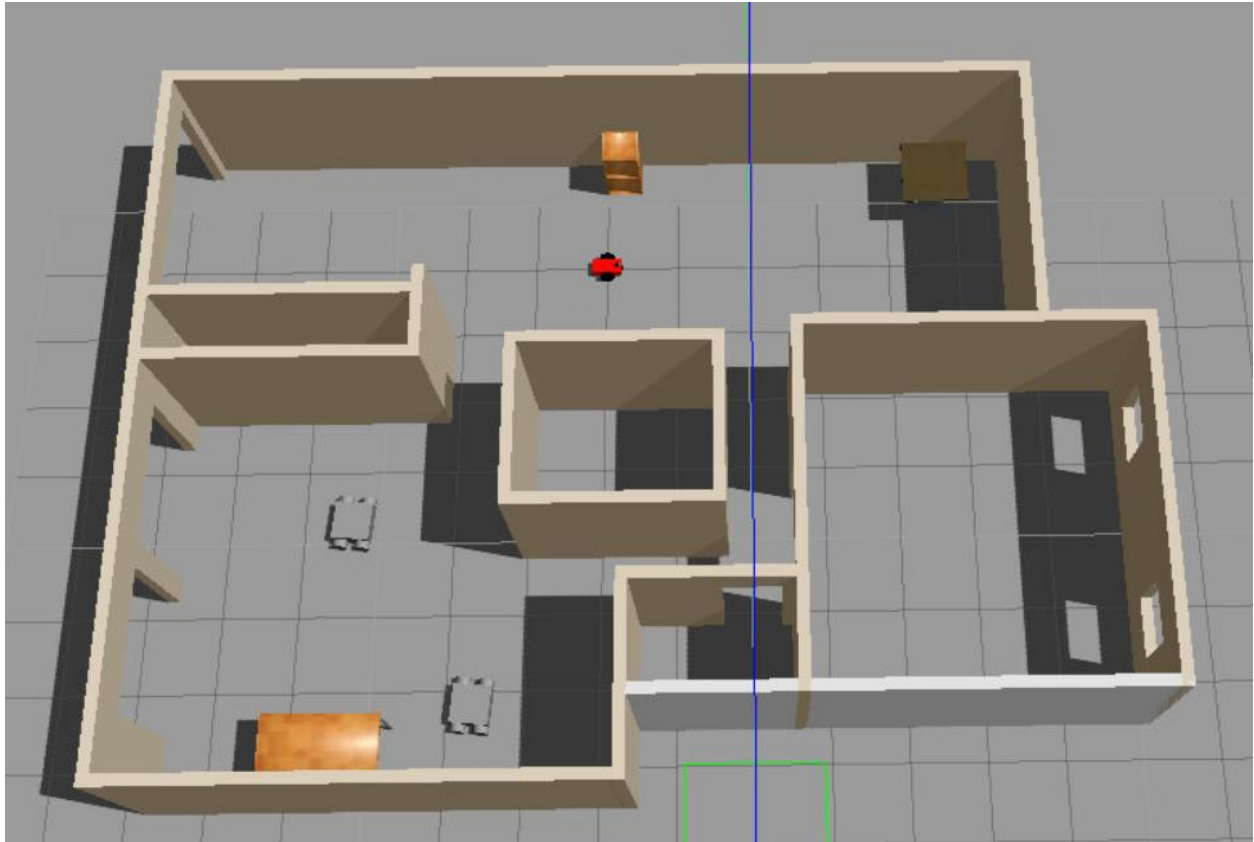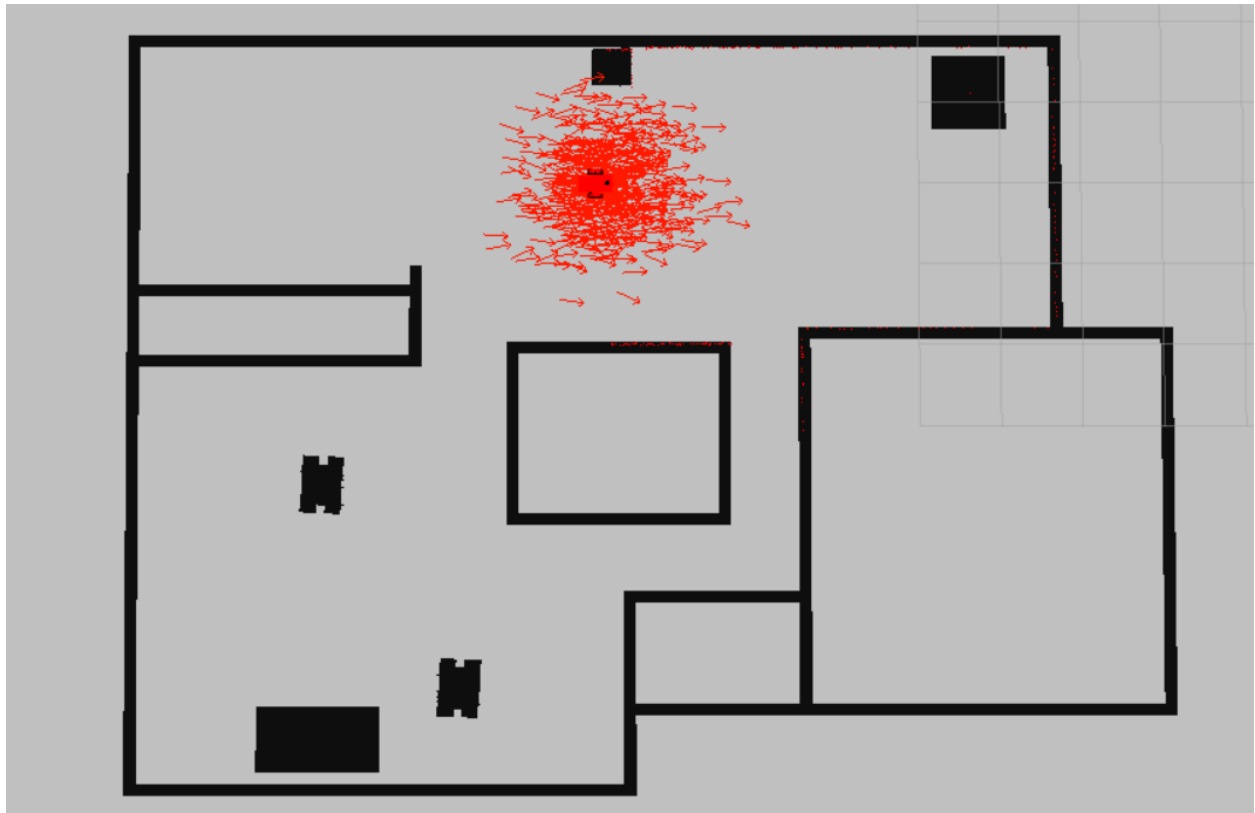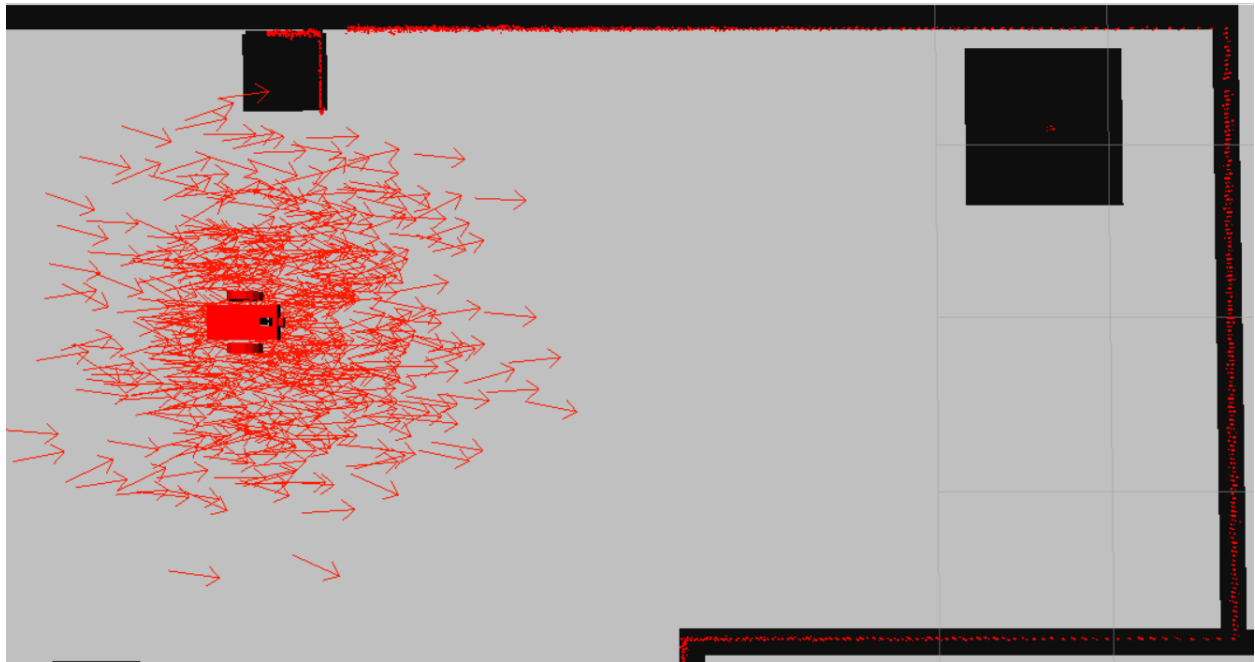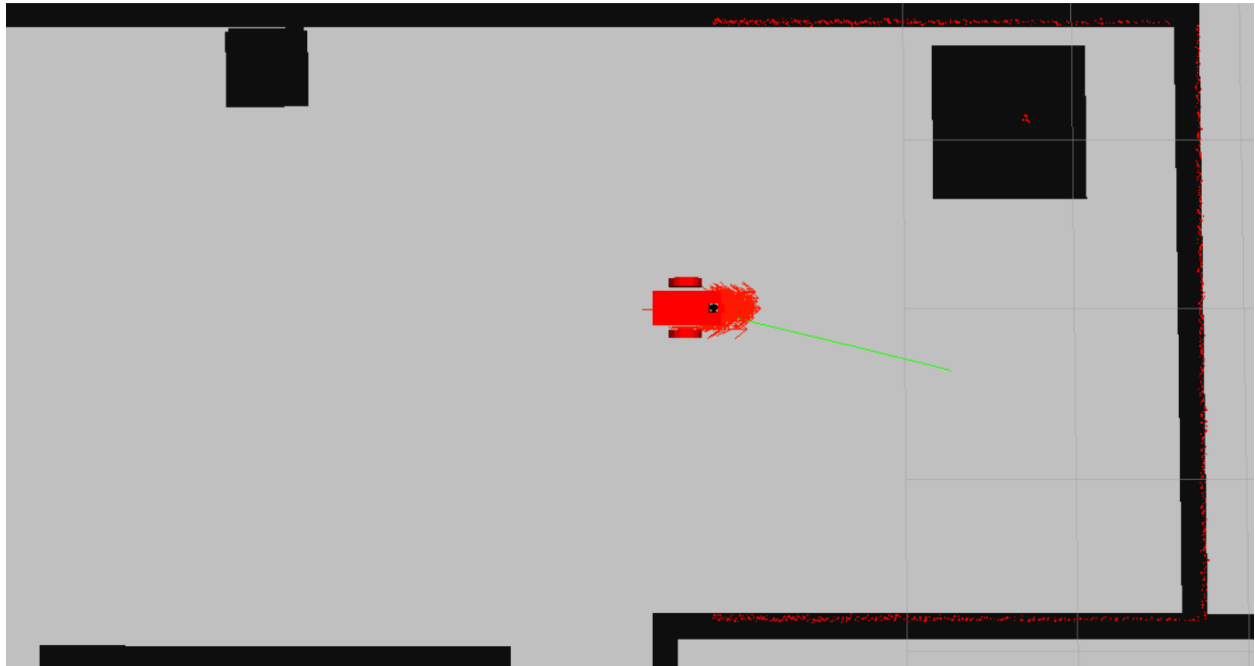**Gazebo