# Sageable Mathematics

# August 5, 2019

Sageable Mathematics is a project that introduces SageMath (or Sage) to students and encourages them to program in Sage. Each student (or each small group of students) will pick a mathematics concept and implement the computation in Sage. The goal is to experience programming through Sage and also gain a deeper insight into the concept.

This document is a gallery of students' work in Math316: Practice of Applied Mathematics at National Sun Yat-sen University, in 2019 Spring. The works, by the authors in each section, in this document are licensed under a Creative Commons Attribution 4.0 International License.



As the instructor, I myself particularly recommend "DihedralGroup", "GradientDescent", "LinearClassifier", "MinimalPolynomial", and "Torque".

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# **Determinant**



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#### Overview

Give an  $n \times n$  matrix,

we want to calculate the **determinant** of the matrix.

#### **Algorithm**

1. Given an 
$$n \times n$$
 matrix 
$$\begin{bmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,n} \\ a_{2,1} & a_{2,2} & \cdots & a_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n,1} & a_{n,2} & \cdots & a_{n,n} \end{bmatrix}$$

- 2. Do row operations to change the matrix into an upper triangular matrix.
- 3. And times all diagonal element then we get the determinant of the matrix.

### **Explanation**

The goal is to calculate the determinant of the  $n \times n$  matrix.

as goal is to calculate the determinant of the 
$$n\times n$$
 matrix. 
$$\begin{bmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,n} \\ a_{2,1} & a_{2,2} & \cdots & a_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n,1} & a_{n,2} & \cdots & a_{n,n} \end{bmatrix}$$
 st we add  $-\frac{a_{i,1}}{a_{1,1}} \times \begin{bmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,n} \end{bmatrix}$  to the  $i$  row for  $i=2,3,\cdots,n-1,n$ . Now we have

First we add  $-\frac{a_{i,1}}{a_{1,1}} \times \begin{bmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,n} \end{bmatrix}$  to the i row for  $i=2,3,\cdots,n-1,n$ . Now we have

$$\begin{bmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,n} \\ 0 & a_{2,2} - \frac{a_{2,1}}{a_{1,1}} \times a_{1,2} & \cdots & a_{2,n} - \frac{a_{2,1}}{a_{1,1}} \times a_{1,n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & a_{n,2} - \frac{a_{n,1}}{a_{1,1}} \times a_{1,2} & \cdots & a_{n,n} - \frac{a_{n,1}}{a_{1,1}} \times a_{1,n} \end{bmatrix}$$

將該矩陣去除第一行及第一列後存成一個新方陣,使用迴圈做相同運算。

#### Example for 3\*3 matrix

```
In [1]:
```

the determinant of M is

**-**79

Here you can try my determinant calculator

# In [2]:

```
##Enter a n*n matrix M
M = matrix(QQ, [
        [1,7,5],
        [5,6,7],
        [5,0,6]
    ])
#Below are my codes.
m,n = M.dimensions()
a = 1
c = 0
for i in range(1,m):
    if M[0,0] == 0:
        c = c+1
        K=M[0,:]
        M[0,:]=M[i,:]
        M[i,:]=K;
    if M[0,0]!=0:
        break;
if M[0,0]==0:
    a=0;
if M[0,0]!=0:
    for i in range(m):
        if m-i>1:
            a = a*M[0,0];
            for j in range(m-i-1):
                if j==m-i-2:
                    M[j+1,:] += -M[j+1,0]/M[0,0] * M[0,:]
                    M = M[1:m-i,1:m-i];
                if j!=m-i-2:
                    M[j+1,:] += -M[j+1,0]/M[0,0] * M[0,:];
        if m-i<=1:
            a = a*M[0,0];
print("the determinant of M is")
if a==0:
    show(a)
if a!=0:
    if c%2!=0:
        show(-a)
    if c%2==0:
        show(a)
```

the determinant of M is

-79

```
In [3]:
```

```
### Jephian: Let's make it a function for convenience.
def matrix_determinant(M):
    #Below is your code.
    m,n = M.dimensions()
    a = 1
    c = 0
    for i in range(1,m):
        if M[0,0] == 0:
            c = c+1
            K=M[0,:]
            M[0,:]=M[i,:]
            M[i,:]=K;
        if M[0,0]!=0:
            break;
    if M[0,0] == 0:
        a=0;
    if M[0,0]!=0:
        for i in range(m):
            if m-i>1:
                 a = a*M[0,0];
                 for j in range(m-i-1):
                     if j==m-i-2:
                         M[j+1,:] \leftarrow -M[j+1,0]/M[0,0] * M[0,:]
                         M = M[1:m-i,1:m-i];
                     if j!=m-i-2:
                         M[j+1,:] += -M[j+1,0]/M[0,0] * M[0,:];
            if m-i<=1:
                 a = a*M[0,0];
    print("the determinant of M is")
    if a==0:
        show(a)
    if a!=0:
        if c%2!=0:
            show(-a)
        if c%2==0:
            show(a)
```

#### In [4]:

```
M = matrix(QQ, [
      [0,2,3],
      [3,5,6],
      [0,8,9]
])
matrix_determinant(M)
print 'sage answer:', M.determinant()
```

6

the determinant of M is

18

sage answer: -18

In [0]:			

# **Good Gaussian elimination**



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#### **Overview**

Given a matrix with finite rows and finite columns, Good Gaussion Elimination aims to reduce a matrix into its upper triangular form within as less time as it could.

# Algorithm

1. Create an  $N \times M$  matrix that you what to reduce.

$$A = \begin{bmatrix} X_{1,1} & \cdots & X_{1,M} \\ \vdots & \vdots & \vdots \\ X_{N,1} & \cdots & X_{N,M} \end{bmatrix}$$

2. Then compute a upper triangular matrix

$$A' = \begin{bmatrix} Y_{1,1} & \cdots & Y_{1,M} \\ \vdots & \vdots & \vdots \\ 0 & \cdots & Y_{N,M} \end{bmatrix}$$

# **Implementation**

```
In [1]:
```

```
##########
## MATN ##
##########
##algorithm part
def gauss eli(A):
    n,m=A.dimensions()
    c=0
    d=[]
    for k in range(0,m):
        t=0
        for i in range(0,n):
            if((A[i,k] != 0) and (t != 1) and (i not in d)):
                t=1
                d=d+[i]
                for j in range(0,n):
                    if(j != i):
                        A[j,0:] = A[j,0:]*A[i,k]-A[i,0:]*A[j,k]
    #answer
    #return A
    #rearrange
    AR = copy(A)
    for p in range(0,m):
        if(p not in d):
            d=d+[p]
    for l in range(0,n):
            AR[1,0:]=A[d[1],0:]
    return AR
##Trials
import numpy as np
a=matrix(np.random.rand(3,4)*10)
a=matrix([[3,3,3],[2,2,2],[4,4,4]])
a=matrix([[0,0,-2,1],[2,2,2,1],[-2,0,0,1]])
print "original matrix"
print a
print '---'
b=copy(a)
print "my answer"
print gauss eli(a)
print "---"
print "sage default answer"
print b.echelon form()
original matrix
[ 0 0 -2 1]
[2221]
[-2 0 0 1]
                                         9
my answer
              0
[ - 128
        0
                  64]
[
   0
      -64
              0
                 -961
   0
        0
                   8]
           - 16
[
```

```
sage default answer
[ 2 0 0 -1]
[ 0 2 0 3]
[ 0 0 2 -1]
In [2]:
A = matrix(QQ, [
    [0,0,1],
    [0,1,1],
    [1,1,0]
])
In [3]:
gauss_eli(A)
Out[3]:
[1 0 0]
[0 1 0]
[0 0 1]
In [4]:
A.echelon_form()
Out[4]:
[1 0 0]
[0 1 0]
[0 0 1]
In [ ]:
```

# **Dihedral Group**



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#### **Overview**

Before definding the dihedral group  $\mathbf{D}_n$  of order n, we explain some terminology that will be used in the definition of dihedral group. From now on we assume that the verties of regular n polygon are labeled counterclockwie with  $1,2,\ldots,n$  and denote  $v_i$  as the vertex labeled with i. If n is odd, we call the line connecting  $v_i$  and the midpoint of  $v_{i+\frac{n-1}{2}},v_{i+\frac{n+1}{2}}$  the i-th symmetry axis of this polygon  $(1 \leq i \leq n)$ . If n is even, we call the line connecting  $v_i$  and  $v_{i+\frac{n}{2}}$  the 2i-1-th symmetry axis and call the line connecting the midpoint of  $v_i,v_{i+1}$  and the midpoint of  $v_{i+\frac{n}{2}},v_{i+\frac{n+2}{2}}$  the 2i-th symmetry axis  $(1 \leq i \leq \frac{n}{2})$  (all subscripts are taken modulo n).

Definition of  $\mathbf{D}_n$ : A regular polygon with n sides has 2n different symmetries; i.e., n rotational symmetries and n reflection symmetries. Denote  $r_i$  as the counterclockwise rotation by  $\frac{2i\pi}{n}$  and  $s_i$  as the reflection through the i-th symmetry axis ( $1 \leq i \leq n$ ). These 2n symmetries form a group with operation the composition of symmetries (written in addition), this group is called the dihedral group  $\mathbf{D}_n$  of order n.

This program creates the Dihedral group elements in Sage.

P.S. 以下用 (i,0,n),(0,j,n) 分別表示  $\mathbf{D}_n$  中的元素  $r_i,s_j$ , 其中  $1\leq i,j\leq n$ .

# **Explanation**

Some facts used in my program:

```
1. r_i+r_j=r_{i+j}, r_i+s_j=s_{i+j}, s_i+r_j=s_{i-j}, s_i+s_j=r_{i-j} (all subscripts are taken modulo n).
```

- 1. To check whether a subset S of a group (G,+) is a subgroup or not, it suffices to test  $a-b\in S$  for every  $a,b\in S$  and  $S\neq\emptyset$ .
- 1. To check whether a subgroup T of a group (G,+) is normal or not, it suffices to test  $b+a-b\in T$  for every  $a\in T,b\in G$  and  $S\neq\emptyset$ .

# **Implementation**

```
In [1]: class Dihedraln:
            def __init__(self,a,b,n):
                self.r = a
                self.s = b
                 self.size = n
            def __str__(self):
                return 'element (r,s)=%s in Dihedraln group of order 2 * %s'%
        ((self.r,self.s), self.size)
            def __repr__(self):
                 return 'element (r,s)=%s in Dihedraln group of order 2 * %s'%
        ((self.r,self.s), self.size)
            def add__(self, other):
                if self.size != other.size:
                     raise TypeError, 'Two elements are in different group'
                else:
                     size = self.size
                     if self.s==0 and other.s==0:
                         if (self.r+other.r)%size==0:
                             return Dihedraln(size,0,size)
                        else:
                             return Dihedraln((self.r+other.r)%size,0,size)
                     elif self.r==0 and other.r==0:
                         if (self.s-other.s)%size==0:
                             return Dihedraln(size,0,size)
                        else:
                             return Dihedraln((self.s-other.s)%size,0,size)
                     elif self.s==0 and other.r==0:
                         if (self.r+other.s)%size==0:
                             return Dihedraln(0,size,size)
                        else:
                             return Dihedraln(0,(self.r+other.s)%size,size)
                     else:
                         if (self.s-other.r)%size==0:
                             return Dihedraln(0, size, size)
                        else:
                             return Dihedraln(0,(self.s-other.r)%size,size)
            def eq (self, other):
                return self.r == other.r and self.s == other.s and self.size
        == other.size
            def inverse(self):
                 size = self.size
                if self.r==0:
                     return self
                else:
                     return Dihedraln(size-(self.r)%size,0,size)
```

# **Examples**

```
In [4]: n = 4
D = [Dihedraln(i,0,n) \text{ for } i \text{ in } range(1,n+1)] + [Dihedraln(0,i,n) \text{ for } i \text{ in } range(1,n+1)]
```

```
In [5]: for ele in D:
    print ele
```

```
element (r,s)=(1, 0) in Dihedraln group of order 2 * 4 element (r,s)=(2, 0) in Dihedraln group of order 2 * 4 element (r,s)=(3, 0) in Dihedraln group of order 2 * 4 element (r,s)=(4, 0) in Dihedraln group of order 2 * 4 element (r,s)=(0, 1) in Dihedraln group of order 2 * 4 element (r,s)=(0, 2) in Dihedraln group of order 2 * 4 element (r,s)=(0, 3) in Dihedraln group of order 2 * 4 element (r,s)=(0, 4) in Dihedraln group of order 2 * 4
```

```
In [6]: for com in Combinations(D):
            if subgroupchecker(com):
                if normalchecker(com):
                    print 'normal subgroup:'
                else:
                    print 'subgroup:'
                for ele in com:
                    print ele
        normal subgroup:
        element (r,s)=(4, 0) in Dihedraln group of order 2 * 4
        normal subgroup:
        element (r,s)=(2, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(4, 0) in Dihedraln group of order 2 * 4
        subgroup:
        element (r,s)=(4, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(0, 1) in Dihedraln group of order 2 * 4
        subgroup:
        element (r,s)=(4, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(0, 2) in Dihedraln group of order 2 * 4
        subgroup:
        element (r,s)=(4, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(0, 3) in Dihedraln group of order 2 * 4
        element (r,s)=(4, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(0, 4) in Dihedraln group of order 2 * 4
        normal subgroup:
        element (r,s)=(1, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(2, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(3, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(4, 0) in Dihedraln group of order 2 * 4
        normal subgroup:
        element (r,s)=(2, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(4, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(0, 1) in Dihedraln group of order 2 * 4
        element (r,s)=(0, 3) in Dihedraln group of order 2 * 4
        normal subgroup:
        element (r,s)=(2, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(4, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(0, 2) in Dihedraln group of order 2 * 4
        element (r,s)=(0, 4) in Dihedraln group of order 2 * 4
        normal subgroup:
        element (r,s)=(1, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(2, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(3, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(4, 0) in Dihedraln group of order 2 * 4
        element (r,s)=(0, 1) in Dihedraln group of order 2 * 4
        element (r,s)=(0, 2) in Dihedraln group of order 2 * 4
        element (r,s)=(0, 3) in Dihedraln group of order 2 * 4
        element (r,s)=(0, 4) in Dihedraln group of order 2 * 4
In [7]: Dihedraln(3,0,7) # r 3 in D_{1}
```

```
Out[7]: element (r,s)=(3, 0) in Dihedraln group of order 2 * 7
```

```
In [8]: Dihedraln(0,5,7) # s_5 in D_7
Out[8]: element (r,s)=(0, 5) in Dihedraln group of order 2 * 7
In [9]: Dihedraln(3,0,7)+Dihedraln(0,5,7) # r_3 + s_5 in D_7
Out[9]: element (r,s)=(0, 1) in Dihedraln group of order 2 * 7
In [10]: subgroupchecker([Dihedraln(7,0,7),Dihedraln(5,0,7)])# chech whether {r_7, r_5} is a subgroup of D_7 or not
Out[10]: False
In [11]: subgroupchecker([Dihedraln(7,0,7),Dihedraln(0,1,7)])# chech whether {(7,0), (0,1)} is a subgroup of D_7 or not
Out[11]: True
In [12]: normalchecker([Dihedraln(7,0,7),Dihedraln(0,1,7)])# chech whether {(7,0), (0,1)} is a normal subgroup of D_7 or not
Out[12]: False
In []:
```

