

Problem 1

Determine if the following matrices are diagonalizable over the field \mathbb{R} . If the matrix is diagonalizable find the eigenspaces and the matrix Q which diagonalizes the matrix.

Part (a):

$$\begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}$$

Part (b):

$$\begin{bmatrix} 0 & 0 & -1 \\ 1 & 0 & -1 \\ 0 & 1 & 1 \end{bmatrix}$$

Part (c):

$$\begin{bmatrix} 7 & -4 & 0 \\ 8 & -5 & 0 \\ 6 & -6 & 3 \end{bmatrix}$$

Solution

For each of these matrices, we will begin by finding the eigen values. With these eigen values, we will then find each corresponding eigenspace. If the sum of the dimensions of these eigenspaces is equal to the dimension of vector space these matrices act on, then we will construct a basis of our vector space consisting of eigenvectors, and use this to find the matrix which diagonalizes our matrix.

Part (a):

We have

$$\begin{vmatrix} 1-\lambda & 2 \\ 0 & 1-\lambda \end{vmatrix} = (1-\lambda)^2 = 0,$$

which means the eigen value of this matrix is $\lambda = 1$, with a multiplicity of 2. Then, to find the eigenspace corresponding to this eigenvalue,

$$\begin{bmatrix} 1-\lambda & 2 \\ 0 & 1-\lambda \end{bmatrix} = \begin{bmatrix} 0 & 2 \\ 0 & 0 \end{bmatrix}.$$

Thus, we have

$$E_1 = \left\{ \begin{bmatrix} s \\ 0 \end{bmatrix} : s \in \mathbb{R} \right\}.$$

Since the dimension of the space spanned by all of our eigenvectors is less than the dimension of \mathbb{R}^2 , we have shown this matrix is not diagonalizable.

Part (b):

Beginning as before,

$$\begin{aligned} \begin{vmatrix} -\lambda & 0 & -1 \\ 1 & -\lambda & -1 \\ 0 & 1 & 1-\lambda \end{vmatrix} &= -\lambda \begin{vmatrix} -\lambda & -1 \\ 1 & 1-\lambda \end{vmatrix} - \begin{vmatrix} 1 & -\lambda \\ 0 & 1 \end{vmatrix} \\ &= -\lambda(-\lambda(1-\lambda) + 1) - 1 \\ &= -\lambda^3 + \lambda^2 - \lambda - 1. \end{aligned}$$

Plugging this polynomial into wolfram alpha, we see that it has only 1 real root, and two complex roots. Thus, since we are working over \mathbb{R} , this matrix is not diagonalizable.

Part (c):

Finally,

$$\begin{aligned}
 0 &= \begin{vmatrix} 7-\lambda & -4 & 0 \\ 8 & -5-\lambda & 0 \\ 6 & -6 & 3-\lambda \end{vmatrix} \\
 &= (3-\lambda) \begin{vmatrix} 7-\lambda & -4 \\ 8 & -5-\lambda \end{vmatrix} \\
 &= (3-\lambda)[(7-\lambda)(-5-\lambda) + 32] \\
 &= (3-\lambda)[-35 - 2\lambda + \lambda^2 + 32] \\
 &= (3-\lambda)[-3 - 2\lambda + \lambda^2] \\
 &= (3-\lambda)(\lambda+1)(\lambda-3) \\
 &= (3-\lambda)^2(\lambda+1).
 \end{aligned}$$

With this, we can now find the eigen vectors corresponding to $\lambda = 3$ and $\lambda = -1$:

$$\begin{aligned}
 \begin{bmatrix} 7-3 & -4 & 0 \\ 8 & -5-3 & 0 \\ 6 & -6 & 3-3 \end{bmatrix} &= \begin{bmatrix} 4 & -4 & 0 \\ 8 & -8 & 0 \\ 6 & -6 & 0 \end{bmatrix} \\
 &\rightarrow \begin{bmatrix} 4 & -4 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} && R_3 - \frac{6}{4}R_1 \wedge R_2 - 2R_1 \\
 &\rightarrow \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} && R_3 - \frac{6}{4}R_1 \wedge R_2 - 2R_1
 \end{aligned}$$

Thus, we have

$$\begin{aligned}
 E_3 &= \left\{ \begin{bmatrix} t \\ t \\ s \end{bmatrix} : s, t \in \mathbb{R} \right\} \\
 &= \text{Span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}
 \end{aligned}$$

which has dimension 2.