Environment right after launch:**

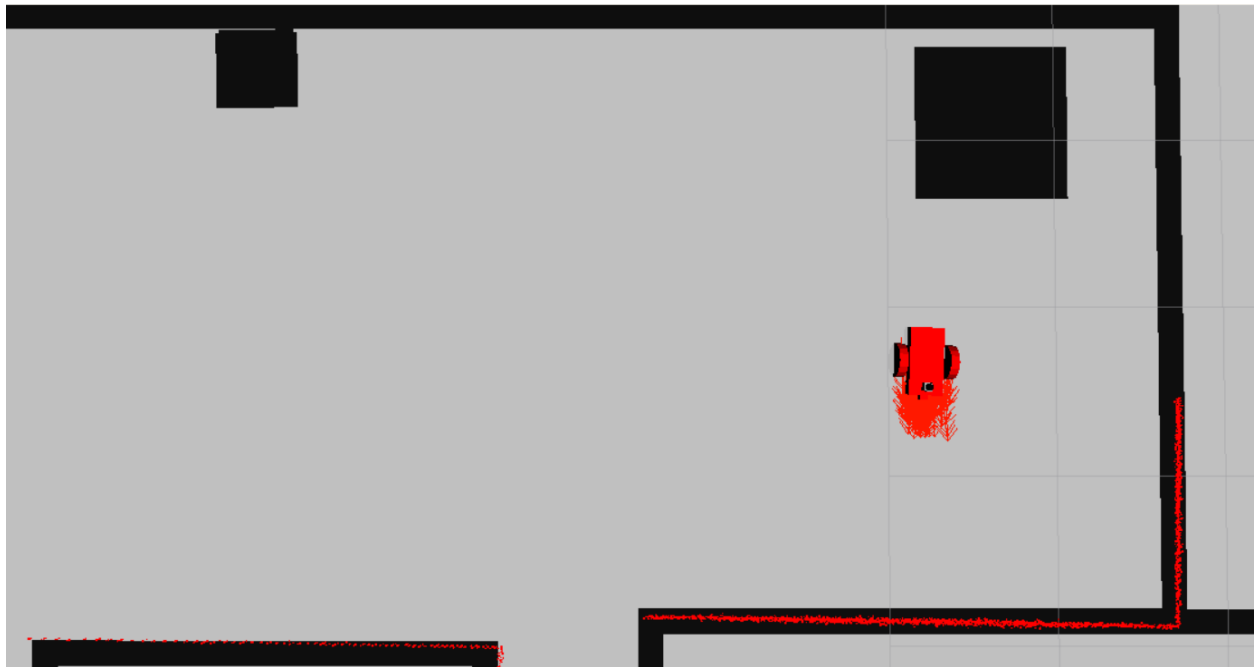**RViz map view right after launch and before giving 2D Nav command:**

**Close up RViz map view right after launch and before giving 2D Nav command:**

**RViz map view after giving 2D Nav command. Robot is on the move. Goal is to the right in the map, facing down:**

**RViz map view after reaching 2D Nav goal. Robot is stationary:**

**Gazebo view after reaching 2D Nav goal. Robot is stationary:**