```
ld_msg_pose
                 + robot_x
                + robot_y
                + robot_th
                 + seconds_since_epoch
                 + server_time
                 + x_recv_time
                + y_recv_time
+ th_recv_time
                 + time_recv_time
                       -goal_buf
                                    -goal_list
                    -current_pose
          cart_status
   - status
   - no_cart
   start_dock
   current_no_armcurrent_dock
   - current_goal
   - current_large_point1
   current_large_point2
   - current_edge_start
   no_arm_buf
   and 7 more..
   + cart status()
   + ~cart_status()
   + set_status()
   + update_current_dock()
   + print_no_arm_list()
   + print_dock_list()
+ print_goal_list()
+ print_large_point1_list()
   + print_large_point2_list()
   + print edge start list()
   and 14 more...
                                    cart_config
                             file_name
                             - runs
                             task_count
                             - err
                             - config_file
                             first_task
                             start
                             - dock list
                             large_point1_list
                             large_point2_list
                             edge_start_list
                             no_arm_list
                             - sum1
             -client_stat
                             - sum2
                              update_count
                             + cart_config()
                             + ~cart_config()
                             + clear_data()
                              + read_file()
                              + write_file()
                             + update_large_points()
                              + update_edge_points()
                              + avg_large_points()
                              + get_count()
                             + get_config()
                              + print_file()
                              + get_err()
    cart_comm_client
- client_id
- port
- ip_addr

    mutex

+ cart_comm_client()
+ ~cart_comm_client()
+ cart_client_connect()
                                              +saved_config
+ cart_client_disconnect()
+ recv()
+ send()
+ cart_comm_client_read()
+ parse_msg()
+ remote_command()
+ local_command()
and 10 more...
- comm_err_client()
                         +cart_client
                         task_args
                         + actuate
                         + ur5
```