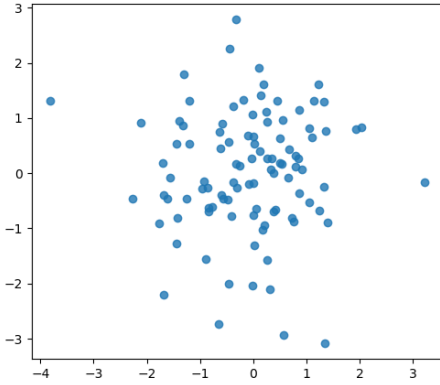


## Simulated Data

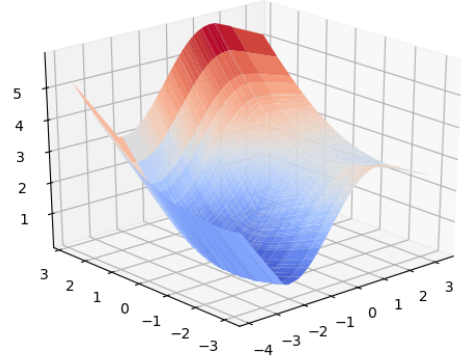
First generate data from a spatial gaussian process with 100 locations, we sample spatial locations  $(x, y)$  iid from standard normal, and assume the pollutant  $z$  follow below Gaussian Process:

$$z(x, y) \stackrel{iid}{\sim} N(f(x, y), \sigma^2 = 0.1)$$

$$f(x, y) = 0.2x + 0.5y + \sqrt{x^2 + y^2} + \sin(x) + \cos(x)$$



(a) Sampled spatial location for monitoring sites (standardized)



(b) Average pollutant surface over space (standardized)

We then generate prediction for  $z(x, y)$  from 5 base GP models, with covariance structure:

1. Linear,
2. Polynomial, degree 3
3. Gaussian RBF, with ARD
4. Matérn  $\frac{5}{2}$ , with ARD
5. MLP, with ARD.

Equivalent to a 2-layer network with Gaussian CDF activation function and infinite hidden units:

$$k(x, y) = \sigma^2 \frac{2}{\pi} \arcsin \left( \frac{\sigma_w^2 x^\top y + \sigma_b^2}{\sqrt{\sigma_w^2 x^\top x + \sigma_b^2 + 1} \sqrt{\sigma_w^2 y^\top y + \sigma_b^2 + 1}} \right)$$

The out-of-sample MSE for 5 models are 4.846, 2.094, 2.011, 1.989, 1.981 respectively.