

Lab #1 - Geometry (part 2)

Informática Gráfica

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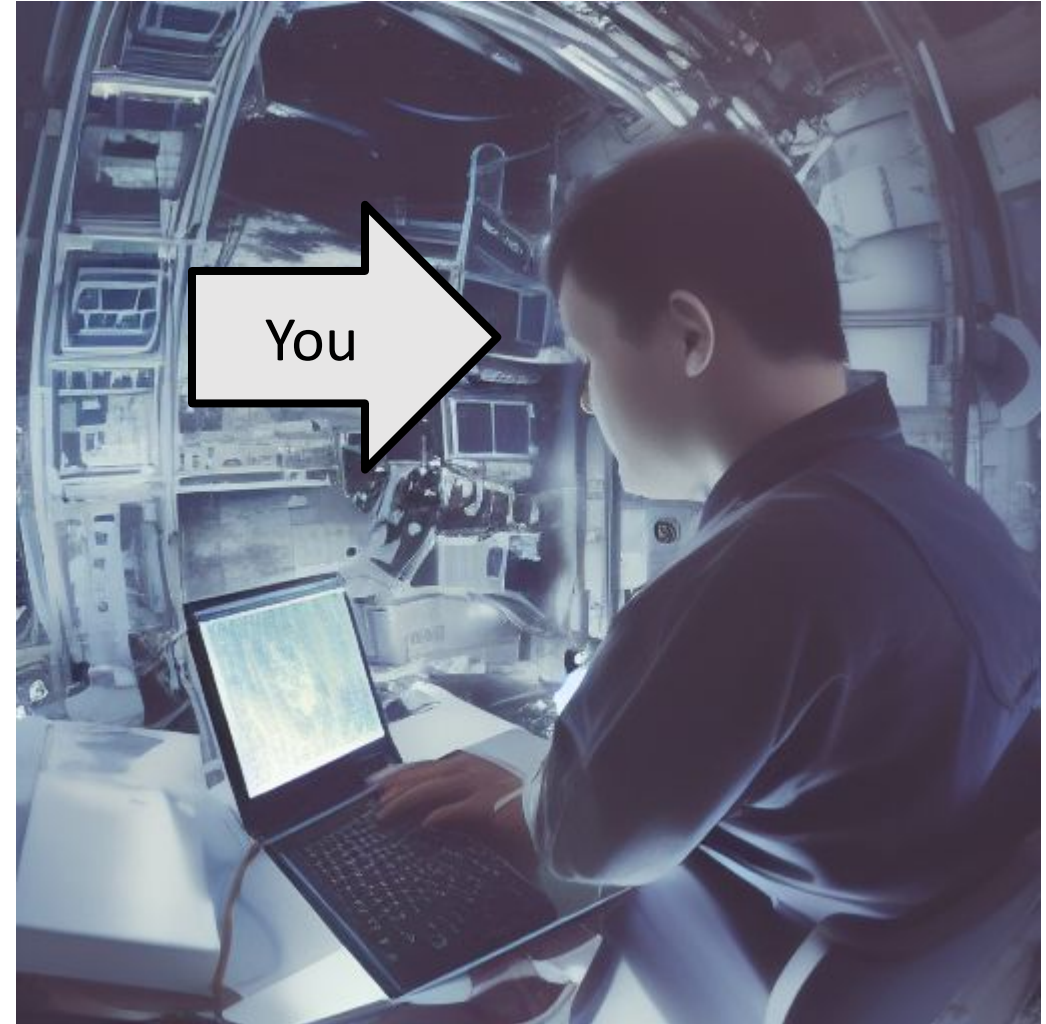
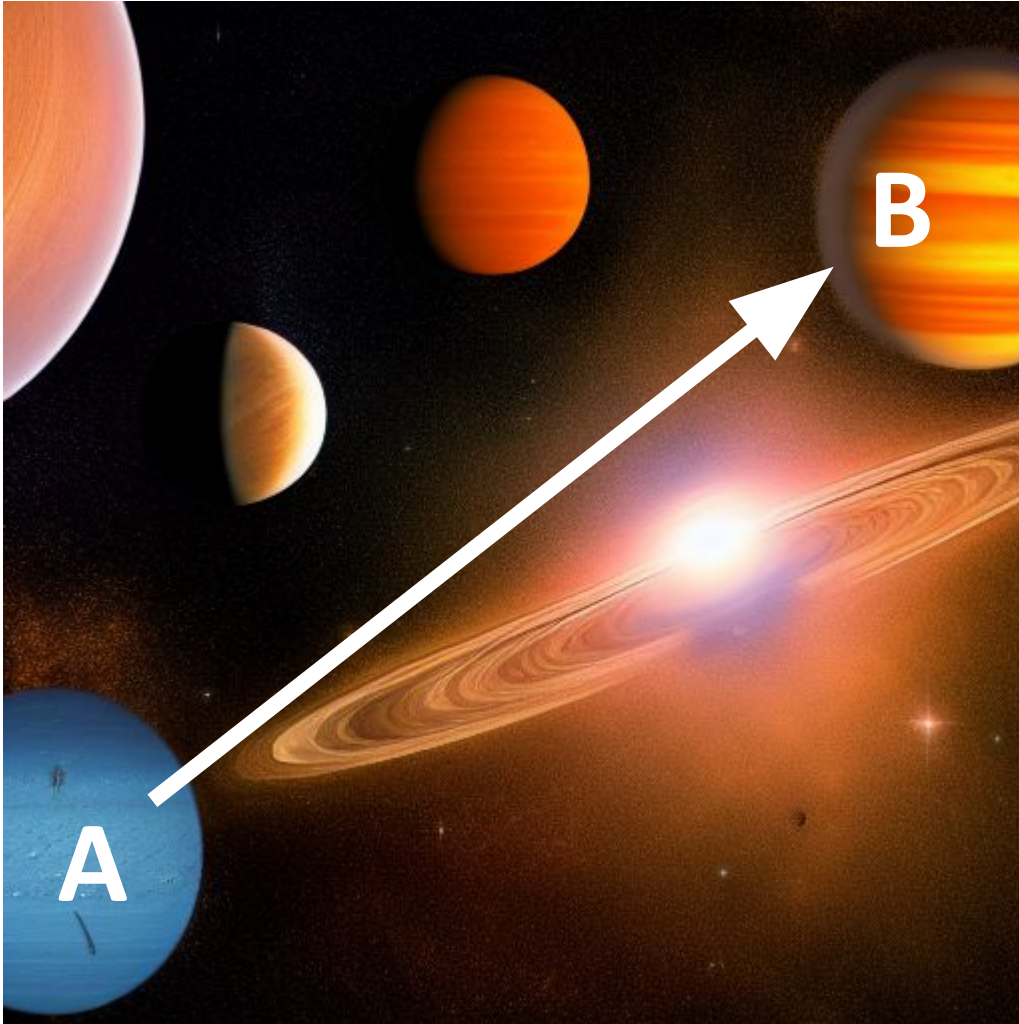
Pablo Luesia - J. Daniel Subías – Óscar Pueyo



Before we begin...

