Lab #3 - Ray tracing (part 2)

Informática Gráfica

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Before we begin...

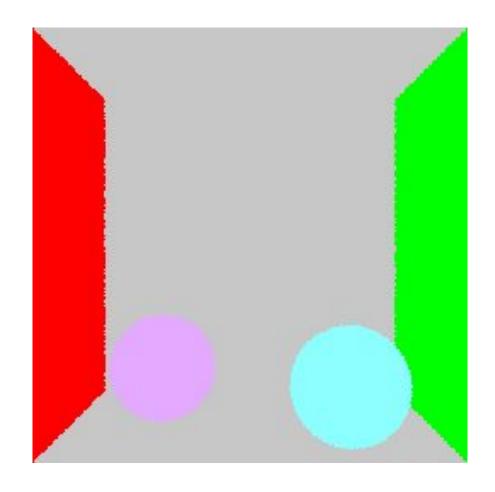


You can generate your first image today :)

Before we begin...



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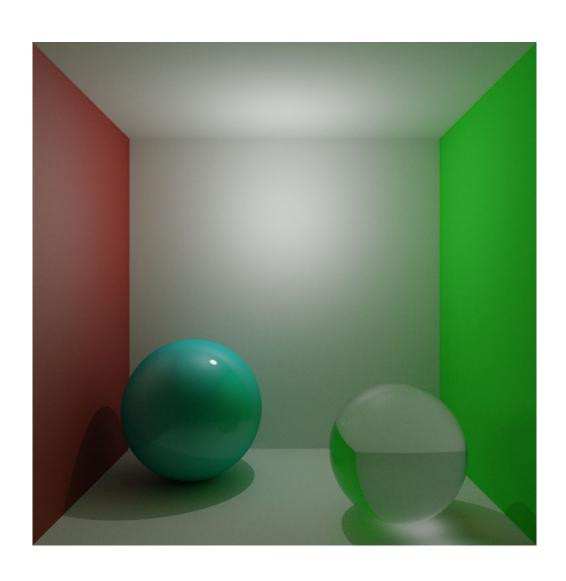
Before we begin...



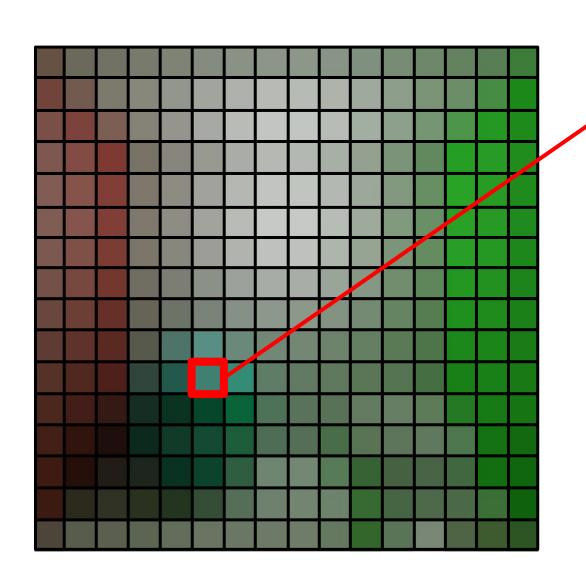
- You can generate your first image today :)
- Careful with the submissions
 - Lab 3 (ray tracing) does not need to be submitted
 - Recommended deadline: October 18th
 - Lab 4 (path tracing) will be submitted at the end of the course
 - All of the code you write today will be used for Lab 4
 - Recommended deadline: November 13th (moodle: January 11th, this is only a recommendation)
- Remember: Final work is 80% of the final grade

Which color do we fill each pixel with? Graphics and Imaging Lab





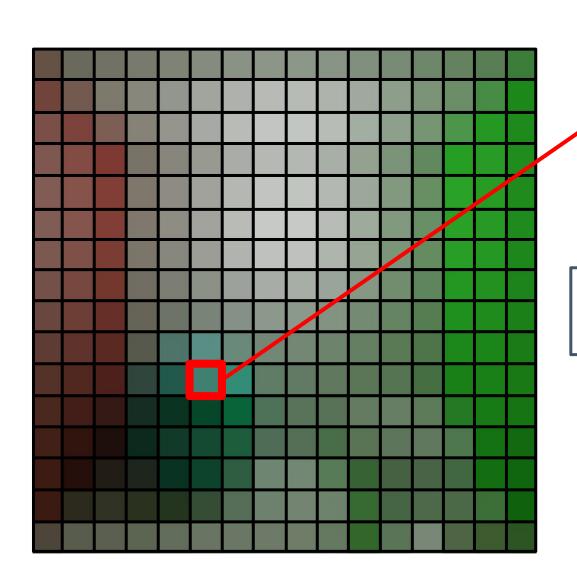




$$R = 0.25 G = 0.5 B = 0.45$$

But how?



