```
ld msg pose
+ robot x
+ robot v
+ robot th
+ seconds since epoch
+ server time
+ x recv time
+ y recv time
+ th recv time
+ time recv time
             +goal list
      config data
   + runs
  + task count
   + start
  + dock list
  + large point1 list
  + large_point2 list
  + edge start list
   + no arm list
   + sum1
   + sum2
  + update count
  + config data()
   + ~config data()
   + print data()
```