- Practical sessions:
 - Intermediate assignments: no submission required
 - **Highly recommended** to be completed at certain tentative deadlines
 - For the first and second sessions: **September 25th**
 - Your final work will build upon the stuff you'll do here!
 - **80%** of the final grade (including written report)
- If you need to find a partner for lab sessions, message us

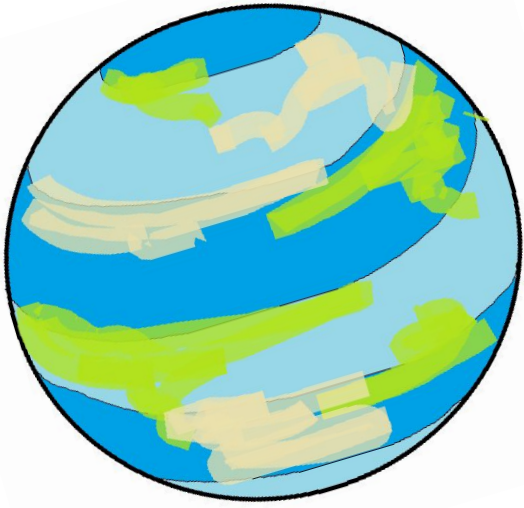
Your new job at FTL dynamics



Images generated using Stable Diffusion

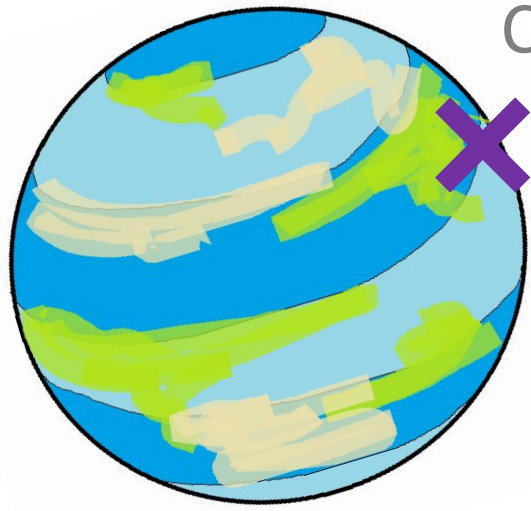
Problem statement

Ideal scenario



Problem statement

Ideal scenario

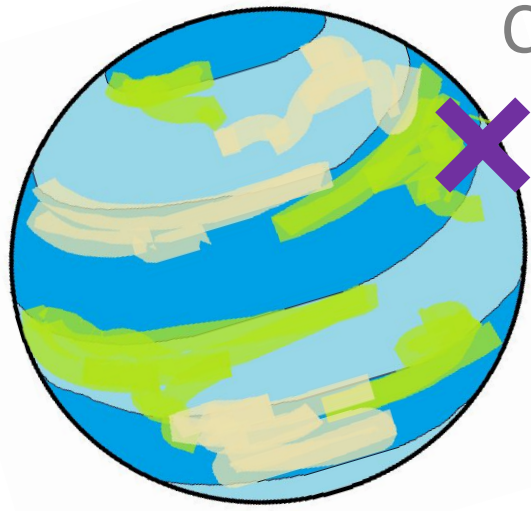


City launcher



Problem statement

Ideal scenario



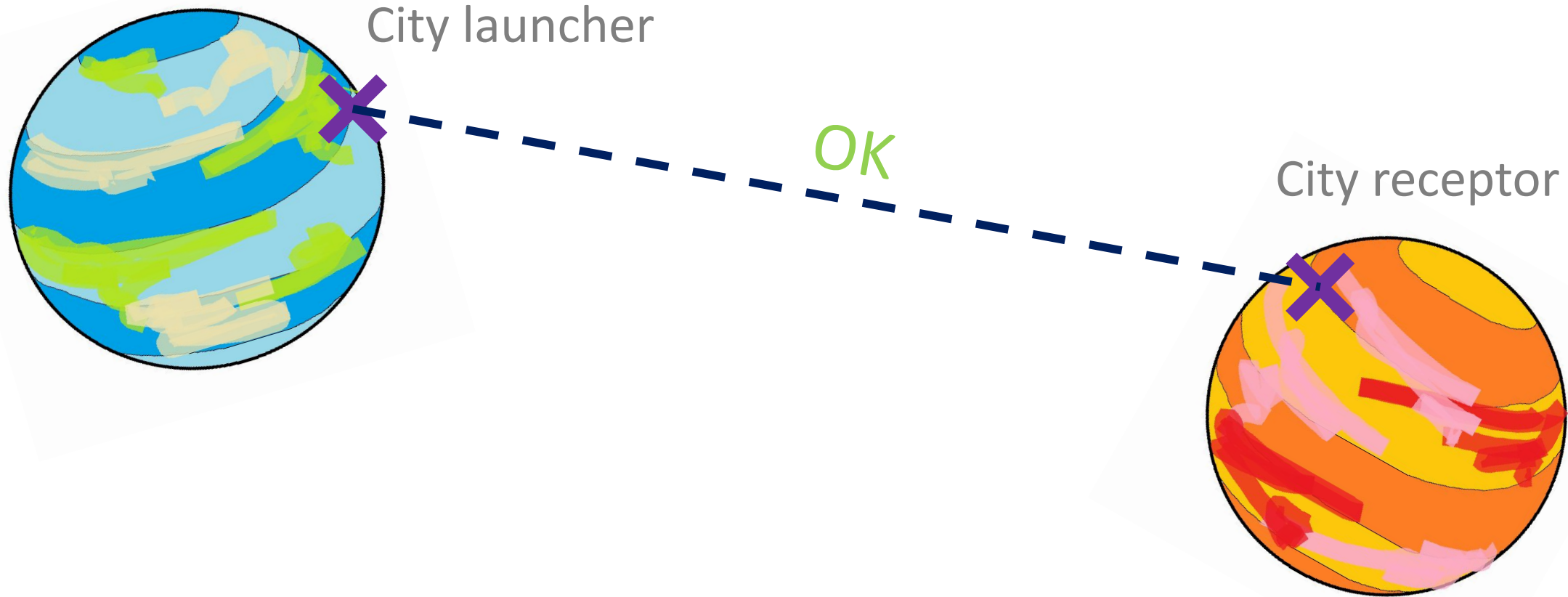
City launcher

City receptor



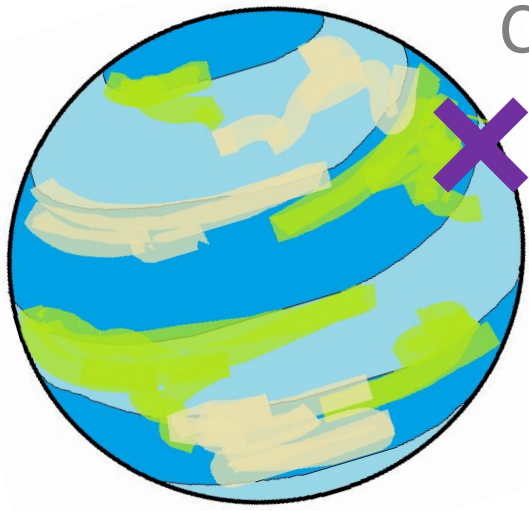
Problem statement

Ideal scenario



Problem statement

Fatal scenario (1)