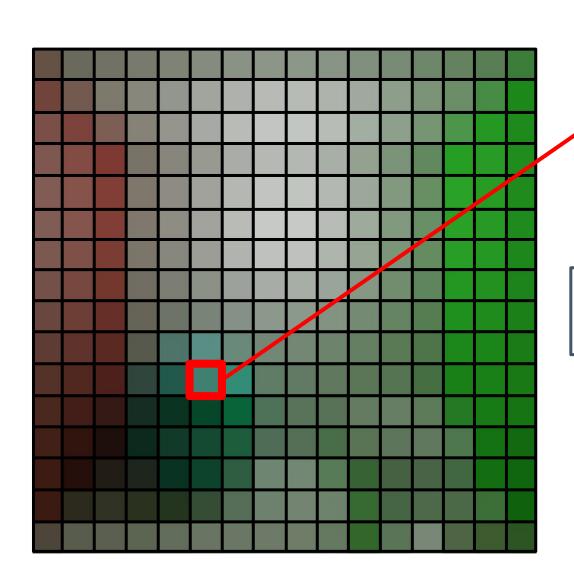


$$R = 0.25 G = 0.5 B = 0.45$$

But how?

$$L_o(\mathbf{x}, \omega_o) = L_e(\mathbf{x}, \omega_o) + \int_{\Omega} L_i(\mathbf{x}, \omega_i) f_r(\mathbf{x}, \omega_i, \omega_o) |\mathbf{n} \cdot \omega_i| d\omega_i$$





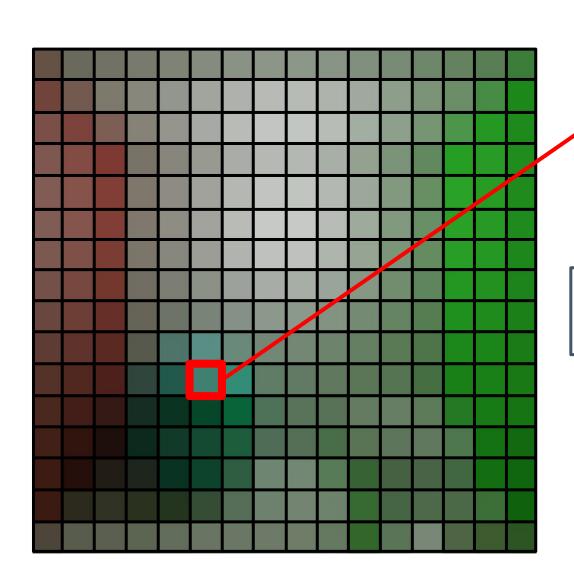
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In this lab, we simplify the render equation:





$$R = 0.25 G = 0.5 B = 0.45$$

But how?

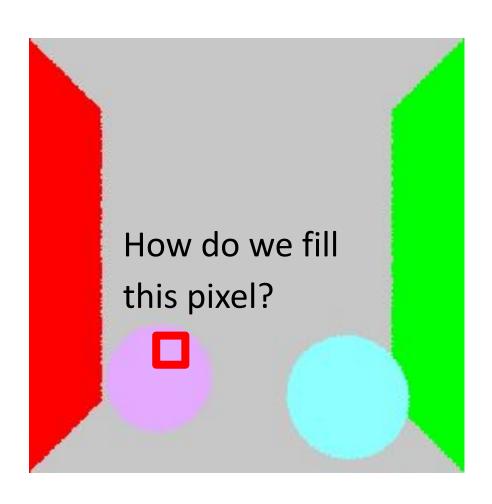
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In this lab,