# **Gradient Descent**



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#### **Overview**

Let  $f: \mathbb{R}^2 \to \mathbb{R}$  be a function. Our main goal is to find a local minimum of a function f.

We use the method of **gradient descent** to find a local minimum of f.

Define a function f from  $\mathbb{R}^2$  to  $\mathbb{R}$ .

For example, when  $f(x, y) = x^2 + y^2$ , the algorithm will return an approximation of the location of the minimum (0, 0).

## Algorithm

- 1. Let f be a function from  $\mathbb{R}^2$  to  $\mathbb{R}$  and choose  $\mathbf{x}_0 = (x_0, y_0) = (0, 0)$  as an initial point.
- 2. Then compute  $\nabla f(x_i, y_i)$ , the gradient of f at  $\mathbf{x}_i$ , and

$$\mathbf{x}_{i+1} = \mathbf{x}_i - \alpha \cdot \nabla f(x_i, y_i)$$

where  $\alpha$  is a small enough number such that the sequence  $(\mathbf{x}_n)$  converges to a local minimum.

1. Repeat Step 2 for several steps.

# **Explanation**

The goal is to find a local minimum of a given function.

Given functions are restricted to be two variables and the gradient of function is needed to be calculated by hands.

We set  $\alpha = 0.05$  and the step of x denoted by  $\epsilon < 10^{-5}$ .

The sequence might converge slowly or not converge, so we need to set the maximum iteration times.

#### **Implimentation**

```
In [1]:
```

```
import numpy as np
def gradient descent(f, gradf, steps=100, alpha=0.5):
    Input:
        f: a function of x,y that we want to evaluate the minimum
        gradf:gradient of the function f
        steps:the steps of iterations
        alpha:step size multiplier
    Output:
        min: the minimum of f
    v1 = vector(np.random.randn(2)); ### next vector
    v2 = vector(np.random.randn(2)); ### current vector
    for i in range(steps):
        v2 = v1;
        v1 = v2 - alpha * vector(gradf(v2));
        h = v1[0] - v2[0];
        if abs(h) <= epsilon :</pre>
            break;
    print("Minimum at",v1," and minimum is",f(v1));
```

# Example 1

```
f(x, y) = x^2 + y^2
```

#### In [2]:

```
epsilon=0.00001;

f = lambda v1: v1[0]^2 + v1[1]^2

gradf = lambda v2: (2*v2[0], 2*v2[1])

gradient_descent(f,gradf, steps=100, alpha=0.5)
```

('Minimum at', (0.0, 0.0), ' and minimum is', 0.0)

#### In [3]:

```
### If we use a large alpha, then the result may be different.
gradient_descent(f,gradf, steps=100, alpha=1)
```

('Minimum at', (1.236371488782072, -0.781210485847116), ' and minimum is', 2.1389042814706842)

#### Example 2

$$f(x, y) = x^2 - y^2 + xy - 4$$

```
In [4]:
```

```
epsilon=0.00001;
f = lambda v1: v1[0]^2 - v1[1]^2 + v1[0]*v1[1] - 4
gradf = lambda v2: (2*v2[0] + v2[1], -2*v2[1]+v2[0])
gradient descent(f,gradf, steps=100)
('Minimum at', (2.792893696625991e+31, -1.1830887552838372e+32), ' and
minimum is', -1.652120563590659e+64)
In [5]:
### example of vectors and functions in SageMath
### tuples are nice but their addition is not what we want
print "(0,0) + (1,0) =", (0,0) + (1,0)
### Use vector instead
v = vector([0,0])
u = vector([1,0])
print "u+v =", u+v
### get vector entries
print "u[0],u[1] =", u[0], u[1]
### a function that takes a vector as input
### syntax:
### lambda input: output
### this is called the lambda method to define a function
f = lambda v: v[0]^2 + v[1]^2
print "f(v) = ", f(v)
print "f(u) =", f(u)
### alternatively, you have to do the classical function define
def g(v):
    return v[0]^2 + v[1]^2
### two methods are almost the same except that the lambda method you don't have to
print "g(v) = ", g(v)
print "g(u) = ", g(u)
### Therefore, the gradf can be
gradf = lambda v: 2*v[0] + 2*v[1]
(0,0) + (1,0) = (0,0,1,0)
u+v = (1, 0)
u[0], u[1] = 10
f(v) = 0
f(u) = 1
g(v) = 0
g(u) = 1
In [ ]:
```

# **Graph Coloring**



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#### Overview

```
Given a simple graph G with a vertex set V = \{v_1, v_2, \dots, v_n\} and a color set [m] := \{1, \dots, m\}, an m-coloring of G is an assignment c: V \to [m].
```

A **proper** m-coloring on a graph G is an m-coloring c such that

 $v_i$  and  $v_i$  have different colors if  $v_i$  and  $v_j$  are connected by an edge  $\forall i, j \in [n]$ .

The goal is to find the smallest m such that G has a proper m-coloring.

This minimum m is called the **chromatic number** of G, denoted as  $\chi(G)$ .

#### Algorithm (Greedy coloring algorithm)

- 1. Given a graph G and a vertex ordering  $\{v_1, v_2, \dots, v_n\}$
- 2. For each i, color  $v_i$  with the smallest positive integer j such that j is not used in any of neighbors of  $v_i$ .
- 3. Output the number of colors used (j).

#### Explanation

```
Given a graph G with a vertex set V and an edge set E Label the vertices as V=\{0,1,\ldots,n-1\}. By the Geedy Algorithm, color the vertex 0 with color \ c[1]. If vertex 1 is a neighbor of vertex 0, then color vertex 1 with \ c[2]. If not, then color vertex 1 with \ c[1]. But notice that the output of Greedy Algorithm might not be the minimum color set.
```

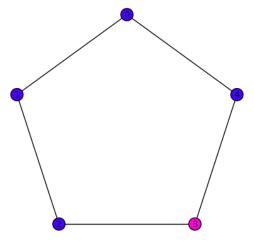
#### Implementation

#### In [1]:

```
def greedy_coloring(g, vertex_order=None, show_color=False):
    Input:
         g: a simple graph
         vertex_order: a list of vertices of g;
                         if None, g.vertices() is taken.
         show_color: show the graph with the output color if True
         a coloring
    if vertex_order==None:
         vertex_order = g.vertices()
    n = g.order()
    coloring={}
    for v in vertex order:
         color_in_nbr = []
colored = coloring.keys()
         for u in g.neighbors(v):
             if u in colored:
         color_in_nbr.append(coloring[u])
for color in range(n):
             coloring[v] = n
             \textbf{if} \ \textbf{u} \ \textbf{in} \ \textbf{g}. \\ \textbf{neighbors}(\textbf{v}):
                  coloring[u] = n + 1
    \textbf{if} \ \mathsf{show\_color} \colon
         num_colors = max(coloring.values()) + 1
         colors = rainbow(num_colors) ### colors is a list of num_colors colors
         ### the coloring few lines create a dictionary {color: [vertices]}
         c = {colors[i]: [] for i in range(num_colors)}
         for v in vertex_order:
             i = coloring[v]
             c[colors[i]].append(v)
         g.show(vertex_color=c)
                                                                      21
    return coloring
```

#### In [4]:

```
g = graphs.CycleGraph(5)
print greedy_coloring(g,show_color=True)
```



{0: 5, 1: 5, 2: 5, 3: 6, 4: 5}

#### In [5]:

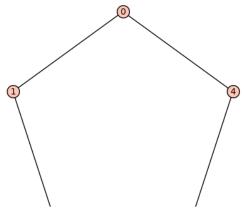
```
### some functions of graph
### graphs contains many built-in graphs
g = graphs.CycleGraph(5)

g.show()

print "vertices", g.vertices()
print "edges", g.edges()
print "neighbors of 0", g.neighbors(0)

### an example of coloring
### c = {vertex: color}
c = {0:0, 1:1, 2:0, 3:1, 4:2}

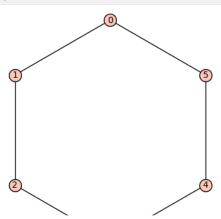
### call a color
print "the color for vertex 3 is", c[3]
```



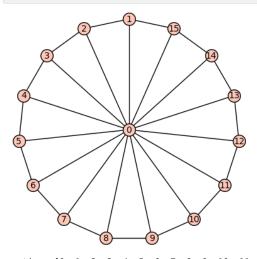
#### Examples

```
In [6]:
```

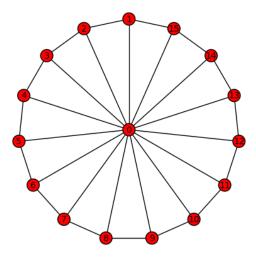
```
### Cycle graph
g = graphs.CycleGraph(6)
g.show()
print "vertices", g.vertices()
print "edges", g.edges()
print "neighbors of 0", g.neighbors(0)
def greedy_coloring(g, vertex_order=None, show_color=False):
     Input:
          g: a simple graph
          vertex_order: a list of vertices of g;
                            if None, g.vertices() is taken.
          show_color: show the graph with the output color if True
     Output:
     a coloring
     if vertex_order==None:
          vertex_order = g.vertices()
     coloring={\overline{}}
     for v in vertex_order:
          coloring[0] = 0
if v + 1 == g.neighbors(v):
               coloring[v + 1] = coloring[v] + 1 ### this part your need to find a proper j and assign coloring[v] = j
          if v + 1 != g.neighbors(v):
                coloring[v + 1] = coloring[v]
     if show_color:
    num_colors = max(coloring.values()) + 1
          colors = max(cotoring, values()) + I
colors = rainbow(num_colors) ### colors is a list of num_colors colors
### the coloring few lines create a dictionary {color: [vertices]}
c = {colors[i]: [] for i in range(num_colors)}
          for v in vertex_order:
                i = coloring[v]
                c[colors[i]].append(v)
          g.show(vertex_color=c)
     return coloring
print greedy_coloring(g,show_color=True)
```



```
### Wheel graph
g = graphs.WheelGraph(16)
g.show()
print "vertices", g.vertices()
print "edges", g.edges()
print "neighbors of 0", g.neighbors(0)
def greedy_coloring(g, vertex_order=None, show_color=False):
     Input:
         g: a simple graph
         vertex_order: a list of vertices of g;
                          if None, g.vertices() is taken.
         show_color: show the graph with the output color if True
    Output:
    a coloring
    if vertex_order==None:
         vertex_order = g.vertices()
     coloring={\overline{}}
     for v in vertex_order:
         coloring[0] = 0
         if v + 1 == g.neighbors(v):
              coloring[v + 1] = coloring[v] + 1 ### this part your need to find a proper j and assign coloring[v] = j
         if v + 1 != g.neighbors(v):
              coloring[v + 1] = coloring[v]
    \textbf{if} \ \mathsf{show\_color} \colon
         num_colors = max(coloring.values()) + 1
         colors = rainbow(num_colors) ### colors is a list of num_colors colors
### the coloring few lines create a dictionary {color: [vertices]}
c = {colors[i]: [] for i in range(num_colors)}
         for v in vertex_order:
              i = coloring[v]
              c[colors[i]].append(v)
         g.show(vertex_color=c)
    return coloring
print greedy_coloring(g,show_color=True)
```

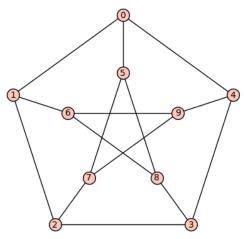


vertices [0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15] edges [(0, 1, None), (0, 2, None), (0, 3, None), (0, 4, None), (0, 5, None), (0, 6, None), (0, 7, None), (0, 8, None), (0, 9, None), (0, 10, None), (0, 11, None), (0, 12, None), (0, 13, None), (0, 14, None), (0, 15, None), (1, 2, None), (1, 15, None), (2, 3, None), (3, 4, None), (4, 5, None), (5, 6, None), (6, 7, None), (7, 8, None), (8, 9, None), (9, 10, None), (10, 11, None), (11, 12, None), (12, 13, None), (13, 14, None), (14, 15, None)] neighbors of 0 [1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14, 15]