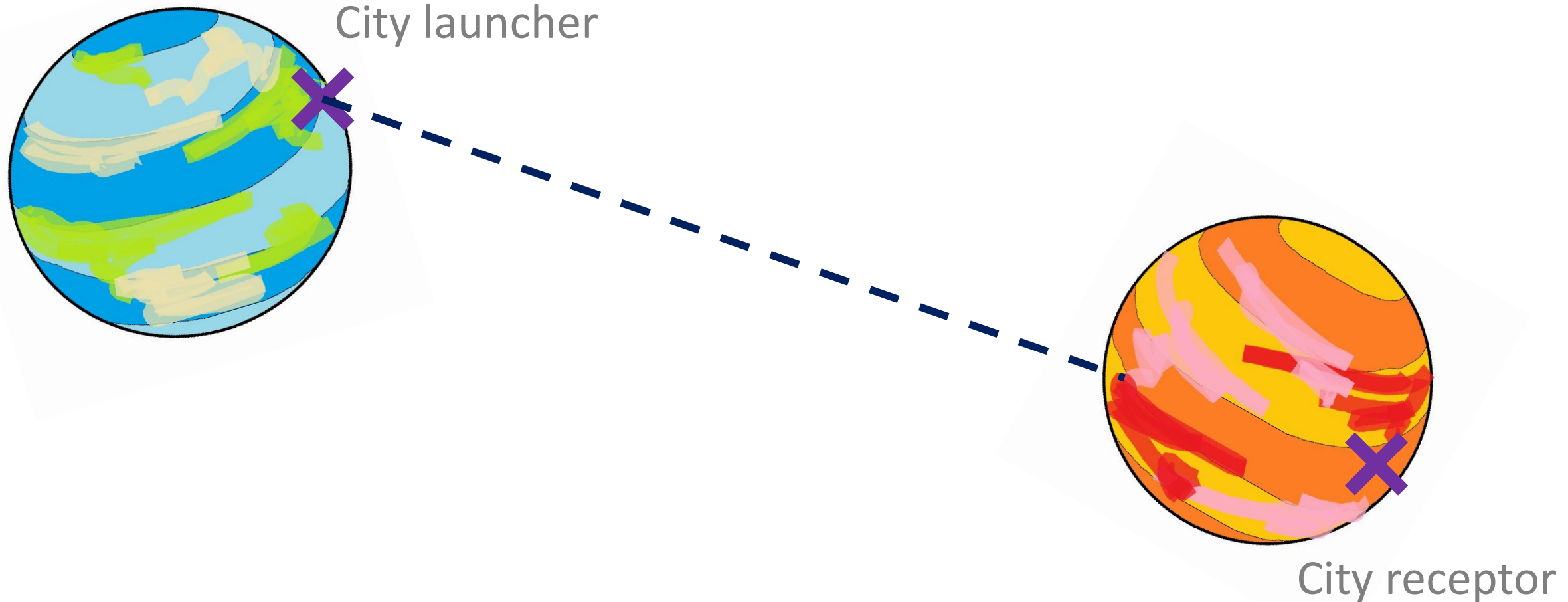
City launcher



City receptor

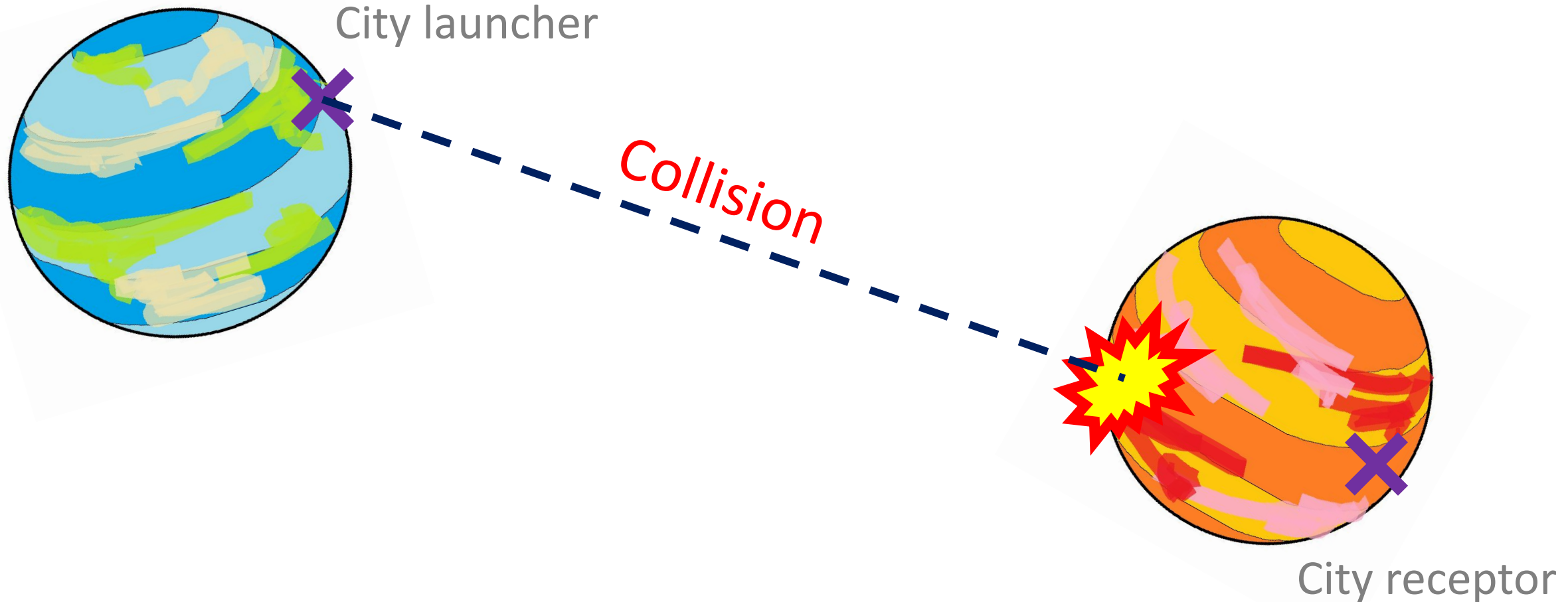
Problem statement

Fatal scenario (1)



Problem statement

Fatal scenario (1)



Problem statement

Fatal scenario (2)



City receptor



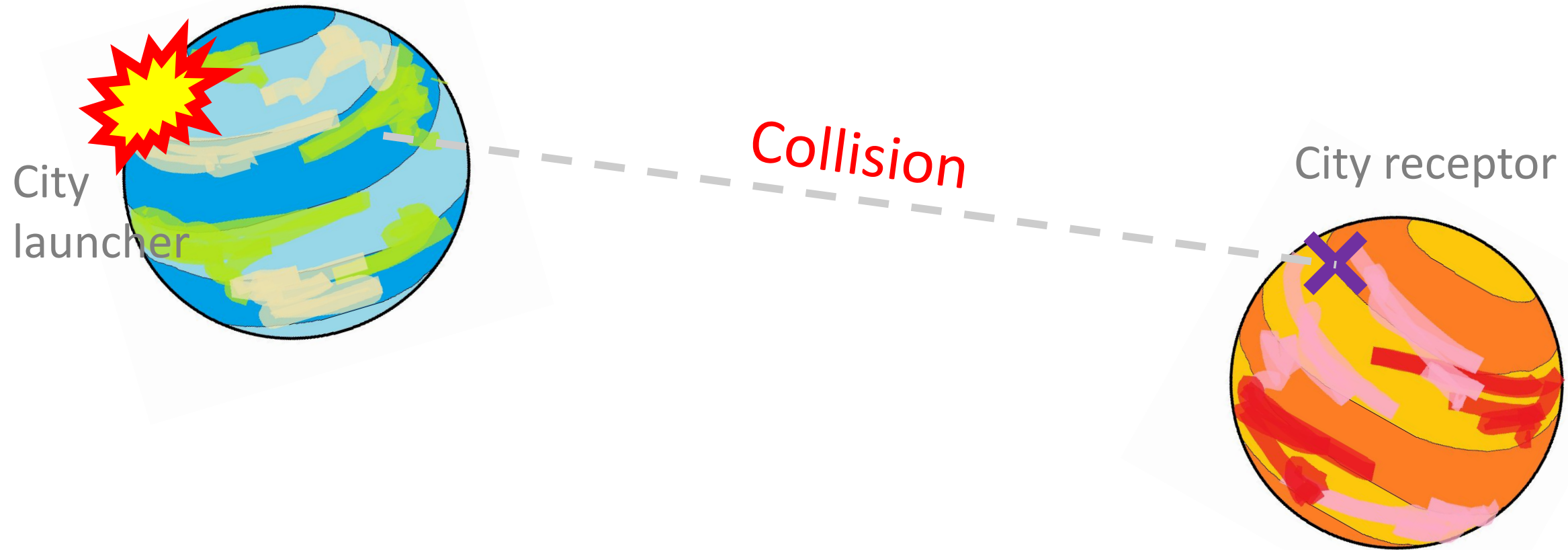
Problem statement