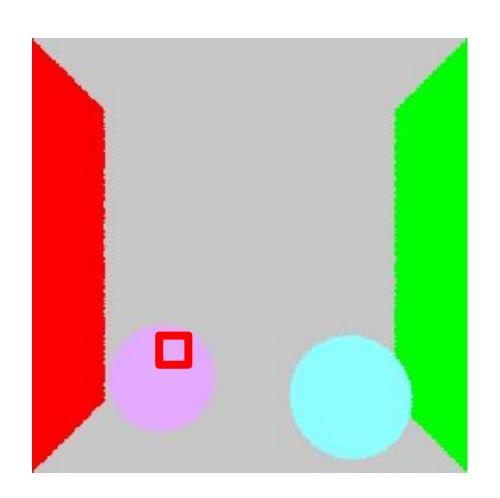
we simplify the render equation:

Everything is an area light

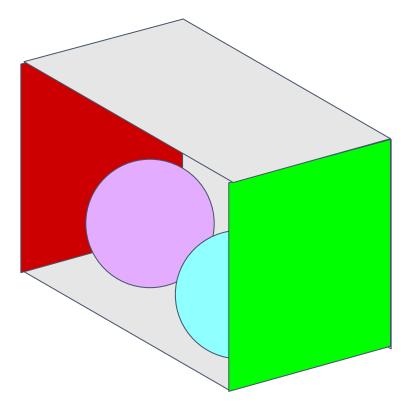




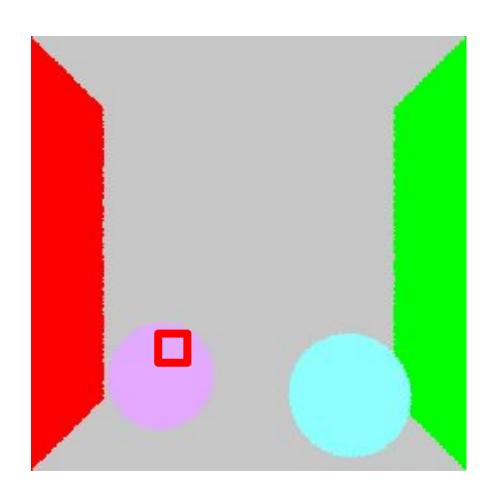




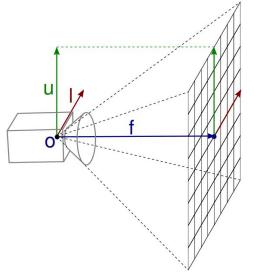
Define your scene's geometry (planes, spheres)