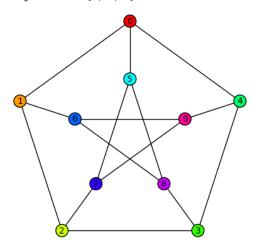


 $\{0:\ 0,\ 1:\ 0,\ 2:\ 0,\ 3:\ 0,\ 4:\ 0,\ 5:\ 0,\ 6:\ 0,\ 7:\ 0,\ 8:\ 0,\ 9:\ 0,\ 10:\ 0,\ 11:\ 0,\ 12:\ 0,\ 13:\ 0,\ 14:\ 0,\ 15:\ 0,\ 16:\ 0\}$ 

```
### Petersen graph
g = graphs.PetersenGraph()
g.show()
print "vertices", g.vertices()
print vertices, g.vertices()
print "edges", g.edges()
print "neighbors of 0", g.neighbors(0)
def greedy_coloring(g, vertex_order=None, show_color=False):
     Input:
         g: a simple graph
         vertex_order: a list of vertices of g;
                          if None, g.vertices() is taken.
         show_color: show the graph with the output color if True
    Output:
    a coloring
    if vertex_order==None:
         vertex_order = g.vertices()
     coloring={\overline{}}
     for v in vertex_order:
         coloring[v] = v ### this part your need to find a proper j and assign coloring[v] = j
         num_colors = max(coloring.values()) + 1
         colors = rainbow(num_colors) ### colors is a list of num_colors colors ### the coloring few lines create a dictionary {color: [vertices]}
         c = {colors[i]: [] for i in range(num_colors)}
         for v in vertex_order:
              i = coloring[v]
         c[colors[i]].append(v)
g.show(vertex_color=c)
     return coloring
print greedy_coloring(g,show_color=True)
```



```
vertices [0, 1, 2, 3, 4, 5, 6, 7, 8, 9] edges [(0, 1, None), (0, 4, None), (0, 5, None), (1, 2, None), (1, 6, None), (2, 3, None), (2, 7, None), (3, 4, None), (3, 8, None), (4, 9, None), (5, 7, None), (5, 8, None), (6, 8, None), (6, 9, None), (7, 9, None)] neighbors of [0, 1, 4, 5]
```



 $\{0\colon\, 0,\ 1\colon\, 1,\ 2\colon\, 2,\ 3\colon\, 3,\ 4\colon\, 4,\ 5\colon\, 5,\ 6\colon\, 6,\ 7\colon\, 7,\ 8\colon\, 8,\ 9\colon\, 9\}$ 

In [0]:

## In [1]:

```
function [Np Nn Nz] = sylv inertia(A)
% compute the Sylvester's inertia of a symmetric matrix
% Np: number of positive eigenvalues of the input matrix
% Nn: number of negative eigenvalues of the input matrix
% Nz: number of zero eigenvalues of the input matrix
[V D] = eig(A) % D is a diagonal matrix composed of the eigenvalues of A
                % V is a matrix composed of the eigenvectors of A
d = diaq(D); % d is a vector composed of all eigenvalues of A
Np = sum(d > 0); % Np is the number of positive eigenvalues of A
Nn = sum(d < 0); % Nn is the number of negative eigenvalues of A
Nz = sum(d == 0); % Nz is the number of zero eigenvalues of A
end
% the main program for calling the sylv inertia function
% clear all; % clear all existing variables
% close all; % close all graph windows
% A is the input symmetric matrix
A = [2 5 8 -7; 5 6 9 12; 8 9 -4 18; -7 12 18 -30]; % example 1
%A = [3 6 8 -7; 6 10 9 12; 8 9 -4 18; -7 12 18 45]; % example 2
%A = [14 -2 28 -7; -2 10 9 12; 28 9 -9 18; -7 12 18 2]; % example 3
disp('The input matrix is ');
disp(A);
[Np Nn Nz] = sylv inertia(A); % call the sylv inertia function
disp('sylv inertia(A)');
disp(['
           Np
                        Nz']);
                  Nn
disp([Np, Nn, Nz]);
The input matrix is
   2
         5
              8
                 - 7
   5
         6
              9
                  12
    8
         9
             - 4
                  18
        12
   - 7
            18
                - 30
V =
  0.227952 -0.076146 -0.922865
                                    0.300932
  -0.160742 -0.661920
                         0.240412
                                    0.691539
  -0.413408
              0.707753
                         0.026099
                                    0.572274
  0.866772 0.234837
                         0.299736
                                    0.322050
D =
Diagonal Matrix
  -42.6514
                   0
                             0
                                       0
             -7.3054
         0
                             0
                                       0
         0
                        2.7447
                                       0
                   0
         0
                   0
                                 21.21218
                             0
sylv inertia(A)
     Np
           Nn
                 Nz
  2
       2
           0
```

# Limit



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#### Introduction

This program aims to show what is the "Limit".

In mathematics, a limit is the value that a function (or sequence) "approaches" as the input (or index) "approaches" some value.

1. Give a simple polynomial, ex:

$$\frac{x+1}{x^2+2x-3}$$

We want to know what will happens when  $x \to 3$ .

2. It's easy to see that

$$\frac{x+1}{x^2+2x-3} \to \frac{1}{3}$$

as  $x \rightarrow 3$ .

3. We can denote as

$$\lim_{x \to 3} \frac{x+1}{x^2 + 2x - 3} = \frac{1}{3}$$

which means the value of  $\frac{x+1}{x^2+2x-3}$  will approach to  $\frac{1}{3}$ , as  $x \to 3$ .

# Algorithm

To solve the problem by the following process:

We can start with giving a value of x.

For example: x=2, which lead  $\frac{x+1}{x^2+2x-3}=\frac{2}{5}$  Then start to approaching to x=3 from x=2 like below

$$x = 2$$

$$\frac{x+1}{x^2+2x-3} = \frac{3}{5} = 0.6$$

$$x = 2.1$$

$$\frac{x+1}{x^2+2x-3} = \frac{3.1}{5.61} = 0.553$$
.

$$x = 2.8$$

$$\frac{x+1}{x^2+2x-3} = \frac{3.8}{10.44} = 0.364$$

$$x = 2.9$$

$$\frac{x+1}{x^2+2x-3} = \frac{3.9}{11.21} = 0.348$$

$$x = 3$$

$$\frac{x+1}{x^2+2x-3} = \frac{1}{3} = 0.333$$

We can see that the value of  $\frac{x+1}{x^2+2x-3}$  is gradually approach to  $\frac{1}{3}$ 

# **Implimentation**

First,need to check if the limit exists or not Except some unique function like  $f(x) = -1^x$ 

If the function is fraction form like  $\frac{x+5}{x-3}$  ,and input approach to some value a

We can check the function does or doesn't have limit when input approach to a by this way

if (x-3)%(x-a)=0, limit doesn't exist if  $(x-3)\%(x-a)\neq0$ , limit exists

For example, we want to know,

$$f(x) = \frac{x^2 - 1}{x} \to ? \text{ if } x \to 2$$

First, check limit does or doesn't exist

```
In [1]:
if (x)%(x-2)==0:
    print "limit doesn't exist"
if (x)%(x-2)!=0:
    print "limit exist"
       _____
                                           Traceback (most recent call
TypeError
last)
<ipython-input-1-a814ec059bdb> in <module>()
---> 1 if (x)%(x-Integer(2))==Integer(0):
            print "limit doesn't exist"
      3 if (x)%(x-Integer(2))!=Integer(0):
            print "limit exist"
sage/structure/element.pyx in sage.structure.element.Element. mod
 (build/cythonized/sage/structure/element.c:13749)()
sage/structure/element.pyx in sage.structure.element.Element._mod_ (bu
ild/cythonized/sage/structure/element.c:14075)()
TypeError: unsupported operand parent(s) for %: 'Symbolic Ring' and 'S
ymbolic Ring'
So we know \lim_{x\to 2} \frac{x^2-1}{x} exists Then we can solve \lim_{x\to 2} \frac{x^2-1}{x}
In [5]:
for i in range(11):
    a=1+0.1*i
    h=(a^2-1)/a
    print h
0.000000000000000
0.190909090909091
0.36666666666667
0.530769230769231
0.685714285714286
0.833333333333333
0.975000000000000
1.11176470588235
1.2444444444444
1.37368421052632
```

We can also use "limit\_app" to solve  $\lim_{x\to 2} \frac{x^2-1}{x} = ?$  since we know limit exists

1.50000000000000

In [6]:

```
def limit_app(f,a):
    Input:
        f: a function (symbolic exporession in x)
        a: a real number
    Output:
        print the approximation of f(x) as a approaches to a

    for i in range(1,11):
        t=(a-1)+0.1*i
        g=f.subs(x=t)
        print g
# return g
```

### In [7]:

```
limit_app((x^2-1)/(x),2)

0.190909090909091

0.3666666666667

0.530769230769231

0.685714285714285

0.83333333333333333333333

0.9750000000000000000

1.11176470588235

1.244444444444444444444

1.37368421052632

1.50000000000000000
```

#### **Explanation**

The goal is to solve what value of function will be approached when the value of x approach to 3

$$x \to 3$$

$$\frac{x+1}{x^2+2x-3} \to ?$$

We can easy to calculate that when value of  $\boldsymbol{x}$  is closer and closer to 3 Value of function

$$\frac{x+1}{x^2+2x-3}$$
 is approaching to  $0.333 = \frac{1}{3}$ 

Notice that not any funtion can approach to a unique value when input approach to some value For example,

```
f(x) = -1^{x} when x = 10 \rightarrow f(x) = 1 But it doesn't mean that \lim_{x \to 10} f(x) = 1
```

Let's see why, We all know

$$f(10) = 1$$

But

The value of f(x) isn't just approaching to 1 while the value of x approaching to 10. The value of f(x) just switch between 1 and -1

Thus  $\lim_{x\to 10} f(x)$  doesn't exist

In the end,we know that  $\lim_{x\to 2} \frac{x^2-1}{x}$  exists and  $\lim_{x\to 2} \frac{x^2-1}{x}=1.5$ 

# **Examples**

**1.** 
$$\lim_{x\to 5} \frac{x^2}{x+5} = ?$$

```
In [8]:
```

```
###check
if (x+5)\%(x-5)==0:
    print "limt doesnt exist"
if (x+5)%(x-5)!=0:
    print "limit exist"
                                           Traceback (most recent call
TypeError
 last)
<ipython-input-8-8930f8a2484e> in <module>()
      1 ###check
----> 2 if (x+Integer(5))%(x-Integer(5))==Integer(0):
            print "limt doesnt exist"
      4 if (x+Integer(5))%(x-Integer(5))!=Integer(0):
            print "limit exist"
sage/structure/element.pyx in sage.structure.element.Element. mod
 (build/cythonized/sage/structure/element.c:13749)()
sage/structure/element.pyx in sage.structure.element.Element. mod (bu
ild/cythonized/sage/structure/element.c:14075)()
TypeError: unsupported operand parent(s) for %: 'Symbolic Ring' and 'S
ymbolic Ring'
In [9]:
for i in range(11):
    x=3+0.2*i
    q=(x^2)/(x+5)
    print g
1.12500000000000
1.24878048780488
1.37619047619048
1.50697674418605
1.64090909090909
1.777777777778
1.91739130434783
2.05957446808511
2.20416666666667
2.35102040816327
2.50000000000000
\lim_{x\to 5} \frac{x^2}{x+5} = 2.5
```

# In [10]:

```
limit_app((x^2)/(x+5),5)
```

- 2.50000000000000
- 2.50000000000000
- 2.500000000000000
- 2.50000000000000
- 2.500000000000000
- 2.500000000000000
- 2.50000000000000
- 2.500000000000000
- 2.50000000000000
- 2.50000000000000

**2.** 
$$\lim_{x\to 7} \frac{x^3-5x}{x-7} = ?$$

# In [11]:

```
###check
if (x-7)%(x-7)==0:
    print "limt doesnt exist"
if (x-7)%(x-7)!=0:
    print "limit exist"
```

limt doesnt exist

 $\lim_{x\to7} \frac{x^3-5x}{x-7}$  doesn't exists

# In [12]:

```
for i in range(11):
    x=5+0.2*i
    g=(x^3-5*x)/(x-7)
    print g
```

- -50.0000000000000
- -63.6711111111111
- -81.5400000000000
- -105.440000000000
- -138.426666666667
- -186.000000000000
- -259.160000000000
- -383.573333333334
- -636.239999999999
- -1402.16000000000
- +infinity

```
In [13]:
```

```
limit app((x^3-5*x)/(x-7),7)
+infinity
\lim_{x\to 7} \frac{x^3-5x}{x-7} doesn't exists
3. \lim_{x\to 10} 3x^2 - 6x - 1 = ?
In [14]:
limit_app(3*x^2-6*x-1,10)
104.000000000000
104.000000000000
104.000000000000
104.000000000000
104.000000000000
104.000000000000
104.000000000000
104.000000000000
104.000000000000
104.000000000000
In [15]:
def existence(h,k):
    Input:
         h:a function
         k:a function
    Output:
         determine limit exist or not
    H=h.polynomial(QQ)
    K=k.polynomial(QQ)
    if H.quo_rem(K) == (t.polinomial(QQ),0)
    print "limit doesn't exist"
    else
    print "limit exists"
  File "<ipython-input-15-1a100a382493>", line 11
    if H.quo_rem(K)==(t.polinomial(QQ),Integer(0))
SyntaxError: invalid syntax
```