Fatal scenario (2)



Problem statement

Fatal scenario (2)



- Homogeneous coordinates

Point

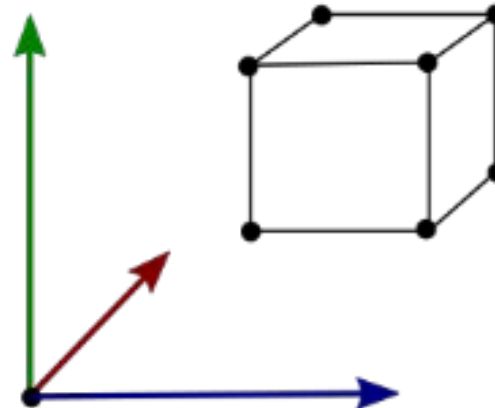
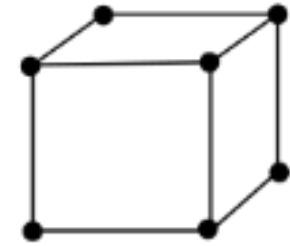
$$\mathbf{p} = \begin{pmatrix} p_x \\ p_y \\ p_z \end{pmatrix} \Rightarrow \mathbf{v} = \begin{pmatrix} p_x \\ p_y \\ p_z \\ 1 \end{pmatrix}$$

