

1)

$$H = \begin{bmatrix} E_0 & \hbar\Omega/2 \\ \hbar\Omega/2 & E_0 \end{bmatrix}$$

$$| \psi \rangle = \begin{bmatrix} c_0 \\ c_1 \end{bmatrix}$$

a) $| \psi \rangle$ must satisfy the Schrödinger equation so

$$i\hbar \frac{\partial}{\partial t} | \psi \rangle = H | \psi \rangle$$

$$\rightarrow i\hbar \begin{bmatrix} \dot{c}_0 \\ \dot{c}_1 \end{bmatrix} = \begin{bmatrix} E_0 & \hbar\Omega/2 \\ \hbar\Omega/2 & E_0 \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \end{bmatrix}$$

$$\rightarrow \dot{c}_0 = -\frac{i}{\hbar} E_0 c_0 - i \frac{\Omega}{2} c_1$$

$$\dot{c}_1 = -i \Omega c_0 - \frac{i}{\hbar} E_0 c_1$$

(1)

b)

$$\text{Let } \tilde{c}_0 = c_0 e^{iE_0 t/\hbar}$$

$$\tilde{c}_1 = c_1 e^{iE_0 t/\hbar}$$

$$\text{So } c_0 = \tilde{c}_0 e^{-iE_0 t/\hbar}$$

$$c_1 = \tilde{c}_1 e^{-iE_0 t/\hbar}$$

$$\text{and } \dot{c}_0 = \dot{\tilde{c}}_0 e^{-iE_0 t/\hbar} - i \frac{E_0}{\hbar} \tilde{c}_0 e^{-iE_0 t/\hbar}$$

$$\dot{c}_1 = \dot{\tilde{c}}_1 e^{-iE_0 t/\hbar} - i \frac{E_0}{\hbar} \tilde{c}_1 e^{-iE_0 t/\hbar}$$

Plugging these into (1) and multiplying by $e^{iE_0 t/\hbar}$ gives

$$\dot{\tilde{c}}_0 = -\frac{i\Omega}{2} \tilde{c}_1$$

$$\dot{\tilde{c}}_1 = -\frac{i\Omega}{2} \tilde{c}_0$$

Which we can rewrite as

$$i\hbar \begin{bmatrix} \dot{\tilde{c}}_0 \\ \dot{\tilde{c}}_1 \end{bmatrix} = \begin{bmatrix} 0 & \hbar \frac{\Omega}{2} \\ \hbar \frac{\Omega}{2} & 0 \end{bmatrix} \begin{bmatrix} \tilde{c}_0 \\ \tilde{c}_1 \end{bmatrix}$$

c)

Setting $E_0 = 0$ and differentiating gives

$$\dot{c}_0 = -i \frac{\Omega}{2} c_1$$

$$\dot{c}_1 = -i \frac{\Omega}{2} c_0$$

$$\rightarrow \ddot{c}_0 = -i \frac{\Omega}{2} \dot{c}_1 = -i \frac{\Omega}{2} \left(-i \frac{\Omega}{2}\right) c_0$$

$$\ddot{c}_1 = -i \frac{\Omega}{2} \dot{c}_0 = -i \frac{\Omega}{2} \left(-i \frac{\Omega}{2}\right) c_1$$

$$\rightarrow \begin{aligned} \ddot{c}_0 &= - \left(\frac{\Omega}{2}\right)^2 c_0 \\ \ddot{c}_1 &= - \left(\frac{\Omega}{2}\right)^2 c_1 \end{aligned}$$

d)

$$C_0(t) = A_0 \sin\left(\frac{\Omega}{2} t\right) + B_0 \cos\left(\frac{\Omega}{2} t\right)$$

$$C_1(t) = A_1 \sin\left(\frac{\Omega}{2} t\right) + B_1 \cos\left(\frac{\Omega}{2} t\right)$$

$t=0$ implies

$$C_0(0) = B_0, \quad C_1(0) = B_1,$$

$$\dot{C}_0(0) = A_0 \frac{\Omega}{2}, \quad \dot{C}_1(0) = A_1 \frac{\Omega}{2}$$

and since

$$\dot{C}_0(0) = -i \frac{\Omega}{2} C_1(0)$$

$$\dot{C}_1(0) = -i \frac{\Omega}{2} C_0(0)$$

we have

$$A_0 = -i C_1(0)$$

$$A_1 = -i C_0(0)$$

So

$$C_0(t) = C_0(0) \cos\left(\frac{\Omega}{2} t\right) - i C_1(0) \sin\left(\frac{\Omega}{2} t\right)$$

$$C_1(t) = C_1(0) \cos\left(\frac{\Omega}{2} t\right) - i C_0(0) \sin\left(\frac{\Omega}{2} t\right)$$

e)

