```
ld msg pose
+ robot x
+ robot y
+ robot th
+ seconds_since_epoch
+ server time
+ x_recv time
+ v recv time
+ th recv time
+ time recv time
             -current pose
    cart status copy
- client id

    status

- no cart
- current dock
- previous dock
+ cart status copv()
+ cart status copy()
+ ~cart status copv()
+ update status init()
+ update_status()
+ update pose()
+ update pose()
+ get id()
+ get status()
+ get no cart()
+ get current dock()
+ get previous dock()
+ update previous dock()
+ print_status()
+ pose to string()
```