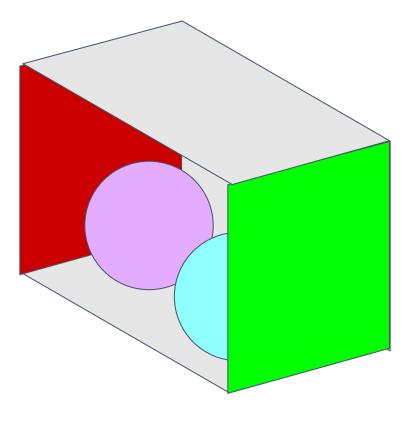




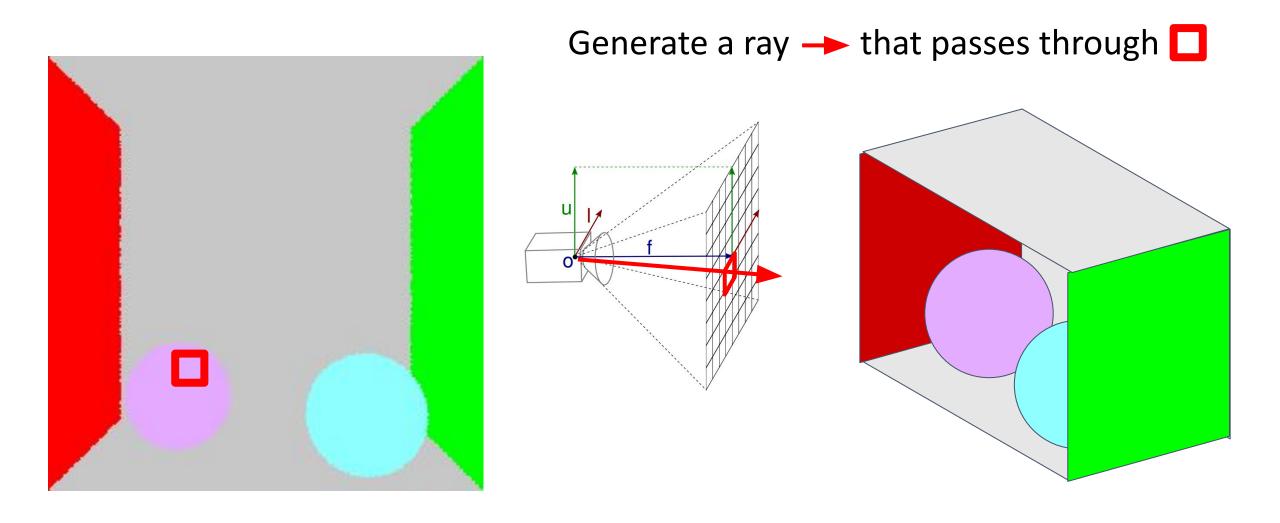


Define your scene's camera (image plane, film)