#### In [16]:

```
### now you can do division algorithm

### create factors in polynomial
factor1 = (x-1).polynomial(QQ)
factor2 = (x+1).polynomial(QQ)

g.quo_rem(factor1) ### you may try factor2
```

```
Traceback (most recent call
AttributeError
last)
<ipython-input-16-c3c66227d409> in <module>()
      2
      3 ### create factors in polynomial
----> 4 factor1 = (x-Integer(1)).polynomial(QQ)
      5 factor2 = (x+Integer(1)).polynomial(QQ)
sage/structure/element.pyx in sage.structure.element.Element.__getattr
__ (build/cythonized/sage/structure/element.c:4303)()
sage/structure/element.pyx in sage.structure.element.Element.getattr f
rom category (build/cythonized/sage/structure/element.c:4412)()
sage/cpython/getattr.pyx in sage.cpython.getattr.getattr from other cl
ass (build/cythonized/sage/cpython/getattr.c:1834)()
AttributeError: 'sage.rings.real_mpfr.RealNumber' object has no attrib
ute 'polynomial'
```

#### In [17]:

```
### functions related to polynomials
f = x^2 + 2x - 3
### originally f is a symbolic expression
print "type(f)", type(f)
g = f.polynomial(QQ)
### put f as a polynomial with QQ (rational numbers) as coefficients
print "type(g)", type(g)
type(f) <type 'sage.rings.real_mpfr.RealNumber'>
                                          Traceback (most recent call
AttributeError
last)
<ipython-input-17-7220011bfae7> in <module>()
      6 print "type(f)", type(f)
----> 8 g = f.polynomial(QQ)
     10 ### put f as a polynomial with QQ (rational numbers) as coeffi
cients
sage/structure/element.pyx in sage.structure.element.Element. getattr
(build/cythonized/sage/structure/element.c:4303)()
sage/structure/element.pyx in sage.structure.element.Element.getattr f
rom category (build/cythonized/sage/structure/element.c:4412)()
sage/cpython/getattr.pyx in sage.cpython.getattr.getattr from other cl
ass (build/cythonized/sage/cpython/getattr.c:1834)()
AttributeError: 'sage.rings.real_mpfr.RealNumber' object has no attrib
ute 'polynomial'
```

```
In [18]:
```

```
f = (x^5).polynomial(QQ)
print_remainder(f,2)
AttributeError
                                          Traceback (most recent call
 last)
<ipython-input-18-efbd6e69877f> in <module>()
---> 1 f = (x**Integer(5)).polynomial(QQ)
      3 print remainder(f,Integer(2))
sage/structure/element.pyx in sage.structure.element.Element.
__ (build/cythonized/sage/structure/element.c:4303)()
sage/structure/element.pyx in sage.structure.element.Element.getattr f
rom category (build/cythonized/sage/structure/element.c:4412)()
sage/cpython/getattr.pyx in sage.cpython.getattr.getattr from other cl
ass (build/cythonized/sage/cpython/getattr.c:1834)()
AttributeError: 'sage.rings.real_mpfr.RealNumber' object has no attrib
ute 'polynomial'
In [19]:
### sample code for recursive programming
### suppose f(x) = a_0 + a_1(x-3) + a_2(x-3)^2 + ... + a_{10}(x-3)^{10}
### let's find a_0, ..., a_10
def print_remainder(f, a):
    Input:
        f: a polynomial
        a: a value
    Output:
        print a_0, ..., a_n recursively.
    if f == (0*x).polynomial(QQ):
        return None
    else:
        quo, rem = f.quo_rem((x-a).polynomial(QQ))
        print rem
        print remainder(quo, a)
```

### In [20]:

```
###請問要如何讓迴圈中的i可以以小數點來計算?

print 'first kind'
for i in range(10):
    k = 3 - 10^(-i)
    print N(k)

print '---'
print 'second kind'
for i in range(10):
    k = 3 + 0.1 * i
    print k

#for i in range(2,4):
# g=(i+1)/(i^2+2*i-3)
# print g;

### Jephian: I don't quite understand what you plan to do?
```

```
first kind
2.000000000000000
2.90000000000000
2.99000000000000
2.99900000000000
2.99990000000000
2.99999000000000
2.99999900000000
2.99999990000000
2.99999999000000
2.9999999900000
second kind
3.00000000000000
3.10000000000000
3.20000000000000
3.30000000000000
3.40000000000000
3.50000000000000
3.60000000000000
3.70000000000000
3.8000000000000
```

3.90000000000000

ass (build/cythonized/sage/cpython/getattr.c:1834)()

# Linear Classifier 線性分類器



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## **Overview**

描述 Linear Classifier 的目的。

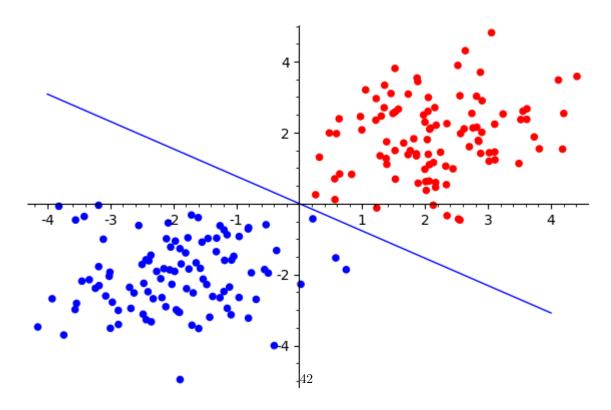
給定兩群正負對比且向量化的資料 A 與 B 其中 A 裡面的每筆資料都為以下形式

 $(x_1, x_2, \ldots, x_m, 1)$ 

而 B 裡面的每筆資料都為以下形式

 $(x_1,x_2,\ldots,x_m,-1)\circ$ 

目的是找到一個通過原點的超平面  $h: z_1x_1+z_2x_2+\cdots+z_mx_m=0$  且其法向量為  $\mathbf{v} = (z_1, z_2, \dots, z_m)$ ,使得 A, B 兩群資料被一分為二。



## **Algorithm**

假設有兩群正負對比的資料,每筆資料有m個不同屬性的類型和1個判斷正負的類型。 輸入 n 筆資料  $[(\mathbf{x}_1,y_1),(\mathbf{x}_2,y_2),\ldots,(\mathbf{x}_n,y_n)],\mathbf{x}_i\in\mathbb{R}^m$  and  $y_i\in\{-1,1\}$  for  $i=1,2,\ldots,n$   $\circ$ 如果資料為正,則  $y_i=1$ 。如果資料為負,則  $y_i=-1$ 。

輸出 
$$\mathbf{v}$$
 使得  $\left\{egin{array}{ll} \mathbf{v}\cdot\mathbf{x}_i > 0 & ext{, if } y_i = 1 \ \mathbf{v}\cdot\mathbf{x}_i < 0 & ext{, if } y_i = -1 \end{array}
ight.$  for  $i=1,2,\ldots,m$   $\circ$ 

- 1. 初始值  $\mathbf{v_0} = \mathbf{0}$
- 2. 找出錯誤 :  $\mathrm{sign}(\mathbf{v_k}\cdot\mathbf{x}_i) 
  eq y_i$

修正錯誤:  $\mathbf{v_{k+1}} = \mathbf{v_k} + y_i \mathbf{x}_i$ 。

3. 重複第2步驟直到沒有任何錯誤。

## **Explanation**

假設有一個超平面區分開兩筆資料,且超平面為  $y=\mathbf{v}$ 。 且 v 經過上述演算法後,會在正號資料的那一區, 使得正號資料跟 $\mathbf{v}$ 內積為正,負號資料跟 $\mathbf{v}$ 內積為負。

之後如有資料  $\mathbf{x} \in \mathbb{R}^m$  輸入,

則 
$$\left\{egin{aligned} \mathbf{v}\cdot\mathbf{x}>0 &, ext{then }y=1, ext{歸類在正號區} \circ \ \mathbf{v}\cdot\mathbf{x}<0 &, ext{then }y=-1, ext{歸類在負號區} \circ \end{aligned}
ight.$$

## **Convergence of Linear Classifier**

假設存在一個法向量  $\mathbf{v}$  能夠將資料分成兩群,那必定會在有限的次數內找到  $\mathbf{v}$  。

Proof:

Suppose 
$$|\mathbf{v}|=1$$
,  $R=\max |\mathbf{x}_i|$ ,  $\alpha=\min |\mathbf{v}\cdot\mathbf{x}_t|$  and  $\mathbf{v}_1=\mathbf{0}$ .

Let 
$$\mathbf{v}_k = \mathbf{v}_{k-1} + y_t \mathbf{x}_t$$
.

We note that  $\mathbf{x}_t$  is chosen because  $\mathbf{v}_{k-1}$  failed to classify  $\mathbf{x}_t$ .

That is,  $\mathbf{v}_{k-1} \cdot \mathbf{x}_t$  and  $y_t$  has opposite signs.

Equivalently,  $\mathbf{v}_{k-1} \cdot y_t \mathbf{x}_t < 0$ .

(1)

$$\mathbf{v}_k \cdot \mathbf{v} = (\mathbf{v}_{k-1} + y_t \mathbf{x}_t) \mathbf{v} \ge \mathbf{v}_{k-1} \cdot \mathbf{v} + \alpha = (\mathbf{v}_{k-2} + y_t \mathbf{x}_t) \mathbf{v} + \alpha \ge \mathbf{v}_{k-2} \cdot \mathbf{v} + 2\alpha \ge \cdots \ge k\alpha$$
 $\implies \mathbf{v}_k \cdot \mathbf{v} > k\alpha$ 

(2)

$$\|\mathbf{v}_{k}\|^{2} = \|\mathbf{v}_{k-1} + y_{t}\mathbf{x}_{t}\|^{2}$$

$$= \|\mathbf{v}_{k-1}\|^{2} + 2(\mathbf{v}_{k-1} \cdot y_{t}\mathbf{x}_{t}) + \|\mathbf{x}_{t}\|^{2}$$

$$\leq \|\mathbf{v}_{k-1}\|^{2} + \|\mathbf{x}_{t}\|^{2}$$

$$\leq \|\mathbf{v}_{k-1}\|^{2} + R^{2} \leq \cdots \leq kR^{2}$$

$$\Longrightarrow \|\mathbf{v}_k\|^2 \leq kR^2$$

From (1)(2), by Cauchy-Schwarz inequality

$$k\alpha \leq \mathbf{v}_k \cdot \mathbf{v} \leq \|\mathbf{v}_k\| \|\mathbf{v}\| \leq \sqrt{kR^2}$$

$$\implies k\alpha \le \sqrt{k}R$$

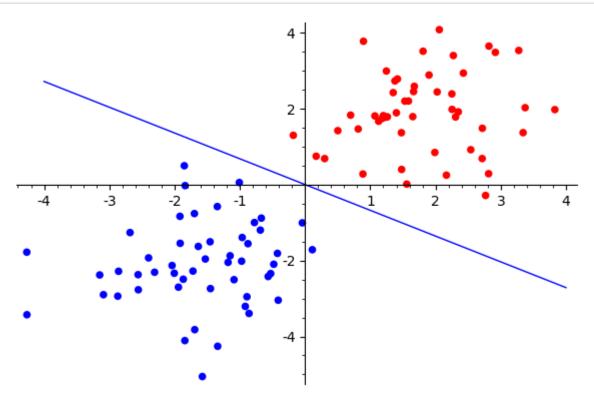
$$\implies k \leq \frac{R^2}{\alpha^2}$$

# **Implementation**

```
In [1]: def discriminate(data, v):
            for i in data:
                 tmp = i[0]*v[0] + i[1]*v[1]
                 if (tmp*i[2])<=0:
                     return [v[0] + i[2]*i[0], v[1] + i[2]*i[1]]
            else:
                 return v
        def linear_classifier(data):
            Input:
                 data: a list of pairs [(x1,y1,k), ..., (xN,yN,k)], k=\{-1,+1\}
                Output v so that the line v = a (xi, yi)
            v = [0,0]
            while(v != discriminate(data, v)):
                 v = discriminate(data, v)
             return v
```

## **Examples 1.**

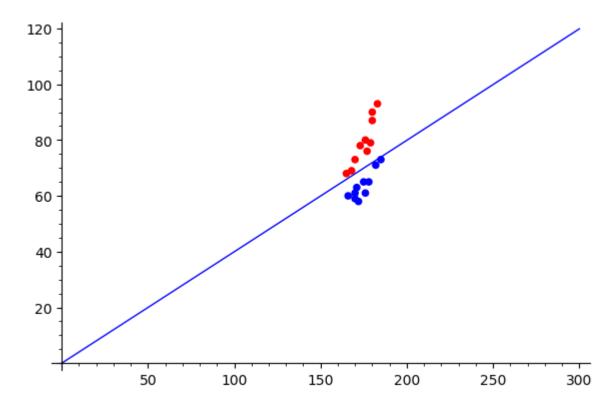
```
In [5]: import numpy as np
        n = 50
        x1 = np.random.randn(n) + 2
        y1 = np.random.randn(n) + 2
        data1 = zip(x1,y1)
        p = point(data1, rgbcolor='red', size=30)
        x2 = np.random.randn(n) - 2
        y2 = np.random.randn(n) - 2
        data2 = zip(x2,y2)
        q = point(data2, rgbcolor='blue', size=30)
        data = zip(x1, y1, [1]*n) + zip(x2, y2, [-1]*n)
        #print data
        v = linear_classifier(data)
        x = var('x')
        g = -(v[0]/v[1])*x
        pic = g.plot(xmin=-4,xmax=4)
        f=p+q+pic
        f.show()
```



