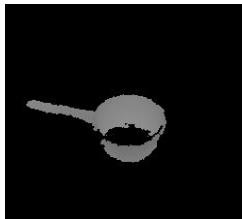


Scene



Depth Image

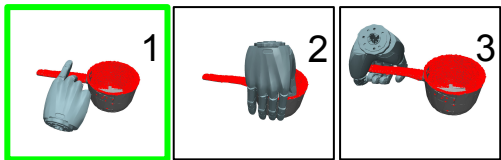


Execution of Top Grasp

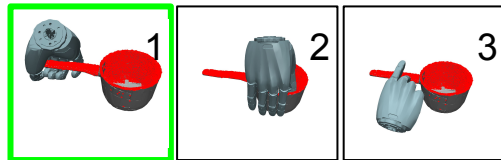


Learned Generative Model

Learned Evaluative Model



Grasps ranked by generative model likelihood



Grasps ranked by predicted success probability