Direction

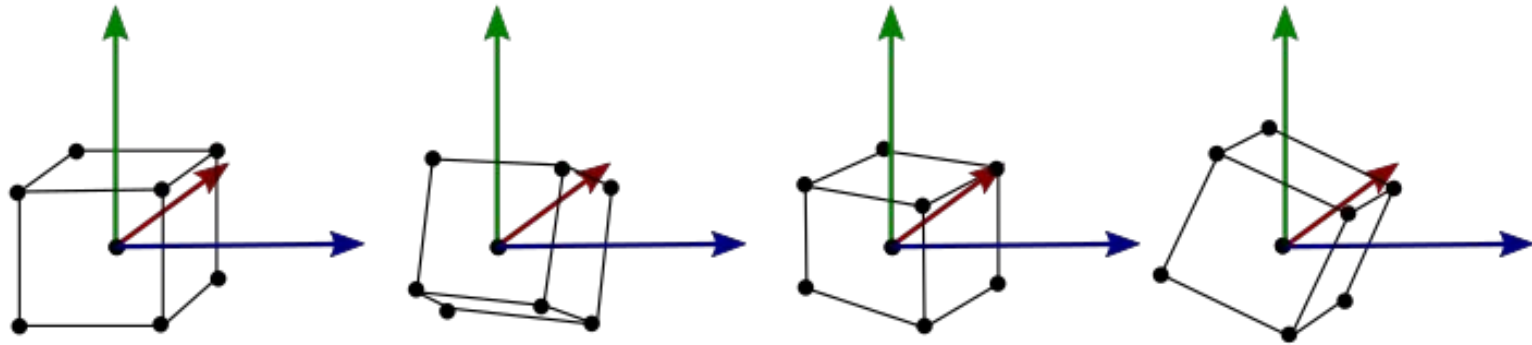
$$\mathbf{d} = \begin{pmatrix} d_x \\ d_y \\ d_z \end{pmatrix} \Rightarrow \mathbf{v} = \begin{pmatrix} d_x \\ d_y \\ d_z \\ 0 \end{pmatrix}$$

Basics

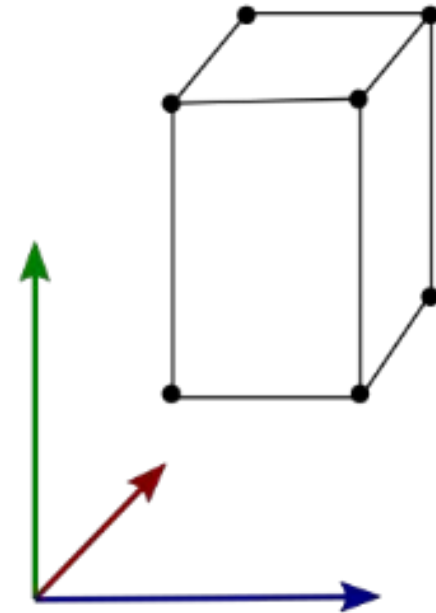
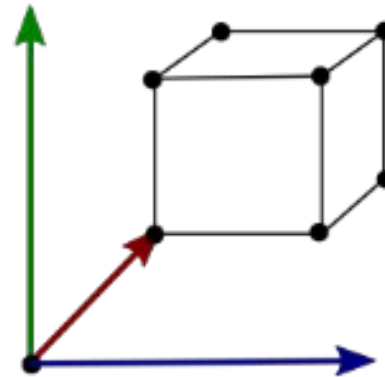
- **Homogeneous coordinates**
- **Transformation matrices**
 - Translation



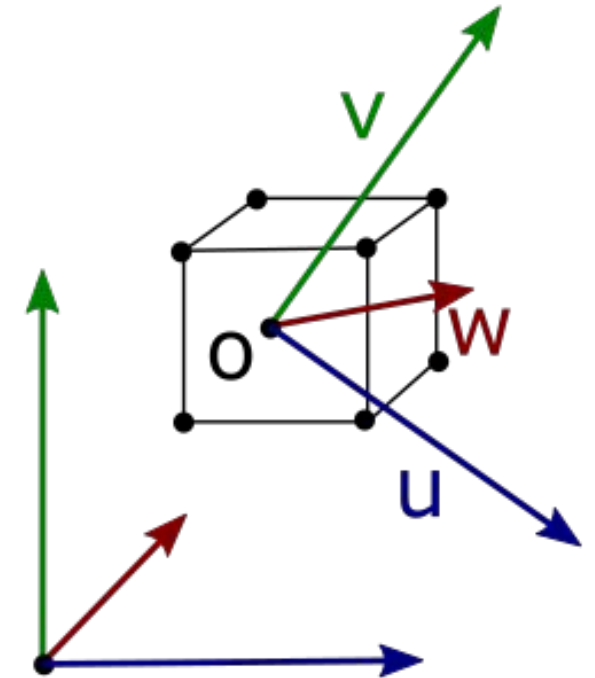
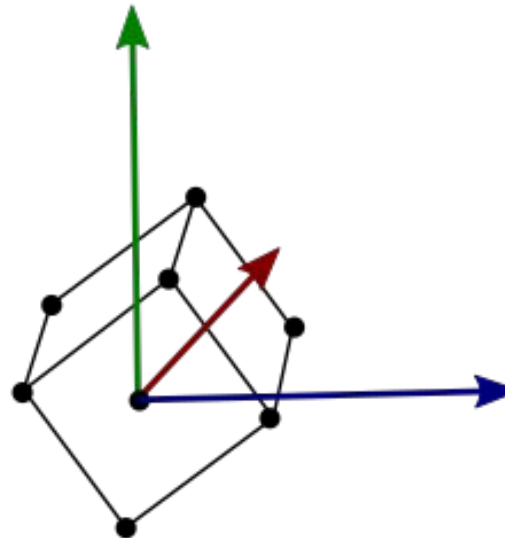
- **Homogeneous coordinates**
- **Transformation matrices**
 - Translation
 - Rotation