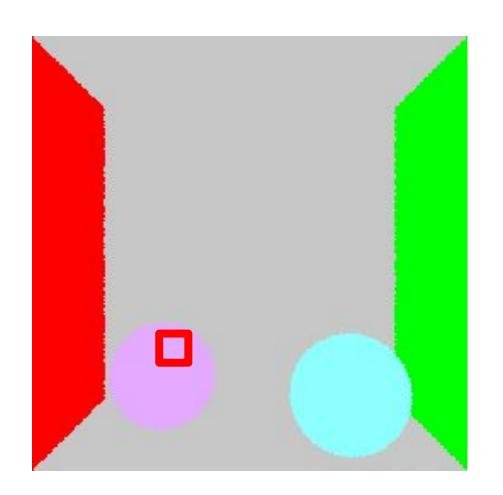




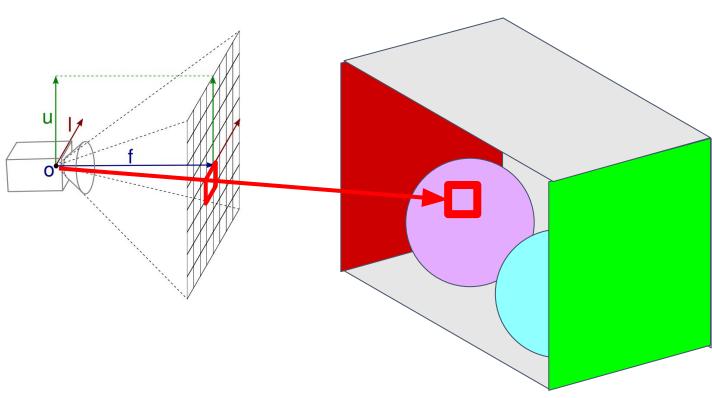




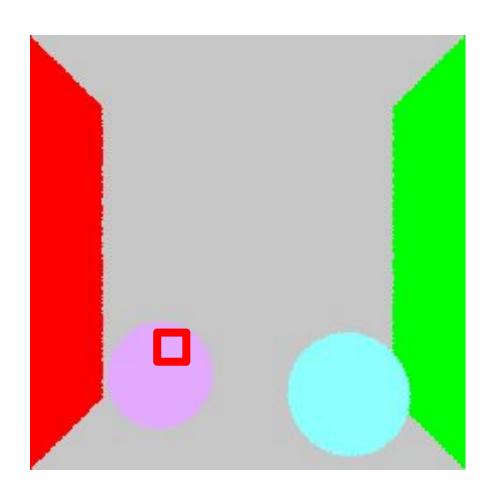




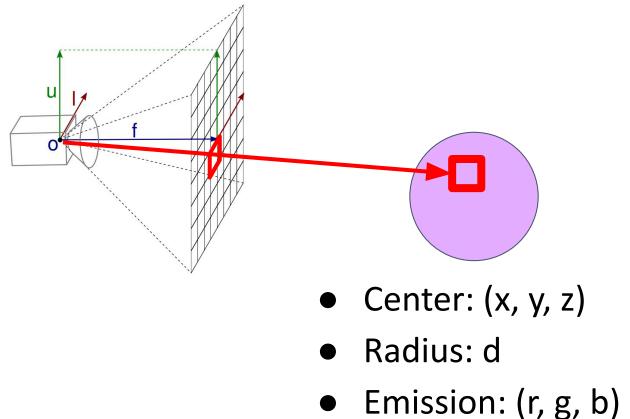
Intersect this ray with your scene



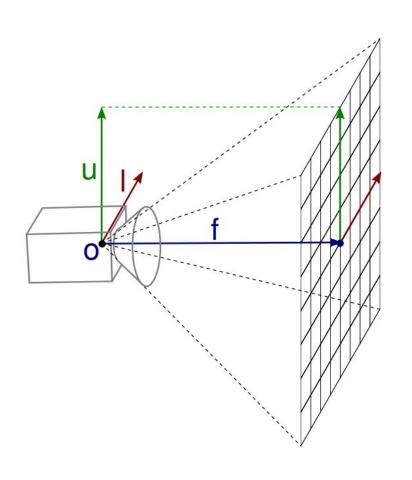




Return your sphere's emission color (everything is an area light in this lab)



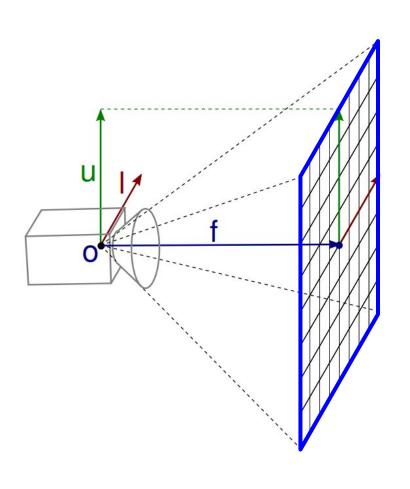




A camera is defined by:

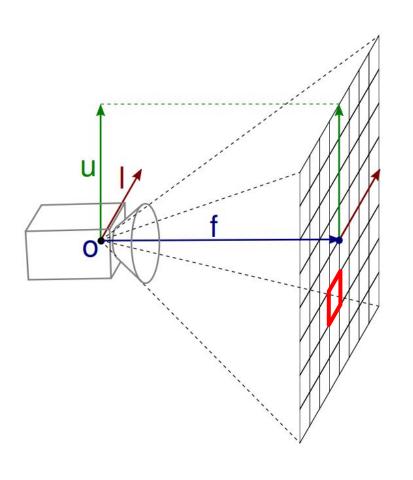
Local coordinate system
 (left L, up U, forward F, origin O)





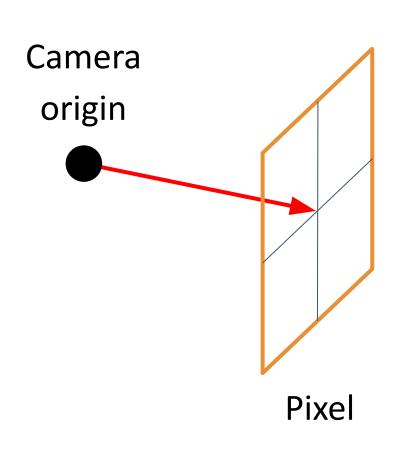
- Local coordinate system
 (left L, up U, forward F, origin O)
- Forward, up & left also define the image plane
 - Divided in pixels (width, height)
 - Pixels should be square (not necessarily)





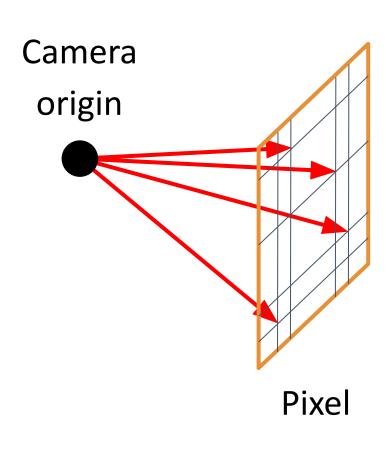
- Local coordinate system
 (left L, up U, forward F, origin O)
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 - Pixels should be square (not necessarily)
- Calculate the boundaries of a pixel
 - Rays: origin O, direction towards pixel