# **Examples 2.**

## In [6]: import numpy as np n = 10x1 = [170, 165, 173, 176, 180, 180, 179, 168, 177, 183]y1 = [73,68,78,80,90,87,79,69,76,93]data1 = zip(x1,y1)p = point(data1, rgbcolor='red', size=30) x2 = [175, 166, 171, 178, 182, 170, 185, 170, 172, 176]y2 = [65,60,63,65,71,61,73,59,58,61]data2 = zip(x2,y2)q = point(data2, rgbcolor='blue', size=30) data = zip(x1, y1, [1]\*n) + zip(x2, y2, [-1]\*n)print data v = linear\_classifier(data) print '身高' print 170 print '體重' print ceil(-170\*v[0]/v[1]) print '身高' print 175 print '體重' print ceil(-175\*v[0]/v[1]) x = var('x')g = -(v[0]/v[1])\*xpic = g.plot(xmin=0,xmax=300) f=p+q+pic f.show()

```
[(170, 73, 1), (165, 68, 1), (173, 78, 1), (176, 80, 1), (180, 90,
1), (180, 87, 1), (179, 79, 1), (168, 69, 1), (177, 76, 1), (183, 93,
1), (175, 65, -1), (166, 60, -1), (171, 63, -1), (178, 65, -1), (182,
71, -1), (170, 61, -1), (185, 73, -1), (170, 59, -1), (172, 58, -1),
(176, 61, -1)
身高
170
體重
68
身高
175
體重
70
```



In [ ]:

# Linear dependent



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#### Overview

Given a subset S of a vector space  $\mathsf{A} = (\vec{a}_1 \ \vec{a}_2 \ \dots \ , \vec{a}_n)$  and  $\mathsf{A} \in \mathbb{R}^n$ 

linear dependent aims to check wether the subset of vector space is linear dependent

$$c_1\vec{a}_1 + c_2\vec{a}_2 + \dots + c_n\vec{a}_n = \vec{0}$$

If  $c_i \in R$  ,  $c_i \neq \mathbf{0}$  , for i=1,2,...,n , then S is linear dependent .

### Algorithm

- 1. Given a subset S of a vector space  $A=(\vec{a}_1,\vec{a}_2,\ldots,\vec{a}_n)$  and  $A\in\mathbb{R}^n$
- 2. Use the #gauss method to check whether the vector is linear dependent

#### Guass thm

A vector after doing the Guass eliminatin thm,

at least a row or a column which the number of the elements are all zero.

The vector is linear dependent.

### In [1]:

```
import numpy as np

A = np.array(
       [
            [1, 1 ,2 ,3],
            [2, 1, 1, 2],
            [3, 0, 1, 5],
            [6, 2, 4, 10]
       ])
```

```
In [2]: 49
```

#Let a set of matrix from your vector(a1,...an)

```
In [3]:
```

## In [4]:

```
nA=Gauss(A)
nA
# now you can check matrix nA has zero vector?
```

## Out[4]:

## In [0]:

# **Matrix exponential**



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#### Overview

我們的目標是寫出一個函數,然後在人們輸入一個矩陣 A 以及一個 正整數 N 的情況下,使得我們的函數最終能夠輸出一個泰勒級數的 前N項和

### **Algorithm**

- 1. Create an  $n \times n$  matrix  $A = \begin{bmatrix} x_{11} & \cdots & x_{n1} \\ \vdots & \ddots & \vdots \\ x_{1n} & \cdots & x_{nn} \end{bmatrix}$  and input an integer N.

  2. Then compute  $A^k$  for  $k = 0, \ldots, N$  and also add the term  $\frac{1}{k!}A^k$
- to the current total.

#### **Explanation**

目標是想找到矩陣的指數  $e^A$  運算過後出來所得的值

對於  $n \times n$  階矩陣 A,我們可以定義矩陣指數 (matrix exponential),方法是仿照指數函數的冪級數定義,如下的 常數指數:

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \cdots$$

將變數 x 以矩陣 A 取代,常數 1 以單位矩陣 I 取代,矩陣指數  $e^A$  即為下列冪矩陣級數

$$e^A = I + A + \frac{A^2}{2!} + \frac{A^3}{3!} + \cdots$$

對於任-x,指數函數  $e^x$  總會收斂;同樣地,對於任-A,矩陣指數  $e^A$  也總會收斂。證明於下,令:

$$e_m(A) = \sum_{k=0}^m \frac{A^k}{k!}$$

若m > p,則

$$e_m(A) - e_p(A) = \sum_{k=0}^m \frac{A^k}{k!} - \sum_{k=0}^p \frac{A^k}{k!} = \sum_{k=p+1}^m \frac{A^k}{k!}$$

使用矩陣範數的不等式性質,

```
||e_m(A) - e_p(A)|| \le \sum_{k=p+1}^m \frac{||A||^k}{k!}
```

上式將問題帶回純量的情況。當m和p同趨於無窮大,不等式右邊趨於零。

## **Implementation**

```
In [1]:
```

```
def matrix_exponential(A, N):
    n = A.dimensions()[0]
    current = identity_matrix(n)
    extra = A

for p in range(1,N+1):
        current = current + extra
        extra = extra * A / (p+1)
return current
```

### In [2]:

### Out[2]:

```
[2757.73213796075 3830.83971400187 5148.75408439439 1196.01097321682]
[3970.57351849152 5518.37372994342 7414.96317963041 1722.19483056945]
[5184.41489902228 7203.90774588497 9682.17227486642 2248.37868792207]
[809.560920353845 1123.68934396104 1511.13939682401 351.789238235083]
```

#### **Examples**

## In [3]:

[0 1 0] [0 0 1]

```
### Example 1
def matrix_exponential(A, N):
    n = A.dimensions()[0]
    current = identity_matrix(n)
    extra = A
    for p in range(1,N+1):
        current = current + extra
        extra = extra * A / (p+1)
    return current
A = matrix([
    [1,0,0],
    [0,1,0],
    [0,0,1]
])
print' when A ='
print A
print 'the exponential of A in Taylor 0 is'
print matrix_exponential(A,0)
when A =
[1 0 0]
[0 1 0]
[0 \ 0 \ 1]
the exponential of A in Taylor \theta is
[1 0 0]
```

## In [4]:

```
### Example 2
def matrix_exponential(A, N):
    n = A.dimensions()[0]
    current = identity matrix(n)
    extra = A
    for p in range(1,N+1):
        current = current + extra
        extra = extra * A / (p+1)
    return current
A = matrix([
    [1,0,0,0],
    [0,1,0,0],
    [0,0,1,0],
    [0,0,0,1]
])
print' when A ='
print A
print 'the exponential of A in Taylor 4 is'
print matrix_exponential(A,4)
when A =
[1 0 0 0]
[0 1 0 0]
```

```
[0 0 1 0]
[0 0 0 1]
the exponential of A in Taylor 4 is
[65/24
         0
                0
                       0]
    0 65/24
                       0]
                 0
          0 65/24
                       0]
    0
                 0 65/24]
[
    0
```

## In [5]:

```
### Example 3
def matrix_exponential(A, N):
    n = A.dimensions()[0]
    current = identity matrix(n)
    extra = A
    for p in range(1,N+1):
        current = current + extra
        extra = extra * A / (p+1)
    return current
A = matrix([
    [1,1,1,1],
    [1,1,1,1],
    [1,1,1,1],
    [1,1,1,1]
])
print' when A ='
print A
print 'the exponential of A in Taylor 1 is'
print matrix_exponential(A,1)
```

```
when A =
[1 1 1 1]
[1 1 1 1]
[1 1 1 1]
[1 1 1 1]
the exponential of A in Taylor 1 is
[2 1 1 1]
[1 2 1 1]
[1 1 2 1]
[1 1 2 1]
```

## In [6]:

[163/60

[

0

0

0

0

1

0

0

0

0

1

0

01

0]

1]

1]

```
### Example 4
def matrix_exponential(A, N):
    n = A.dimensions()[0]
    current = identity matrix(n)
    extra = A
    for p in range(1,N+1):
        current = current + extra
        extra = extra * A / (p+1)
    return current
A = matrix([
    [1,0,0,0],
    [0,0,0,0],
    [0,0,0,1],
    [0,0,0,0]
])
print' when A ='
print A
print 'the exponential of A in Taylor 5 is'
print matrix_exponential(A,5)
when A =
[1 0 0 0]
[0 0 0 0]
[0 \ 0 \ 0 \ 1]
[0 0 0 0]
the exponential of A in Taylor 5 is
```

## In [7]:

```
### Example 5
def matrix_exponential(A, N):
    n = A.dimensions()[0]
    current = identity matrix(n)
    extra = A
    for p in range(1,N+1):
        current = current + extra
        extra = extra * A / (p+1)
    return current
A = matrix([
    [1,0,0,0,1],
    [0,0,0,0,0],
    [0,0,0,0,0],
    [0,0,0,0,0],
    [1,0,0,0,1]
])
print' when A ='
print A
print 'the exponential of A in Taylor 10 is'
print matrix_exponential(A,10)
when A =
[1 0 0 0 1]
[0 \ 0 \ 0 \ 0]
[0 \ 0 \ 0 \ 0]
[0 \ 0 \ 0 \ 0]
[1 0 0 0 1]
the exponential of A in Taylor 10 is
                                             0 15094/4725]
[19819/4725
                      0
                      1
                                  0
          0
                                             0
                                                         0]
          0
                      0
                                  1
                                             0
                                                         0]
          0
                      0
                                  0
                                             1
                                                         0]
[15094/4725
                      0
                                  0
                                             0 19819/4725]
In [ ]:
```

# Maximum matchings with any edge you want



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#### Overview

First, we need to know a few things about the maximum matching.

Maximum, the largest size of a matching.

A **matching** means a set of pairwise non-adjacent edges, none of which are loops; that is, no two edges share a common vertex.

Maximum matchings is the largest number of pairwise non-adjacent edges in a set.

### 程式邏輯

Select an edge, select the two points (B, C) of the edge, and regard it as a path. Take the shrimp to extend the path,

use the selected two sides as a waypoint, and extend one edge to create a path.

New path (A, B, C, D) and reverse the label of the entire path.

舉例:標記B-C邊,將原本的路徑擴充行新的路徑A-B-C-D,並將路徑上的標記做反轉,使得標記變為A-B、C-D

## **Algorithm**

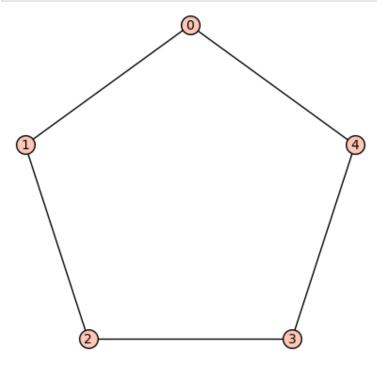
- 1.Input your graph.
- 2.mark any edges you choose, regarded as a path.
- 3.make its vertices expand along the edge and the other two vertices and invert the edges of the mark until all edges are selected.

### **Explanation**

可以選取一條邊並找島包含他的最大值,因為它是延你所選的邊一條一條的延伸,所以不會有遺漏任何邊

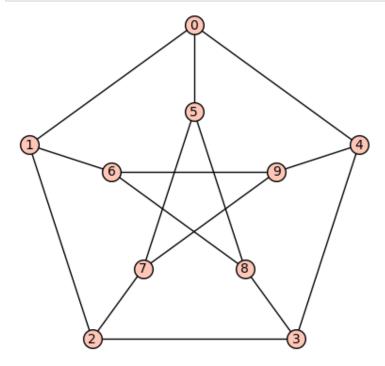
## **Implementation**

```
In [1]:
```



# In [2]:

```
# g = graphs.CycleGraph(5)
g = graphs.PetersenGraph()
g.show()
```



## In [0]:

# **Minimal Polynomial**



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#### Overview

### 多項式代入矩陣

• 若  $p(x)=a_nx^n+a_{n-1}x^{n-1}+\cdots+a_0$  是一個多項式, 則定義  $p(A)=a_nA^n+a_{n-1}A^{n-1}+\cdots+a_0I$ 。

## Cayley-Hamilton定理:

• A 為一個 n imes n 階矩陣且 p(t) 為 A 的特徵多項式(  $p(t) = \det(A - tI)$  )。將矩陣 A 替换 t 得到的矩陣 多項式滿足 p(A) = O。

## 最小多項式 $m_A(t)$ :

- 1. 滿足 p(A) = O 的方程式中次數為最小者
- 2. 最高次項係數為1

### 最小多項式的重要性質:

- 1. A 之所有的特徵值  $\lambda_i$  皆使  $m_A(\lambda_i)=0$
- 2. 若  $p(t)=(t-\lambda_1)^{m_1} imes(t-\lambda_2)^{m_2} imes\cdots imes(t-\lambda_k)^{m_k}, m_1+m_2+\cdots+m_k=n$ 則  $m_A(t)=(t-\lambda_1)^{d_1} imes (t-\lambda_2)^{d_2} imes \cdots imes (t-\lambda_k)^{d_k}, 1\leq d_i\leq m_i$ , orall i
- 3. A 可對角化  $\iff m_A(t) = (t-\lambda_1) \times (t-\lambda_2) \times \cdots \times (t-\lambda_k)$  ; i.e 最小多項式沒有重根

## **Algorithm**

- 1. Compute  $I, A, \ldots, A^n$  and flaten them into vectors in  $\mathbb{R}^{n^2}$ .
- 2. Find the smallest k such that  $\{I,A,\ldots,A^k\}$  is dependent.
- 3. Suppose  $A = [a_{i,j}]$ .