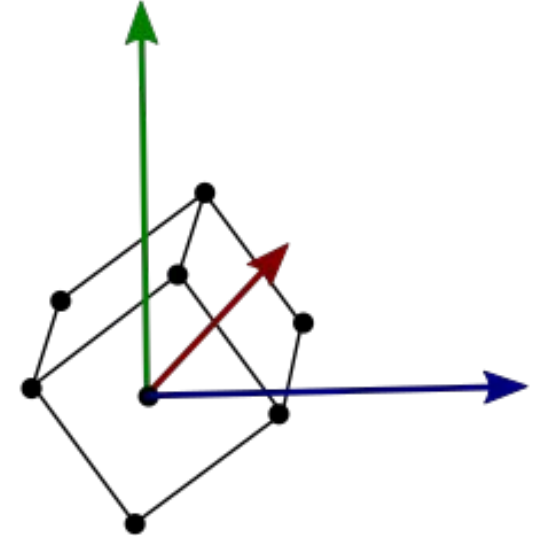
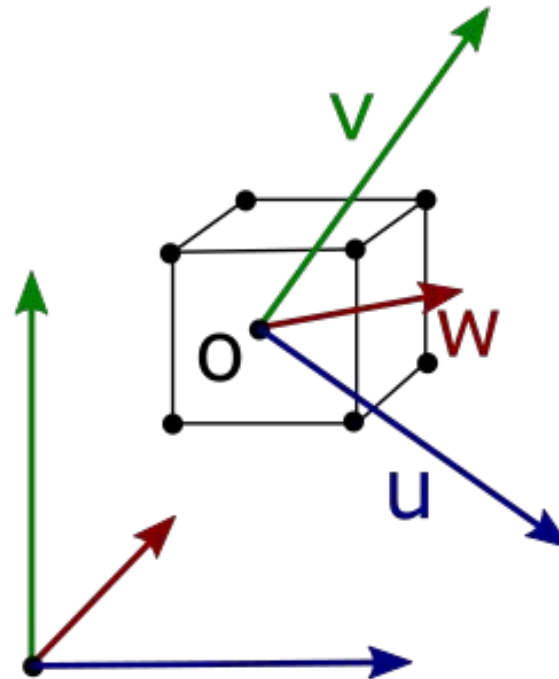
- **Homogeneous coordinates**
- **Transformation matrices**
 - Translation
 - Rotation
 - Scale



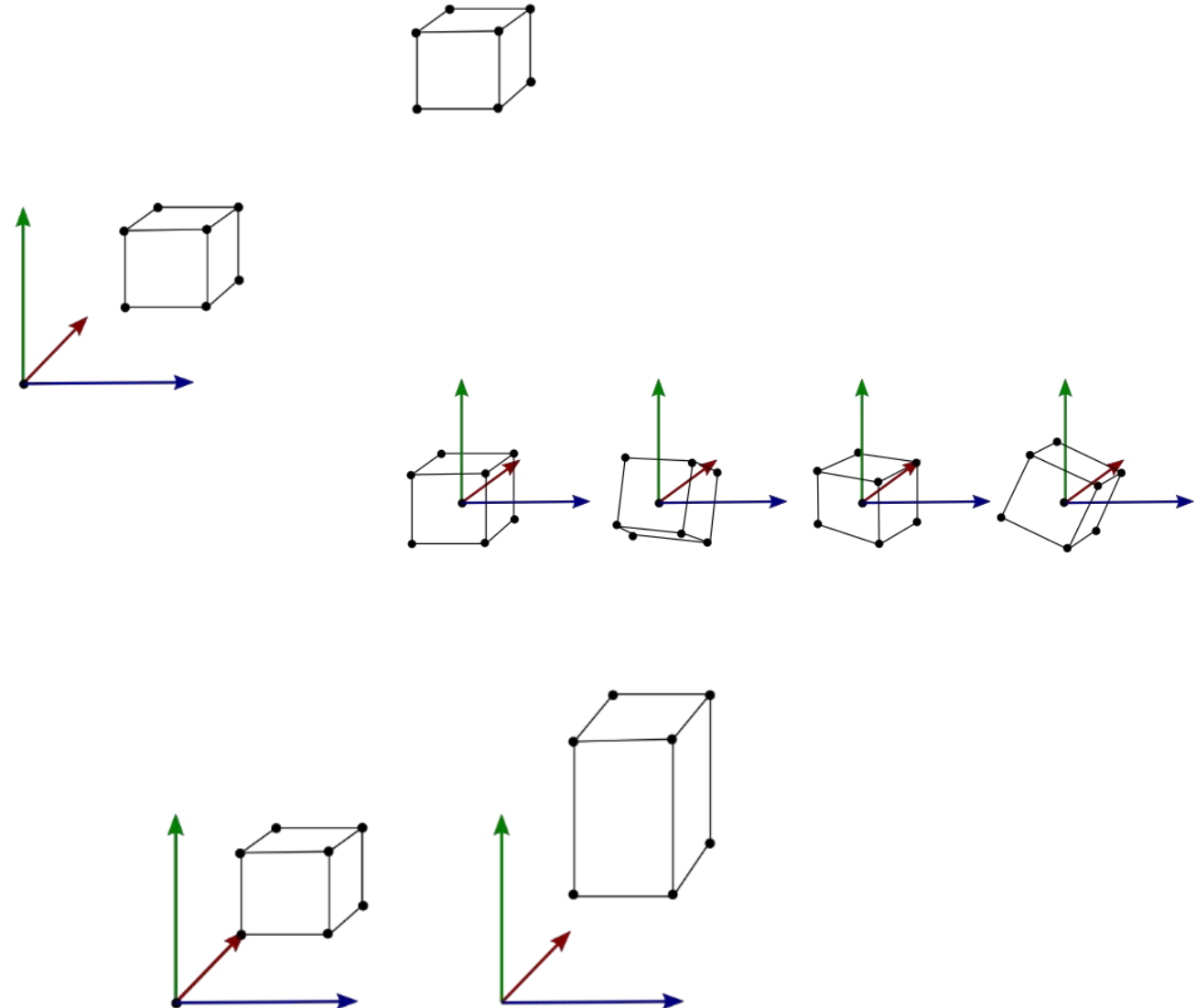
- Homogeneous coordinates
- Transformation matrices
 - Translation
 - Rotation
 - Scale
 - Change of base