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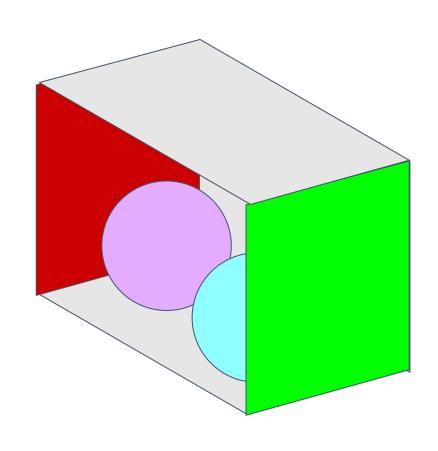


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Example scene: Cornell Box



Geometry



Planes defined by normal (n) and distance (d)

Left plane n = (1, 0, 0), d = 1

Right plane n = (-1, 0, 0), d = 1

Floor plane n = (0, 1, 0), d = 1

Ceiling plane n = (0, -1, 0), d = 1

Back plane n = (0, 0, -1), d = 1

Spheres defined by center (c) and radius (r)

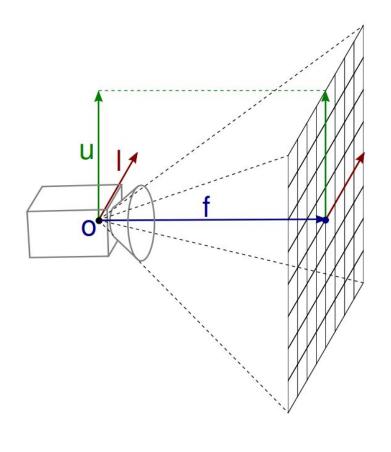
Left sphere c = (-0.5, -0.7, 0.25), r = 0.3

Right sphere c = (0.5, -0.7, -0.25), r = 0.3

Example scene: Cornell Box



Camera



Camera and image plane defined by

Origin O = (0, 0, -3.5)

Left L = (-1, 0, 0)

Up U = (0, 1, 0)

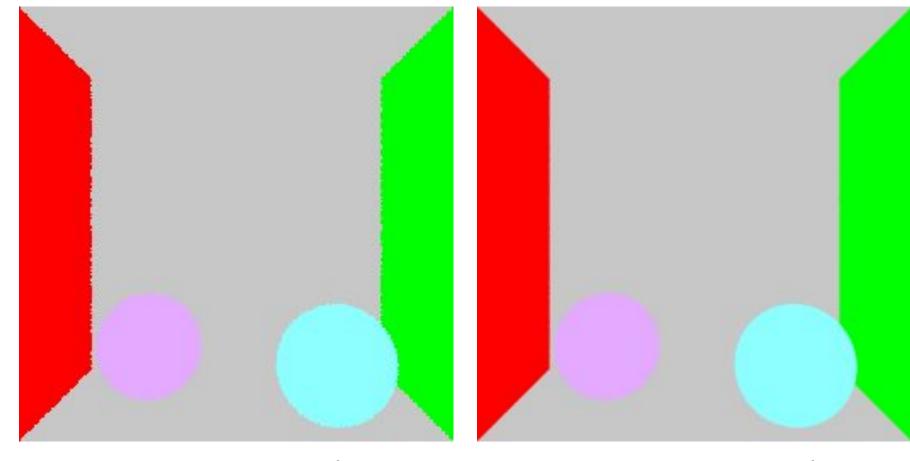
Forward F = (0, 0, 3)

Size 256x256 pixels

Example scene: Cornell Box



Results



1 ray per pixel

64 rays per pixel

Questions



DO ASK questions, either now or after the lab

But be reasonable, please:)

<u>pluesia@unizar.es</u> | <u>dsubias@unizar.es</u> | <u>o.pueyo@unizar.es</u>

What to expect from this session



In the programming language of your choice, implement:

- Scene (collection of geometry primitives)
 - Spheres, planes, etc. (position, emission) should be hardcoded
- Pinhole camera
 - Generate a ray for a specific pixel
 - Intersect this ray with your scene
 - Generate an image
- Recommended deadline: October 18th.
 - Extensions (do not count towards deadline):
 - Other primitives: cones, cylinders, ellipsoids, disks or triangles
 - Acceleration structures: bounding volumes, multi-threading, etc.
 - Constructive solid geometry: google it or ask us:)