Now, for our remaining eigenvalue, we have

$$\begin{aligned}
 \begin{bmatrix} 7+1 & -4 & 0 \\ 8 & -5+1 & 0 \\ 6 & -6 & 3+1 \end{bmatrix} &= \begin{bmatrix} 8 & -4 & 0 \\ 8 & -4 & 0 \\ 6 & -6 & 4 \end{bmatrix} \\
 &\rightarrow \begin{bmatrix} 8 & -4 & 0 \\ 0 & 0 & 0 \\ 6 & -6 & 4 \end{bmatrix} && R_2 - R_1 \\
 &\rightarrow \begin{bmatrix} 8 & -4 & 0 \\ 6 & -6 & 4 \\ 0 & 0 & 0 \end{bmatrix} && \text{Row swapping} \\
 &\rightarrow \begin{bmatrix} 8 & -4 & 0 \\ 0 & -3 & 4 \\ 0 & 0 & 0 \end{bmatrix} && R_2 - \frac{6}{8}R_1 \\
 &\rightarrow \begin{bmatrix} 2 & -1 & 0 \\ 0 & 1 & -\frac{4}{3} \\ 0 & 0 & 0 \end{bmatrix} && \frac{1}{8}R_1 \wedge -\frac{1}{3}R_2
 \end{aligned}$$

Then,

$$E_{-1} = \text{Span} \left\{ \begin{bmatrix} 2 \\ 4 \\ 3 \end{bmatrix} \right\}.$$

With this, we can define a basis of \mathbb{R}^3

$$\{v_1, v_2, v_3\} = \left\{ \begin{bmatrix} 2 \\ 4 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

The change of basis matrix from our eigenbasis to the standard basis is then

$$Q = \begin{bmatrix} 2 & 1 & 0 \\ 4 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix}.$$

To find the inverse matrix, we augment to the identity matrix and reduce to RREF:

$$\begin{aligned} [Q|I] &= \begin{bmatrix} 2 & 1 & 0 & 1 & 0 & 0 \\ 4 & 1 & 0 & 0 & 1 & 0 \\ 3 & 0 & 1 & 0 & 0 & 1 \end{bmatrix} \\ &\rightarrow \begin{bmatrix} 2 & 1 & 0 & 1 & 0 & 0 \\ 0 & -1 & 0 & -2 & 1 & 0 \\ 3 & 0 & 1 & 0 & 0 & 1 \end{bmatrix} \\ &\rightarrow \begin{bmatrix} 2 & 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 2 & -1 & 0 \\ 3 & 0 & 1 & 0 & 0 & 1 \end{bmatrix} \\ &\rightarrow \begin{bmatrix} 2 & 0 & 0 & -1 & 1 & 0 \\ 0 & 1 & 0 & 2 & -1 & 0 \\ 3 & 0 & 1 & 0 & 0 & 1 \end{bmatrix} \\ &\rightarrow \begin{bmatrix} 1 & 0 & 0 & -1/2 & 1/2 & 0 \\ 0 & 1 & 0 & 2 & -1 & 0 \\ 3 & 0 & 1 & 0 & 0 & 1 \end{bmatrix} \\ &\rightarrow \begin{bmatrix} 1 & 0 & 0 & -1/2 & 1/2 & 0 \\ 0 & 1 & 0 & 2 & -1 & 0 \\ 0 & 0 & 1 & 3/2 & -3/2 & 1 \end{bmatrix} \\ &= [I|Q^{-1}]. \end{aligned}$$

Therefore, we have

$$Q^{-1} = \begin{bmatrix} -1/2 & 1/2 & 0 \\ 2 & -1 & 0 \\ 3/2 & -3/2 & 1 \end{bmatrix},$$

and, if we let our matrix be denoted A , we can see

$$\begin{aligned} Q^{-1}AQ &= \begin{bmatrix} -1/2 & 1/2 & 0 \\ 2 & -1 & 0 \\ 3/2 & -3/2 & 1 \end{bmatrix} \begin{bmatrix} 7 & -4 & 0 \\ 8 & -5 & 0 \\ 6 & -6 & 3 \end{bmatrix} \begin{bmatrix} 2 & 1 & 0 \\ 4 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix} \\ &= \begin{bmatrix} -1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix}. \end{aligned}$$

Problem 2

Theorem 1. Part (a):

Not every invertible matrix is diagonalizable.