- Homogeneous coordinates
- Transformation matrices
 - Translation
 - Rotation
 - Scale
 - Change of base
 - Inverse transform

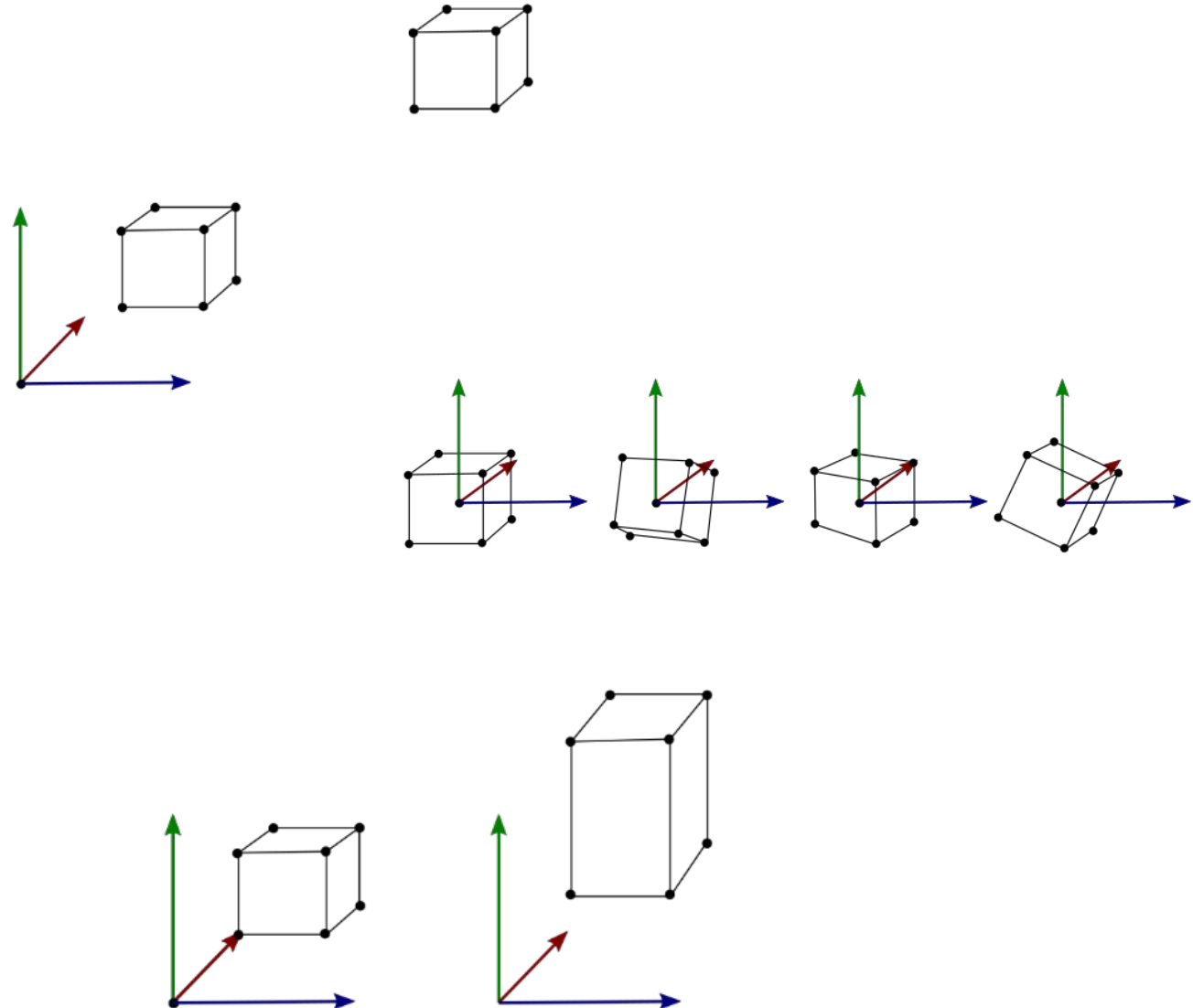


- **Homogeneous coordinates**
- **Transformation matrices**
 - Translation
 - Rotation
 - Scale
 - Change of base
 - Inverse transform
- **Combine transform matrices**



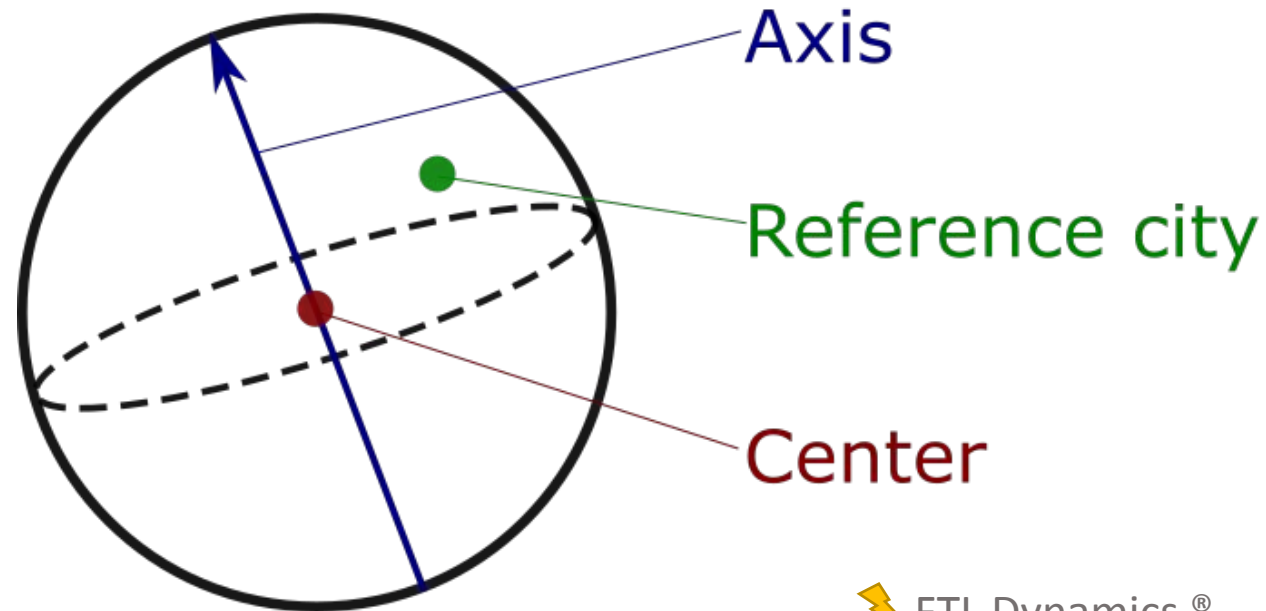
- **Homogeneous coordinates**
- **Transformation matrices**
 - Translation
 - Rotation
 - Scale
 - Change of base
 - Inverse transform
- **Combine transform matrices**

```
std::cout << matrix << std::endl;  
/ 1.0  0.0  0.0  0.0 \  
| 0.0  1.0  0.0  0.0 |  
| 0.0  0.0  1.0  0.0 |  
\ 0.0  0.0  0.0  1.0 /
```