If $c_0(t=0) = 1$ then

$$|c_0(0)|^2 + |c_1(0)|^2 = 1$$

$$\text{So } c_1(0) = 0$$

Therefore,

$$P_0(t) = |c_0(t)|^2$$

$$P_0(t) = \cos\left(\frac{\Omega}{2}t\right)^2$$

$$P_0(t) = \frac{1}{2} + \frac{1}{2} \cos(\Omega t)$$

Which oscillates between 1
and 0 with frequency Ω

2)

$$H = \frac{\hbar}{2} \begin{bmatrix} -\Delta & \Omega \\ \Omega & \Delta \end{bmatrix}$$

a)

$$i\hbar |\dot{\psi}\rangle = H |\psi\rangle$$

$$\psi = \begin{bmatrix} c_0 \\ c_1 \end{bmatrix}$$

gives

$$\dot{c}_0 = i \frac{\Delta}{2} c_0 - i \frac{\Omega}{2} c_1$$

$$\dot{c}_1 = -i \frac{\Omega}{2} c_0 - i \frac{\Delta}{2} c_1$$

b)

$$\ddot{c}_1 = i \frac{\Delta}{2} \dot{c}_0 - i \frac{\Omega}{2} \dot{c}_1$$

$$\begin{aligned} \ddot{c}_1 &= i \frac{\Delta}{2} \left(i \frac{\Delta}{2} c_0 - i \frac{\Omega}{2} c_1 \right) \\ &\quad - i \frac{\Omega}{2} \left(-i \frac{\Omega}{2} c_0 - i \frac{\Delta}{2} c_1 \right) \end{aligned}$$

$$\begin{aligned} \ddot{c}_0 &= - \left(\frac{\Delta}{2} \right)^2 c_0 + \frac{\Delta \Omega}{4} c_1 \\ &\quad - \left(\frac{\Omega}{2} \right)^2 c_0 - \frac{\Delta \Omega}{4} c_1 \end{aligned}$$

$$\begin{aligned} \ddot{c}_1 &= -i \frac{\Omega}{2} \left(i \frac{\Delta}{2} c_0 - i \frac{\Omega}{2} c_1 \right) \\ &\quad - i \frac{\Delta}{2} \left(-i \frac{\Omega}{2} c_0 - i \frac{\Delta}{2} c_1 \right) \end{aligned}$$

$$\begin{aligned} \ddot{c}_1 &= \frac{\Omega \Delta}{4} c_0 - \left(\frac{\Omega}{2} \right)^2 c_1 - \frac{\Delta \Omega}{4} c_0 \\ &\quad - \left(\frac{\Delta}{2} \right)^2 c_1 \end{aligned}$$

$$\begin{aligned} \rightarrow \quad \ddot{c}_0 &= - \left(\left(\frac{\Delta}{2} \right)^2 + \left(\frac{\Omega}{2} \right)^2 \right) c_0 \\ \ddot{c}_1 &= - \left(\left(\frac{\Omega}{2} \right)^2 + \left(\frac{\Delta}{2} \right)^2 \right) c_1 \end{aligned} \quad (2')$$

c)

As with problem 1,

$$c_0(t) = c_0(0) \cos\left(\frac{1}{2} \tilde{\Omega} t\right) - i c_1(0) \sin\left(\frac{1}{2} \tilde{\Omega} t\right)$$

$$c_1(t) = c_1(0) \cos\left(\frac{1}{2} \tilde{\Omega} t\right) - i c_0(0) \sin\left(\frac{1}{2} \tilde{\Omega} t\right)$$

$$\text{Where } \tilde{\Omega} = \sqrt{\Delta^2 + \Omega^2}$$

d) If $c_0(0) = 1$ then $c_1(0) = 0$

So

$$P_0(t) = |c_0(t)|^2$$

$$P_0(t) = \cos^2\left(\frac{1}{2} \tilde{\Omega} t\right)$$

$$P_0(t) = \frac{1}{2} + \frac{1}{2} \cos(\tilde{\Omega} t),$$

$$\tilde{\Omega} = \sqrt{\Delta^2 + \Omega^2}$$

3)

Let

$$P_R(\max) = 4ccs^2\theta \sin^2\theta$$

$$\tan(2\theta) = \frac{|\Omega|}{\Delta}, \quad (0 \leq \theta < \frac{\pi}{2})$$

Then we have

$$\tan(2\theta) = \frac{|\Omega|}{\Delta}$$

$$P_R(\max) = 4ccs^2\theta \sin^2\theta = \sin^2(2\theta)$$

$$\begin{aligned} P_R(\max) &= \sin^2\left(\arctan\left(\frac{|\Omega|}{\Delta}\right)\right) \\ &= \frac{\left(\frac{|\Omega|}{\Delta}\right)^2}{\left(\frac{|\Omega|^2}{\Delta^2} + 1\right)} \end{aligned}$$

$$P_R(\max) = \frac{\Omega^2}{\Omega^2 + \Delta^2}$$