```
ld_msg_pose
+ robot_x
+ robot_y
+ robot th
+ seconds since epoch
+ server time
+ x recv time
+ v recv time
+ th recv time
+ time recv time
             -goal_list
       cart config
- file name
- runs

    task count

- err
- config file
- first task
- start
- dock list
large_point1_list
- large_point2 list
- edge start list
- no arm list

    sum1

    sum2

- update count
+ cart config()
+ ~cart config()
+ clear_data()
+ read file()
+ write file()
+ update_large_points()
+ update edge points()
+ avg_large_points()
+ get count()
+ get config()
+ print file()
+ get err()
```