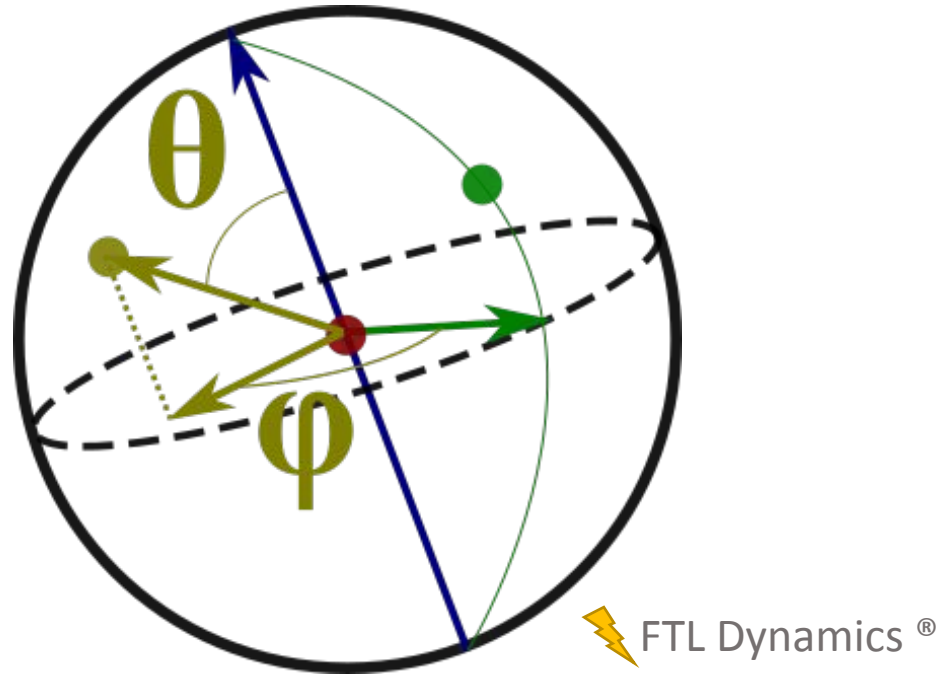
Planetary stations

- How to define a planet



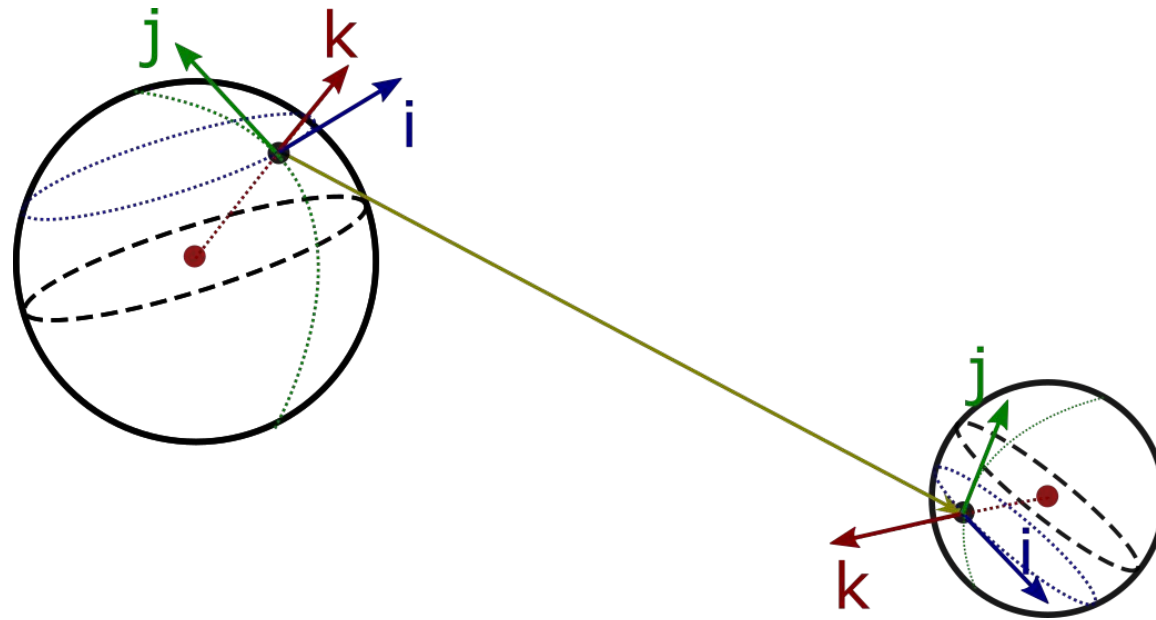
Planetary stations

- How to define a planet
- How to define a city



Planetary stations

- How to define a planet
- How to define a city
- Interplanetary connections



DO ASK questions, either now or after the lab

But be reasonable, please :)

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What to expect from this session

In the programming language of your choice, implement:

- **Data basics:** Matrices, homogeneous coordinates
- **Transformation matrices:**
 - Translation, rotation, scale
 - Change of basis, inverse transformation, combine transform matrices
 - Pretty stdout operator
- Use your new math powers on your job at FTL dynamics
- Recommended deadline: September 25th. Do you have **extra time**?
 - Go home and rest :)
 - Next session: read/write PPM images, tonemapping
 - Try programming ray-sphere intersections, test it with planetary stations