You may flatten them as a vector  $f(A)=(a_{1,1},\ldots,a_{1,n},a_{2,1}\ldots,a_{n,n})$  in  $\mathbb{R}^{n^2}$ 

- 4. Create a huge matrix H whose columns are  $f(I), f(A), \ldots, f(A^n)$  and do Gaussian elimination on H.
- 5. Find the minimum k such that  $\{f(I), f(A), \ldots, f(A^k)\}$  is dependent.
- 6. Find coefficients so that  $a_k f(A^k) + \dots a_0 f(I) = 0$  and  $a_k = 1$ .
- 7. Thus  $a_kA^k+\ldots a_0I=O$  and  $m(t)=a_kt^k+\cdots +a_0$  is the minimal polynomial.

## **Explanation**

判斷 $A_{n\times n}$ 是否可對角化

$$p(t) = det(A-tI) = (t-\lambda_1)^{m_1} imes (t-\lambda_2)^{m_2} imes \cdots imes (t-\lambda_k)^{m_k}$$

找出p(t)的最小多項式 $m_A(t)$ 使得 $m_A(A)=0$ 如果 $m_A(t)$ 中 $(t-\lambda_i)$ 的次數皆為1次,則A為可對角化 如果 $m_A(t)$ 中其中一項 $(t-\lambda_i)^k, 2 \leq k$ ,則A為不可對角化

## **Implementation**

```
In [1]:
        def minimalpolynomial(data):
            Input:
                data: 給定一方陣A
            Output:
                Output 最小多項式 m_A(t) 中沒有重根,則方陣A為可對角化。
            data.change ring(QQ)
            m,n = data.dimensions()
            if (m == n):
                I = identity matrix(n)
        單位矩陣
                flattened I = [I[i,j] for i in range(m) for j in range(n)] #
        攤平單位矩陣
                flattened data = [flattened I] #將I存成[I]
                for k in range(1, m+1):
                    data i=data^k
                    flattened_data_i= [data_i[i,j] for i in range(m) for j in
        range(n)] #data^k矩陣攤平
                    flattened data.append(flattened data i) #將矩陣變為[I,data^
        1, . . . , data^k]
                M = matrix(flattened data).transpose()
                show(M)
                r = M.rank()
                sliced M = M[:,0:r+1]
                show(sliced M)
                factor=sliced_M.right_kernel()
                show(factor.basis()[0])
                A=matrix(factor.basis()[0])
                0=vloq
                for k in range(0,r+1): #取出係數將其變為一多項式
                    item=x^k*A[0,k]
                    poly+=item
                if(A[0,r]<0):
                                          #讓首項系數為1
                    poly*=-1
                return poly
            else:
                print'data is not square matrix'
        def diagonalizable(data):
            poly=minimalpolynomial(data)
            show(poly)
            polyprime=poly.derivative()
            show(polyprime)
            poly.gcd(polyprime)
            show(poly.gcd(polyprime))
            if (poly.gcd(polyprime)==1):
                print'The square matrix is diagonalizable' # If p and pprim
        e has common factor other than 1, then p is not square free
```

else:

print'The square matrix is non-diagonalizable'

**Examples** 

```
In [2]: | ### diagonalizable
        data= matrix([[3,-3,2],[-1,5,-2],[-1,3,0]])
        print "Matrix:"
         show(data)
        print "---"
        diagonalizable(data)
```

Matrix:

$$\begin{pmatrix} 3 & -3 & 2 \\ -1 & 5 & -2 \\ -1 & 3 & 0 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 3 & 10 & 36 \\ 0 & -3 & -18 & -84 \\ 0 & 2 & 12 & 56 \\ 0 & -1 & -6 & -28 \\ 1 & 5 & 22 & 92 \\ 0 & -2 & -12 & -56 \\ 0 & -1 & -6 & -28 \\ 0 & 3 & 18 & 84 \\ 1 & 0 & -8 & -48 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 3 & 10 \\ 0 & -3 & -18 \\ 0 & 2 & 12 \\ 0 & -1 & -6 \\ 1 & 5 & 22 \\ 0 & -2 & -12 \\ 0 & -1 & -6 \\ 0 & 3 & 18 \\ 1 & 0 & -8 \end{pmatrix}$$

$$(8, -6, 1)$$

$$x^2 - 6x + 8$$

$$2x-6$$

1

The square matrix is diagonalizable

```
In [3]:
         ### random matrix diagonalizable
         import numpy as np
         data= matrix(np.random.randint(0,100,[4,4]))
         print "Matrix:"
show(data)
         print "---"
         diagonalizable(data)
```

Matrix:

```
80
16
     17
          85
     95
          63
               62
54
               30
92
     82
          21
17
     30
          89
               74
```

```
10354
1
   16
               2000122
                          468850888
0
   17
       11257
                2499105
                          580081175
0
   85
       11336
               2788893
                          623279608
0
       10804
                2665830
   80
                          595892480
       12844
0
   54
                3007798
                          685429428
       16969
1
   95
               3759155
                          852325901
0
   63
       17416
                4011755
                          918228560
   62
        16688
0
                3836990
                          877981360
   92
         8342
0
                2521098
                          547877358
0
   82
       11976
                3058308
                          683480468
1
   21
       16097
                3162761
                          742568597
0
   30
       15294
               3024538
                          710001578
0
   17
       11338
                2142788
                          507180048
0
   30
       12657
                2702921
                          627465001
0
   89
       11790
                3020285
                          672750650
1
   74
       11366
               2886558
                          643217984
       10354
1
   16
               2000122
                          468850888
0
       11257
                          580081175
   17
                2499105
0
   85
       11336
               2788893
                          623279608
0
   80
       10804
               2665830
                          595892480
0
   54
       12844
                3007798
                          685429428
1
   95
       16969
                3759155
                          852325901
   63
       17416
                          918228560
0
                4011755
   62
       16688
0
                3836990
                          877981360
   92
0
         8342
               2521098
                          547877358
0
   82
       11976
                3058308
                          683480468
1
   21
        16097
                3162761
                          742568597
       15294
0
   30
                3024538
                          710001578
0
   17
       11338
               2142788
                          507180048
0
   30
       12657
                2702921
                          627465001
                          67\overline{27}750650
0
   89
       11790
               3020285
1
                          643217984
   74
        11366
               2886558
```

(3113554, 249790, -6175, -206, 1)

$$x^4 - 206 \, x^3 - 6175 \, x^2 + 249790 \, x + 3113554$$
  
 $4 \, x^3 - 618 \, x^2 - 12350 \, x + 249790$ 

The square matrix is diagonalizable

```
### non-diagonalizable
In [4]:
        data = matrix([[1,-1],[1,3]])
        print "Matrix:"
        show(data)
        print "---"
        diagonalizable(data)
```

Matrix:

$$\begin{pmatrix} 1 & -1 \\ 1 & 3 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & -1 & -4 \\ 0 & 1 & 4 \\ 1 & 3 & 8 \end{pmatrix}$$

$$\begin{pmatrix} 1 & 1 & 0 \\ 0 & -1 & -4 \\ 0 & 1 & 4 \\ 1 & 3 & 8 \end{pmatrix}$$

$$(4, -4, 1)$$

$$x^2 - 4x + 4$$

$$2x - 4$$

$$2x - 4$$

The square matrix is non-diagonalizable

```
In [5]:
        ### non-diagonalizable
        data =matrix([[1,0,0,0],[0,2,0,0],[0,0,4,1],[0,0,0,4]])
        print "Matrix:"
        show(data)
        print "---"
        diagonalizable(data)
```

Matrix:

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 4 & 1 \\ 0 & 0 & 0 & 4 \end{pmatrix}$$

70

$$x^4 - 11\,x^3 + 42\,x^2 - 64\,x + 32$$
 $4\,x^3 - 33\,x^2 + 84\,x - 64$ 
 $x - 4$ 

The square matrix is non-diagonalizable

In [0]:

# **Monty Fall Problem**



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#### Overview

#### **Algorithm**

- 1. 假設有3個箱子,隨機選一個箱子放東西
- 2. 讓玩家選擇其中一項後,隨機開啟另外兩個其中之一的箱子, 如果開到有東西的,則此局不算,重新開始。
- 3. 問玩家在選擇不要換,後開啟選擇的箱子。

### **Explanation**

- 1. 有3個箱子A、B、C,隨機選一個箱子放球。
- 2. 讓一位玩家選擇其中一個箱子。
- 3. 開啟另外兩個其中一個箱子。
- 4. 如果開到有放球的則此局結束。 沒開到則繼續。
- 5. 然後詢問玩家要不要換,決定後直接開啟。

### **Implementation**

## In [1]:

```
from random import choice

def Monty_Fall_game():
    box = ['A','B','C']

    ball = choice(box)
    player = choice(box)
    not_selected = [x for x in box if x != player]
    opened_box = choice(not_selected)
    if opened_box == ball:
        return Monty_Fall_game()
    else:
        change = [x for x in box if x != player and x != opened_box]

        final = choice(change)
    return (final == ball)
        72
```

```
In [2]:
```

```
def probability(k):
    counter = 0;
    for _ in range(k):
        if Monty_Fall_game():
            counter += 1
    return N(counter / k)
```

# Examples

# In [3]:

```
##重複1000次種球的機率
probability(1000)
```

Out[3]:

0.5100000000000000

Type  $\mathit{Markdown}$  and  $\mathit{LaTeX}$ :  $\alpha^2$ 

# The Monty Hall Problem

# BY 顏廷維 Justin Yen



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#### Overview

### Algorithm

開始 Monty Hall 的遊戲 先設三個變數1、2、3 再來設兩個隨機的變數selection、prize 再用門去扣掉這兩個變數 定義一個新的變數 Opendoor 由於Opendoor 不會和selection跟prize的門一樣 所以最後面抉擇會是要繼續選擇selection 或是選擇另一個變數 change: (不會是selection也不會是Opendoor) 再去比較最後 是selection=prize的機會比較高 還是change=prize得機率比較高

#### **Explanation**

對我來說這個問題有一個極其重要的地方 那就是遊戲中打開的門,一定會是非車的門 既然打開的門存在車子機率已經不在了 那在原本大局觀中,他的機率就會附加在那些還沒開過的門 舉個常見的例子、那便是一有一千道門裡頭只有一個有大獎 你一開始選了一道門、那目前那道門中獎機率是1/1000 非那道門中獎機率是999/1000、今天我們打開了剩下門中的998道 那些都沒有大獎、那原本999/1000的機率就會附加在剩下那道還沒開也還沒選的 這個就可以大致拿來形容Monty Hall 的問題

#### **Implementation**

#### In [3]:

```
import random
doors = [1,2,3]
##先製造三道門
prize = random.choice(doors)
##獎品在隨機一個門裡面
selection = random.choice(doors)
##自己的選擇也是其中一扇門
L = [x for x in doors if x != prize and x != selection]
##設Open door為不是你的選擇也不是獎品的一個門
opened door = random.choice(L)
##由於門有可能不只一個可4只能選一個
montyopendoor = L[0]
q = [x \text{ for } x \text{ in doors if } x != \text{selection and } x != \text{opened door}]
##再設change為非selection和非open door的門
change = q[0]
##老師程式可能還有一點小瑕疵,有可能會跑出Opendoor跟change是一樣的選項
##有可能是因為一開始的opendoor是隨機的L,然後到另一個迴圈時他又會那入考慮
##不過我試過出錯的機率很低,而且對答案不會有干擾
print "Prize: %r" % prize
print "Selection: %r " % selection
print "monty's open door %r " % montyopendoor
print "change: %r " % change
Prize: 2
Selection: 2
monty's open door 1
change: 1
In [4]:
##不換門的
def gods plan():
   doors = [1,2,3]
   prize = random.choice(doors)
   selection = random.choice(doors)
   L = [door for door in doors if door != prize and door != selection]
   opened door = random.choice(L)
   montyopendoor = L[0]
   q = [door for door in doors if door != selection and door != opened door]
   change = q[0]
   return (selection == prize)
```

```
In [5]:
def selection(k):
    counter = 0;
    for in range(k):
        if gods plan():
            counter += 1
    return N(counter / k)
In [6]:
selection(1000)
Out[6]:
0.323000000000000
In [7]:
##我是分隔線
In [8]:
##選擇另一道門的
def good plan():
    doors = [1,2,3]
    prize = random.choice(doors)
    selection = random.choice(doors)
    L = [door for door in doors if door != prize and door != selection]
    opened door = random.choice(L)
    montyopendoor = L[0]
    q = [door for door in doors if door != selection and door != opened door]
    change = q[0]
    return (change == prize)
In [9]:
def change(k):
    counter = 0;
    for
          in range(k):
        if good plan():
            counter += 1
    return N(counter / k)
In [10]:
```

```
change (5000)
```

Out[10]:

0.658800000000000

# **Torque**



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#### Overview

#### 力矩:

我會先給輸入者輸入一個位置,這個位置代表物體的重心  $G(a_1,b_1,c_1)$ , 然後再給輸入者輸入兩個向量,一個是受力的點  $O(a_2,b_2,c_2)$ , 另一個是力的方向與大小  $F(a_3,b_3,c_3)$ 

