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## The beginning steps of SUMO TraCl programming with Python script

- 1. Unpack the example folder containing:
  - SUMO files (net file, configuration file, etc.), and
  - Python script file.
- 2. Start Spyder (Anaconda).

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3. Open the **roundabout.py** script file, and the following simple TraCl program will appear:

```
import os, sys
import time
if 'SUMO_HOME' in os.environ:
    tools = os.path.join(os.environ['SUMO_HOME'], 'tools')
    sys.path.append(tools)
    sys.exit("please declare environment variable 'SUMO_HOME'")
import traci
import traci.constants
sumoBinary = "C:"+os.sep+"Sumo"+os.sep+"bin"+os.sep+"sumo-gui.exe"
sumoCmd = [sumoBinary, "-c", "roundabout.sumocfg", "--start"]
traci.start(sumoCmd)
print("Starting SUMO")
traci.gui.setSchema("View #0", "real world")
j = 0;
while(j < 60):
    #this runs one simulation step
    time.sleep(0.5);
    traci.simulationStep();
    vehicles=traci.vehicle.getIDList();
    if (j%10)==0: #every 10 sec....
        for i in range(0,len(vehicles)):
            #print(len(vehicles))
            print(vehicles[i])
            traci.vehicle.setSpeedMode(vehicles[i],0)
            #sets the speed of vehicles to 15 (m/s)
            traci.vehicle.setSpeed(vehicles[i],15)
            #get actual speed, emission, edge ID and total distance
travelled of vehicles
            print("Speed ", vehicles[i], ":
",traci.vehicle.getSpeed(vehicles[i]), " m/s")
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```

- 4. Start simulation by clicking **Run file** or pressing **F5**.
- 5. Further help on TraCl programming is available on the SUMO website: https://sumo.dlr.de/docs/TraCl.html

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