Part (b):

Not every diagonalizable matrix is invertible.

Solution

Proof. Part (a):

Consider a matrix representing a counter clockwise rotation in \mathbb{R}^2 by $0 < \theta < 2\pi$ radians. This matrix is invertible (inverse matrix rotates by θ radians clockwise). Now, since the only vector that remains pointing in the same direction after being rotated by θ radians is the zero vector, we can conclude this matrix has no eigenvectors, and is therefore not diagonalizable.

Part (b):

Let A be a matrix in \mathbb{R}^2 with eigen values 0 and 1. These eigen values are unique, thus they correspond to two linearly independent eigen vectors that span \mathbb{R}^2 . However, this means that A has a nonzero vector in its nullspace, which implies it is not injective (since A is linear), and therefore non-invertible. \square

Problem 3

In this question, you may only assume that $|AB| = |A||B|$ for $n \times n$ matrices A and B with entries from a field F .

Theorem 2. Part (a):

If Q is an $n \times n$ invertible matrix, then $|Q^{-1}| = |Q|^{-1}$.

Part (b):

Similar matrices have the same determinant.

Part (c):

Similar matrices have the same characteristic polynomial.

Solution

Proof. Part (a):

We have

$$\begin{aligned} 1 &= |I| \\ &= |QQ^{-1}| \\ &= |Q||Q^{-1}| \\ |Q|^{-1} &= |Q^{-1}|, \end{aligned}$$

as desired.

Part (b):

Let A and Q be $n \times n$ matrices with Q having inverse Q^{-1} . Then, we have

$$\begin{aligned} |Q A Q^{-1}| &= |Q||A||Q^{-1}| \\ &= |A| \end{aligned} \quad \text{By Part (a).}$$

Thus, similar matrices have the same determinant.

Part (c):

Define A and Q as before, and let

$$B = Q A Q^{-1}.$$

Then, we have

$$\begin{aligned} |B - \lambda I| &= |Q A Q^{-1} - \lambda I| \\ &= |Q^{-1}(Q A Q^{-1} - \lambda I)Q| && \text{By Part (b)} \\ &= |Q^{-1}Q A Q^{-1}Q - Q^{-1}\lambda I Q| \\ &= |I A I - \lambda I| \\ &= |A - \lambda I|, \end{aligned}$$

and we have shown that similar matrices have the same characteristic polynomial. \square

Problem 4

Theorem 3. Let $B \in M_{n \times n}(\mathbb{C})$ be an invertible matrix.

Part (a):

Every matrix $A \in M_{n \times n}(\mathbb{C})$ has an eigenvalue.

Part (a):

For any matrix $A \in M_{n \times n}(\mathbb{C})$, there is a number $c \in \mathbb{C}$ such that $\det(A + cB) = 0$.

Solution

Proof. Part (a):

The characteristic polynomial of A is an n^{th} degree polynomial with complex coefficients. By the Fundamental theorem of algebra, every non-zero, single-variable, degree n polynomial with complex coefficients has, counted with multiplicity, exactly n complex roots. Since the roots of the characteristic polynomial are the eigenvalues of A , we are done with the proof of Part (a).

Part (b):

Since B is invertible, it and its inverse have non zero determinants. Thus, we have

$$\begin{aligned} |A + cB| &= \frac{1}{|Q^{-1}|} |(A + cB)B^{-1}| \\ &= \frac{1}{|Q^{-1}|} |(A + cB)B^{-1}| \\ &= \frac{1}{|Q^{-1}|} |AB^{-1} + cBB^{-1}| \\ &= \frac{1}{|Q^{-1}|} |AB^{-1} + cI|. \end{aligned}$$

Letting $\lambda = -c$, we have

$$|A + cB| = \frac{1}{|Q^{-1}|} |AB^{-1} - \lambda I|,$$

where $|AB^{-1} - \lambda I|$ is the characteristic polynomial of AB^{-1} . By Part (a), this matrix has an eigenvalue, and our proof is complete. \square