## 算法:

先計算施力方向與受力點—重心連線的角度(令為 $\theta$ ),再計算受力點—重心連線的長度(令為y), 接著計算力的大小(令為f),然後力矩為

 $fu\sin\theta$ 

## **Algorithm**

1. 
$$\cos\theta=\dfrac{(a_1-a_2)\times a_3+(b_1-b_2)\times b_3+(c_1-c_2)\times c_3}{\sqrt{(a_1-a_2)^2+(b_1-b_2)^2+(c_1-c_2)^2}\times\sqrt{a_3^2+b_3^2+c_3^2}}$$
2.  $y=\sqrt{(a_2-a_1)^2+(b_2-b_1)^2+(c_2-c_1)^2}$ 
3.  $f=\sqrt{(a_3^2+b_3^2+c_3^2)}$ 
4.  $x=fy\sqrt{1-\cos^2\theta}$ 
5. output  $x$ 

#### **Explanation**

因為力矩的定義是,力乘上力臂,力臂就是將重心與力臂的延伸線作相連接,且連接點要垂直,重心與這連接點 的距離即為力臂。

為了要計算力臂的長度,我們先算出力與重心到受力點練線的角度,但角度無法直接算出來,所以我們藉由餘弦 定理 $\cos$ 等於與角相鄰的兩邊向量內積除以兩邊向量長度的乘積,即可求得 $\cos \theta$ 

然後再利用畢達哥拉斯恆等式

$$\sin^2 \theta + \cos^2 \theta = 1$$

來計算出

$$\sin\theta = \sqrt{1 - \cos^2\theta}$$

求出角度後,接著便要計算受力點與重心的距離,然後令為y

$$y=\sqrt{\left(a_{2}-a_{1}
ight)^{2}+\left(b_{2}-b_{1}
ight)^{2}}$$

這時便可求得力臂等於 $y\sin heta=y\sqrt{1-\cos^2 heta}$ 

接著將力的大小算出,也就是力的長度,即f=|F|,最後帶入力矩的公式:力乘以力臂  $fy\sqrt{1-\cos^2\theta}$ 

其算出的數值便是力矩

#### **Implementation**

```
In [1]: def torque(G, 0, F):
            a1,b1,c1 = G
            a2,b2,c2 = 0
            a3,b3,c3 = F
            cos numerator = (a1-a2)*a3 + (b1-b2)*b3 + (c1-c2)*c3
            cos denominator = sqrt((a1-a2)^2 + (b1-b2)^2 + (c1-c2)^2) * sqrt(
        a3^2 + b3^2 + c3^2
            cos value = cos numerator / cos denominator
            y = sqrt((a1-a2)^2 + (b1-b2)^2 + (c1-c2)^2)
            f = sqrt(a3^2 + b3^2 + c3^2)
            x = f*y*sqrt(1-cos value^2)
            return N(x)
```

## **Examples**

```
In [2]: def torque(G, 0, F):
            a1,b1,c1 = G
            a2,b2,c2 = 0
            a3,b3,c3 = F
            cos numerator = (a1-a2)*a3 + (b1-b2)*b3 + (c1-c2)*c3
            cos denominator = sqrt((a1-a2)^2 + (b1-b2)^2 + (c1-c2)^2) * sqrt(
        a3^2 + b3^2 + c3^2
            cos value = cos numerator / cos denominator
            y = sqrt((a1-a2)^2 + (b1-b2)^2 + (c1-c2)^2)
            f = sqrt(a3^2 + b3^2 + c3^2)
            x = f * y * sqrt(1 - cos_value^2)
            return N(x)
```

```
In [3]: a1=0
          b1 = 0
          c1 = 0
          a2 = 1
          b2 = 1
          c2 = 1
          a3 = 3
          b3 = 2
          c3=1
          G = [a1,b1,c1]
          0 = [a2,b2,c2]
          F = [a3,b3,c3]
          torque(G, 0, F)
```

# Out[3]: 2.44948974278318

```
In [4]: a1=3
          b1 = 4
          c1=1
          a2 = 9
          b2 = 8
          c2 = 10
          a3 = 5
          b3 = 6
          c3=1
          G = [a1, b1, c1]
          0 = [a2,b2,c2]
          F = [a3,b3,c3]
          torque(G, 0, F)
```

#### Out[4]: 65.3987767469698

```
In [5]: a1=12.5
         b1=89
         c1=0.5
         a2 = 42
         b2 = 35
         c2 = 36.3
         a3 = 4
         b3 = 5
         c3=79
         G = [al,bl,cl]
         0 = [a2,b2,c2]
         F = [a3,b3,c3]
         torque(G, 0, F)
Out[5]: 4967.33716794018
```

In [ ]:

# **Rook polynomial**



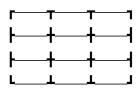
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#### Introduction

首先定義  $r_{B_k}(x)$  為在棋盤 B 中放入不同行不同列 k 個棋子的可能種數,

例如:當B 為  $3 \times 3$  的棋盤



 $B_n$  表示在board置入n個不同行不同列的城堡棋子

$$r_{B_0}(x) = 1$$
,  $r_{B_1}(x) = 9$ ,  $r_{B_2}(x) = 18$ ,  $r_{B_3}(x) = 6$ 

考慮  $B \stackrel{.}{\wedge} m \times n$  的棋盤 ( $m \leq n$ )

然後我們定義
$$R_{(m,n)}(x) = \sum_{k=0}^{m} r_{B_k} x^k$$
。

考慮一般的square board

Let 
$$R_n(x) = R_{(n,n)}(x)$$
.

$$R_1(x) = r_1(x)x + r_0(x) = x + 1$$

$$R_2(x) = r_2(x)x^2 + r_1(x)x + r_0(x) = 2x^2 + 4x + 1$$

$$R_3(x) = r_3(x)x^3 + r_2(x)x^2 + r_1(x)x + r_0(x) = 6x^3 + 18x^2 + 9x + 1$$

$$R_4(x) = r_4(x)x^4 + r_3(x)x^3 + r_2(x)x^2 + r_1(x)x + r_0(x) = 24x^4 + 96x^3 + 72x^2 + 16x + 1$$

#### Overview

"rook polynomial" 是由John Riordan創造的。

在探討的是,在各種的board中,如何擺置不同行也不同列的城堡棋,依照

擺的數量不同,情況也會有所不同,進而藉由未知數x來表示我們擺的棋子

及其不同的種數,然而每個board也並非為完整沒有限制的。

Let B be a board (a set of grid points).

Suppose (i, j) is a point in B.

Let B - (i, j) be the board obtained from B by removing the point (i, j).

Let B(i,j) be the board obtained from B by removing the i-th row and the j-th column.

Then  $R_B(x) = R_{B-(i,j)}(x) + xR_{B(i,j)}(x)$ .

for example.

$$B = \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 1 & 1 \end{pmatrix}$$

針對(3,3)格子

$$B - (3,3) = \begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 1 & 1 & 0 \end{pmatrix} B(3,3) = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

可得到 $R_B(x) = R_{B-(3,3)}(x) + xR_{B(3,3)}(x) = (1+3x+1x^2) + x \times (1+1x) = 1+4x+2x^2$ 

### **Explanation**

for nxn board

 $B_{m,n} =$ 

$$\begin{pmatrix} b_{11} & b_{12} & \cdots & b_{1n} \\ b_{21} & b_{22} & \cdots & b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ b_{m1} & b_{m2} & \cdots & b_{mn} \end{pmatrix}$$

where  $b_{ij} = 0$  or 1 (0: black 1:white)

for example :  $B_1$  =

$$\begin{pmatrix} 0 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

means  $b_{11}$  is forbiddened and its rook polynomial is  $R_{B_1}(x) = 1 + 8x + 14x^2 + 4x^3$ 

and in

$$C = \begin{pmatrix} 1 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 1 \end{pmatrix}$$

$$C_1 = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

$$C_2 = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 \end{pmatrix}$$

令 r(C, x): rook polynomial,

 $r(C_1,x)$ ,  $r(C_2,x)$  分別表左上及右下角禁區放的方法數,

則 
$$r(C_1, x) = 1x^0 + 5x^1 + 4x^2$$
, 其中

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 $1x^0$  是表示在此區放 0 個 rook 有 1 種方法

 $5x^1$  是表示在此區放 1 個 rook 有 5 種方法  $4x^2$  是表示在此區放 2 個 rook 有 4 種方法 同理可以列出  $r(C_2,x)=1+5x+5x^2$ 

=>

$$r(C,x) = r(C_1,x) \times r(C_2,x)$$
  
=  $(1 + 5x + 4x^2) \times (1 + 5x + 5x^2)$   
=  $1 + 10x + 34x^2 + 45x^3 + 20x^4$ 

# Implementation

```
### sample code for Rn
def rec board(m,n):
    board = []
    for i in range(m):
        for j in range(n):
            board.append((i,j))
    return board
print "This is board(2,2)"
print rec board(2,2)
def rook_polynomial(board):
    Input:
        board: a list of possible positions
    Output:
        the rook polynomial of the board
    ### trivial and base cases
    if len(board) == 0:
        return 1
    elif len(board) == 1:
        return \times + 1
    else:
        i,j = board[0] ### pick a position
        board minus ij = copy(board)
        ### do something to create board minus ij
        ### board minus ij = board - (i, j)
        board minus ij.remove((i,j))
        board ij = [pos for pos in board if pos[0] != i and pos[1] != j]
        #pos 去掉i 列j 行 p[0] 代表列, p[1] 代表行
        ### previous code:
        \#board\ ij = copy(board)
        ### do something to create board_ij
        #for pos in board:
             if pos[0] == i or pos[1] == j:
                 board ij.remove(pos)
        return expand(rook polynomial(board minus ij) + x*rook polynomial(board ij)
### This is called recursive programming
```

```
This is board(2,2) [(0, 0), (0, 1), (1, 0), (1, 1)]
```

```
In [2]:
B = rec board(2,3)
print B
f = rook polynomial(B)
print f
f.subs(x=1)
[(0, 0), (0, 1), (0, 2), (1, 0), (1, 1), (1, 2)]
6*x^2 + 6*x + 1
Out[2]:
13
Examples
In [3]:
import random
def rec board(m,n):
    board = []
    for i in range(m):
        for j in range(n):
            board.append((i,j))
    return board
def random board(m,n):
    Input:
        m,n: dimensions of the board
        k: number of positions
    Output:
        a board in the m \times n board with k random positions
    k= random.randint(0,N(m*n))
    B = rec board(m,n)
    random.shuffle(B)
    return B[:k]
In [4]:
A=random board(5,5)
print A
[(1, 3), (4, 2), (1, 0), (2, 2), (2, 0), (0, 0), (3, 1), (4, 1), (3, 1)]
(0), (1, 1), (2, 1), (2, 3), (3, 2), (4, 4), (3, 4), (1, 4), (3, 3)
In [5]:
g=rook polynomial(A)
print g
11*x^5 + 103*x^4 + 172*x^3 + 90*x^2 + 17*x + 1
```

```
In [6]:
q.subs(x=1)
##可能的種數
Out[6]:
394
參考的式子與資料
Jephien: Here are some hint for general board.
Let B be a board (a set of grid points).
Suppose (i, j) is a point in B.
Let B - (i, j) be the board obtained from B by removing the point (i, j).
Let B(i,j) be the board obtained from B by removing the i-th row and the j-th column.
Then R_B(x) = R_{B-(i,i)}(x) + xR_{B(i,i)}(x).
(This is my thought, you may check if that is correct.)
In [7]:
def rec board(m,n):
    board = []
    for i in range(m):
         for j in range(n):
              board.append((i,j))
    return board
#print "This is board(2,2)"
B = rec board(2,4)
print B
print len(B)
print B[5]
B.remove(B[3])
[(0, 0), (0, 1), (0, 2), (0, 3), (1, 0), (1, 1), (1, 2), (1, 3)]
(1, 1)
Out[7]:
[(0, 0), (0, 1), (0, 2), (1, 0), (1, 1), (1, 2), (1, 3)]
In [8]:
a = [1,2,3]
b = a
print a
b[0] = 5
print a
print b
                                               87
[1, 2, 3]
[5, 2, 3]
```

[5, 2, 3]

```
In [9]:
a = [1,2,3]
b = copy(a)
print a
b[0] = 5
print a
print b
[1, 2, 3]
[1, 2, 3]
[5, 2, 3]
In [10]:
f = (x+1) * (x+4)
print f
(x + 4)*(x + 1)
In [11]:
print expand(f)
x^2 + 5*x + 4
In [12]:
sum([k^2 for k in range(1,11)])
Out[12]:
385
In [13]:
n = 30
sum([k^2 for k in range(1,n+1)])
Out[13]:
9455
In [ ]:
```

# **Shortest Paths**



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#### Overview

在圖上選一點作為出發點,出發點與終點間的路線上不會經過同一個點和同一條邊,為一個 Path。

利用 Breadth first search 找到兩點之間的最短距離(shortest path)。

### Algorithm

#### Breadth first search

- 1.BFS(g,v,e) 輸入g,v,e。g為一圖形,v為初始點,e為終點
- 2.level首先會記錄v點為0, reached中

3.

