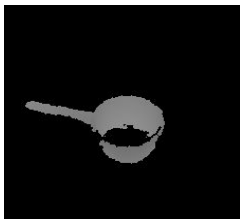


Scene



Depth Image



Learned Generative Model

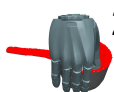
Execution of Top Grasp



Learned Evaluative Model



1

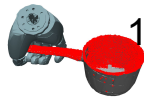


2



3

Grasps ranked by generative
model likelihood



1



2



3

Grasps ranked by predicted
success probability