#### **Explanation**

先選定一點作為出發點,再輸入另一點作為結束點,將出發點標記為Level=0,接著找相鄰的點,標記為Level=1。

之後依次將與Level=1相鄰的點標記為Level=2,不斷往下標記到所有點都被標記為止。

#### **Implementation**

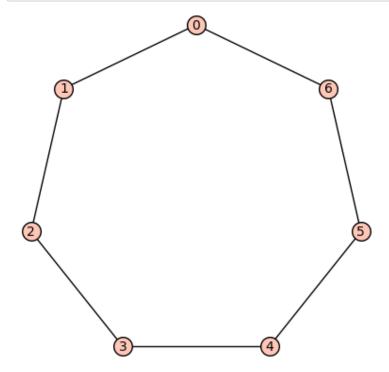
#### In [1]:

```
### The function below returns the order found by Breadth-First Search
def BFS(g, v, e):
    Input:
        g: a simple graph
        v: a vertex
        e: end vertex
    Output:
       An order given by the BFS & distance of vertex v and e
    level = {}
                   ### set level as a dictionary
    level[v] = 0 ### set level[v] as 0
    reached = [v] ### vertices that have been found by BFS
    to be searched = [v] ### vertices that have been found but we have not apply
    while to be searched != []:
        vtx = to be searched.pop(0) ### set vtx as the zero-th element and remove i
        extra reached = [i for i in g.neighbors(vtx) if i not in reached]
        l = level[vtx]
        for u in extra reached:
            level[u]=l+1;
        reached = reached + extra reached ### update reached
        to be searched = to be searched + extra reached ### update to be searched
    print v,"和",e,"的最短距離 =",level[e];
    ###return level[e];
```

### **Examples**

# In [2]:

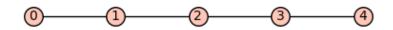
```
### Example 1
g = graphs.CycleGraph(7)
g.show()
BFS(g,2,6)
```



2 和 6 的最短距離 = 3

# In [3]:

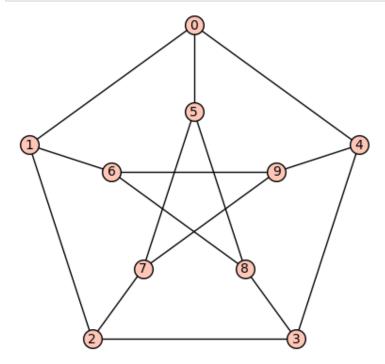
```
### Example 2
g = graphs.PathGraph(5)
g.show()
BFS(g,4,1)
```



# 4 和 1 的最短距離 = 3

# In [4]:

```
### Example 3
g = graphs.PetersenGraph()
g.show()
BFS(g,2,3)
```



2 和 3 的最短距離 = 1

# In [0]:

# Spaces related to a matrix

#### Overview

輸入一個矩陣,利用矩陣的運算來求出該矩陣的行、列空間。

#### Review liner algebra

 $RS(A) = \{xA : x \in \mathbb{F}_{1 \times m}\}$  為 A 之**各列任意組合**  $CS(A) = \{Ax : x \in \mathbb{F}_{n \times 1}\}$  為 A 之**各行任意組合** 

## Algorithm

- 1. 先輸入矩陣 A=B=matrix().
- 2. 將該矩陣的維度assign給 m,n.
- 3. 將矩陣裡的元素設定成有裡數.
- 4. 求出簡化列梯陣後即得到列(行)空間.
- 5. 設定一個迴圈將該矩陣的每一列(行)印出來,並刪除零列(行).
- 6. 最後便得到簡化後的列(行)空間.

### **Explanation**

- 1. 目標是在求列空間與行空間,
- 2. 將矩陣中的元素設成有理數的原因是為了之後在做簡化列梯陣時能出現分數,
- 3. 而在做簡化列梯陣的過程就是將矩陣中每一列成為線性獨立,便能得到列空間.
- 4. 最後行空間的作法與列空間相似,只要先將輸入的矩陣轉置並做一樣的步驟便能得到行空間.

### **Implementation**

# In [1]:

[1 0 0] [0 1 0] None

```
#Row Space
def row_space(matrix):
    m,n = A.dimensions()
    AA = copy(A) ### make a copy so that we won't modify A
    AA = AA.change ring(QQ) ### change the base ring to rational numbers QQ
    R = AA.echelon form()
    print "簡化列梯陣為:"
    print R
    print "---"
    print "列空間為:"
    for i in range(m):
        if R[i,:]!=zero matrix(1,n):
            print R[i,:]
        else:
            R.delete_rows([i])
A = matrix([[1,0,0],[0,1,0],[1,0,0]])
print A
print "---"
print row_space(A)
[1 0 0]
[0 1 0]
[1 0 0]
簡化列梯陣為:
[1 0 0]
[0 1 0]
[0 0 0]
- - -
列空間為:
```

### In [2]:

```
#Column Space
def col_space(matrix):
    m,n=B.dimensions()
    BB=copy(B)
    BB=BB.change ring(QQ)
    print "轉置矩陣為:"
    C=BB.transpose()
    print C
    D=C.echelon_form()
    print "經由列變換後得出:"
    print D
    print "---"
    print "行空間為:"
    for i in range(n):
        if D[i,:]!=zero_matrix(1,m):
            print D[i,:]
        else:
            D.delete_rows([i])
B = matrix([[1,0,0],[0,1,0],[1,0,0]])
print B
print "---"
print col_space(B)
[1 0 0]
[0 1 0]
[1 0 0]
- - -
轉置矩陣為:
[1 \ 0 \ 1]
[0 1 0]
[0 0 0]
經由列變換後得出:
[1 0 1]
```

# 行空間為: $[1 \ 0 \ 1]$

[0 1 0] [0 0 0]

[0 1 0]

None

## Example

```
In [3]:
```

 $[1 \ 0 \ 0]$ 

```
#example
print "Example 1"
A=B=matrix(3, range(9))
print A
print "---"
print row space(A)
print col space(B)
print "-----
print "Example 2"
A=B=matrix([[1,0,0],[2,0,0],[0,1,0],[3,4,0],[0,0,1]])
print A
print "---"
print row space(A)
print col space(B)
print "-----
print "Example 3"
A=B=matrix([[1,2,8],[3,4,18],[0,1,3]])
print "---"
print row_space(A)
print col_space(B)
Example 1
[0 \ 1 \ 2]
[3 4 5]
[6 7 8]
簡化列梯陣為:
[1 \ 0 \ -1]
[0 1 2]
[0 0 0]
列空間為:
[1 \ 0 \ -1]
[0 1 2]
None
轉置矩陣為:
[0 3 6]
[1 4 7]
[2 5 8]
經由列變換後得出:
[ 1 0 -1]
[0 1 2]
[0 0 0]
行空間為:
[1 \ 0 \ -1]
[0 1 2]
None
Example 2
[1 \ 0 \ 0]
[2 0 0]
[0 \ 1 \ 0]
                                        96
[3 4 0]
[0 \ 0 \ 1]
簡化列梯陣為:
```

```
[0 1 0]
[0 \ 0 \ 1]
[0 0 0]
[0 0 0]
- - -
列空間為:
[1 0 0]
[0 1 0]
[0 \ 0 \ 1]
None
轉置矩陣為:
[1 2 0 3 0]
[0 0 1 4 0]
[0 0 0 0 1]
經由列變換後得出:
[1 2 0 3 0]
[0 0 1 4 0]
[0 0 0 0 1]
- - -
行空間為:
[1 2 0 3 0]
[0 0 1 4 0]
[0 0 0 0 1]
None
Example 3
[128]
[ 3 4 18]
[ 0 1 3]
簡化列梯陣為:
[1 0 2]
[0 1 3]
[0 0 0]
- - -
列空間為:
[1 0 2]
[0 1 3]
None
轉置矩陣為:
[130]
[241]
[ 8 18 3]
經由列變換後得出:
[ 1
      0 3/2]
   0
        1 - 1/2
[
[
        0 0]
   0
行空間為:
[ 1 0 3/2]
  0
      1 -1/2]
None
```

# **Vector space**



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#### Overview

#### Find representation

 $P_n := \{\text{all polynomials with degree at most } n \}$  and n 為正整數

Let  $B = \{1, x - 1, (x - 1)^2\}$  be a basis of  $P_2$  then B has n + 1 polynomials.

Record the coefficients of each polynomial in B as the columns of a matrix A, such that

$$A = \begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}.$$

Thus A is an  $3 \times 3$   $((n + 1) \times (n + 1))$  matrix.

If  $f = x^2$  , then the goal is to find

 $Rep_B(f)$ .

#### Algorithm

1. If 
$$f=x^2$$
 , record the coefficients of  $f=x^2$  --> 
$$\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

2. Suppose 
$$Rep_B(f) = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$
 such that  $c = a \times 1 + b \times (x - 1) + c \times (x - 1)^2$ 

3. We know 
$$A = \begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}$$
 and  $\begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ . Then find  $A^{-1}$ 

4. Hence , we get 
$$Rep_B(f) = \begin{bmatrix} a \\ b \\ c \end{bmatrix} = A^{-1} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

#### Explanation

目標是尋找  $Rep_B(f)$ , 要找尋f轉換在B基底底下的座標(表示法)

First we change 
$$B=\{1,(x-1),(x-1)^2\}$$
 to another basis matrix form  $\begin{bmatrix}1\end{bmatrix}=\begin{bmatrix}1\\0\\0\end{bmatrix}$ ,  $\begin{bmatrix}-1+x\end{bmatrix}=\begin{bmatrix}-1\\1\\0\end{bmatrix}$ , and  $\begin{bmatrix}1-2x+x^2\end{bmatrix}=\begin{bmatrix}-1\\2\\1\end{bmatrix}$ 

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$$\operatorname{Get} A = \begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}; \operatorname{And} f = x^2, \operatorname{do} \operatorname{the} \operatorname{same} \operatorname{change} \operatorname{to} \operatorname{make} f \operatorname{the} \operatorname{same} \operatorname{form} \operatorname{as} B \operatorname{did}.$$

記錄 
$$f$$
 的係數,得  $f=\begin{bmatrix}0\\0\\1\end{bmatrix}$ . 再來假設  $Rep_B(x^2)=\begin{bmatrix}a\\b\\c\end{bmatrix}$ 

代表  $a \times 1 + b \times (x - 1) + c \times (x - 1)^2 = x^2$  又可表示成下面形式

$$\begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

則可得出 
$$\begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

```
得解 Rep_B(f) = \begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}
```

#### Implementation

In [2]:

```
def get_coefficient(f, n):
    """

Input:
        f: polynomial
        n: degree
Output:
        a list of (n+1) coefficients of f,
        (treating f as a polynomial of degree n)

"""

l = f.coefficients(sparse=False)
coeffs = [0] * (n+1)
for i in range(len(l)):
        coeffs[i] = l[i]
return coeffs
```

In [3]:

```
def representation(basis, poly):
    """
    Input:
        basis: a list of vectors [B0, ..., Bk] ( a basis of all polynomials of degree at most k)
        poly: a polynomial
    Output:
            the representation of poly with respect to basis
    """
    k = len(basis) - 1
    coeffs_list = [get_coefficient(basis[i], k) for i in range(k+1)]
    A = matrix(coeffs_list).transpose()
    v = matrix(k+1, get_coefficient(poly,k))
    print "representation(basis, polynomial) = "
    show(A.inverse()*v)
```

In [4]:

```
### sample code範例程式
## Let basis
B1=1+0*x
B2=(x-1)
B3=(x-1)^2
f = x^2
B=\{B1,B2,B3\}
f_poly = f.polynomial(QQ)
B_1 = B1.polynomial(QQ)
B_2 = B2.polynomial(QQ)
B_3 = B3.polynomial(QQ)
### construct the matrix
A = matrix([get\_coefficient(B\_1,2), get\_coefficient(B\_2,2), get\_coefficient(B\_3,2)]).transpose()
v = matrix(3,get_coefficient(f_poly,2))
print "representation(basis, polynomial) = "
show(A.inverse()*v)
```

representation(basis, polynomial) =

 $\begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix}$ 

#### Examples

```
In [6]:
B1=1+0*x
B2=6*x
B3=2*x^2
B4=1+x^3
B5=x^4
B6=x^5
B={B1,B2,B3,B4,B5,B6}
B_1 = B1.polynomial(QQ)
B_2 = B2.polynomial(QQ)
B_3 = B3.polynomial(QQ)
B_4 = B4.polynomial(QQ)
B_5 = B5.polynomial(QQ)
B_6 = B6.polynomial(QQ)
basis = [B_1, B_2, B_3, B_4, B_5, B_6]
representation(basis, (3*x^5+7*x^4+5*x^3-4*x^2+3*x+7).polynomial(QQ))
representation(basis, polynomial) =
  \frac{1}{2}
  -2
   5
   7
   3 .
In [7]:
B1=1+0*x
B2=x
B3=x^2
B4=1+x^3
B5=x^4
B6=2*x^5
B7=(x+1)^6
B8=(x-1)^7
B9=x^8
B10=(x-2)^9
B={B1,B2,B3,B4,B5,B6,B7,B8,B9,B10}
B_1 = B1.polynomial(QQ)
B_2 = B2.polynomial(QQ)
B_3 = B3.polynomial(QQ)
B_4 = B4.polynomial(QQ)
B_5 = B5.polynomial(QQ)
B_6 = B6.polynomial(QQ)
B_7 = B7.polynomial(QQ)
B_8 = B8.polynomial(QQ)
B_9 = B9.polynomial(QQ)
B_{10} = B10.polynomial(QQ)
basis = [B_1, B_2, B_3, B_4, B_5, B_6, B_7, B_8, B_9, B_10]
representation(basis, (x^8+3*(x-5)^7+x^6+2*x^5-6*x^4+3*(x+5)^3).polynomial(QQ))
representation(basis, polynomial) =
  -301097
   328827
 -195522
    67183
  -11781
     1006
      -83
         3
         1
         0
```

In [ ]: